



Give Your Robot a Soft Hand



Version 2.9



Suzhou Rochu Robotics Co.,Ltd.

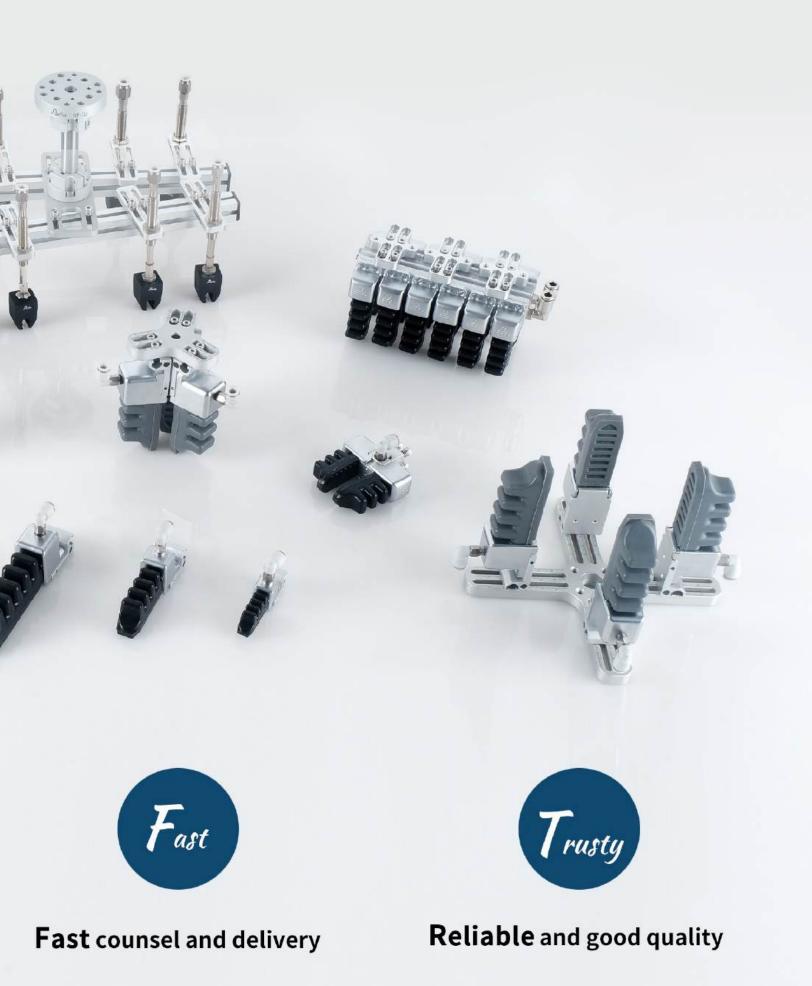




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Suzhou Rochu Robotics Co., Ltd., is located in Suzhou, China. We focus on soft robot technology and are committed to providing soft gripper solutions for industrial automation. Combined with the bionic design concept, Rochu provides a wide range of industrial solutions with soft grippers and robots. The company's main products are Rochu grippers and the control units, which have been used in 3C\* electronics, the food industry, auto parts, garment manufacturing, medical treatment, robot education, packaging logistics, etc.

The company is capable of structural design, material manufacture, and mass production of soft grippers. It has an accredited laboratory in line with CNAS ISO17025 standards. The self-built 3000 m<sup>2</sup> factory has obtained the ISO9001 certification. Our products comply with the FDA, the 1935 / 2004 / EC Food safety certification, the CE Electronic safety certification, and RoHS Environmental safety certification. Our products have obtained many patents from China, Japan, South Korea, the Unites States, and other countries. In addition to China, we have customers from Japan, South Korea, India, Germany, France, the Unites States, etc.

Rochu gives your robot a soft hand. We look forward to hearing from you and cooperating with you soon.

\*:3C: Computer, Communication, and Consumer electronics.

### Abundant product models

We provide a large number of soft gripper models, with modular applications, which can quickly work out your soft gripping solution.

### Many ways to help you choose

Don't know how to choose models? Don't worry.

We have professional consultants to assist you, and we can also provide gripping tests for your samples if provided to eliminate your worries.

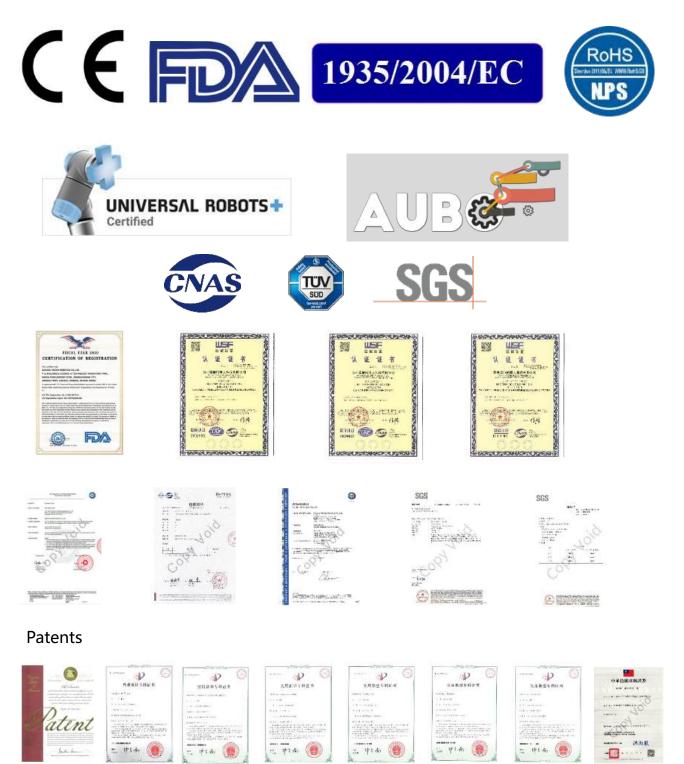
#### Save design time

You can download 3D-CAD-models at www.rochu.com, a variety of models for your choice!

### Fast customizable service

Rochu's professional technical team provides you with customizable services. The average develop-time is 30 working days.

# Honor and qualification



Rochu

Partners

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# **Product Advantages**





- Bionics structure design and covering clamp enable the soft grippers to grasp the objects with **centimeter-level adaptive ability**.
- Facing the soft production line of small-batch and multi-batch in the factory, Rochu can effectively save the switching time of the production line.
- Can adapt to most industrial scenes with **300 times/min opening and closing speed**, ±0.05mm precision, millions of times service life, 9kg maximum load, good chemical and temperature resistance.



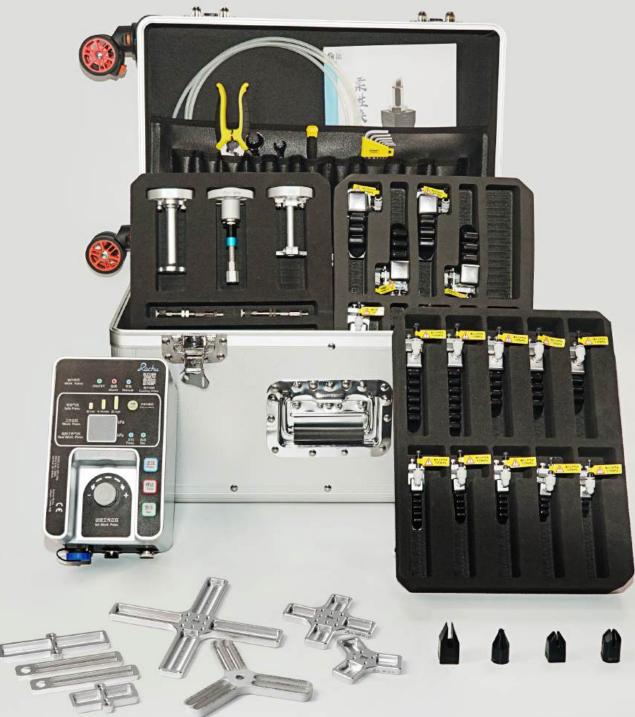
- Rochu' s soft gripper is made of **pure soft material** and possesses **adjustable clamping strength**, making it **safe** to pick and place soft and flimsy objects.
- To deal with vulnerable and fragile products, Rochu' s soft gripper can not only avoid damage but also avoid scratches on the surface while the safety of the operator is also guaranteed.
- The material has obtained **FDA Certification** and can be in direct contact with food.



- The **standardized** finger module makes the construction of soft gripper as simple as building blocks and saves design time.
- Rochu Control Unit is equipped with a standard communication interface, which is seamlessly matched with all kinds of mechanical arms and PLC, as easy as using a USB flash drive.
- The controller has a wireless remote control function and built-in air source (ACU configuration), which is convenient for installation and adjustment. It can also be used in **the mobile working environment** without an air source.

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# **DK Development Kit**



### **DK** Rochu Development Kit

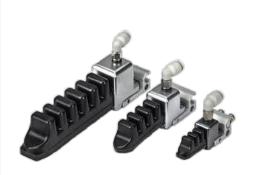
- It includes a full range of Rochu grippers from soft beaks to fingers.
- It can be used without additional accessories and tools. Modules can be assembled and tested quickly in minutes.
- Contains a standard plug-and-play control unit that can be driven by compressed air or power.
- It can be used for the food fresh, 3C electronic parts, clothing fabrics, and auto parts industry, etc.

Rochu

# **DK Development Kit**

#### Rochu Development Kit 2.0

### Bom list



Finger Module ×22



Tools kit ×1



Connection Modules ×6



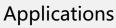
Slide Mounting Plate ×8



Control Unit ×1



Trolley case×1







# Applications

The movement of the Rochu grippers is inspired by the tentacles of the octopus, which can softly wrap the object without damaging the object or leaving scratches on its surface. The grippers can be widely used in auto parts, 3C electronics, food, medical, clothing, daily chemicals, and other industries. Soft Fingers can be used in a variety of industrial applications such as assembly, sorting, and handling, as well as in new retail industries such as vending machines. High safety, good versatility, and convenient installation make up for the vacancy that mechanical grippers and vacuum suction cups can not be applied on some occasions.



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### **3C Electronics**

It applies to the highprecision plug and pull of precision electronic instruments, as well as the assembly, sorting, testing, packaging, and other production processes of related accessories of mobile phones, circuit boards, silicon wafers, thin glass, and other workpieces.



### **Auto parts**

It is used for sorting, handling, loading, and unloading automobile headlights, metal special-shaped parts, and exterior parts. Especially suitable for small batch and multibatch soft production requirements.



#### Fabric

It is suitable for layered grasping or multi-layer simultaneous grasping of knitted and woven fabrics. During layered grabbing, it can only grab the top layer or handle a whole stack of pieces.



### Food

Food safe materials. It has obtained FDA Certification and can directly contact the food. It is especially suitable for sorting and packaging fruits and vegetables, irregular vacuum packaged food, dairy products, dough cakes, and so on.



### **Smart Fetching**

Intelligent grab based on artificial intelligence technology can be used for disorderly stacking, incoming material sorting and logistics packaging in complex scenes.



# **Medical Supplies**

It is used for grasping medical consumables such as infusion tubes, test tubes, ampoules, as well as bottled and bagged reagents, and for the process of production and disinfection of medical instruments.

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# **Rochu Gripper Introduction**

Rochu gripper is a kind of soft fixture independently researched and developed by Rochu Robotics. Rochu's soft gripper applies the principle of bionics to imitate the action of octopus tentacles wrapping the object and grasping the object in a wrapped manner.

Traditional fixtures often cannot provide a successful grasping scheme because of many limitations, such as object shape, material, grasping requirements, and so on. Rochu soft gripper is made of soft materials, which will not damage the target object. At the same time, due to its centimeter-level adaptive ability, it has high versatility. One gripper is universal and suitable for objects of different shapes. Users do not need to change the gripper frequently.

Rochu gripper fills the vacancy of the robot's end gripper and greatly expands the application scene of the industrial robot.

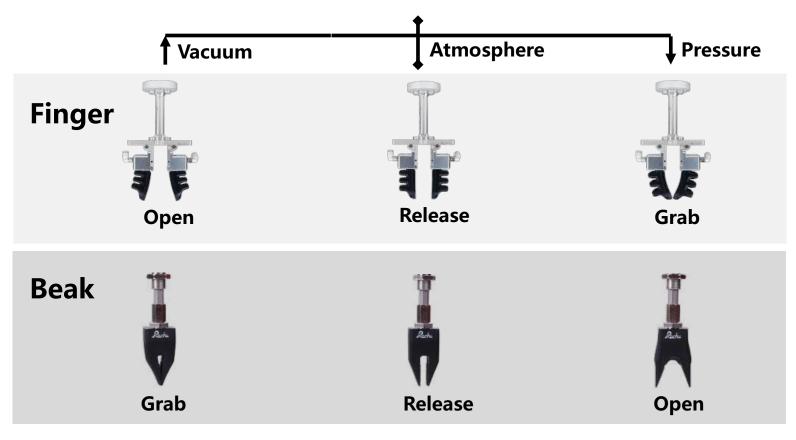
### Working principle

Rochu soft gripper adopts pneumatic drive technology. Through positive and negative pressure switching, the gripper achieves soft fingers/soft beak opening and closing action, so as to achieve grasp or outward expansion action.

At the same time, by adjusting the air pressure to control the clamping strength of the gripper or the angle of opening and closing, to achieve the flexible grasp of different objects, while avoiding pinching objects.

**Rachu** 柔融

**Rochu Control Unit** 



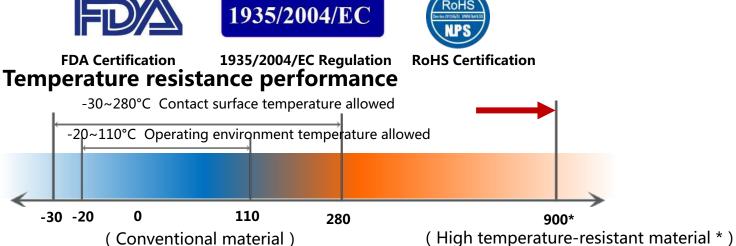
The air pressure must be strictly controlled within the Safe Pressure range. Overload use may cause irreversible damage to the product. It is recommended to use the original Rochu control unit to ensure the service life and stability of the product. Please refer to the product page or package identification for the air pressure of the product.

Rochu

# Soft finger & soft beak material characteristics

### Material safety performance





\* : High temperature-resistant fingers need to be customized according to the requirements of the scene.

Please consult relevant technical support for specific information.

### **Chemical resistance performance**

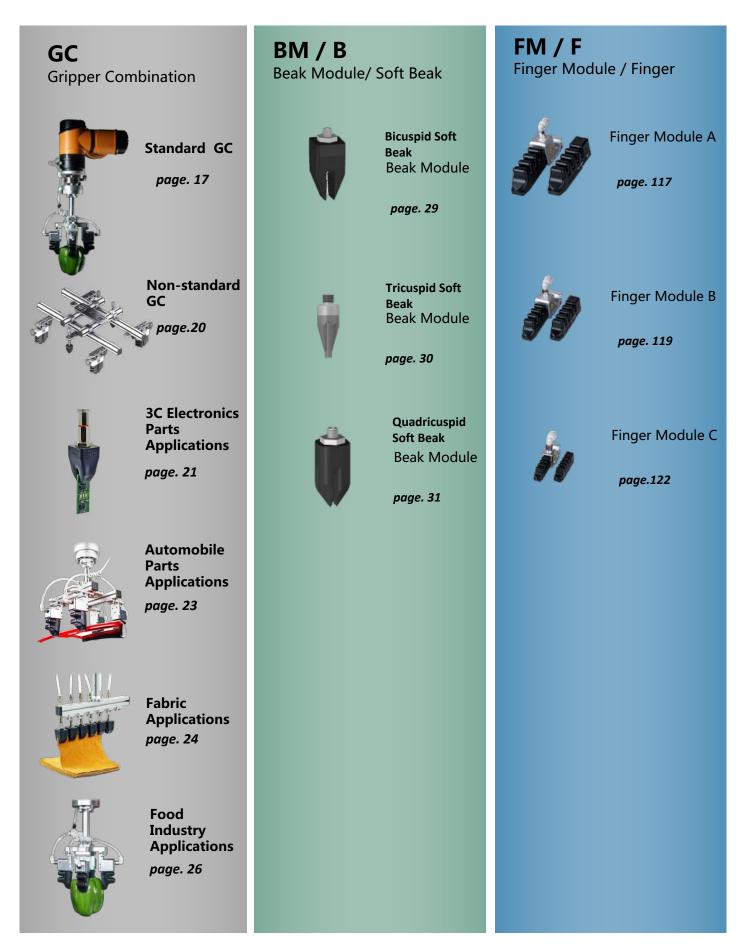
Classification	Concrete Conditions	Performance
	General aging resistance	Excellent
Weather Fastness	UV-Resistance	Good
	Ozone resistance	Good
	Vegetable oil resistance	Excellent
Oil Resistance	Fuel resistance: gasoline	Normal
	Fuel resistance: light oil	Not good
Solvent Resistance	Alcohol and 96% ethanol resistance	
Organic solvents resistance (benzene, toluene, acetone, ethyl acetate)		Normal
	Resistance to strong acid (hydrochloric acid, sulfuric acid, nitric acid, etc.)	Normal
	Resistance to strong base (sodium hydroxide, potassium hydroxide, etc.)	Normal
Acid-base	Resistance to weak acid and pH: 6-7 (such as low concentration	Good
Resistance	phosphoric acid, oxalic acid, etc.)	GOOd
	Resistance to weak base and pH: 7-8 (low concentration ammonia, etc.)	Good
	Hydrofluoric acid and other highly corrosive substances	Not good
The Others	Steam resistance	Excellent
The Others	Wear-resistance	Normal

### Anti-static materials [AS] electrical parameters

<b>.</b>		Material	
Project	Test Standard	Anti-Static Material [AS]	<b>Conventional Material</b>
Surface resistance[Ω]	IEC 61340-2-3:2016	10 <sup>6</sup> —10 <sup>9</sup>	>10 <sup>10</sup>

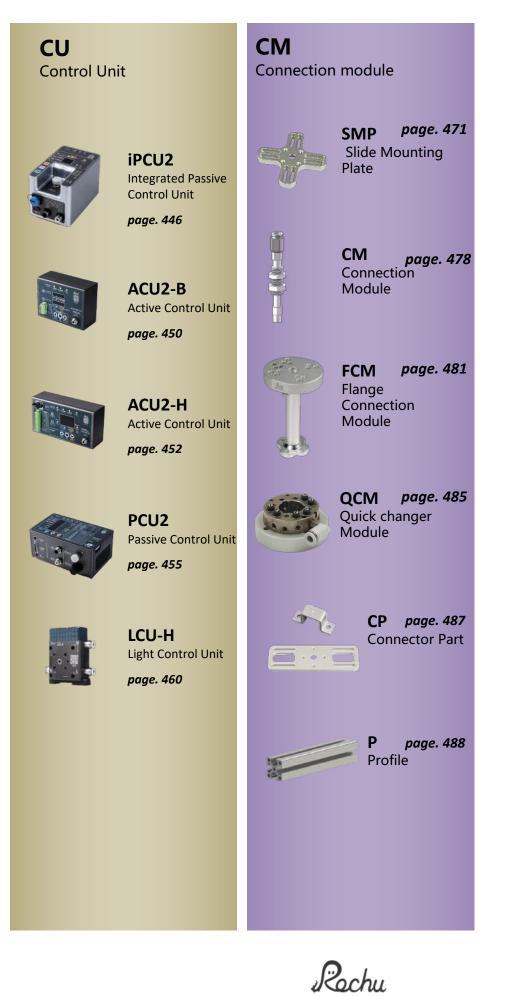


### **General Index**

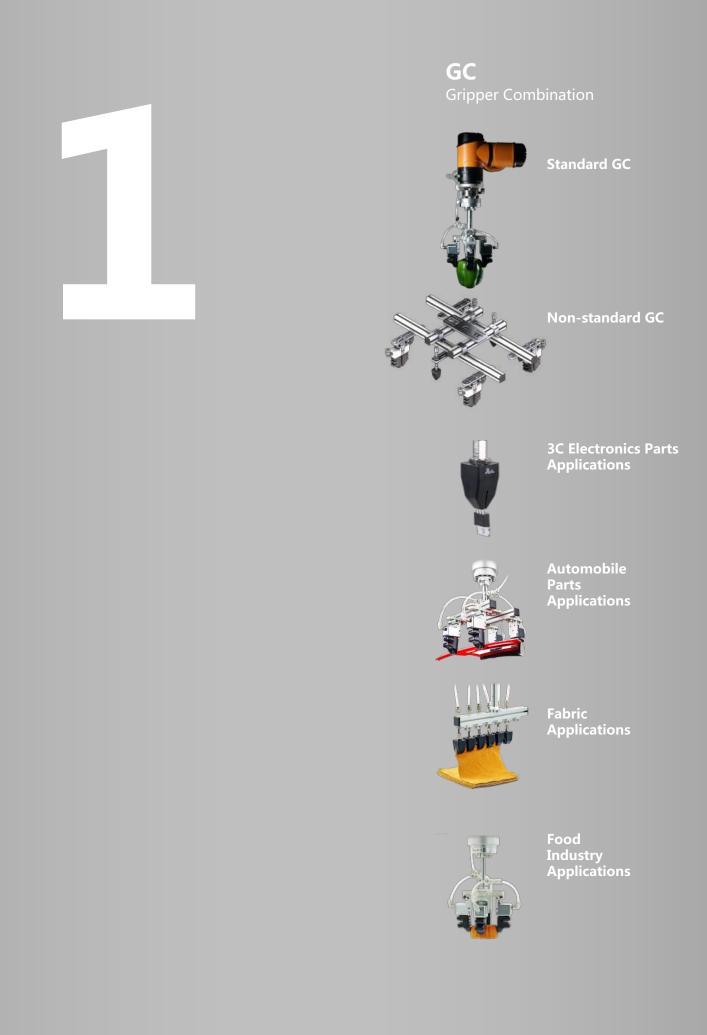


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### **General Index**



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### Standard Gripper Combination

A standard Rochu Soft finger Gripper Combination [GC] is built of different modules and named in a standard way. The building of modules can be in the following steps: 1. Finger module [FM], 2.Slide Mounting plate [SMP], 3.Flange Connection Module [FCM], 4.Quick changer Module [QCM] (Optional).

# QCM (Optional)

### Quick changer module

Quick changer module [QCM] is an optional module for automatic and quick replacement of spare grippers. Quick changer module[QCM] is installed between the flange connection module [FCM] and the end of the robot arm. A pair of QCMs can be divided into two parts, the robot side (R side, installed at the end of the robot arm) and the gripper side (G side, installed at the gripper end).

### FCM

#### Flange connection module

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Flange connection module [FCM] is a connector between the end of the robot arm and the sliding mounting plate [SMP]. It can also be connected with quick changer module [QCM]. There are two types of [FMC], the spring rod type (S) and the rigid rod type (R).

# SMP

#### Slide Mounting Plate

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The **sliding mounting plate [SMP]** is the standard mounting plate for Rochu finger module [FM], and the mounting plate is equipped with a standard chute and scale mark. The installation position and posture angle of the finger module [FM] in the chute can be adjusted freely.

# FM

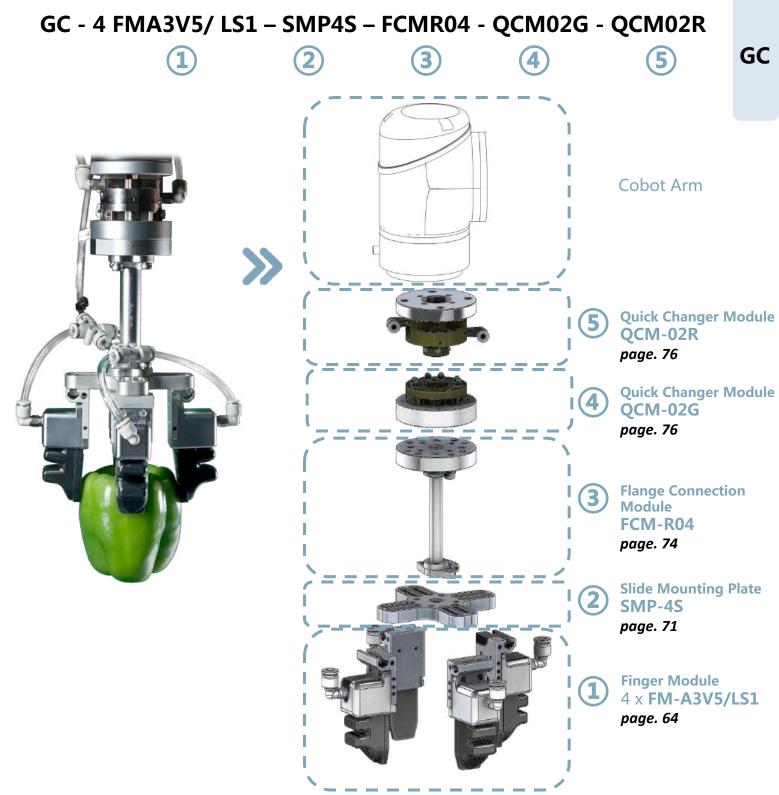
#### Finger Module

page. 48 Finger module [FM] is the actuator of Rochu claw. According to the finger load capacity, it can be divided into three series, finger(A), finger(B), and finger(C). Each module can be installed separately or combined seamlessly, which is easy to assemble and disassemble.

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**Encoding Method of standard Gripper Combination** 

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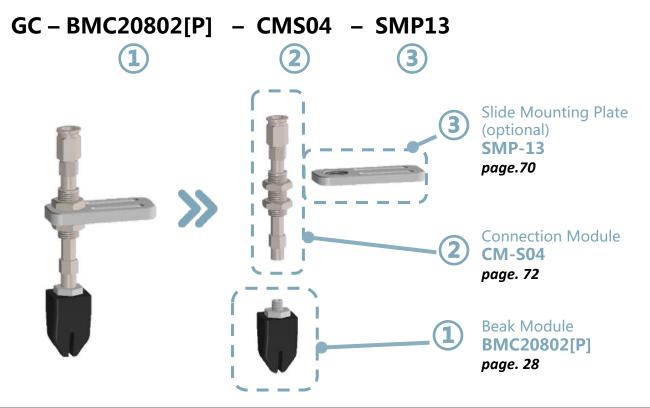


### **Encoding Method of standard Gripper Combination**



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**Standard Rochu beak gripper combination [GC]** can be combined in the following order, 1. Soft beak module **[BM]**, 2. Connection module **[FCM] / [CM]**, 3. Sliding mounting plate **[SMP]** (optional).



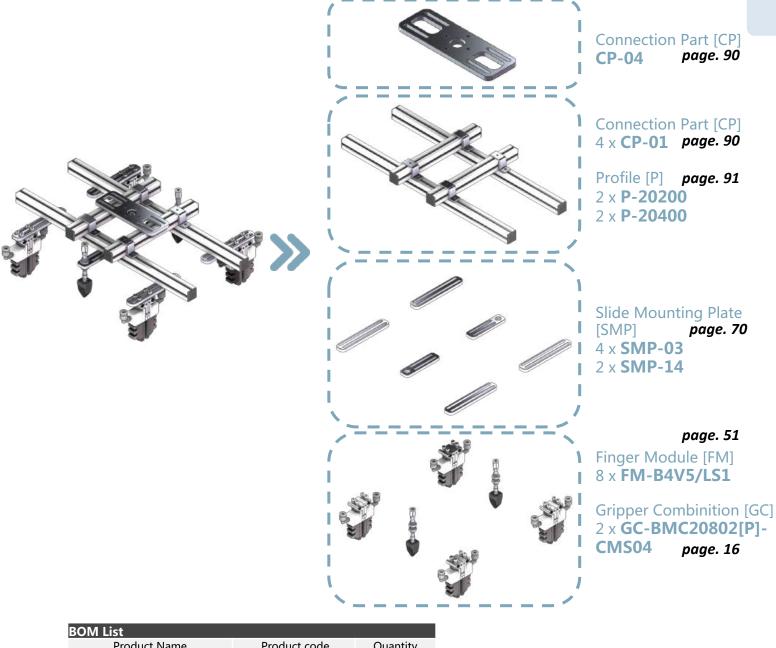
GC – BML20802[P] – FCMS01 (1) (2) Flange Connection Module FCM-S01 page. 73 (1) Beak Module BML20802[P] page. 28



#### **Non-standard Gripper Combination**

#### **Product Features**

- Suitable for products with large volumes or irregular shapes.
- Aluminum alloy profiles are used for combination and connection.
- Standard gripper combination [GC] or module [FM] can be installed in any part of the bracket.
- Suction cups, sensors, cylinders, or other components can also be added according to the working conditions.
- The gripper plan adopts the BOM(Bill Of Materials) method.



BOM List		
Product Name	Product code	Quantity
Connection Part	CP-04	1
onnection Part	CP-01	4
Profile	P-20200	2
Profile	P-20400	2
Slide Mounting Plate	SMP-03	4
Slide Mounting Plate	SMP-14	2
Finger Module	FM-B4V5/LS1	8
Standard Gripper Combination	GC –BM2B-CMS04	2



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GC





Gripper combination for flat parts



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page. 79



GC – 2FMA3V5/LS1– SMP2L

#### **Gripper Combination Plans**



GC

Finger Module: FM-C3V5/LS1 Slide Mounting Plate: SMP-4L



Standard Gripper Combination: GC-4FMC3V5/LS1-SMP4L



Finger Module: FM-A4V5/LS1 Slide Mounting Plate: SMP-3L



Standard Gripper Combination: | GC-3FMA4V5/LS1-SMP3L



#### Non-standard

**Integrated Passive Control Unit – Standard Model\*** 

\* : For other Control Units, see page. 402.

Product code	Quantity
FM-A3V5/LS8 [AS]	8
P-20400	2
P-20300	2
CP-01	4
CP-04	1
FCM-R08	1
	FM-A3V5/LS8 [AS] P-20400 P-20300 CP-01 CP-04



Integrated circuit

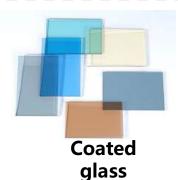


Silicon wafers



iPCU2-SMN

Optical lens



Pechu

### 夹爪组合 / Gripper Combination

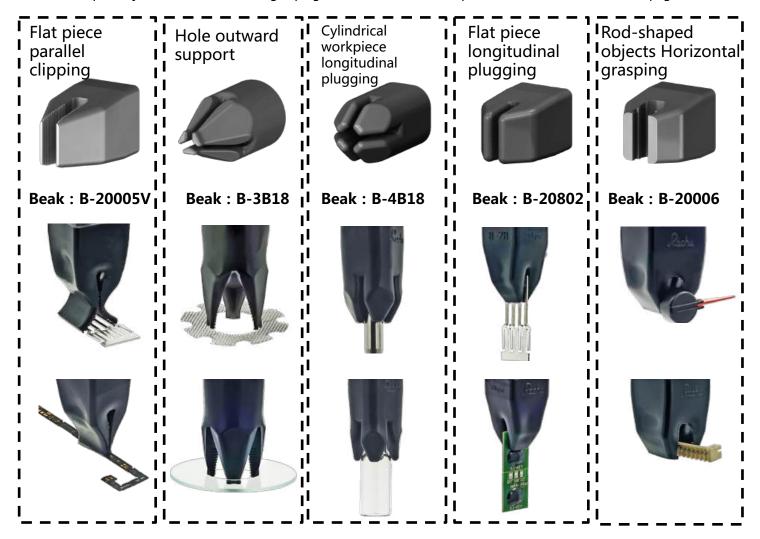


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# 3C Electronics Parts Applications : • Soft beak for micro and small parts



**Recommended soft beak:** Select the soft beak according to the shape, volume, material and working condition of the clamped object to achieve the best grasping effect. For the technical parameters of the soft beak, see page. 40.



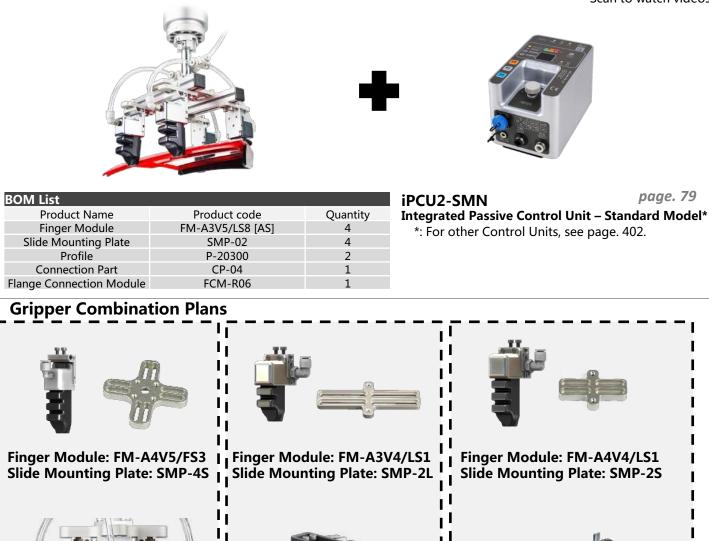
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GC

**Automobile Parts Applications** 

• Gripper combination for car headlight, seat slide, bearing, soft pack battery, etc.









Standard Gripper Combination . IStandard Gripper Combination: Standard Gripper Combination: GC-6FMA3V4/LS1-SMP2L

GC-8FMA4V4/LS1-3SMP2S



**Car Headlight** 

Bearing Soft Pack Battery

LOID

Seat Slide

**Seat Headrest** 





#### Fabric Handling Applications :

• Beak module combinations can be used for soft and breathable thin knitting and woven fabrics in layers. Only the first piece of multi-layer fabrics can be grabbed at a time.



#### **Customized gripper combination:**

BOM List		
Product Name	Product code	Quantity
Gripper Combination	GC -BMC20006[P]-CMS04-SMP13	8
Profile	P-20400	2
Connection Part	CP-04	1
Flange Connection Module	FCM-R04	1
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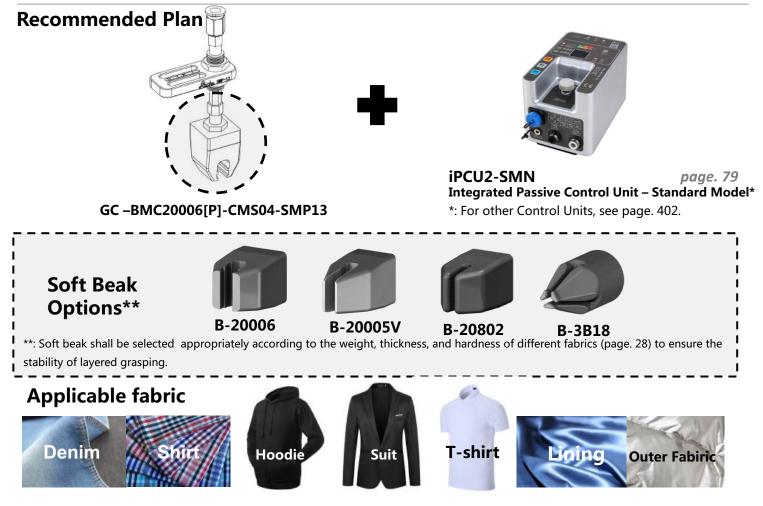
Note: For large soft fabric layers (e.g. T-shirts, sweatshirts, etc.), it is recommended to install multiple independent soft beak grippers at

intervals along the edge of the fabric.

#### **Customized gripper combination:**

BOM List		
Product Name	Product code	Quantity
Gripper Combination	GC -BMC20006[P]-CMS04-SMP13	6
Profile	P-20200	1
Flange Connection Module	FCM-R08	1

Note: For hard fabric layers (e.g., denim, etc.), it is recommended to install multiple soft beak grippers closely in rows.







GC



GC



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#### Fabric Handling Applications:

The two-finger gripper can be used for layered grasping of thick and hard fabrics, such as wool textile, towel, carpet, etc. the gripper can be combined with customized bracket in series according to the shape of the fabric.



#### **Customized gripper combination:**

BOM List		
Product Name	Product code	Quantity
Gripper Combination	GC –2FMB4V5/FS3-SMP2S	2
Profile	P-20200	1
Flange Connection Module	FCM-R04	1

#### **Recommended Plan**



GC –2FMB4V5/FS3-SMP2S





#### page. 79 iPCU2-SMN **Integrated Passive Control Unit – Standard Model\***



\*: For other Control Units, see page. 402.





#### FM-C5V5/FS3

\*\*: Finger modules shall be selected appropriately according to the weight, thickness, and hardness of different fabrics to ensure the stability of layered grasping.

### Applicable fabric

**Optional Finger Module\*\*** 





FM-A4V5/FS3



FM-B4V5/FS3







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GC

#### **Food Industry Applications**

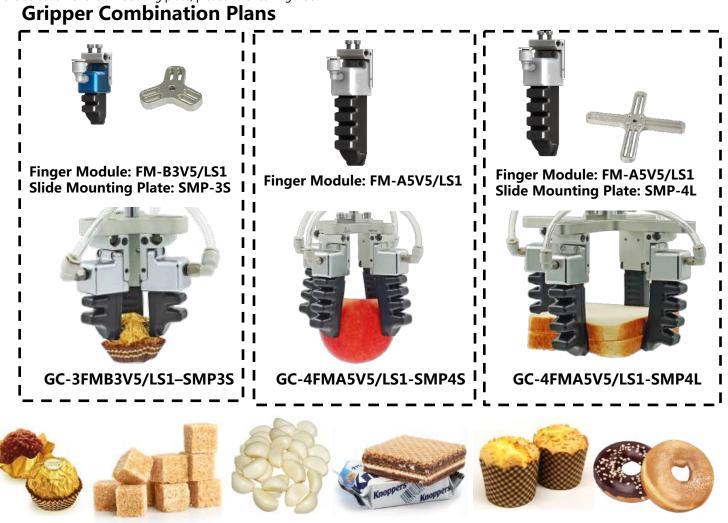
• Multi-finger centripetal gripper combination, suitable for spherical or square candy, pastry, or fruit.



GC – 4FMA3V5/LS1 - SMP4S - FCMR02

**iPCU2-HMN** Integrated Passive Control Unit – High-speed model\* \*: For other Control Units, see page. 402.

When the grasped object changes, the finger module or slide mounting plate should be replaced according to the shape, volume, weight, and material of the grasped object to achieve the best grasping effect. For the selection of the finger module, please refer to Page. 38. For the selection of slide mounting plate, please refer to Page. 58.



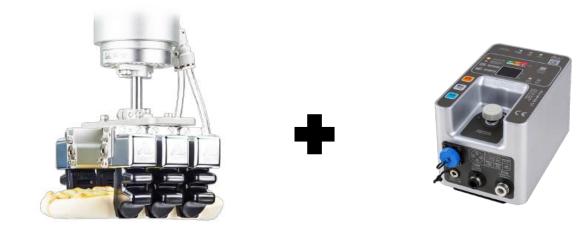
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#### Food Industry Applications

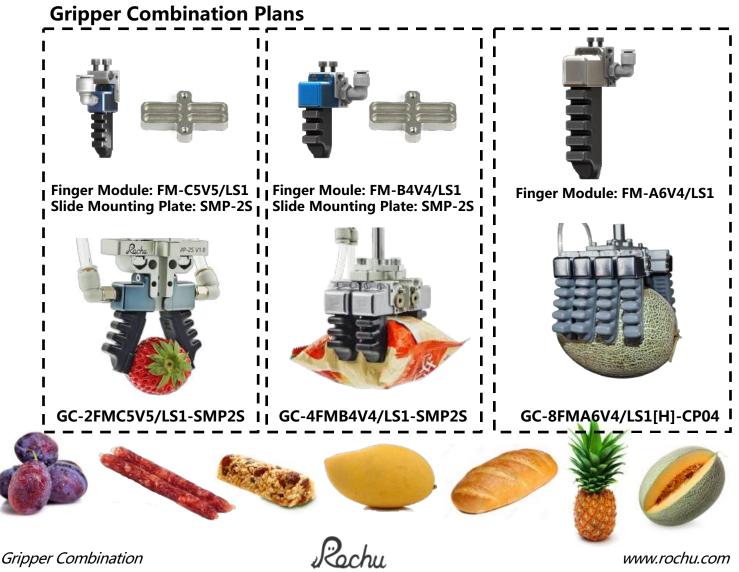
GC-6FMA3V4/LS1-CP04-FCMR02

• Multi-finger subtending gripper combination, suitable for the strip, oval-shaped fruit, food, etc.



iPCU2-HMN page. 79 Integrated Passive Control Unit – High-speed model\* \*: For other Control Units, see page. 402.

When the grasped object changes, the finger module or slide mounting plate should be replaced according to the shape, volume, weight, and material of the grasped object to achieve the best grasping effect. For the selection of the finger module, please refer to Page. 38. For the selection of slide mounting plate, please refer to Page. 58.





## BMC / BML/ B

Beak Module/ Soft Beak

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#### BMC / BML/ B Beak Module/ Soft Beak

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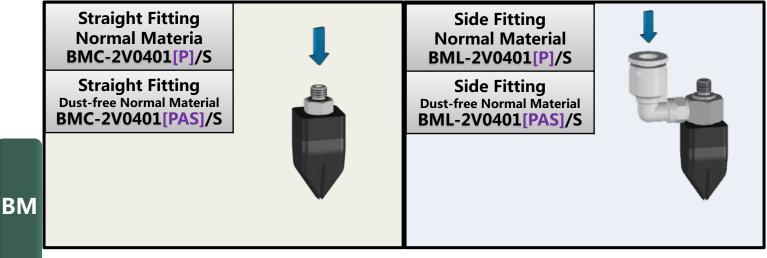
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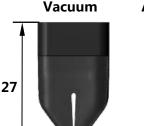
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#### Product features

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.

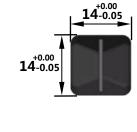


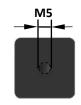




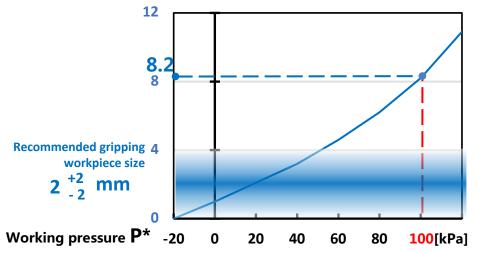








Gripping fingertip distance G [mm]



#### Parameter

Repetitive Precision	Recommend -ed Load <sup>25g</sup>	Lifetime times*	Safe Pressure	+100kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	8g Ko	BML Weight17g 🖉

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.



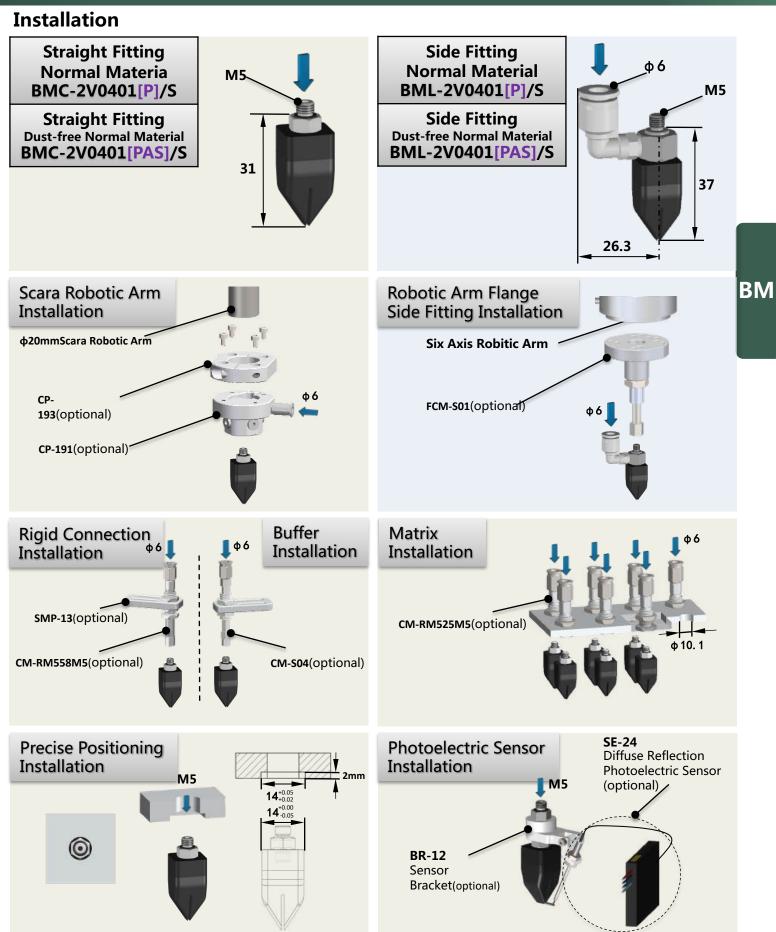
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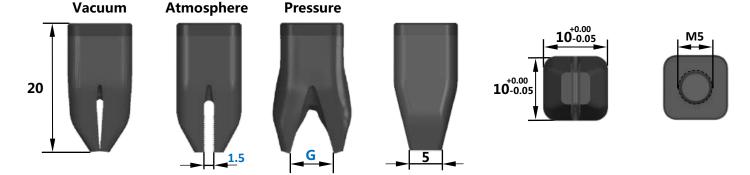
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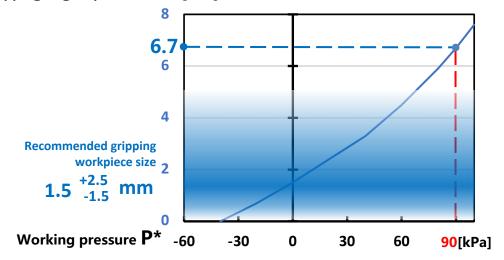


- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance **G** can be adjusted by working pressure. Soft beak material is divided into Normal Material **[P]** and Dust-free Normal Material **[PAS]**. When the workpiece is light, or
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.





Gripping fingertip distance G [mm]



#### Parameter

Repetit Precisi	ve 5n ±0.05mm	Recommend -ed Load	20g	Lifetime	1.5 million times*	Safe Pressure	+90kPa		Contact Temperature	180°C	2
Frequer	cy6times/sec	External gripping force	()-() ZN	Internal gripping force	X	BMC Weight	3.7g	л 9	BML Weight	13g	л Я

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.



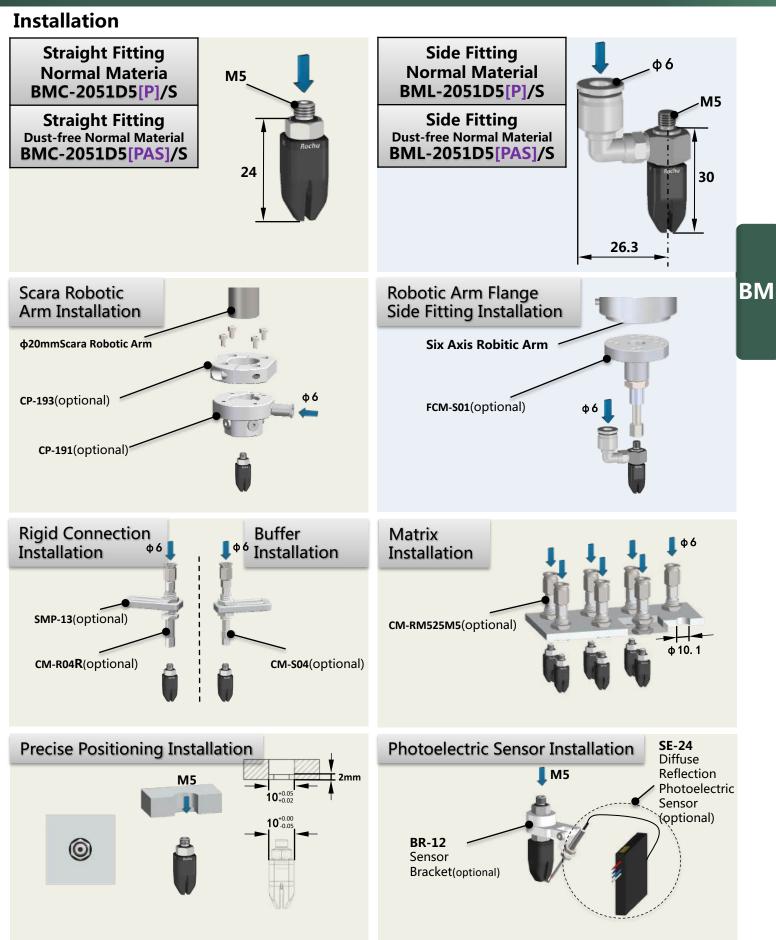
### Beak Module

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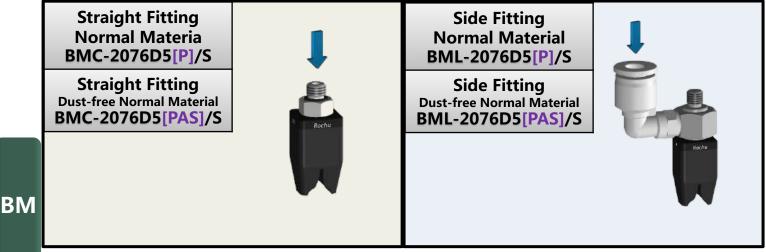
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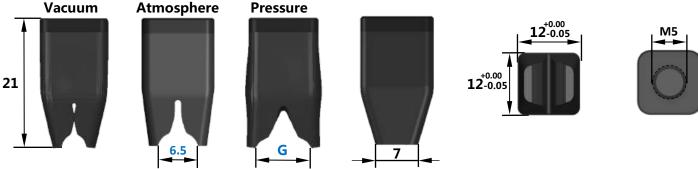
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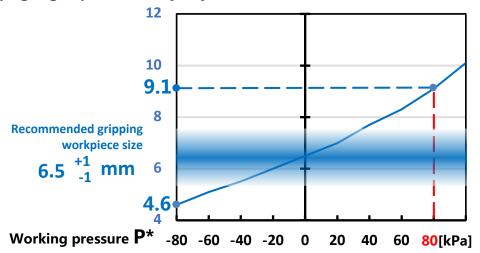
#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.





Gripping fingertip distance G [mm]



#### **Parameter**

Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime times*	Safe Pressure	+80kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	6g 🛱	BML Weight15g 🛛 👸

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.

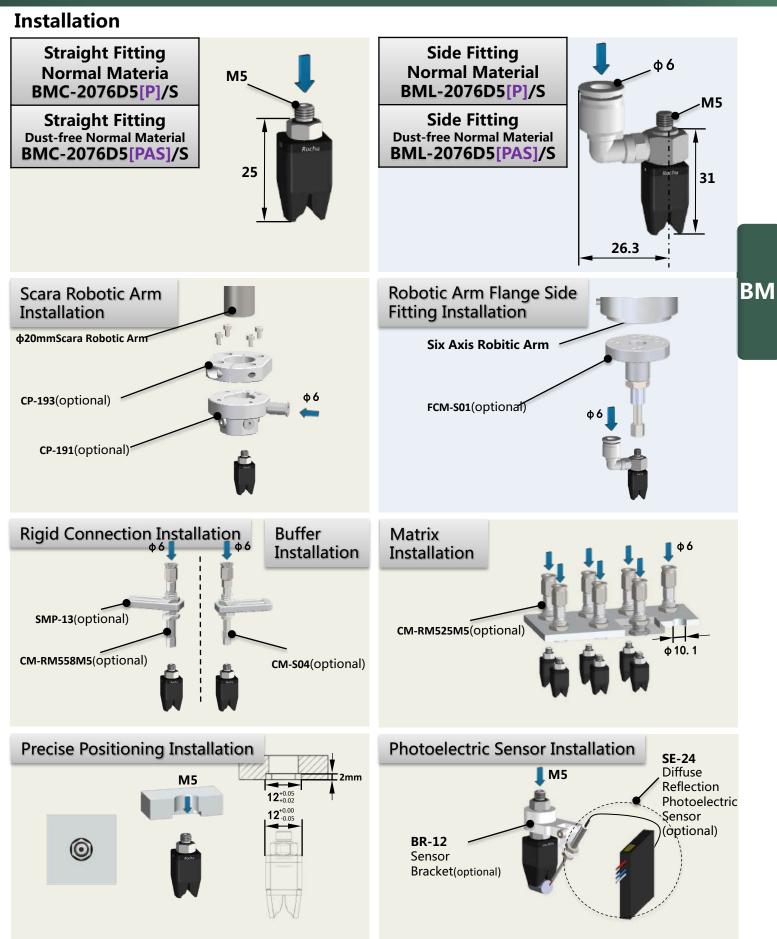


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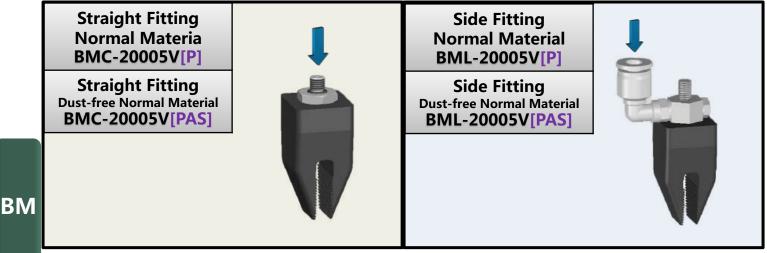
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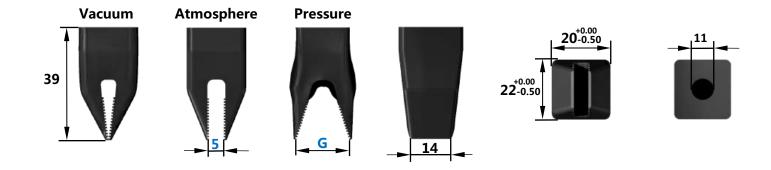
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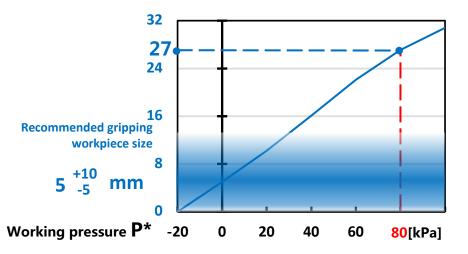
#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.





#### Gripping fingertip distance G [mm]



#### Parameter

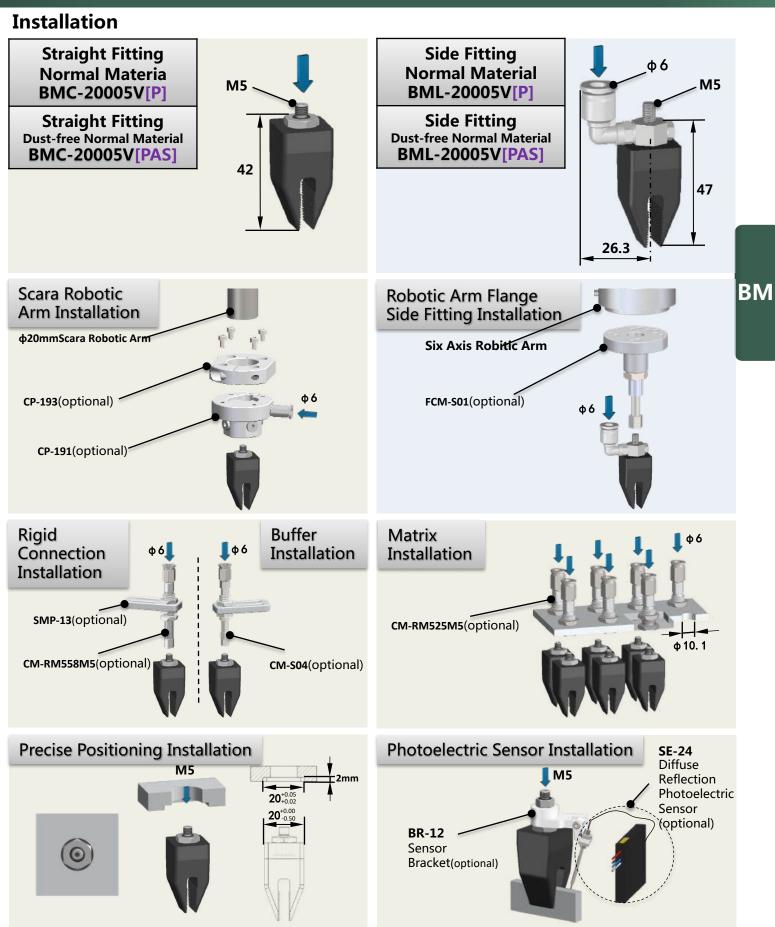
Repetitive Precision ±0.05mm	Recommend -ed Load <sup>30g</sup>	Lifetime 1.5 million times*	Safe Pressure	+80kPa 👔	Contact Temperature 180℃
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	18g 🛱	BML Weight 27.5g 🚡



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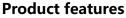




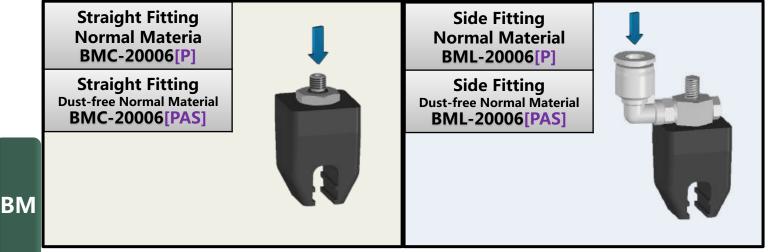
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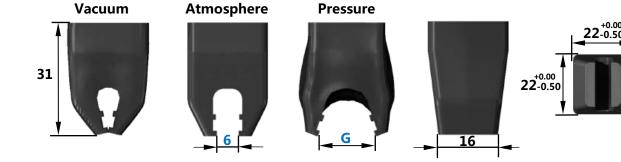
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- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure. Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or
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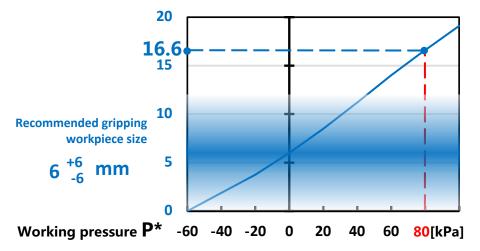






+0.00

Gripping fingertip distance G [mm]



#### Parameter

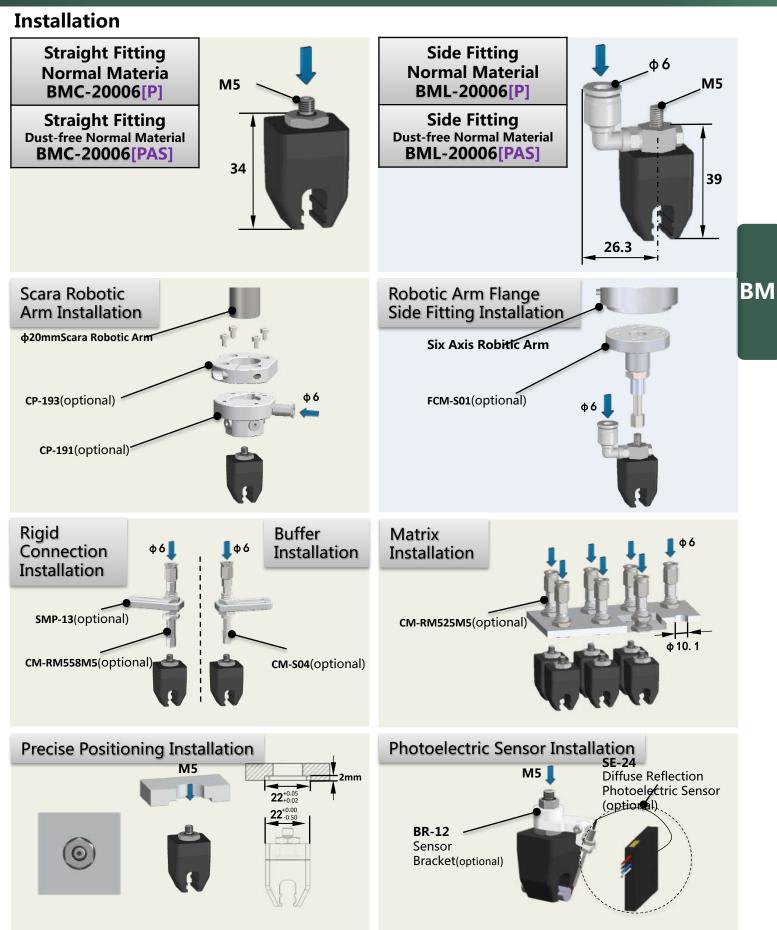
Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime times*	Safe Pressure	+80kPa 🛕	Contact Temperature 180℃
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	18g 🔤	BML Weight 22.5g 🚡



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Rochu

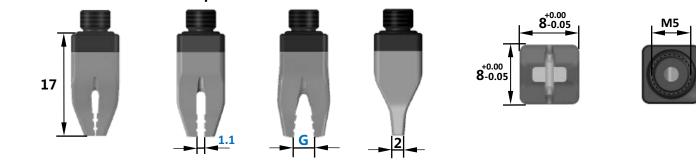
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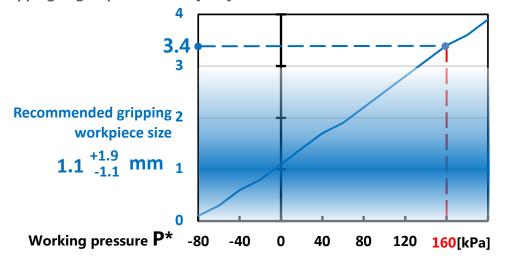
#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.





Gripping fingertip distance **G** [mm]



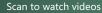
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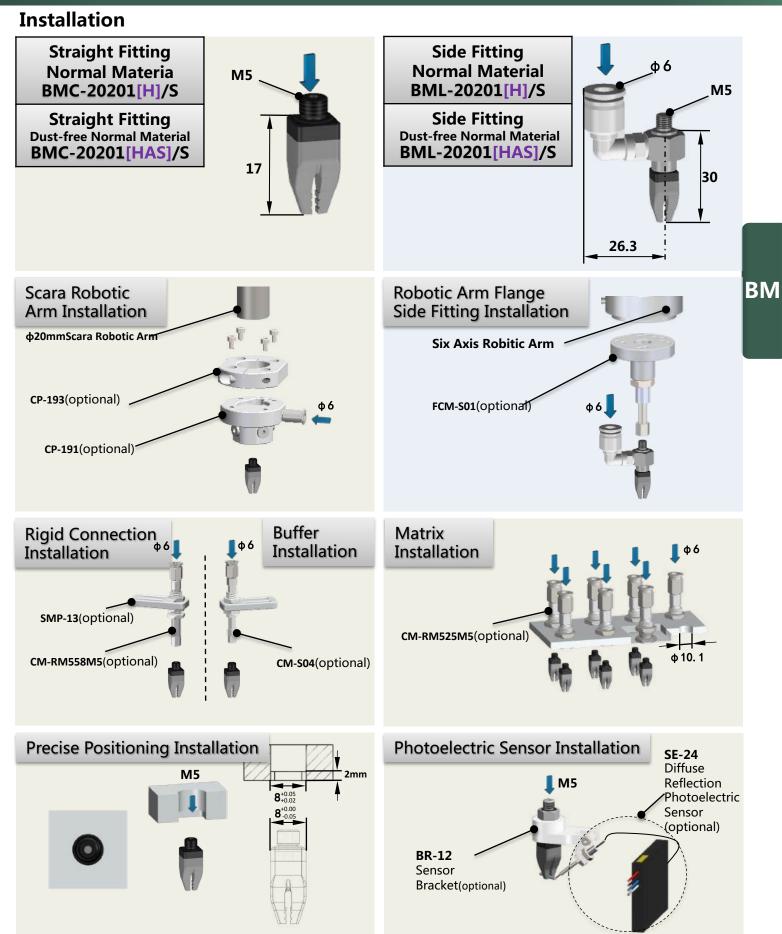
Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime times*	Safe Pressure	+160kPa 🛕	Contact Temperature 180℃
Frequency6times/se	c External 0-0.1N	Internal gripping force	BMC Weight	2.5g 🚡	BML Weight 14.5g 🚦



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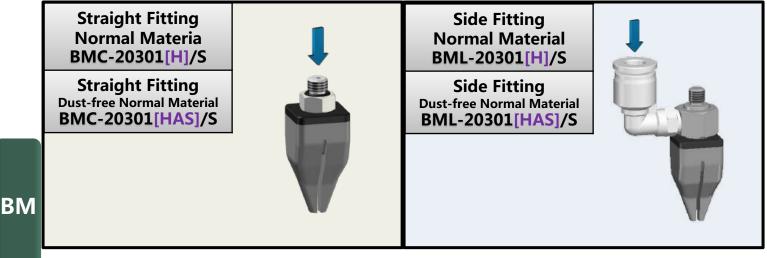
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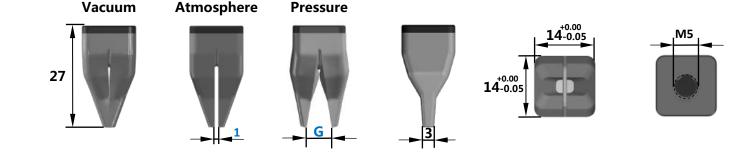


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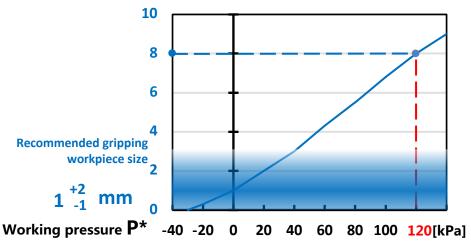
#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.





Gripping fingertip distance G [mm]



#### Parameter

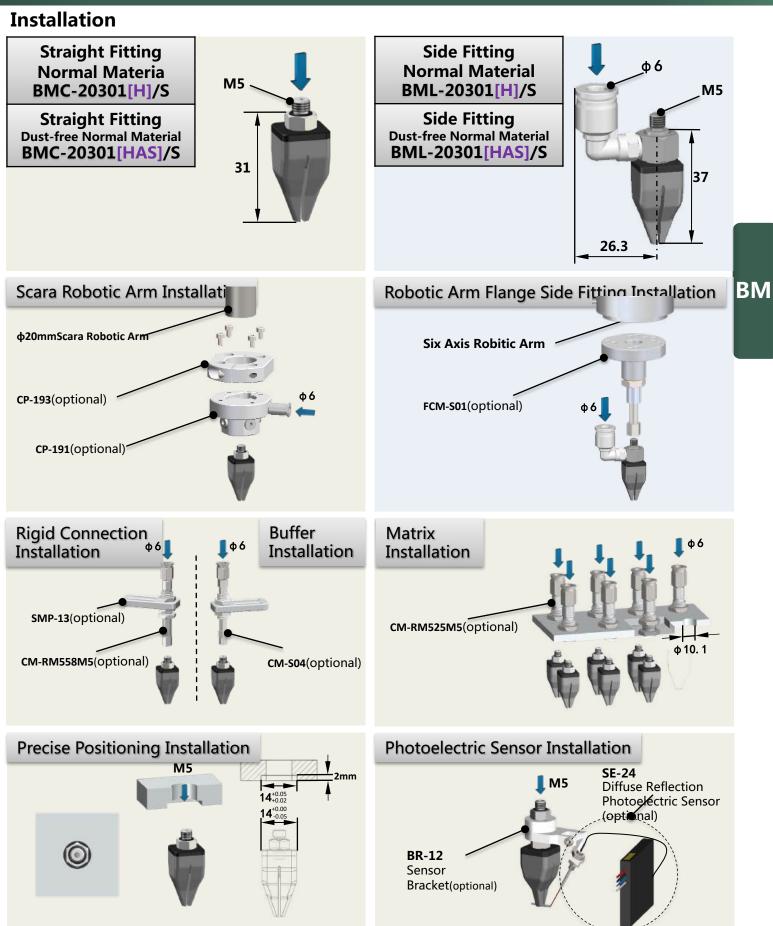
Repetitive Precision ±0.05mn	Recommend -ed Load <sup>25g</sup>	Lifetime 1.5 million times*	Safe Pressure	+120kPa 🛕	Contact Temperature 180℃
Frequency6times/se	c External gripping force 0-0.25N	Internal gripping force	BMC Weight	6g 🚡	BML Weight15.5g 👸



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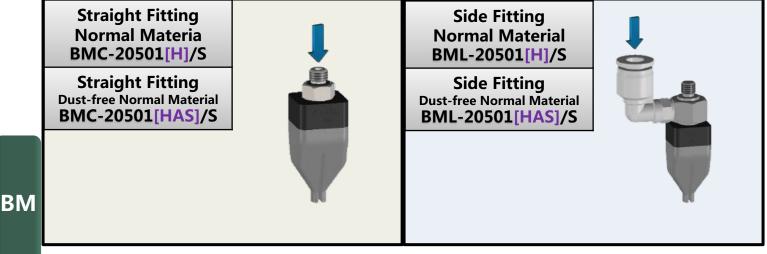
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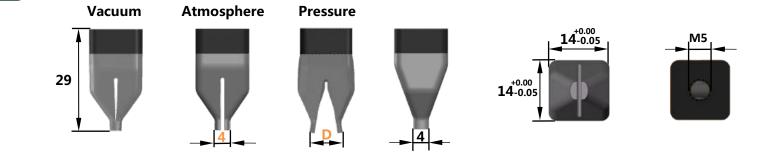
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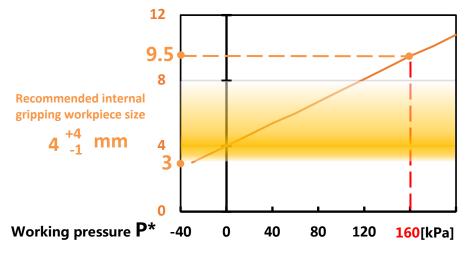
#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Internal gripping fingertip distance D can be adjusted by working pressure. Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or
- very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.





#### Internal gripping fingertip distance D [mm]



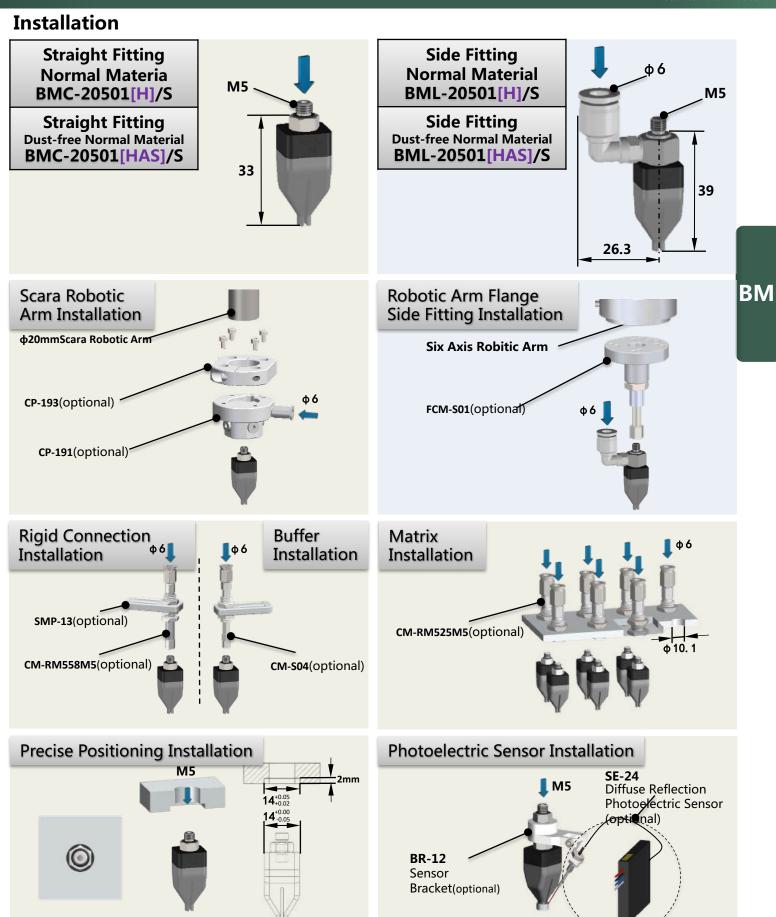
#### **Parameter**

Repetitive Precision ±0.05mm	Recommend -ed Load <sup>5</sup> g	Lifetime times*	Safe Pressure	+160kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	7g 🏹	BML Weight 16g 🖉





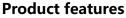




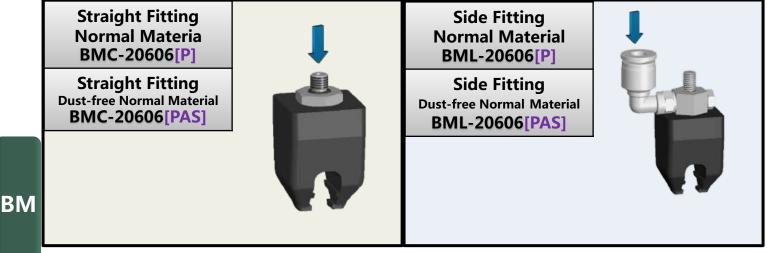
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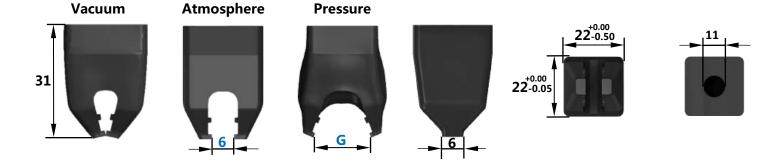
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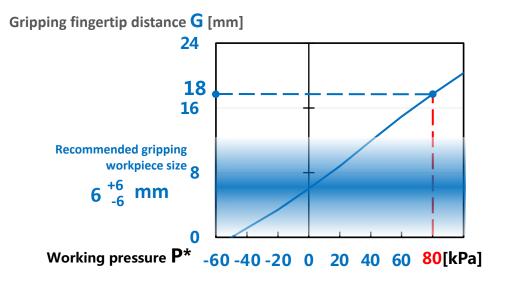
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- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.







#### Parameter

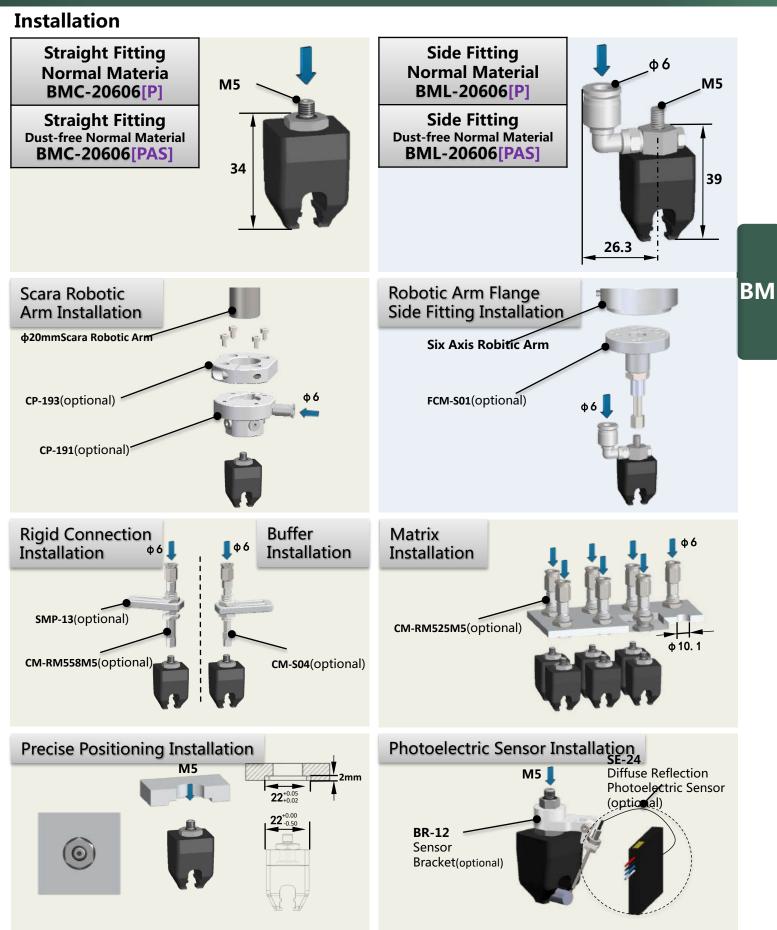
Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime 1.5 million times*	Safe Pressure	+80kPa 👔	Contact Temperature 180℃
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	17g 👸	BML Weight26.5g 👸



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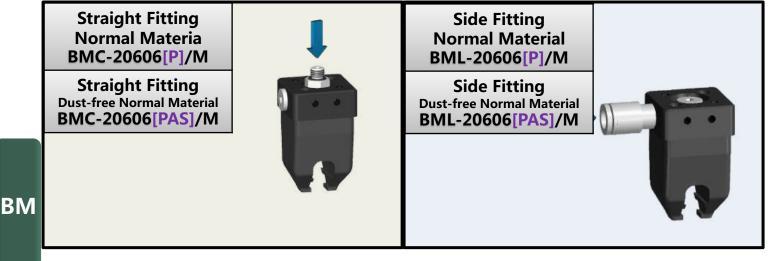
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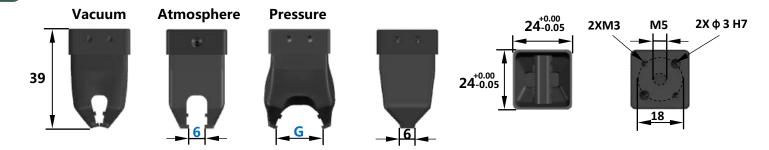


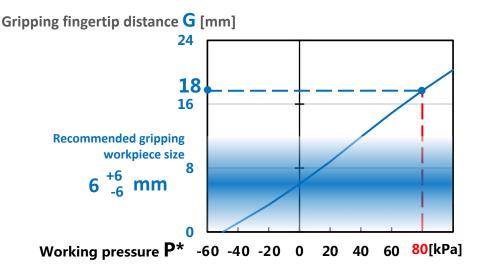
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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.







#### Parameter

Repe Prec	titive ision ±0.05mm	Recommend -ed Load	g Lifetime	1.5 million times*	Safe Pressure	+80kPa		Contact Temperature	180°C	2
Frequ	ency6times/sec	External gripping force	0.3N Internal gripping force	X I	BMC Weight	22g	л I	BML Weight	21g	д Ø

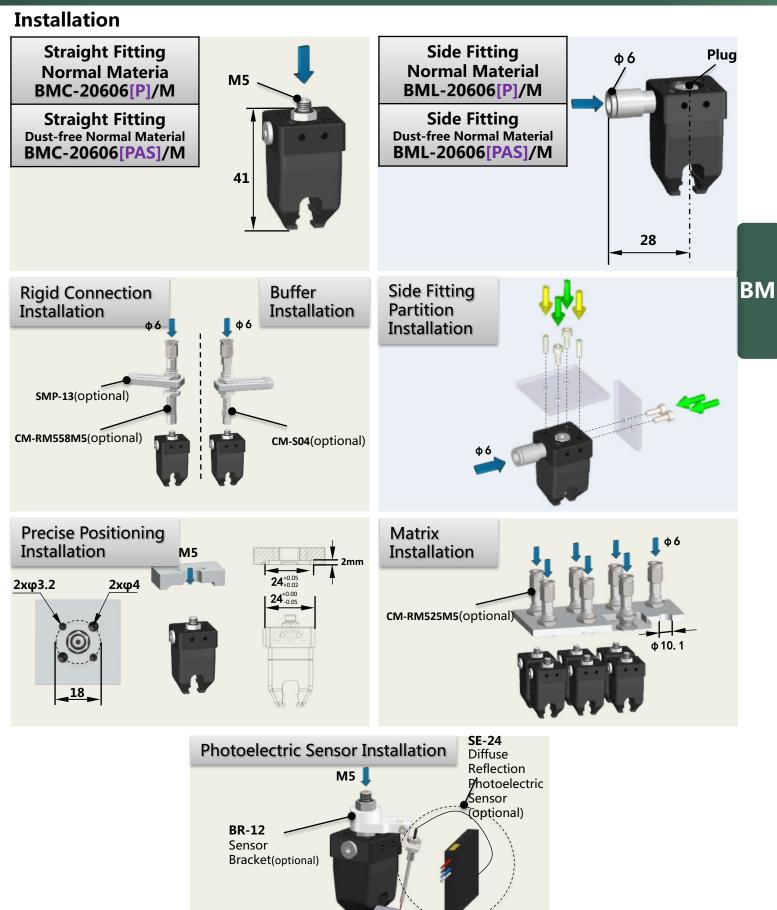


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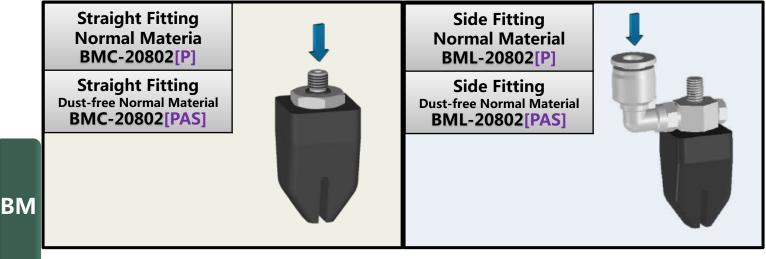


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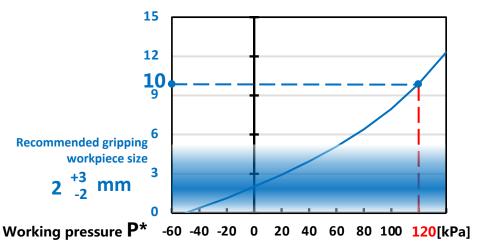
#### Product features

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#### Gripping fingertip distance G [mm]



#### Parameter

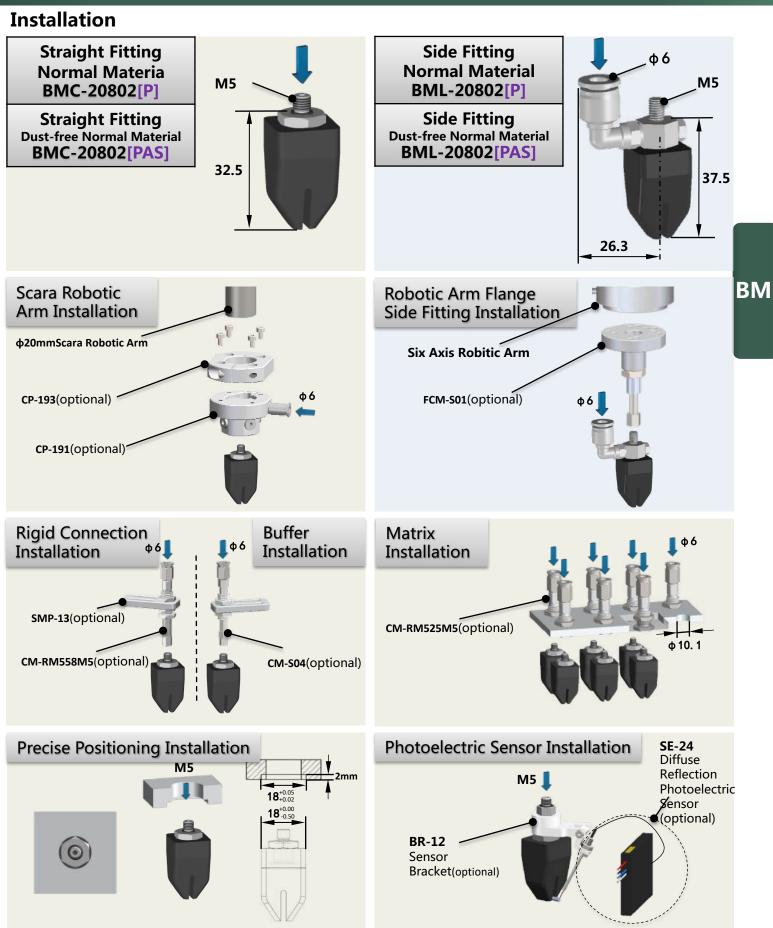
Repetitive Precision ±0.0	05mm Recomi -ed	nend Load <sup>20g</sup>	Lifetime	1.5 million times*	Safe Pressure	+120kPa 🛕	Contact Temperature	180°C	:
Frequency 6tin	nes/sec	ternal force	Internal gripping force	X	BMC Weight	14g 🚡	BML Weight	23g	л II



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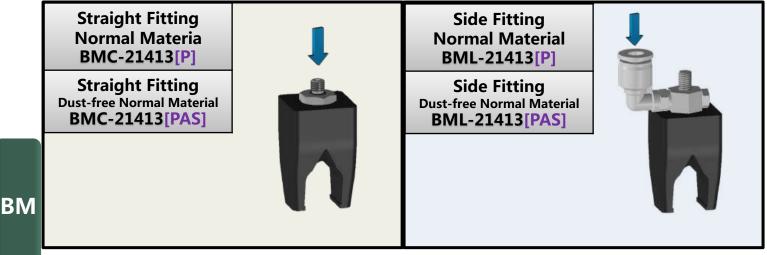
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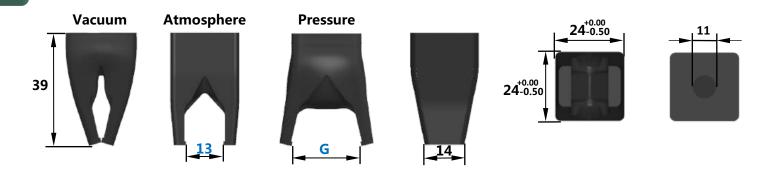
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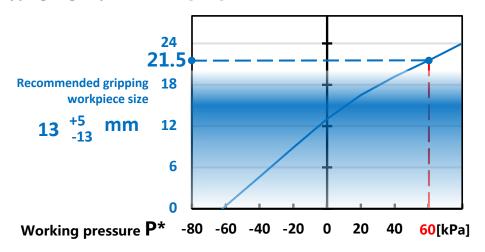
#### **Product features**

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Gripping fingertip distance **G** [mm]



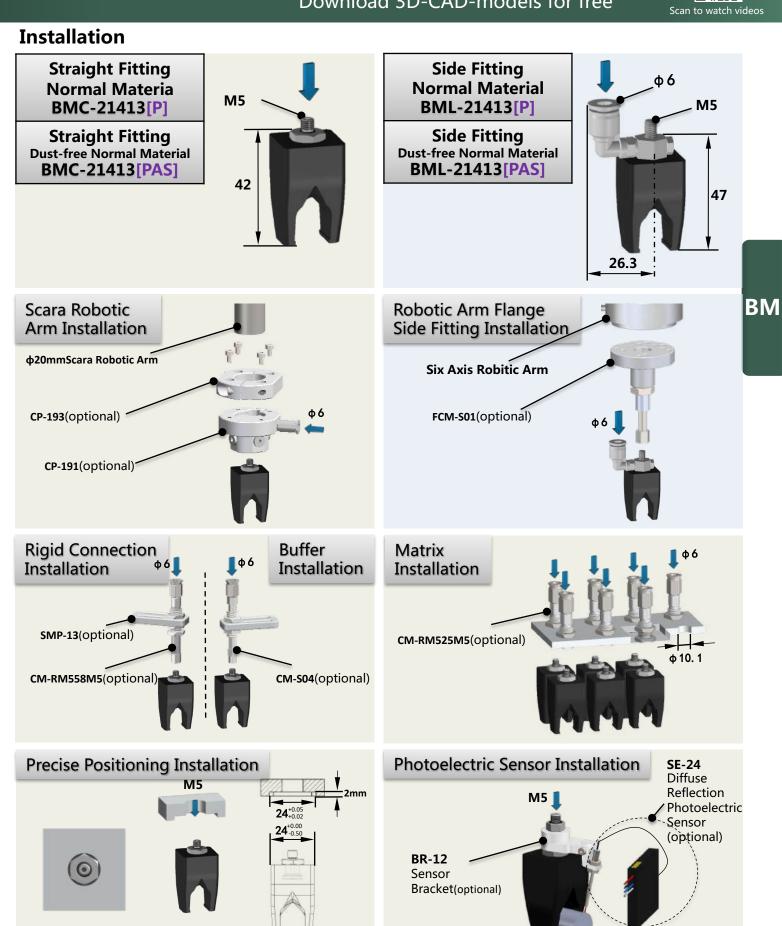
#### Parameter

Repetitive Precision ±0.05mm	Recommend -ed Load <sup>50</sup> g	Lifetime times*	Safe Pressure	+60kPa		Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	20.6g	л I	BML Weight 30g 🖉









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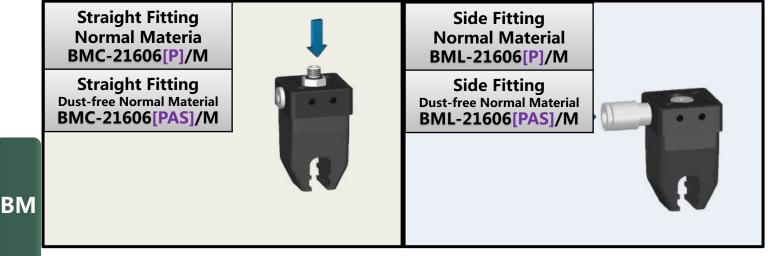
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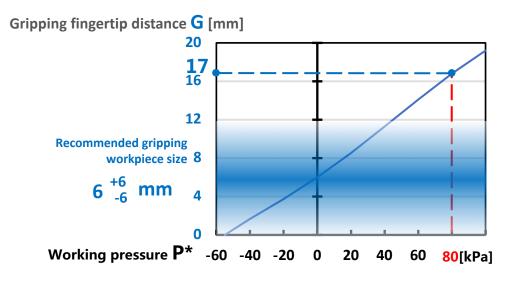
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- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.







#### Parameter

Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime 1.5 million times*	Safe Pressure	+80kPa 🛕	Contact Temperature
Frequency 6times/sec	External gripping force	Internal gripping force	BMC Weight	24g 🛱	BML Weight23g 🖉

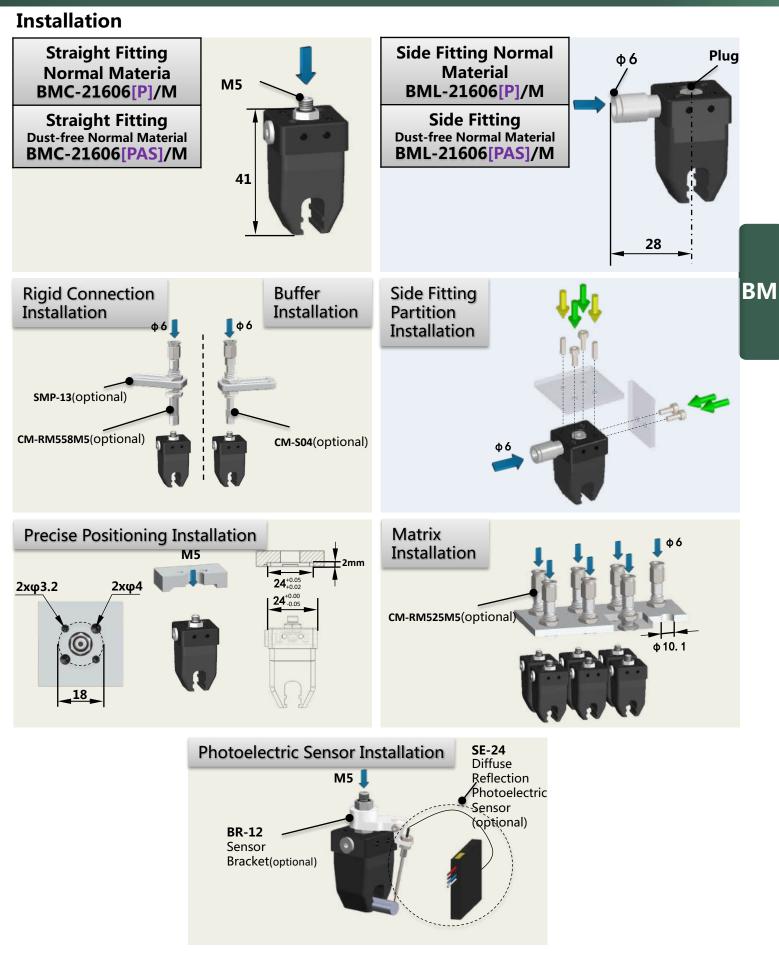


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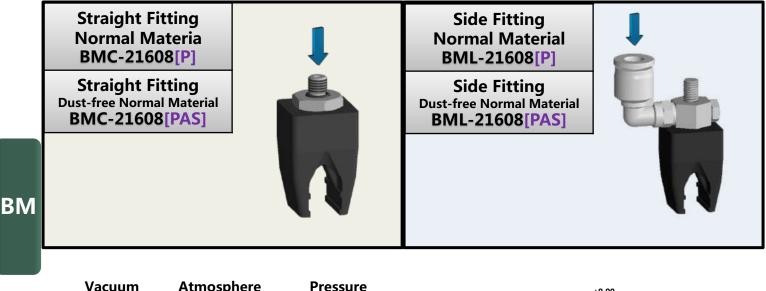
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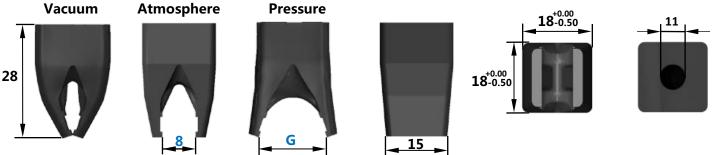
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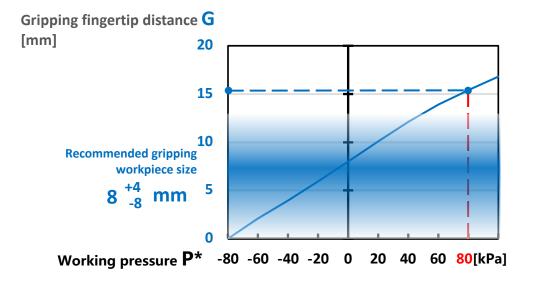


#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.







#### Parameter

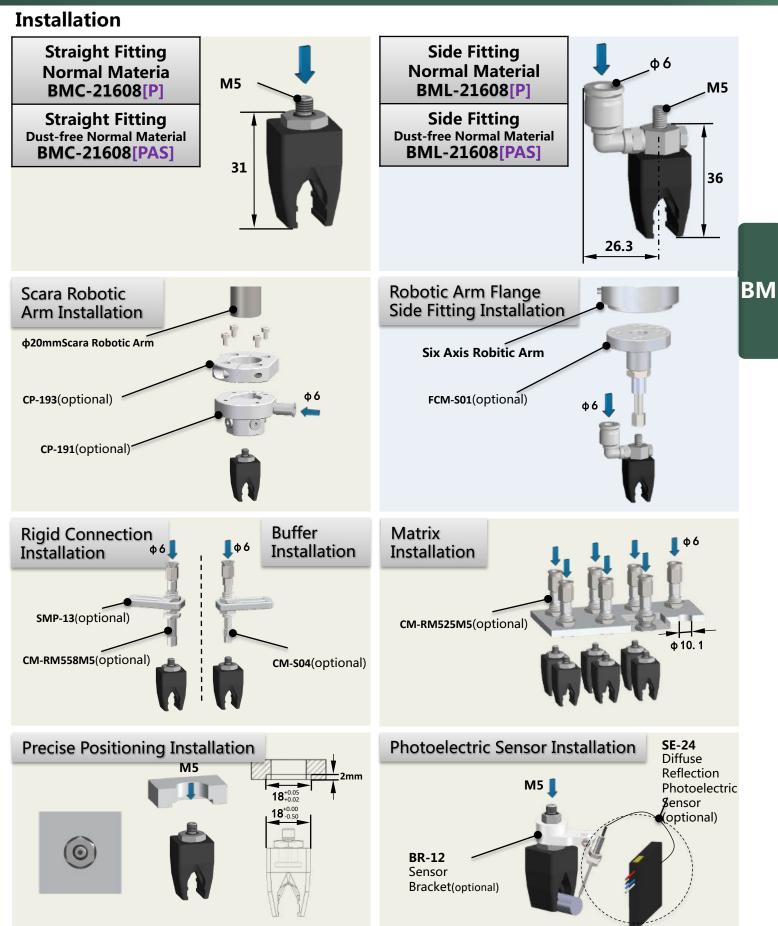
Repetitive Precision ±0.05mm	Recommend -ed Load <sup>20g</sup>	Lifetime times*	Safe Pressure	+80kPa 🥂	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	17g 🚡	BML Weight26.5g 👸



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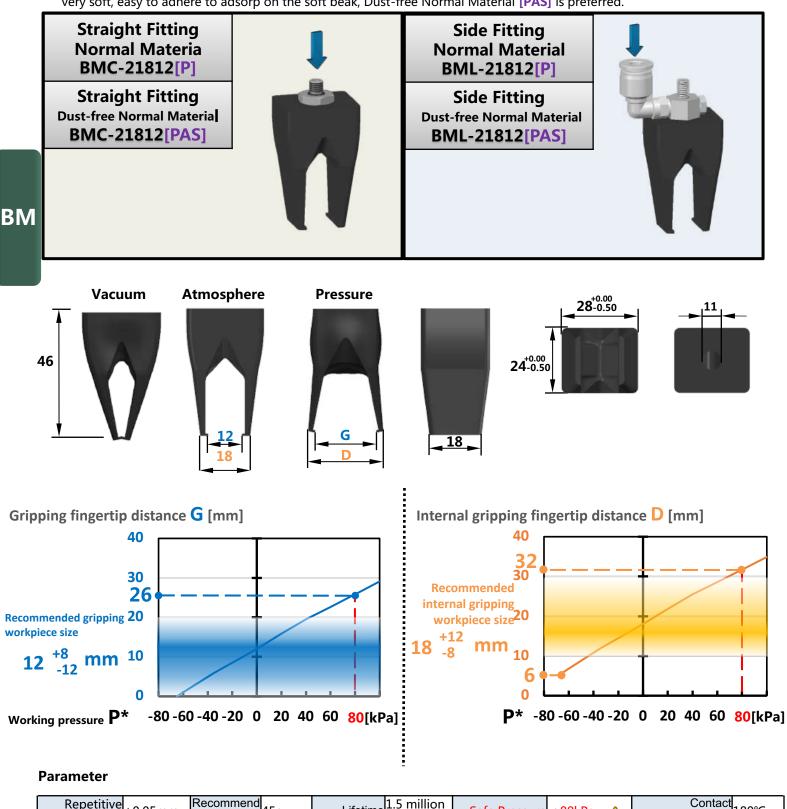
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**Product features** 

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime times*	Safe Pressure	+80kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	20g 👸	BML Weight 29g 🖉

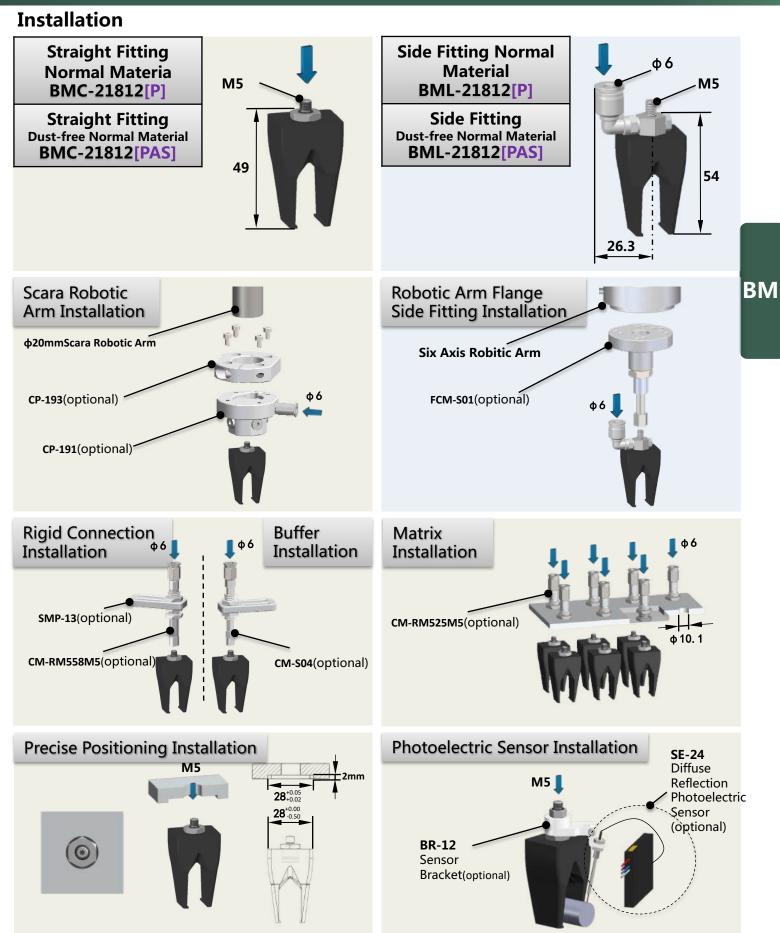


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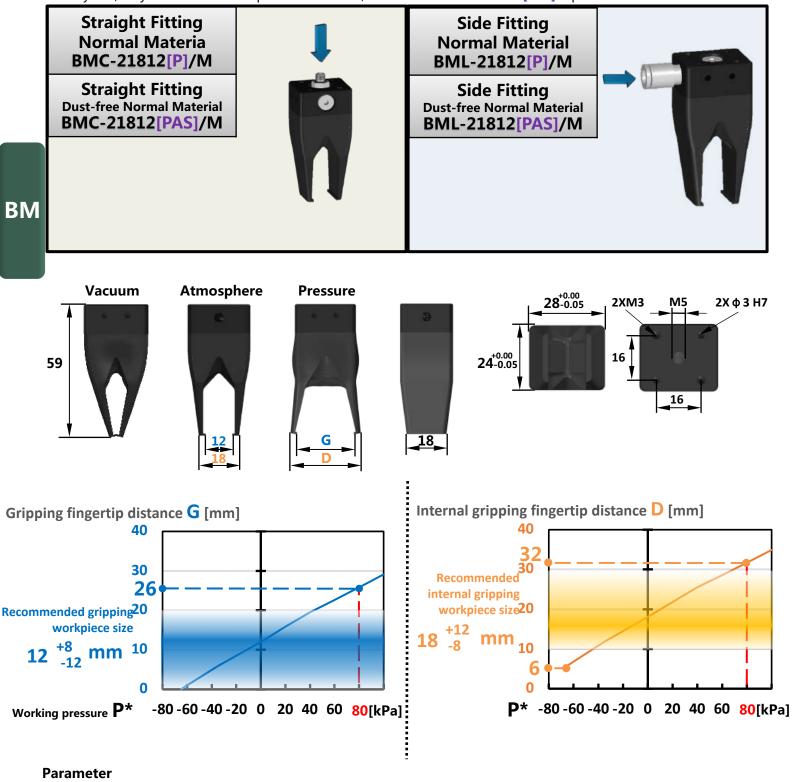
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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



Repetitive Precision ±0.05mm Recommend -ed Load 45g		Lifetime 1.5 million times*	Safe Pressure	+80kPa 🛕	Contact Temperature 180℃	
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	40g 👸	BML Weight 50g 🛛 👸	



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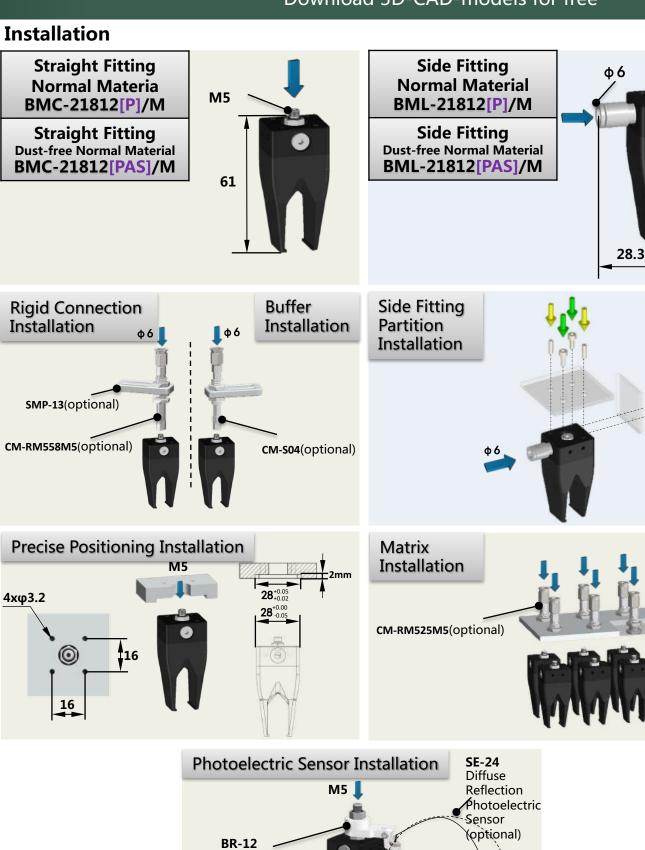
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Plug

BM





Sensor

Bracket(optional)

φ6

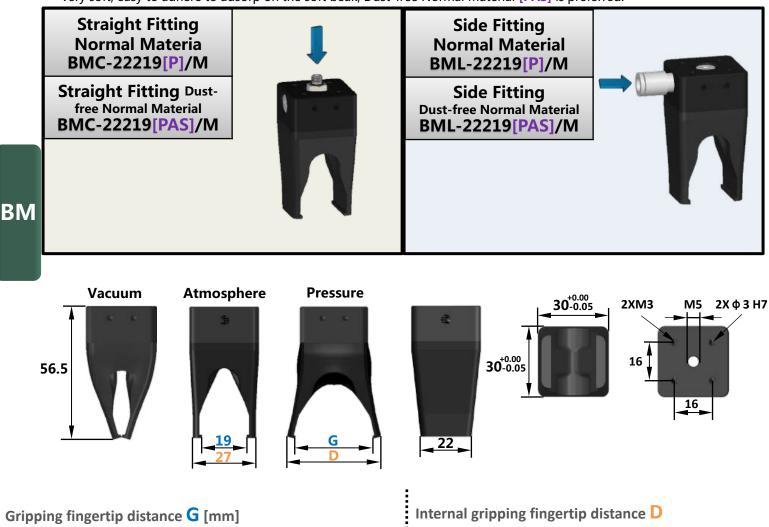
φ<sup>1</sup>10.1

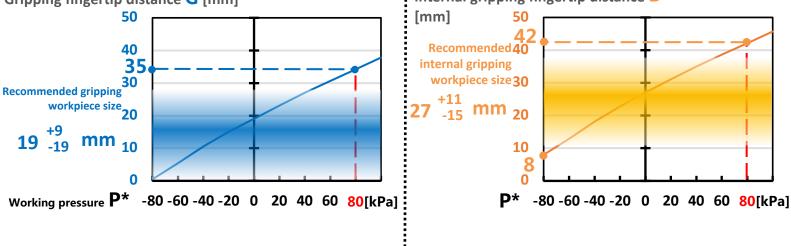


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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.





#### Parameter

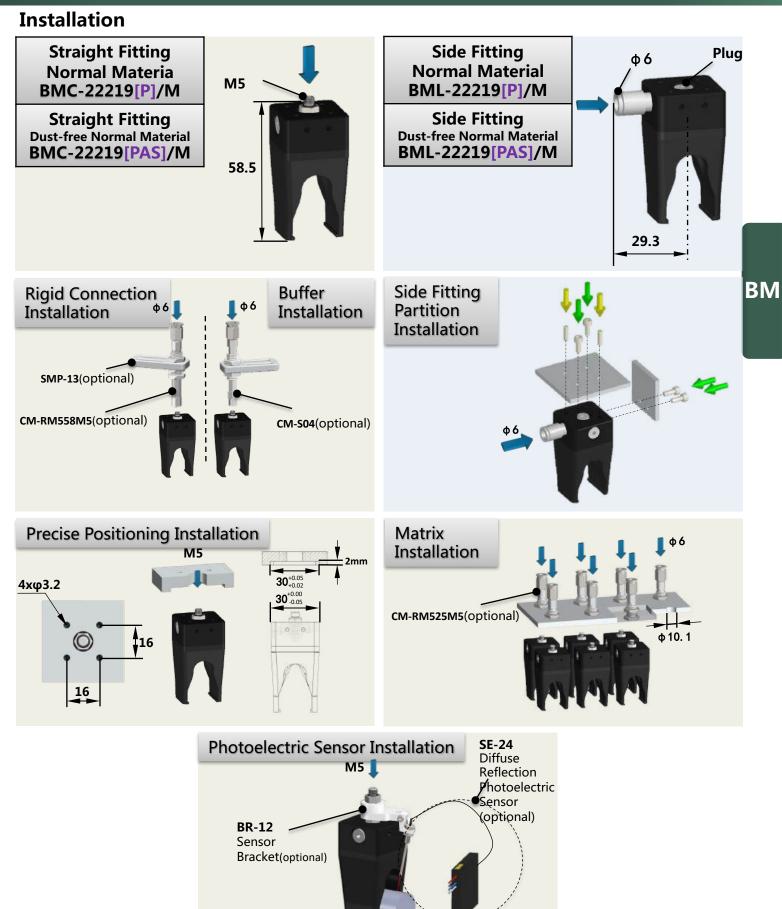
Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime 1.5 million times*	Safe Pressure	+80kPa 🛕	Contact Temperature 180℃	
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	48g 🚡	BML Weight 47g 🛛 👸	



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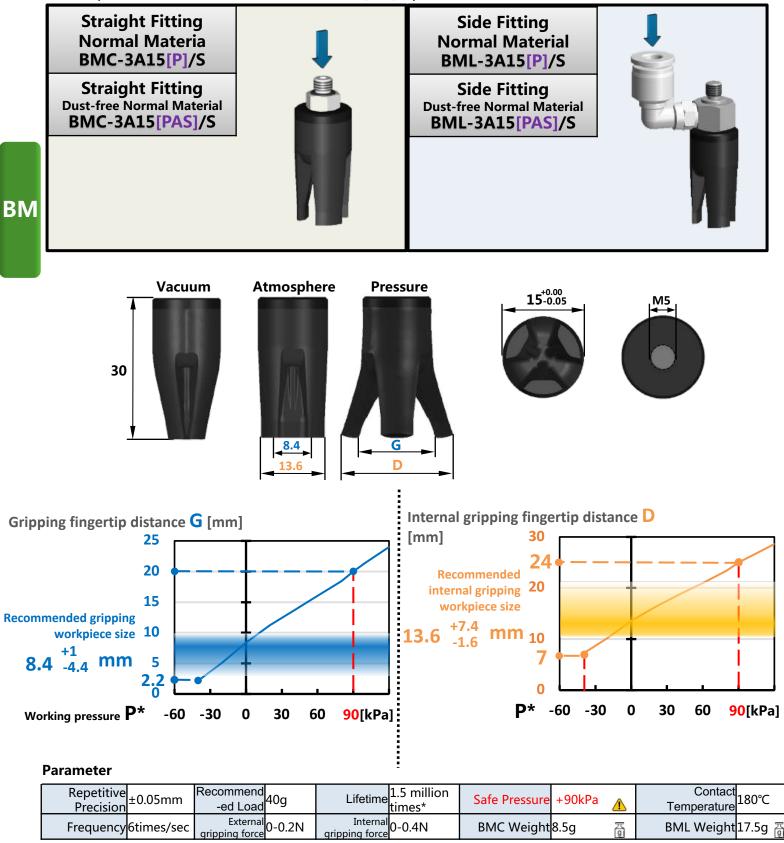


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#### **Product features**

Finger open in positive pressure state, clamped in vacuum state. It is recommended to use with Rochu control unit. Gripping fingertip distance **G** and outer support fingertip distance **D** can be adjusted by working pressure.Soft beak material is divided into Normal Material [**P**] and Dust-free Normal Material [**PAS**]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [**PAS**] is preferred.

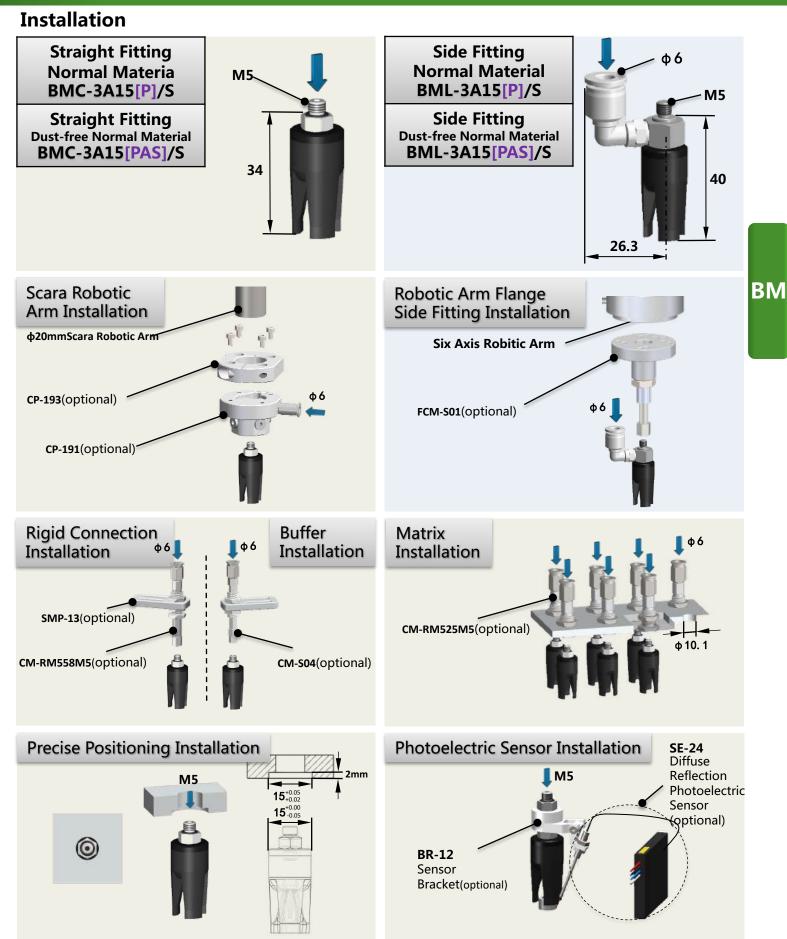


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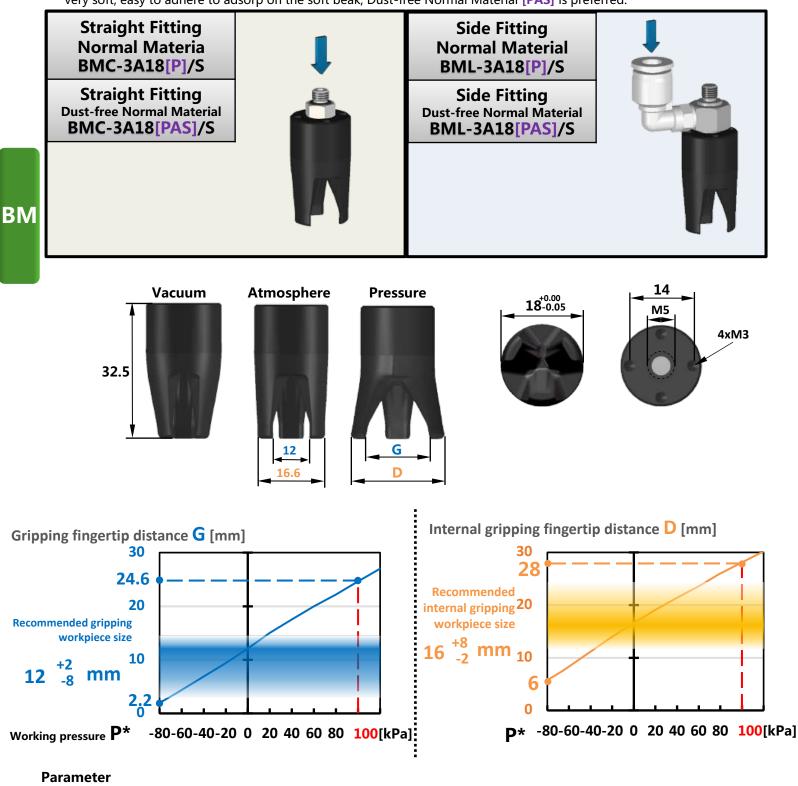
videos

Scan to v

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**Product features** 

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



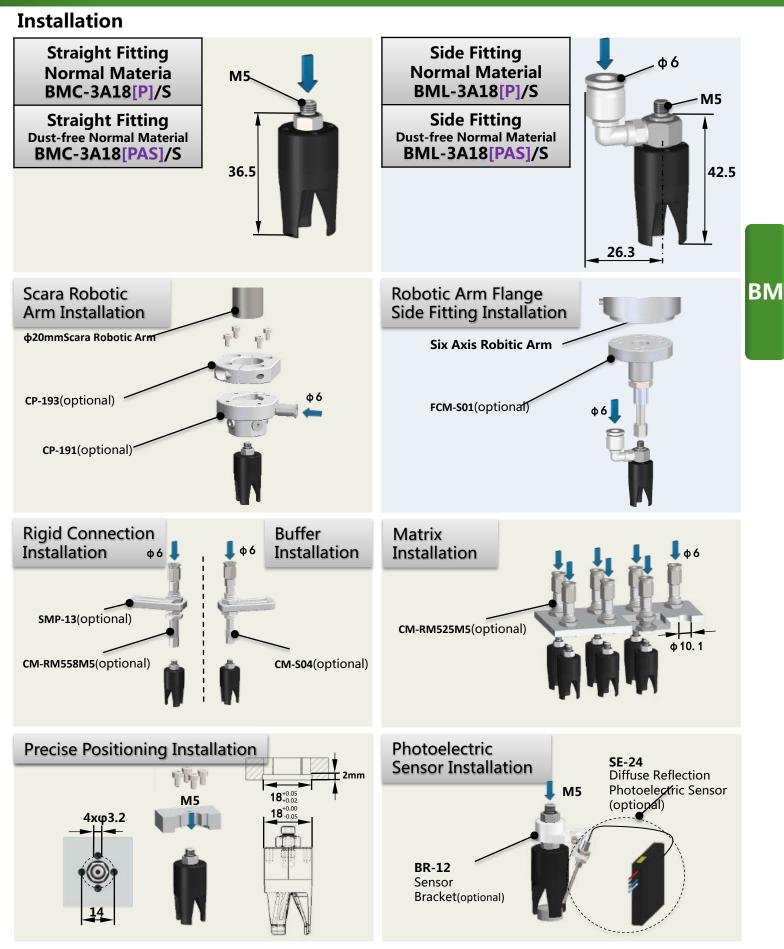
Repetitive Precision	1+0.05mm I		Lifetime times*		Safe Pressure	+100kPa 🛕	Contact Temperature			
Frequency6	itimes/sec	External gripping force	U-U 5IN	Internal gripping force	U-1.5IN I	BMC Weight	10g 풀	BML Weight	19g	핐

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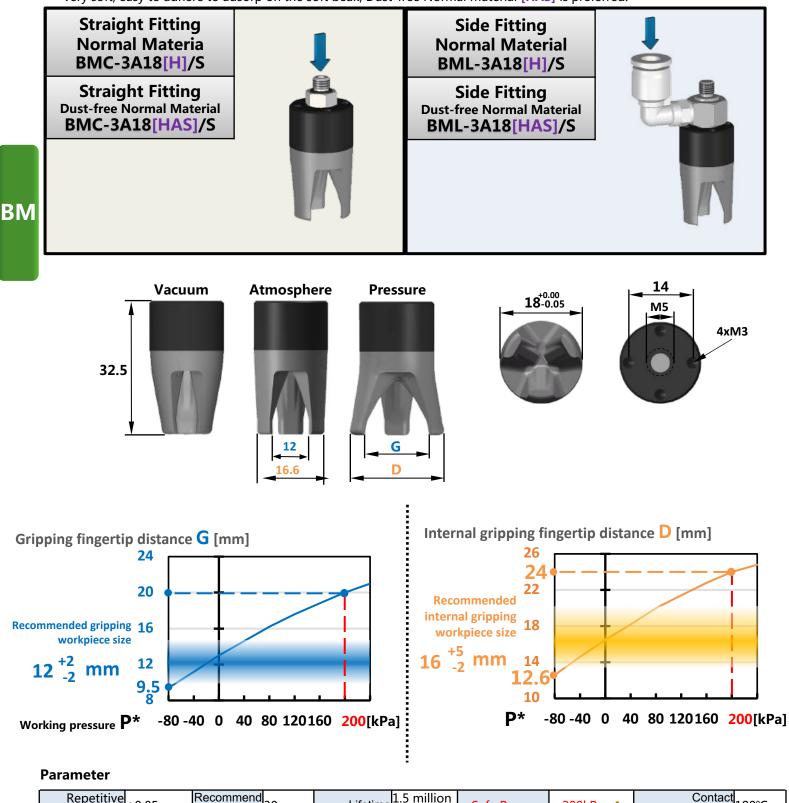
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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping fingertip dictance G and internal gripping fingertip dictance D can be adjusted by working pressure.
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.



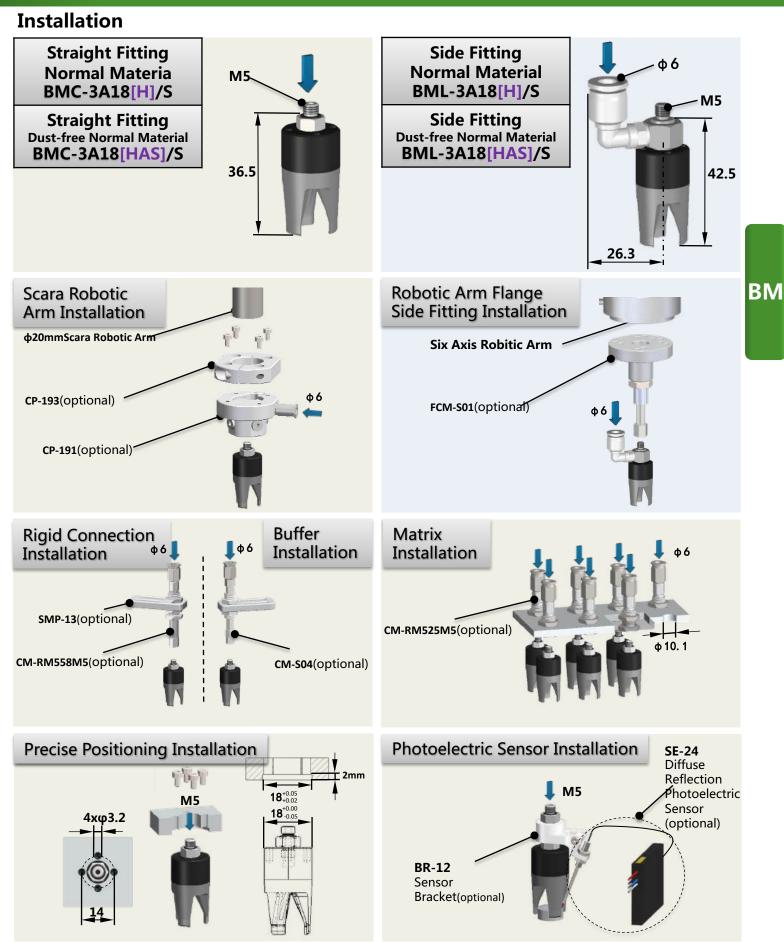
Repetitive Precision ±0.05mm	Recommend -ed Load <sup>30g</sup>	Lifetime times*	Safe Pressure	+200kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	10.5g 🚡	BML Weight 19.5g 👸

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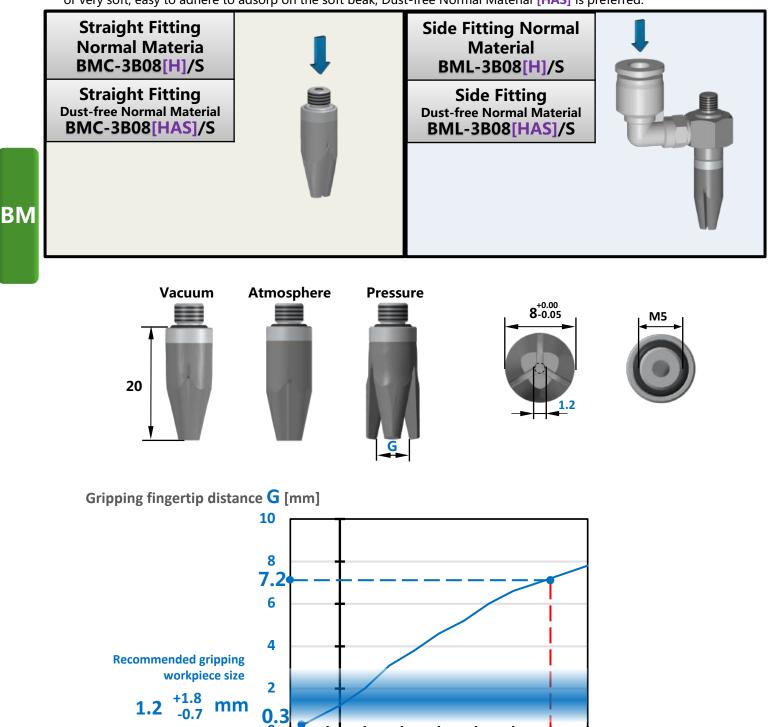
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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.



#### Parameter

Working pressure **P**\*

-40

-10

20

Repetitive Precision	±0.05mm	Recommend -ed Load	4a	Lifetime	1.5 million times*	Safe Pressure	+170kPa 🗴	Contact Temperature	$\Gamma \alpha v v$	:
Frequency	6times/sec	External gripping force	0-0.04N	Internal gripping force	IX I	BMC Weight	5g 🛱	BML Weight	14g	а D

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.

50

80

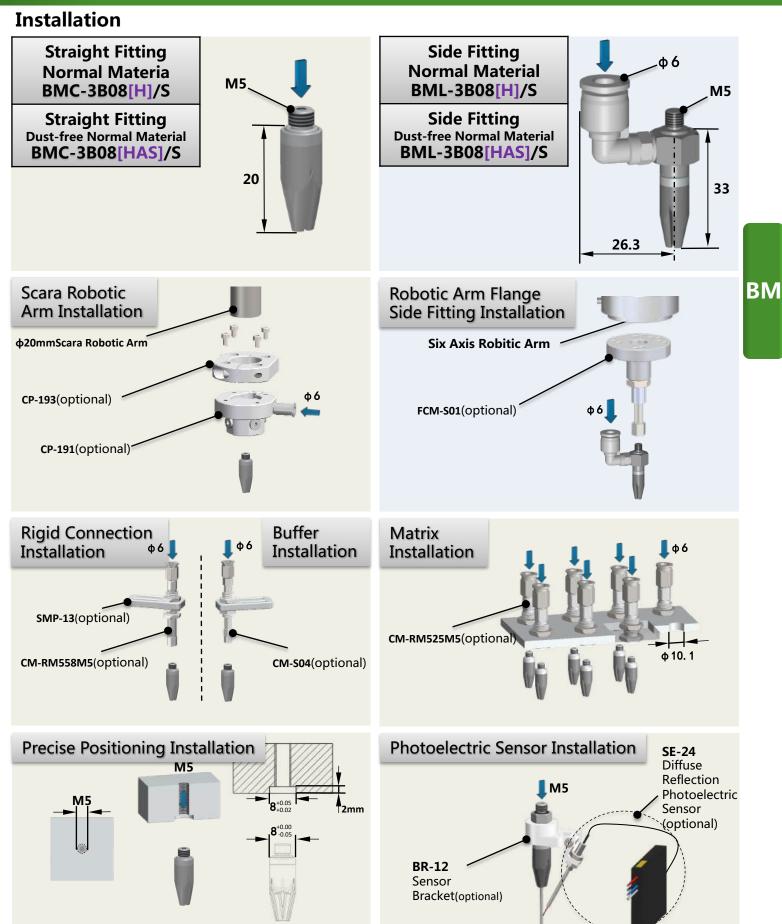
110 140 170[kPa]



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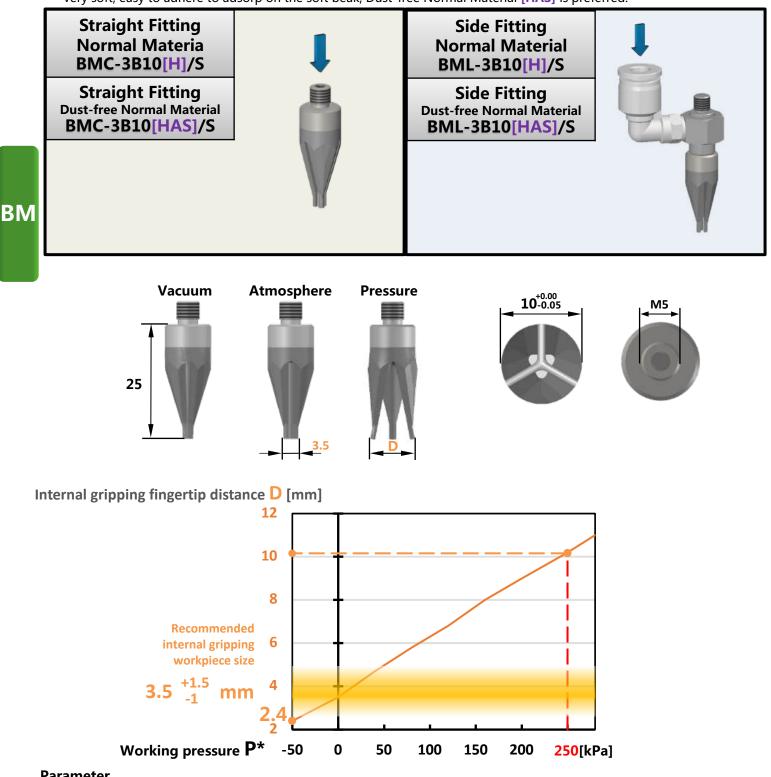
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### **Product features**

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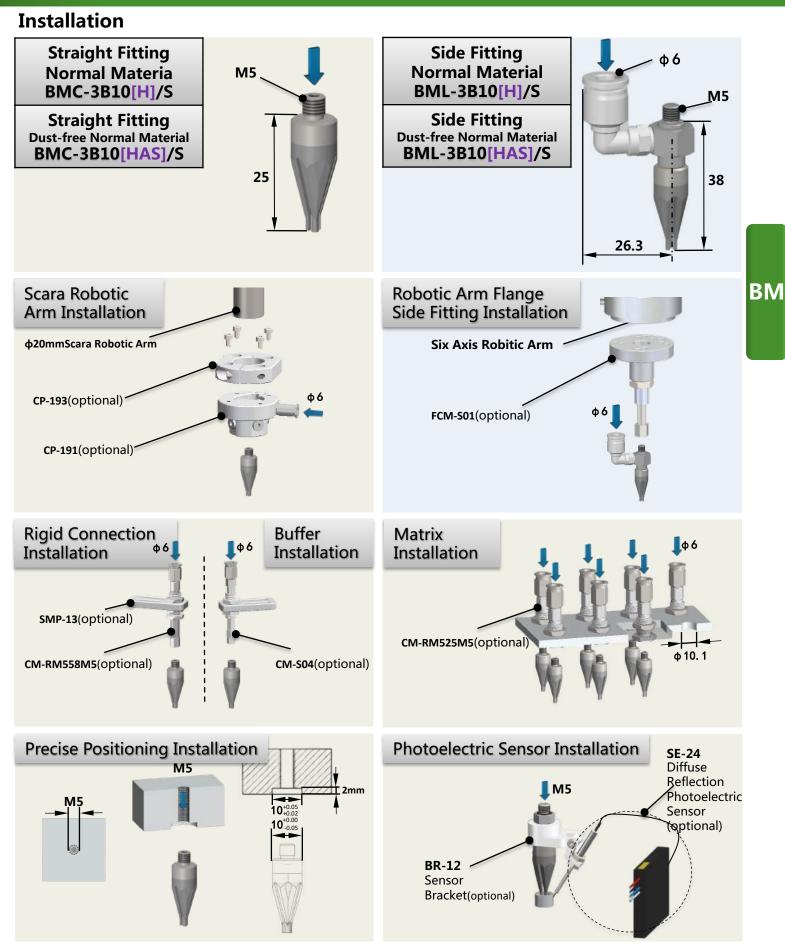
#### Parameter

Repetitive Precision ±0.05mm	Recommend -ed Load <sup>2</sup> g	Lifetime times*	Safe Pressure	+250kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	5g 🖥	BML Weight14g   🗑

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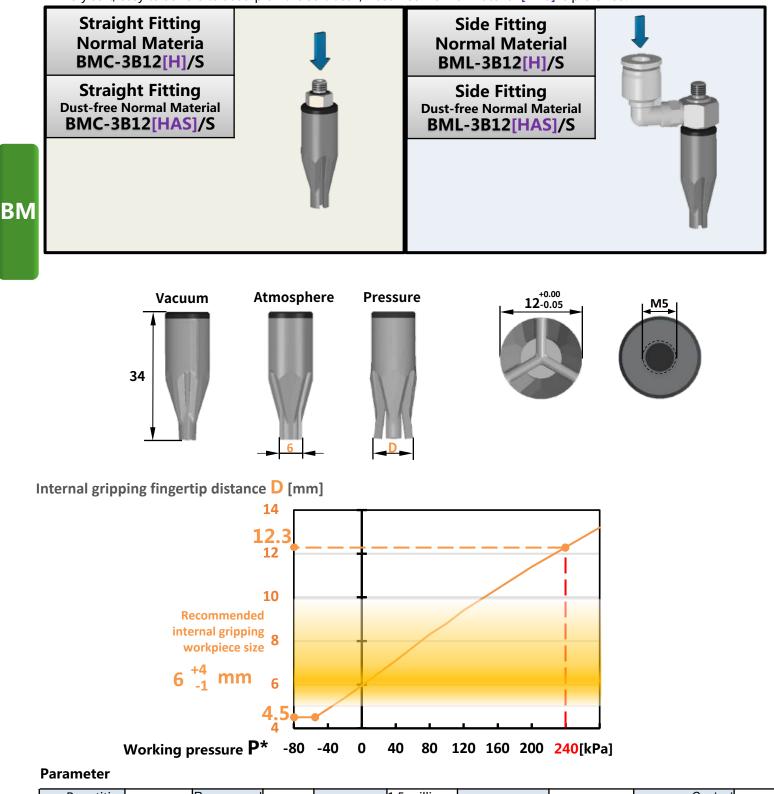
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### **Product features**

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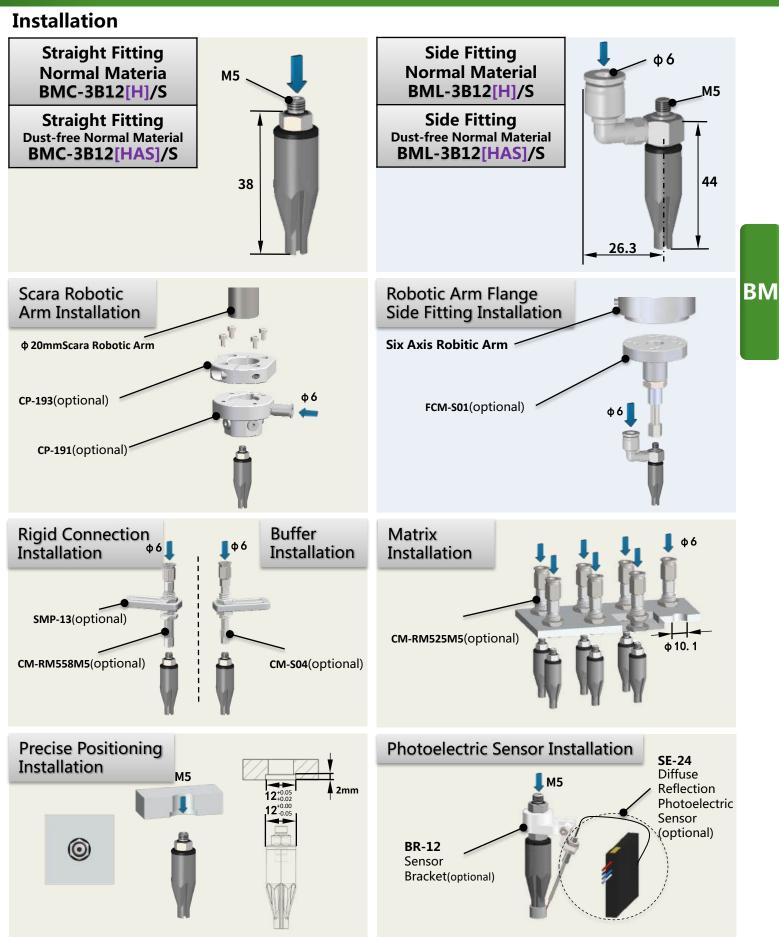
Repetitive Precision ±0.05mm	Recommend -ed Load <sup>10</sup> g	Lifetime 1.5 million times*	Safe Pressure	+240kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	6g 🖥	BML Weight15g 🖉

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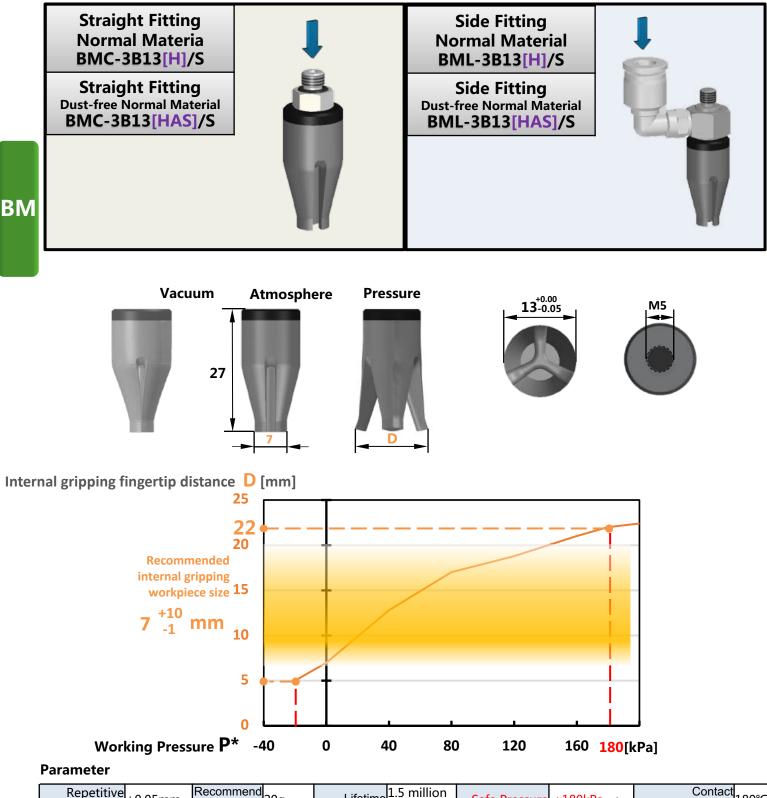
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### **Product features**

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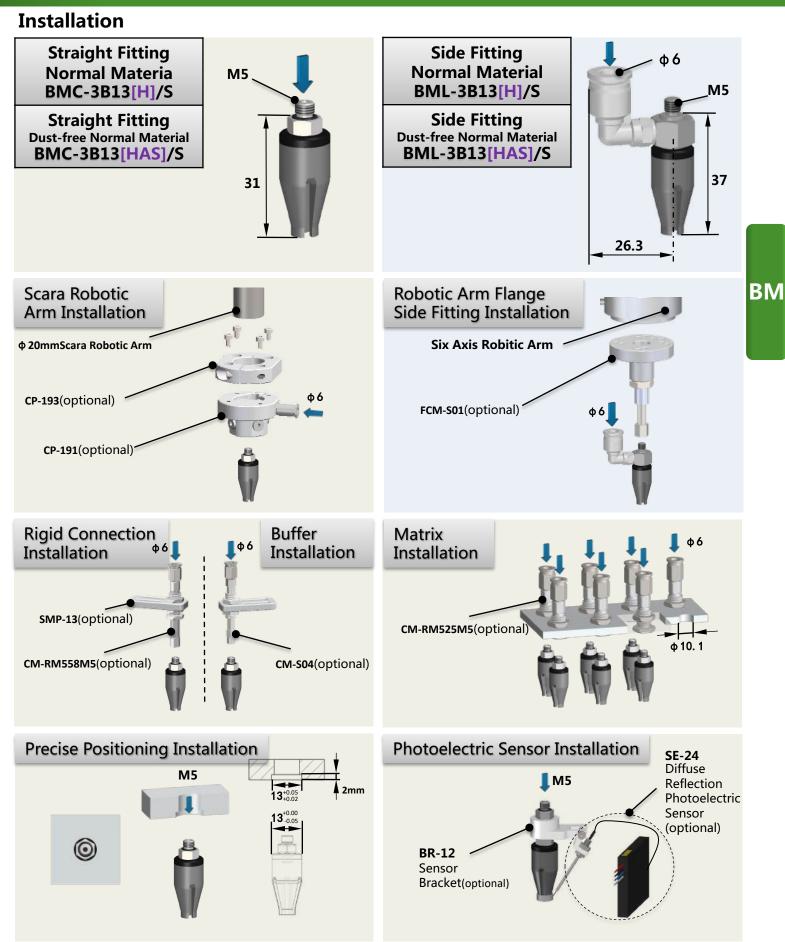


Repetitive Precision	Recommend -ed Load <sup>20g</sup>	Lifetime times*	Safe Pressure	+180kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	8g 🛱	BML Weight17g   👸

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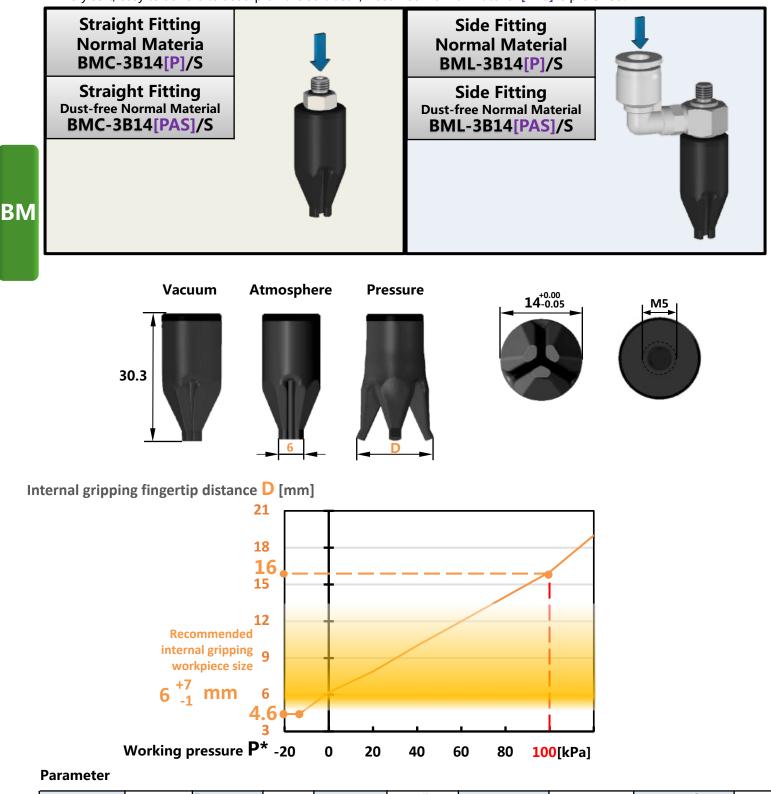
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### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Internal
  gripping fingertip distance D can be adjusted by working pressure.
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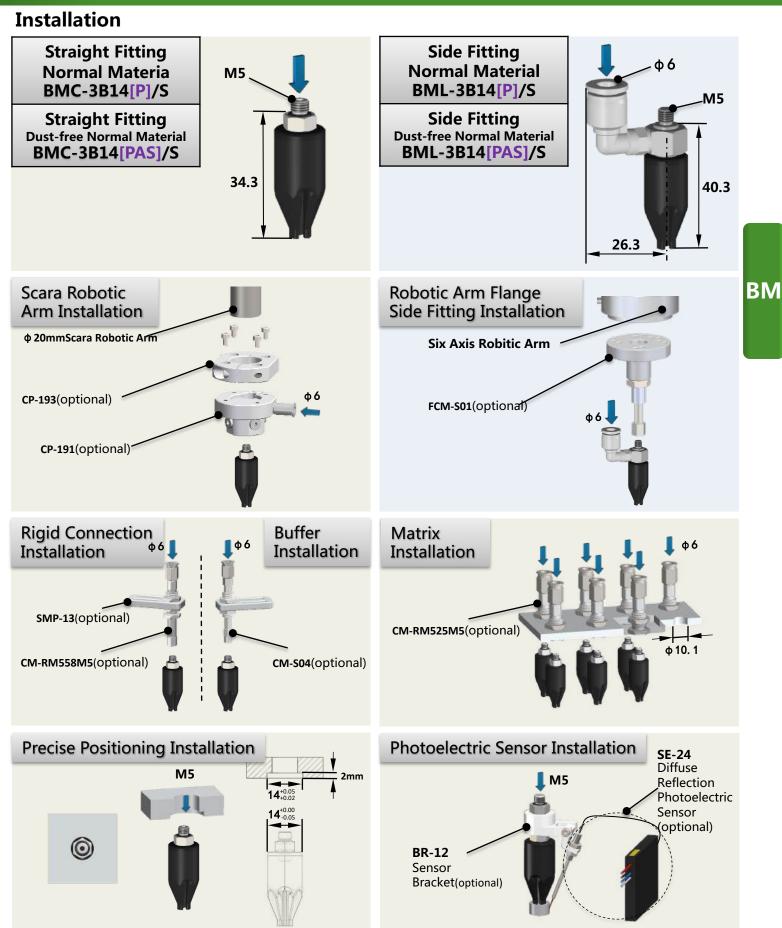
I	Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime 1.5 million times*	Safe Pressure	+100kPa 🛕	Contact Temperature
F	Frequency 6times/sec	External gripping force	Internal gripping force	BMC Weight	6g 👸	BML Weight15g

Cochu

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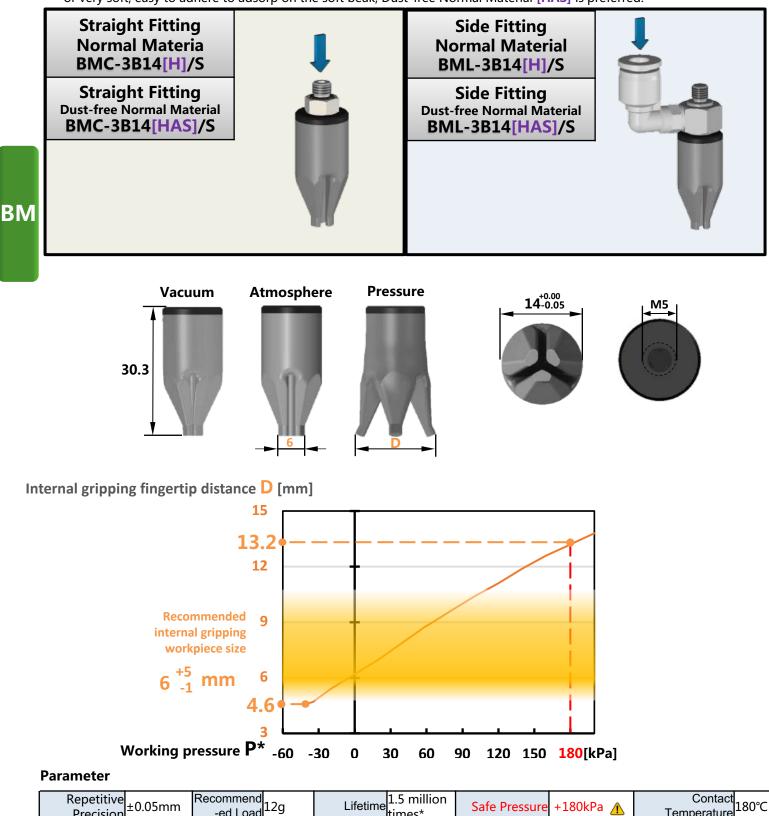
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   Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light,
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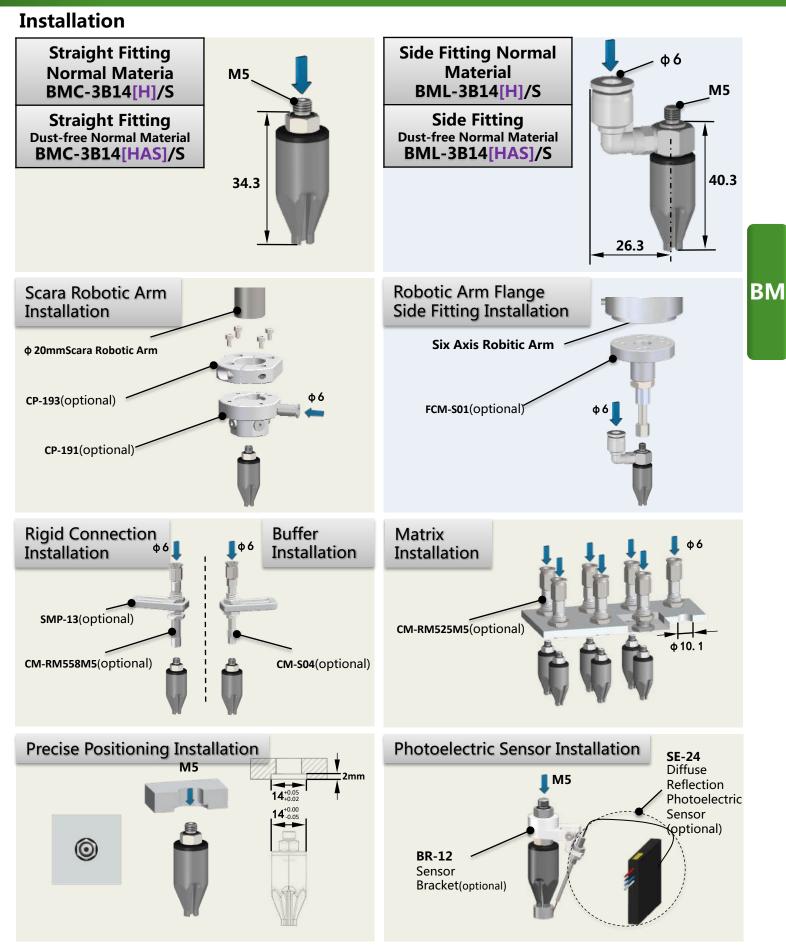


Repetitive Precision ±0.0	5mm Recomme -ed Lo	11.7~	Lifetime	1.5 million times*	Safe Pressure	+180kPa 🚹	Contact Temperature	180℃
Frequency6tim	es/sec Bripping for	nal rce ×	Internal gripping force	0-0.12N	BMC Weight	6.5g 👸	BML Weight	15.5g д

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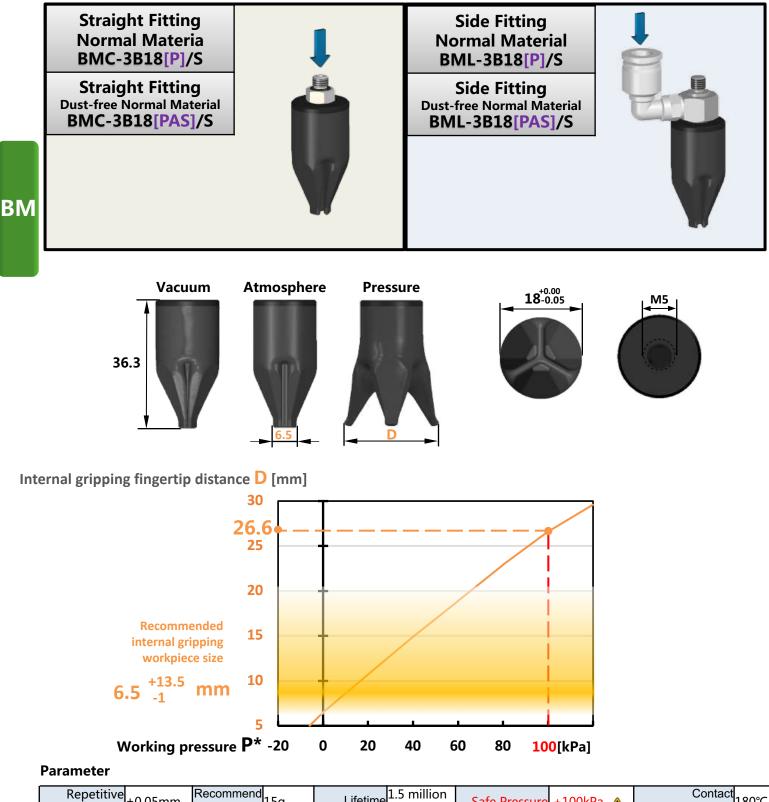
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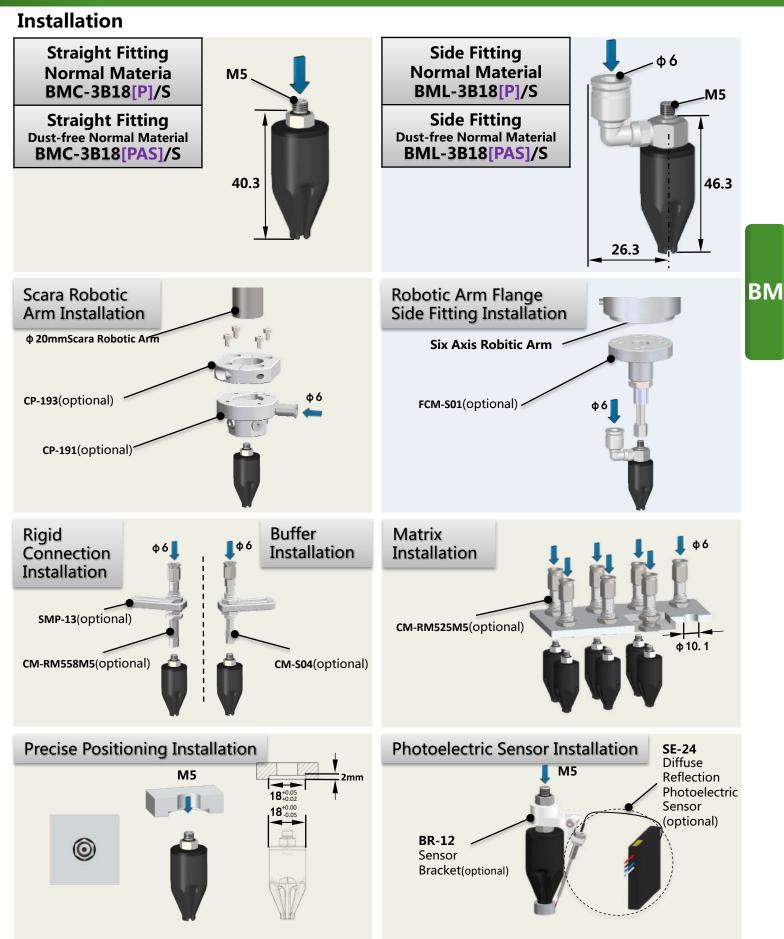


Precision ±0.05mm	ed Load 15g	Lifetime <sup>1.5</sup> million times*	Safe Pressure	+100kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force ×	Internal gripping force	BMC Weight	15g 👸	BML Weight24g 👸

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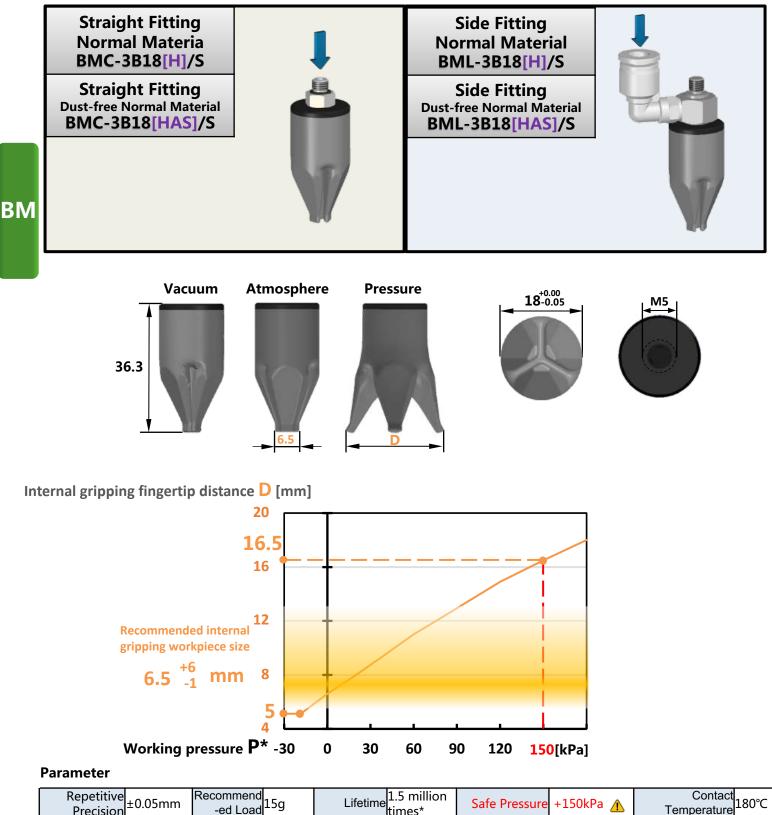
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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Internal gripping fingertip distance D can be adjusted by working pressure. Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or
- very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.

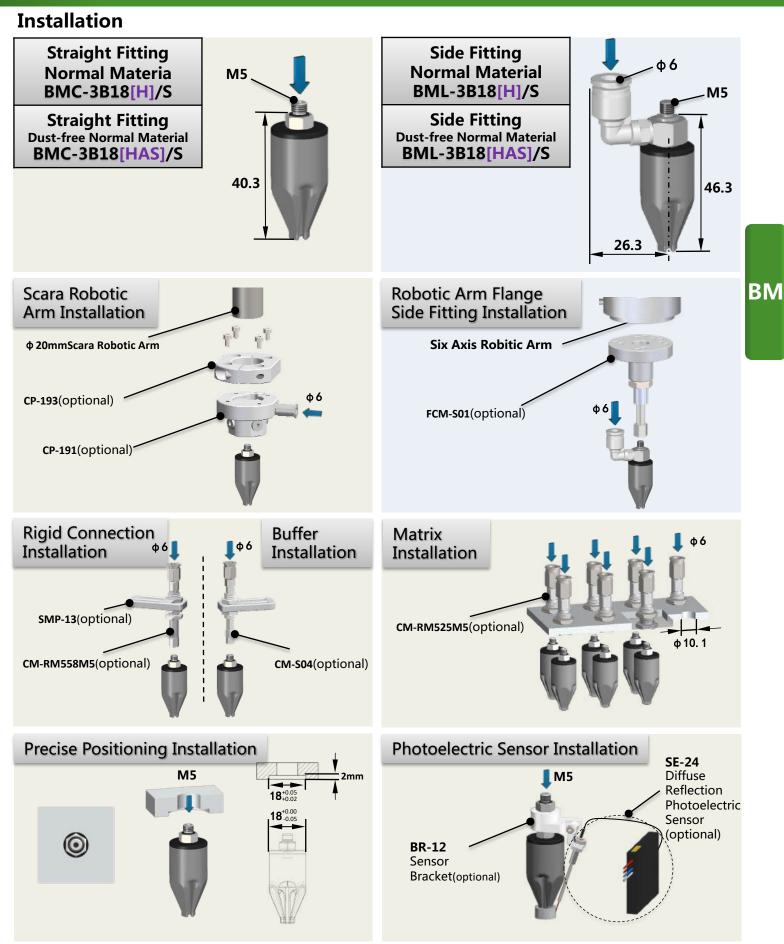


Repetitive Precision	Recommend -ed Load <sup>15g</sup>	Lifetime times*	Safe Pressure	+150kPa 🛕	Contact Temperature <sup>180℃</sup>
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	16.5g 👸	BML Weight25.5g 👸

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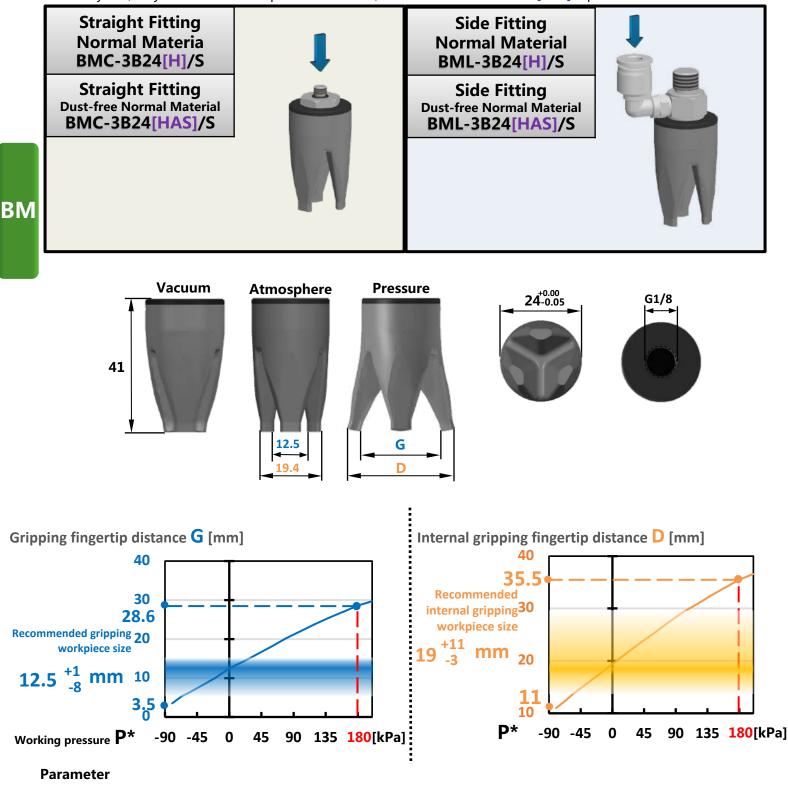
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**Product features** 

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping
- fingertip distance **G** and internal gripping fingertip distance **D** can be adjusted by working pressure. Soft beak material is divided into Normal Material **[H]** and Dust-free Normal Material **[HAS]**. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.

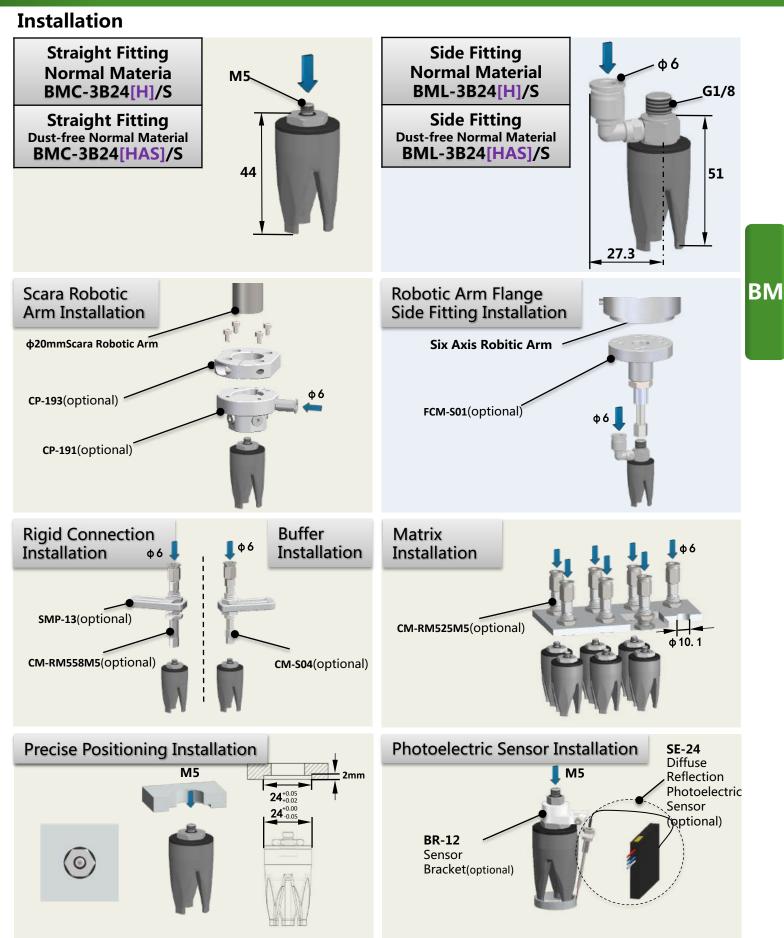


Repetitive Precision ±0.05mm	Recommend -ed Load <sup>30g</sup>	Lifetime times*	Safe Pressure	+180kPa 🛕	Contact Temperature 180℃
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	25.5g 🛱	BML Weight40.5g 👸

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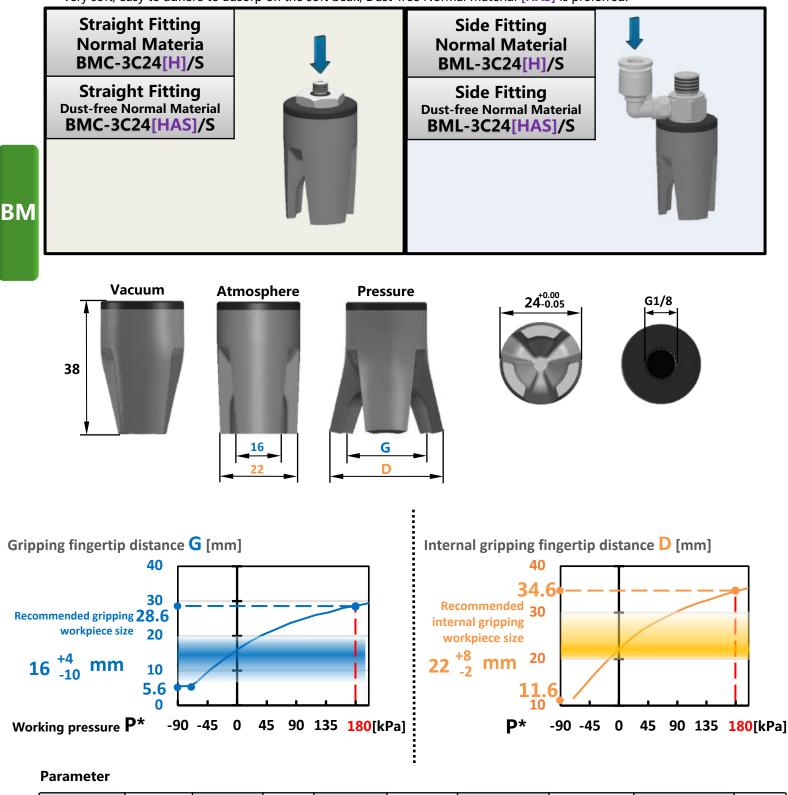
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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.

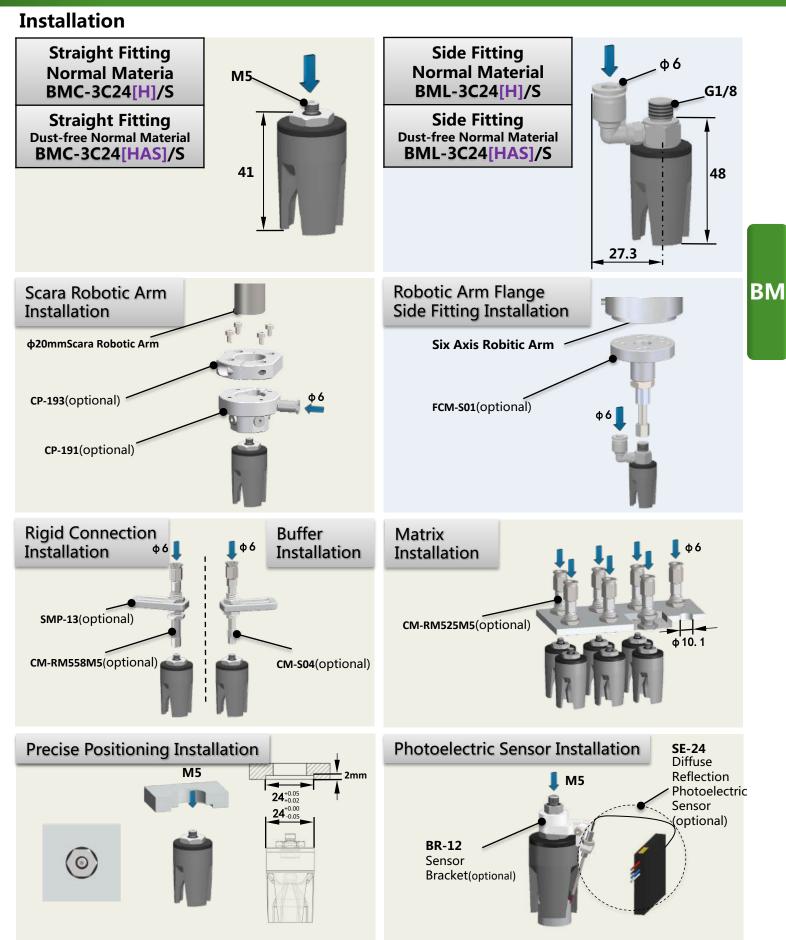


Repetitive Precision ±0.05mm	Recommend -ed Load	Lifetime 1.5 million times*	Safe Pressure	+180kPa 🛕	Contact Temperature	
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	20g 🛱	BML Weight 35g   🗑	

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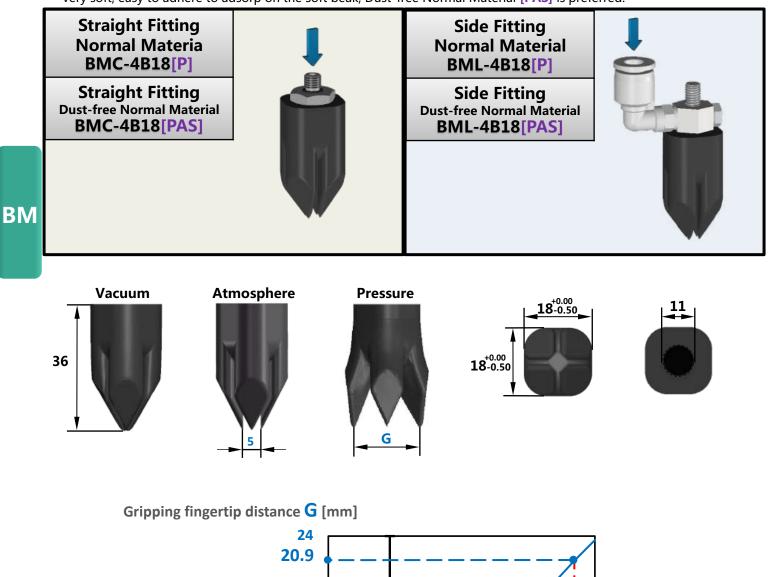
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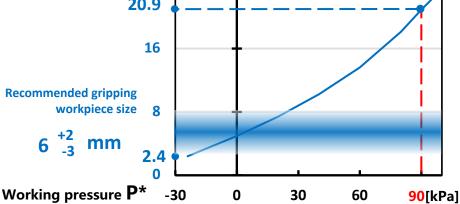
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### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Fingertip distance G can be adjusted by working pressure.
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#### Parameter

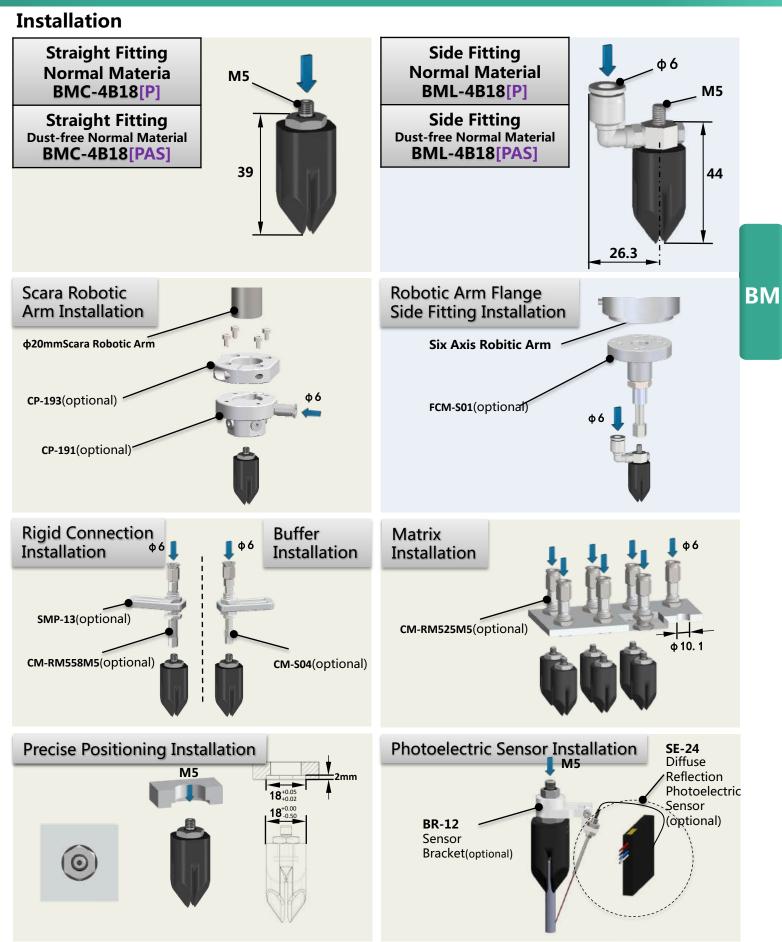
Repetitive Precision ±0.05mm	Recommend -ed Load <sup>5</sup> g	Lifetime times*	Safe Pressure	+90kPa 🛕	Contact Temperature 180℃
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	13.6g 🚡	BML Weight22g 🛛 👸



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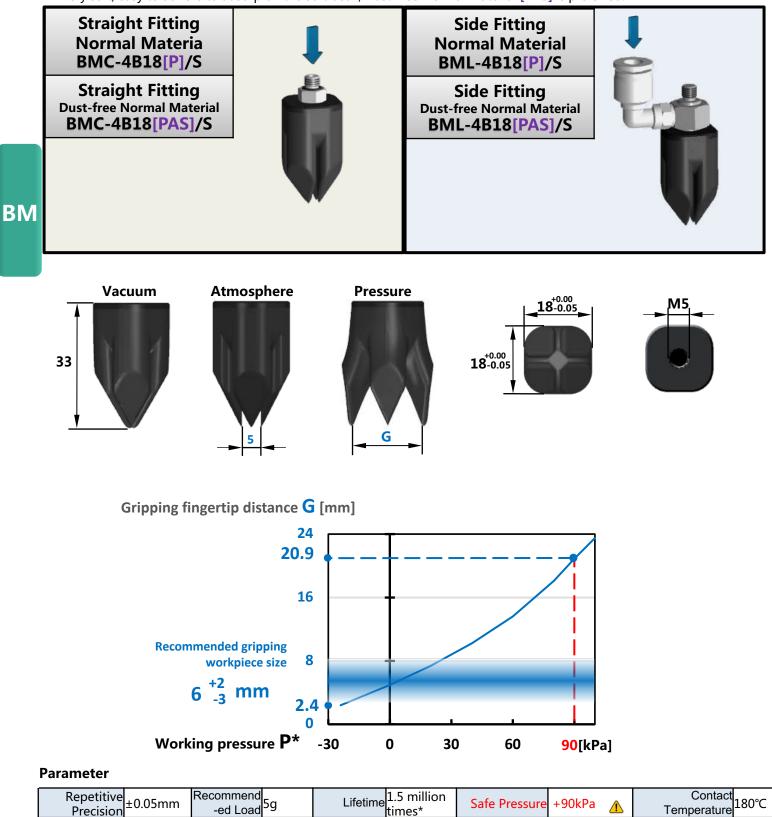
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#### **Product features**

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- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



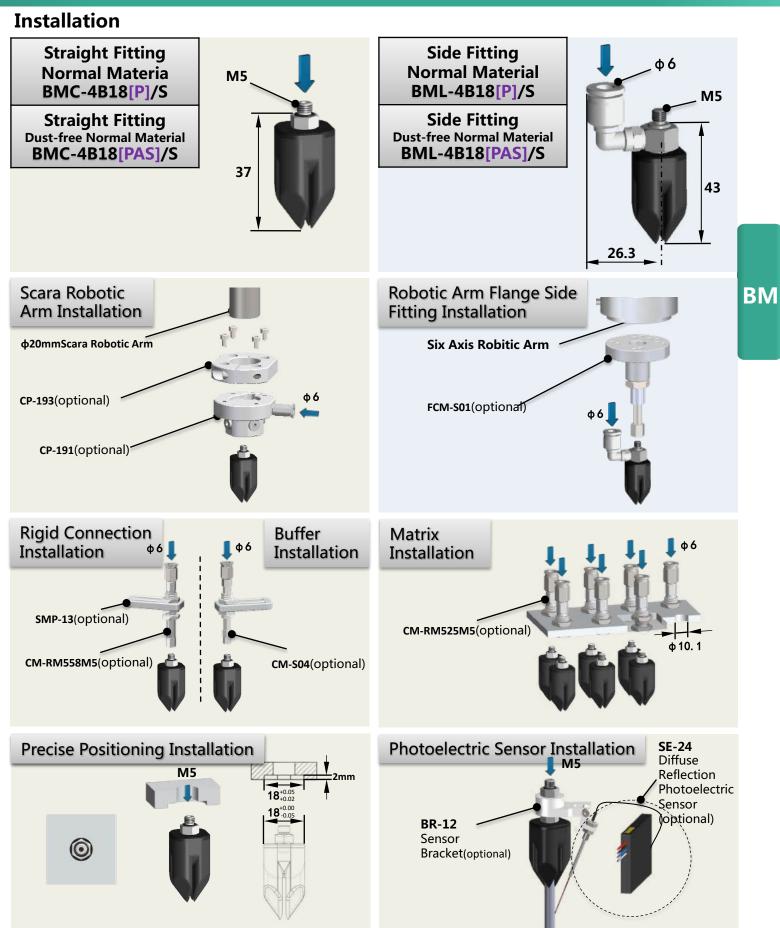
Precision	.0.0511111	-ed Load	9		times*	Sure Tressure	· Solara		Temperature	100 C	
Frequency6	times/sec	External gripping force	J-U.U.SIN I	Internal gripping force	×	BMC Weight	11g	д 9	BML Weight	20g	핐
* . A	4 h				fl-						



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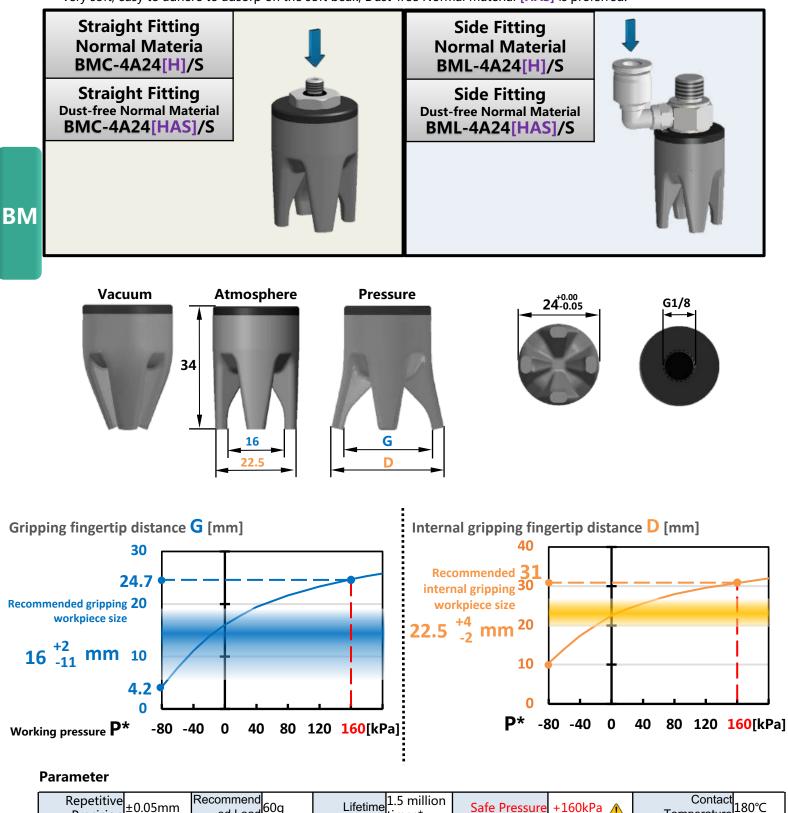
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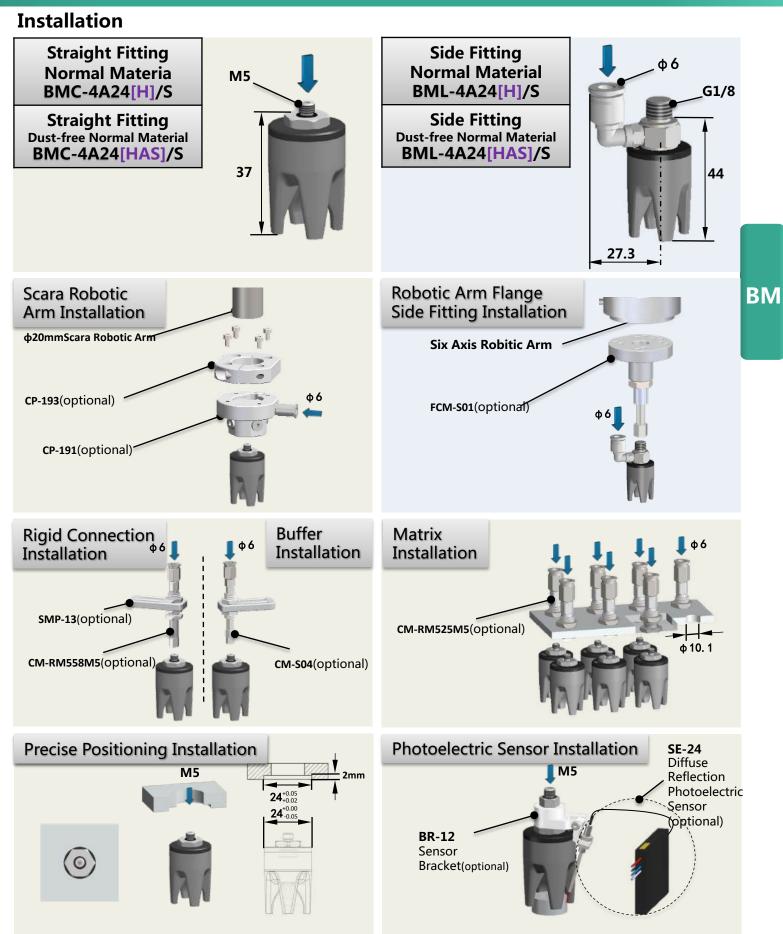
Repetitive Precision	Recommend -ed Load	Lifetime times*	Safe Pressure	+160kPa 🚹	Contact Temperature	$\Pi OU C$	
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	19g 👸	BML Weight	34g	i



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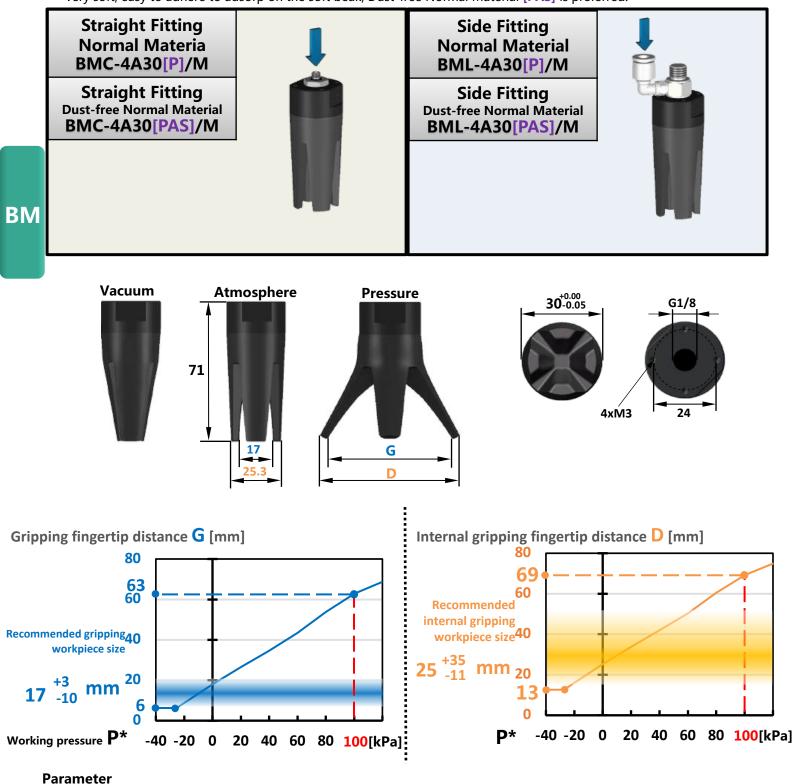


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#### **Product features**

- Finger opens in pressure state, grasps in vacuum state. It is recommended to use with Rochu control unit, gripping fingertip distance G and outer support fingertip distance D can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.

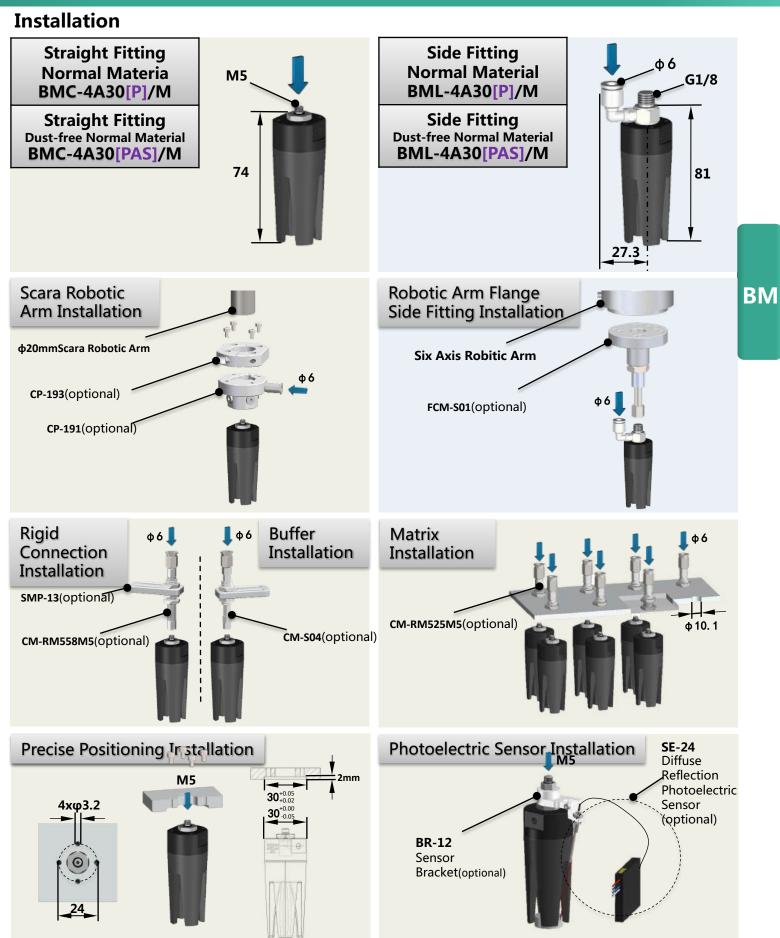




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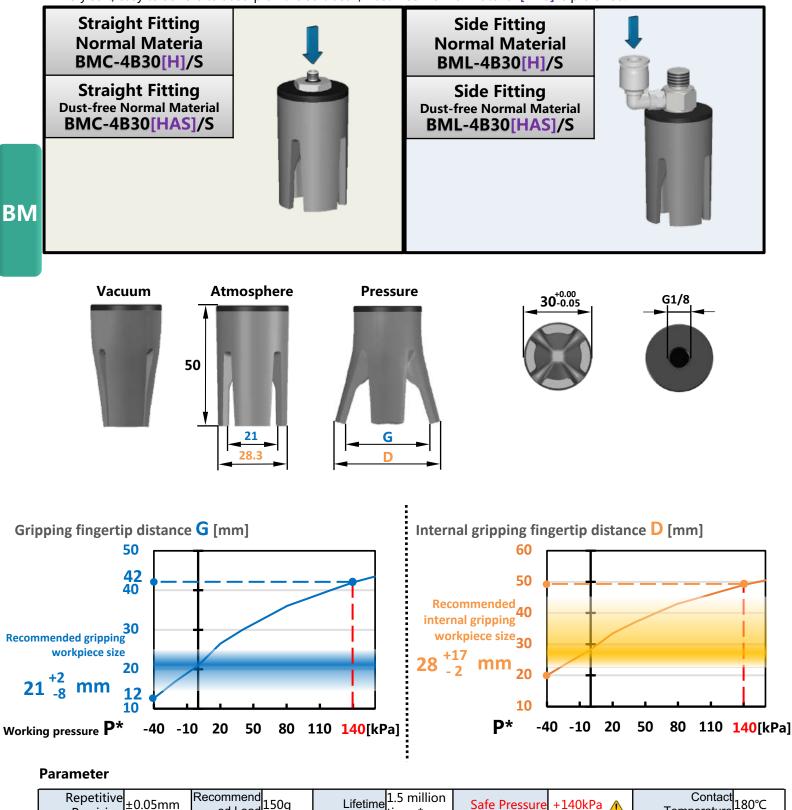




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- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.



Precision ±0.05mm	-ed Load <sup>150g</sup>	Lifetime times*	Sate Pressure	+140kPa 🛕		180°C	
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	33g 🗑	BML Weight	48g 👸	
*		a second state a surface a second		.  . '	time a second by a ffer at a	-1 4 -	-



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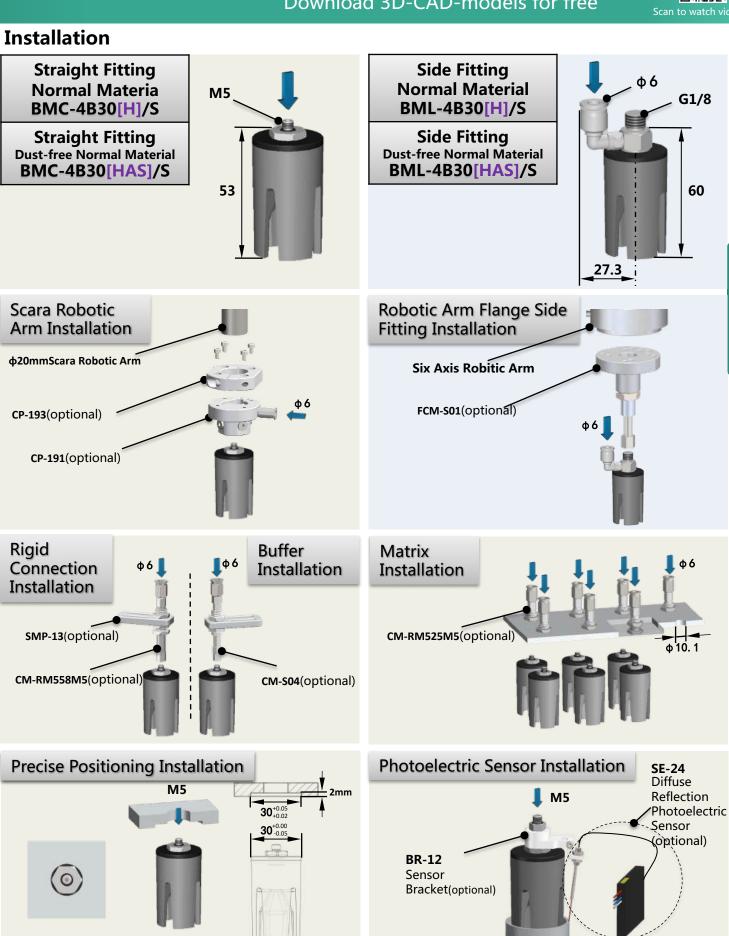


G1/8

60

φ6

BM



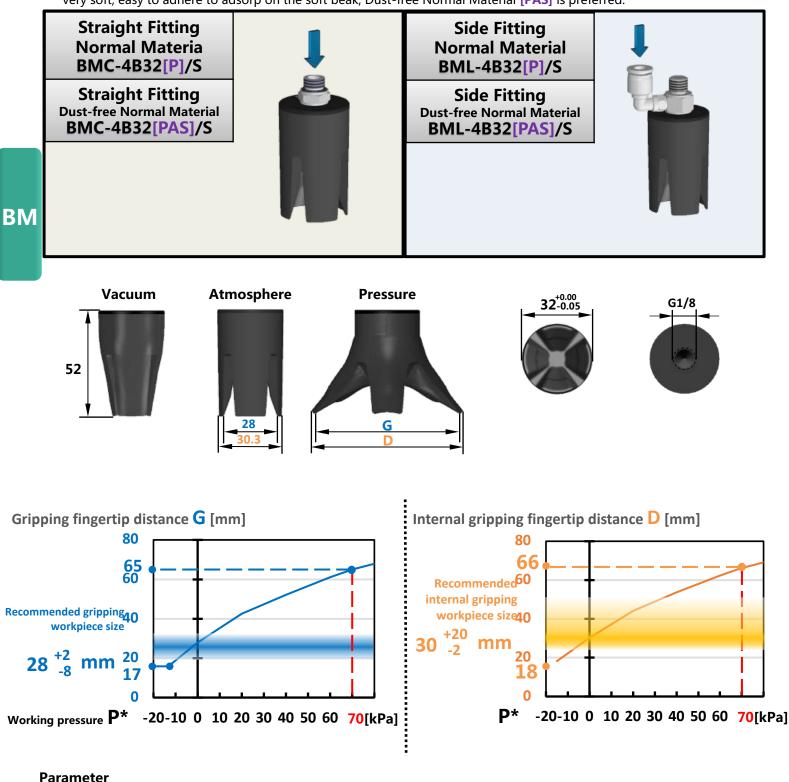
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  Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



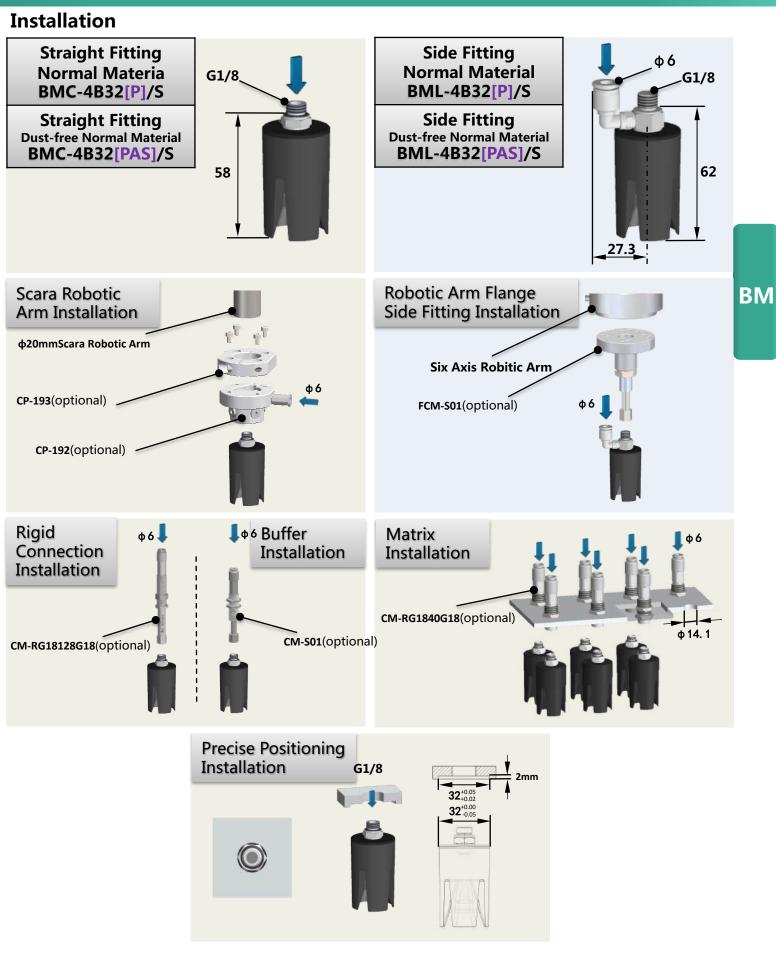
ſ	Repetitive Precision ±0.05mm	Recommend -ed Load <sup>50</sup> g	Lifetime times*	Safe Pressure	+70kPa 🛕	Contact Temperature
	Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	46g 👸	BML Weight 57g 🛛 👸



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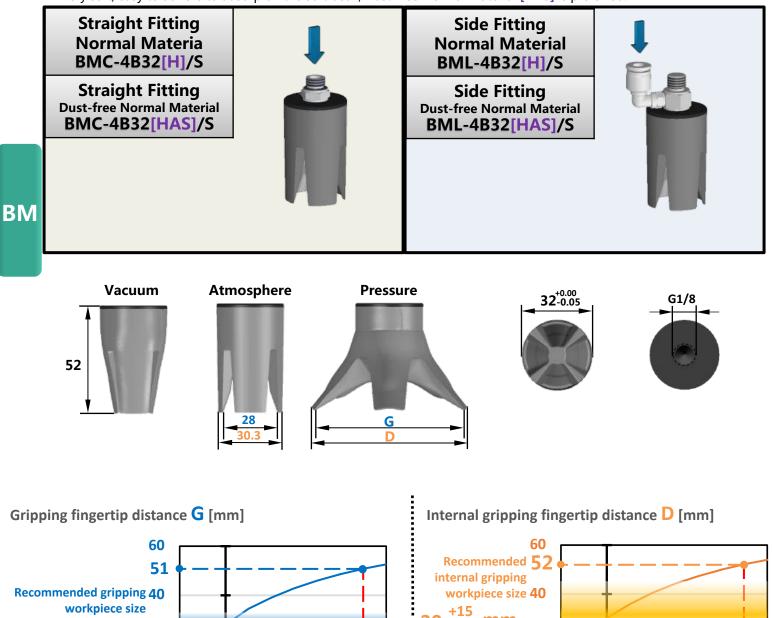




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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping fingertip distance C and internal gripping fingertip distance C and internal gripping fingertip.
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.



+15 30 mm 28 +2 -8 mm 20 20 18. 17 n Working pressure **P**\* **P**\* -40 -40 0 40 80 0 40 80 120[kPa]

#### Parameter

R	epetitive Precision	Recommend -ed Load	Lifetime times*	Safe Pressure	+120kPa 🚹	Contact Temperature
Fr	equency6times/sec	External gripping force	Internal gripping force	BMC Weight	51g 🛱	BML Weight62g   👸

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.

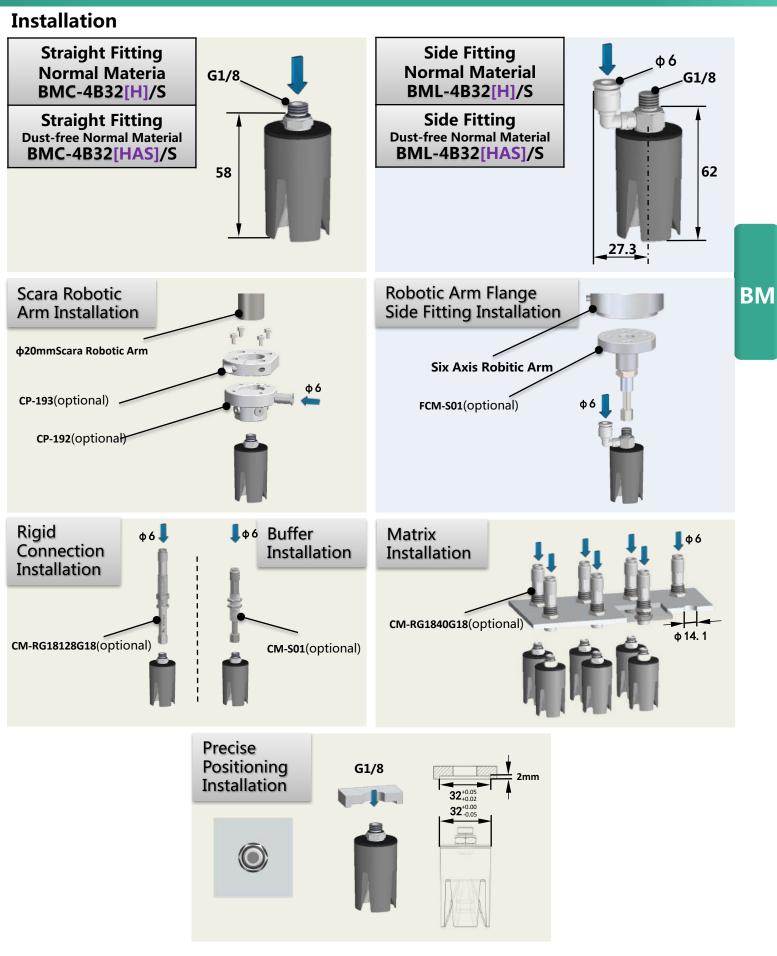


120[kPa]

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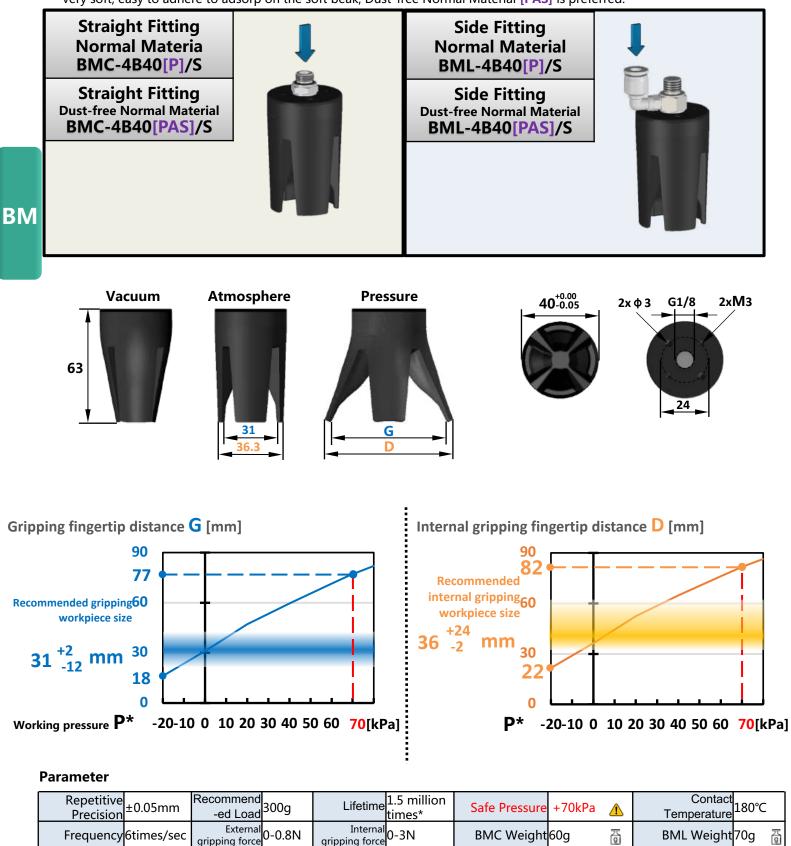




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#### **Product features**

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping fingertip dictance G and internal gripping fingertip dictance D can be adjusted by working pressure.
- fingertip distance G and internal gripping fingertip distance D can be adjusted by working pressure.
  Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.

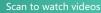


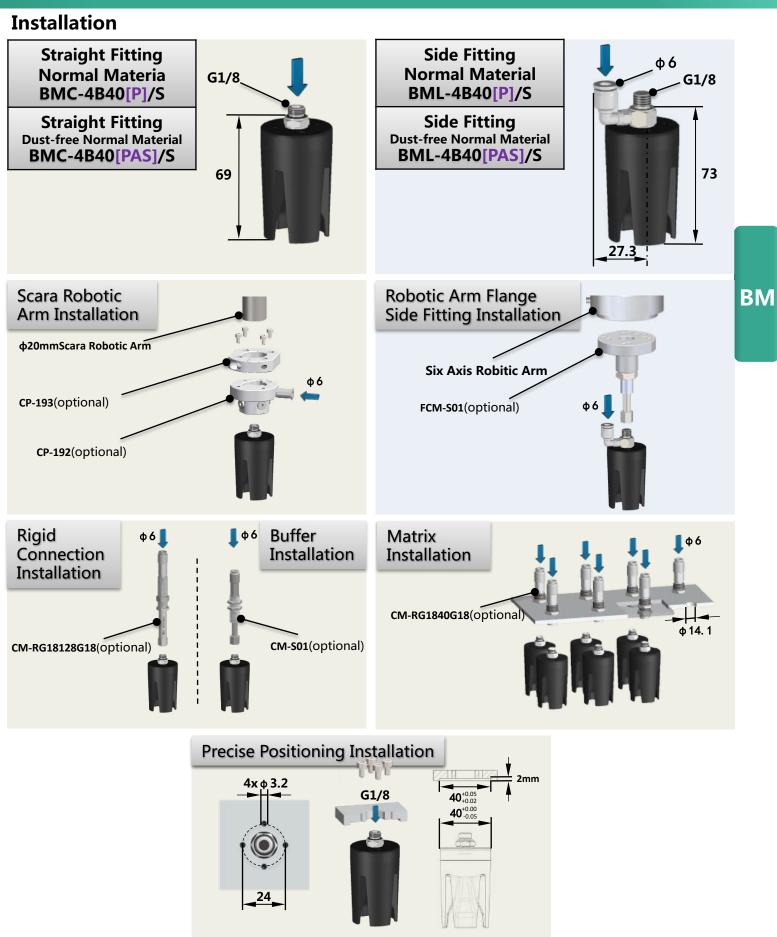


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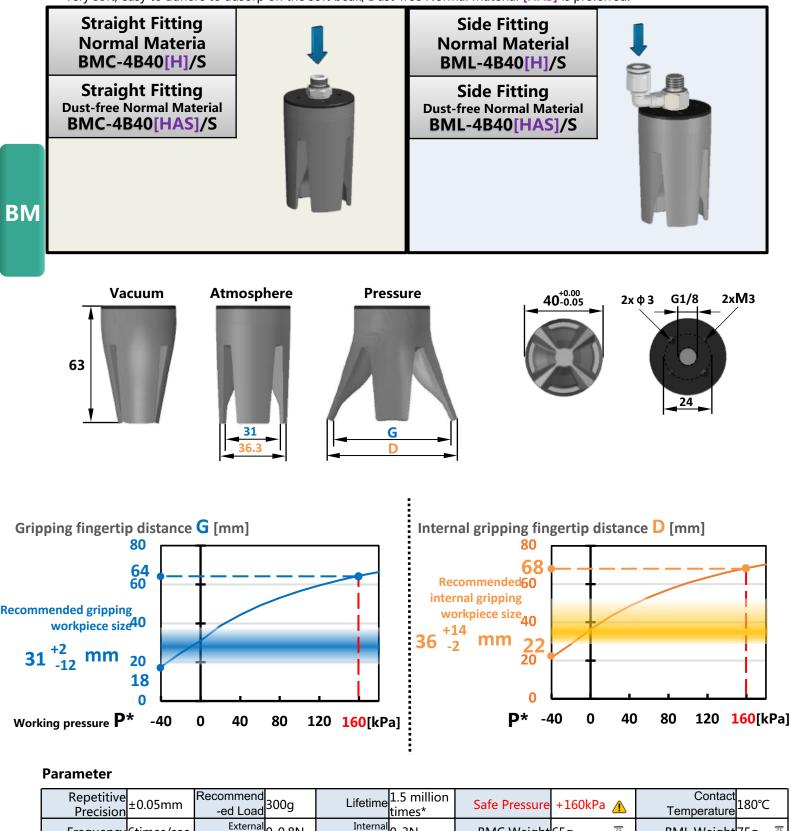


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**Product features** 

- Fingertip open under pressure and clamped in a vacuum. It is suggested to be used with Rochu control unit. Gripping fingertip distance **G** and internal gripping fingertip distance **D** can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.



: According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.

arippina force

0-3N

BMC Weight 65g

裔

0-0.8N

arippina force

Frequency 6times/sec



靣

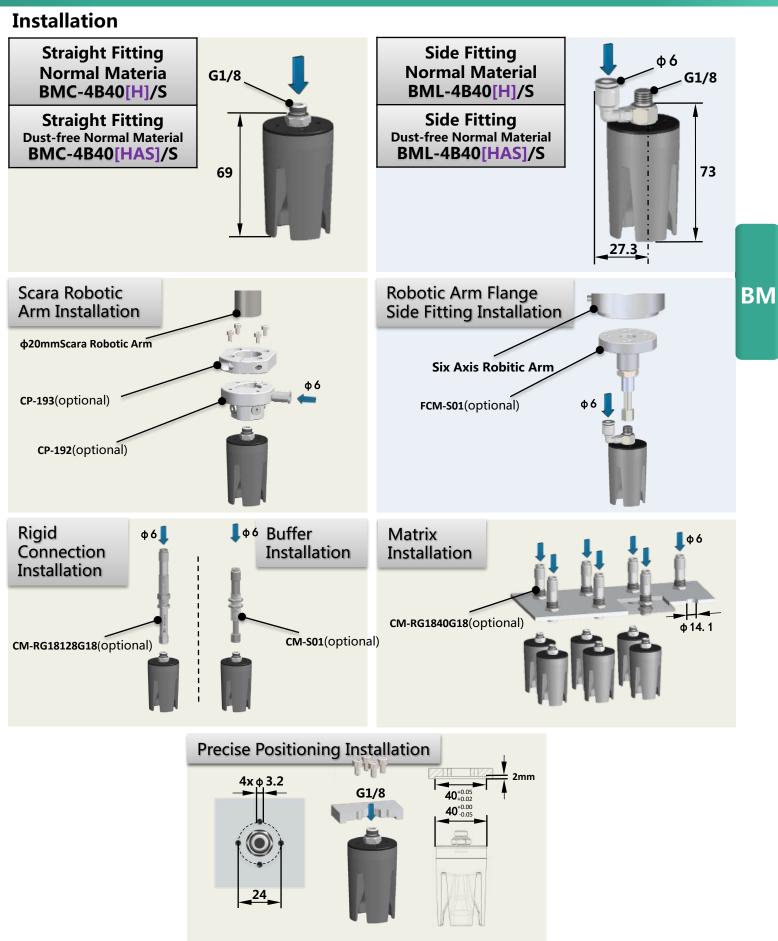
BML Weight 75g

#### **Beak Module**

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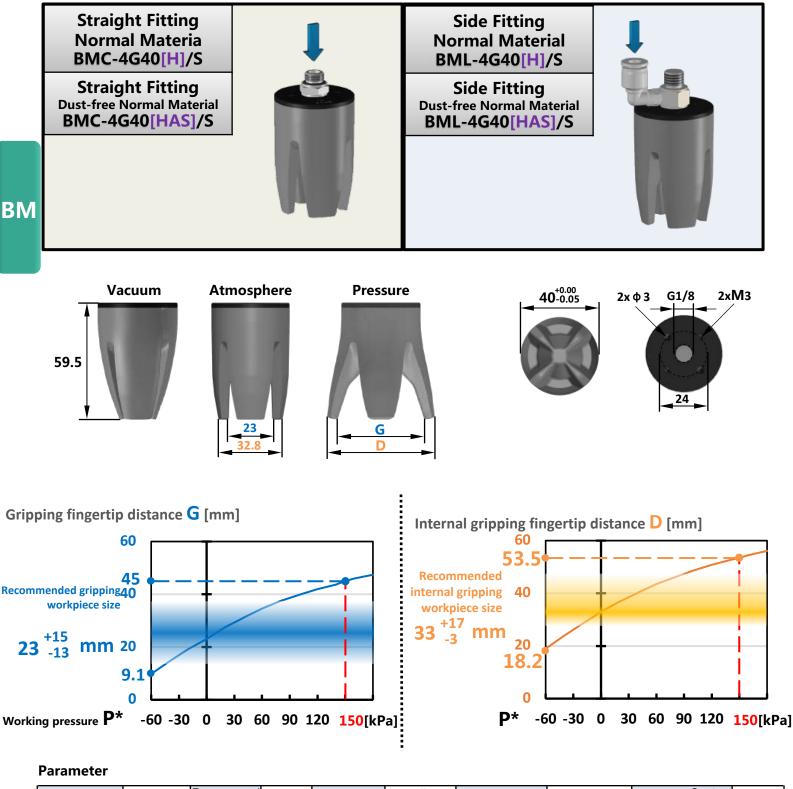
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#### **Product features**

- Finger opens in pressure state, grasps in vacuum state. It is recommended to use with Rochu control unit, gripping fingertip distance G and outer support fingertip distance D can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [H] and Dust-free Normal Material [HAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [HAS] is preferred.



Repetitive Precision ±0.05mm	Recommend -ed Load <sup>200</sup> g	Lifetime times*	Safe Pressure	+150kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	71g  🗑	BML Weight 82g 🖉

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.

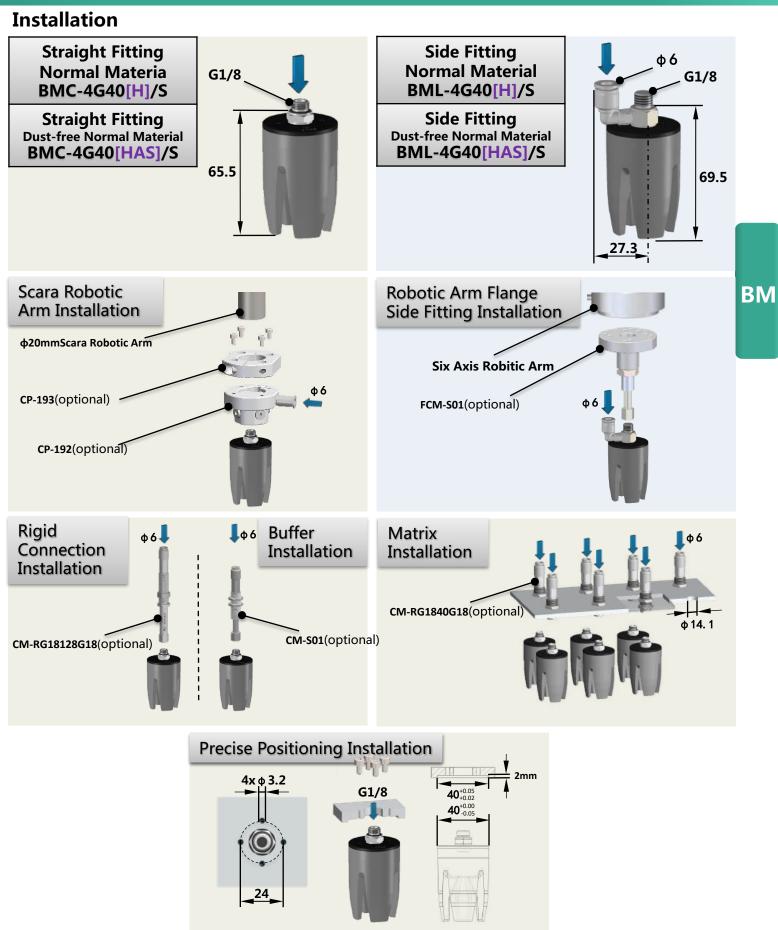


#### Beak Module

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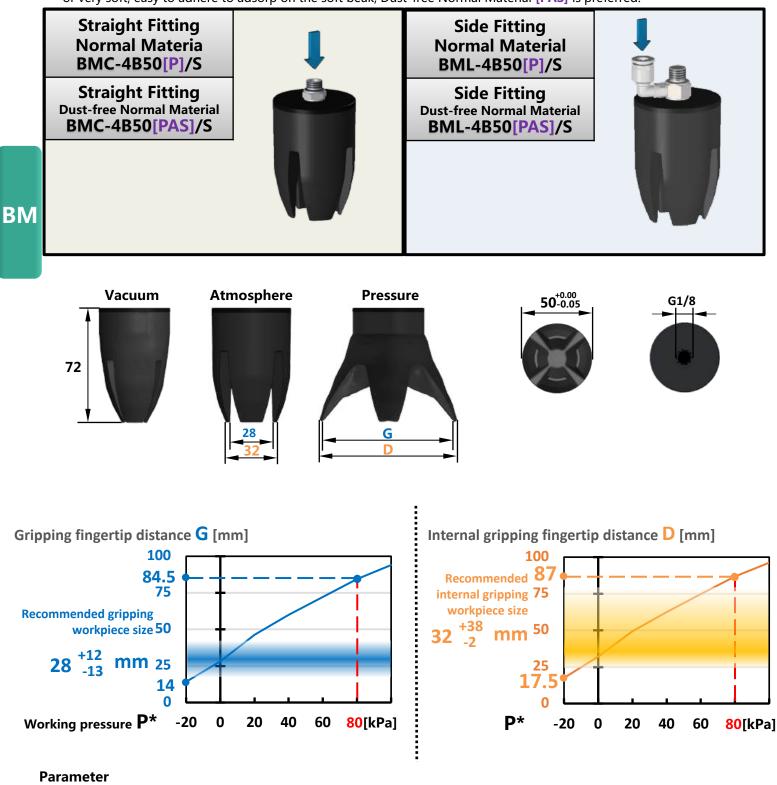
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#### **Product features**

- Finger opens in pressure state, grasps in vacuum state. It is recommended to use with Rochu control unit, gripping fingertip distance G and outer support fingertip distance D can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



Repetitive Precision	Recommend -ed Load	Lifetime times*	Safe Pressure	+80kPa 🛕	Contact Temperature
Frequency6times/sec	External gripping force	Internal gripping force	BMC Weight	91g 🛱	BML Weight102g   👸

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.

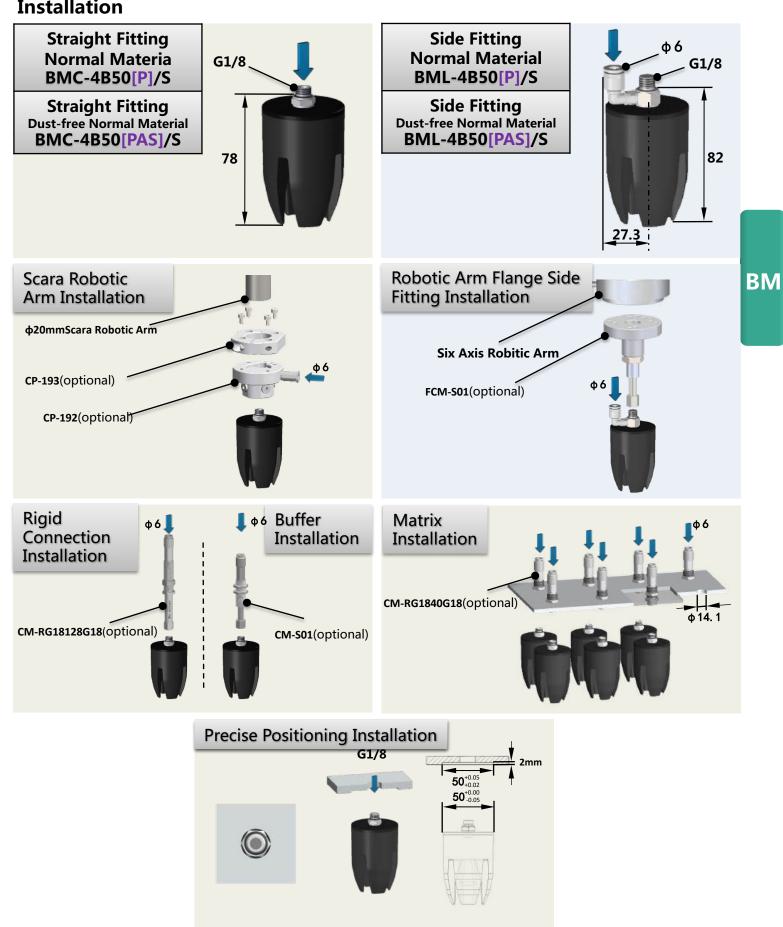


#### Beak Module

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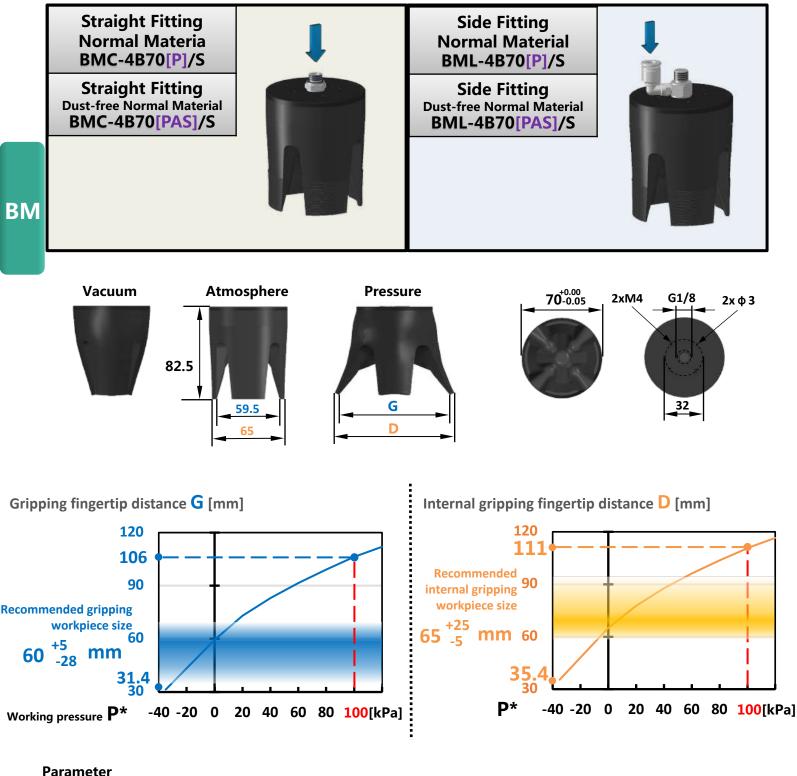
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#### **Product features**

- Finger opens in pressure state, grasps in vacuum state. It is recommended to use with Rochu control unit, gripping fingertip distance G and outer support fingertip distance D can be adjusted by working pressure.
- Soft beak material is divided into Normal Material [P] and Dust-free Normal Material [PAS]. When the workpiece is light, or very soft, easy to adhere to adsorp on the soft beak, Dust-free Normal Material [PAS] is preferred.



Repetitive Precision	±0.05mm	Recommend -ed Load	1500g	Lifetime	1.5 million times*	Safe Pressure	+100kPa 🛕	Contact Temperature	180℃
Frequency	6times/sec	External gripping force	U-4N	Internal gripping force	0-8N	BMC Weight	196g 🛱	BML Weight	207g 👸

\* : According to the working air pressure in the use scene and the surface roughness of the grabbed object, the lifetime may be affected to varying degrees. It is recommended to use Rochu control Unit. The working air pressure should not exceed the safe working pressure range.



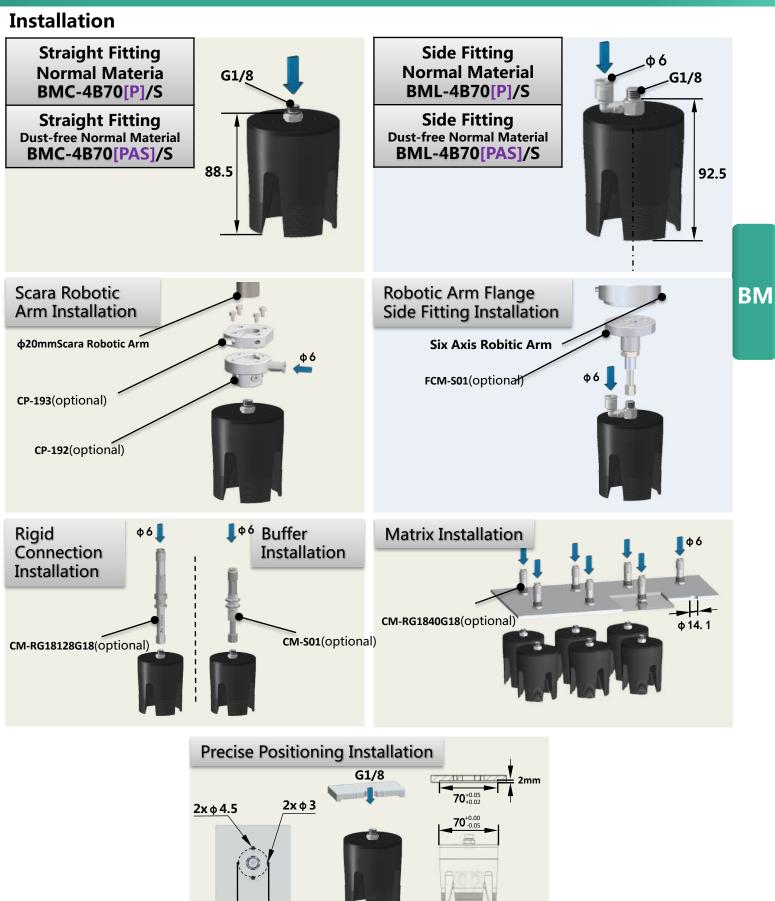
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**FM / F** Finger Module / Finger



Finger Module A



Finger Module B



Finger Module C



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FM-A3V1/LS8	FM-A3V2/LS8	FM-A3V3/LS8	FM-A3V4/LS8	FM-A3V5/LS8	F-A3T/LS8
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FM-A4V1/LS1	FM-A4V2/LS1	FM-A4V3/LS1	FM-A4V4/LS1	FM-A4V5/LS1	F-A4T/LS1
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#### **FM / F** Finger Module / Finger



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FM-B4V1/LS8	FM-B4V2/LS8	FM-B4V3/LS8	FM-B4V4/LS8	FM-B4V5/LS8	F-B4T/LS8
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FM-B8V1/LF1	FM-B8V2/LF1	FM-B8V3/LF1	FM-B8V4/LF1	FM-B8V5/LF1	F-B8T/LF1



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FM-C3V1/NS	FM-C3V2/NS	FM-C3V3/NS	FM-C3V4/NS	FM-C3V5/NS	F-C3T/NS
Page. 352	page. 353	<b>1</b> page. 354	page. 355	page. 356	page. 357
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FM-C5V1/LS1	FM-C5V2/LS1	FM-C5V3/LS1	FM-C5V4/LS1	FM-C5V5/LS1	F-C5T/LS1
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FM-C5V1/LS8	FM-C5V2/LS8	FM-C5V3/LS8	FM-C5V4/LS8	FM-C5V5/LS8	F-C5T/LS8
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FM-C5V1/FS3	FM-C5V2/FS3	FM-C5V3/FS3	FM-C5V4/FS3	FM-C5V5/FS3	F-C5T/FS3

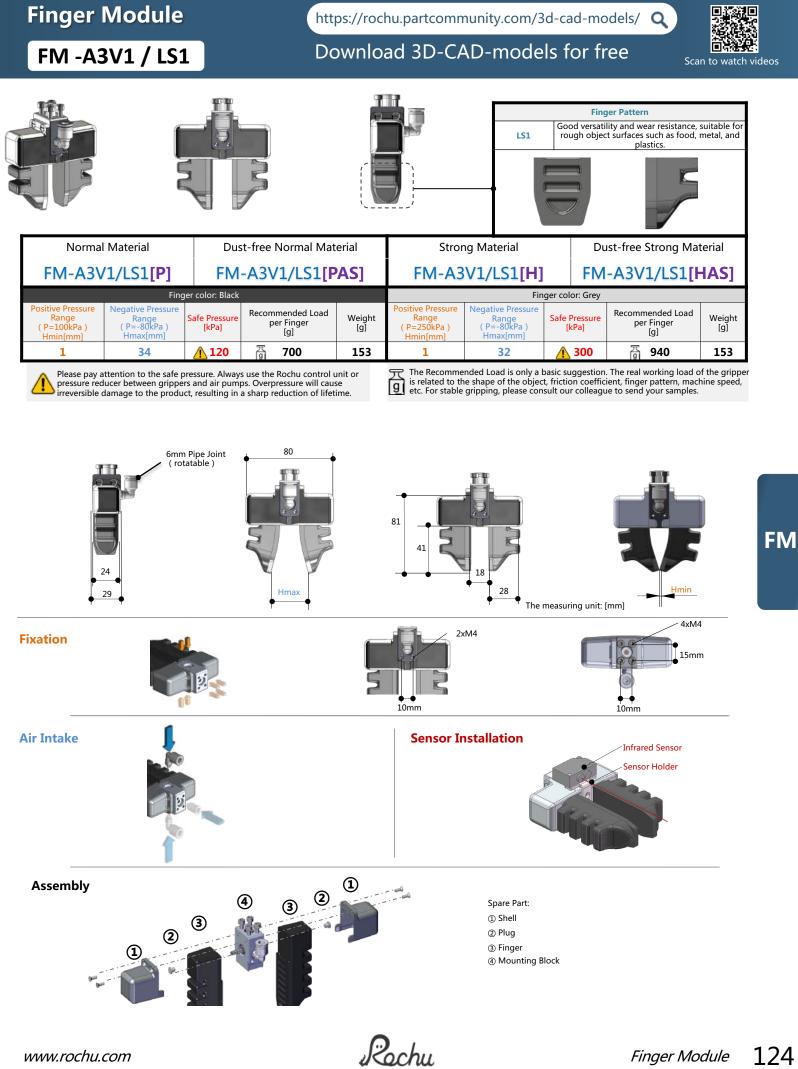
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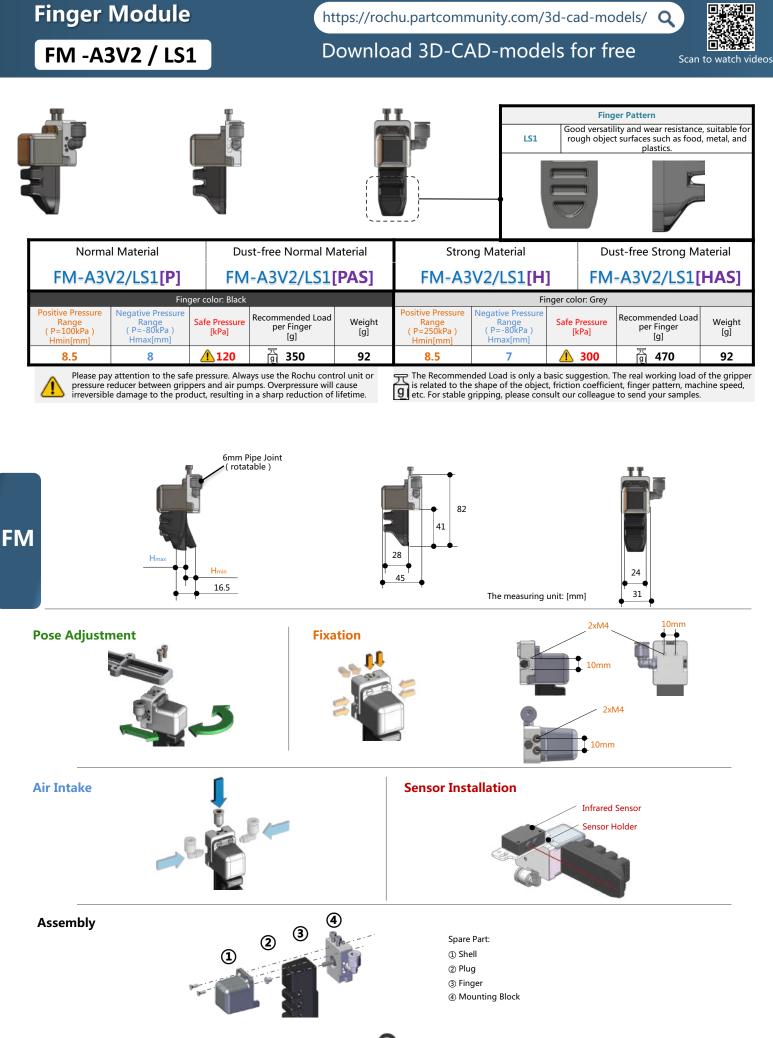


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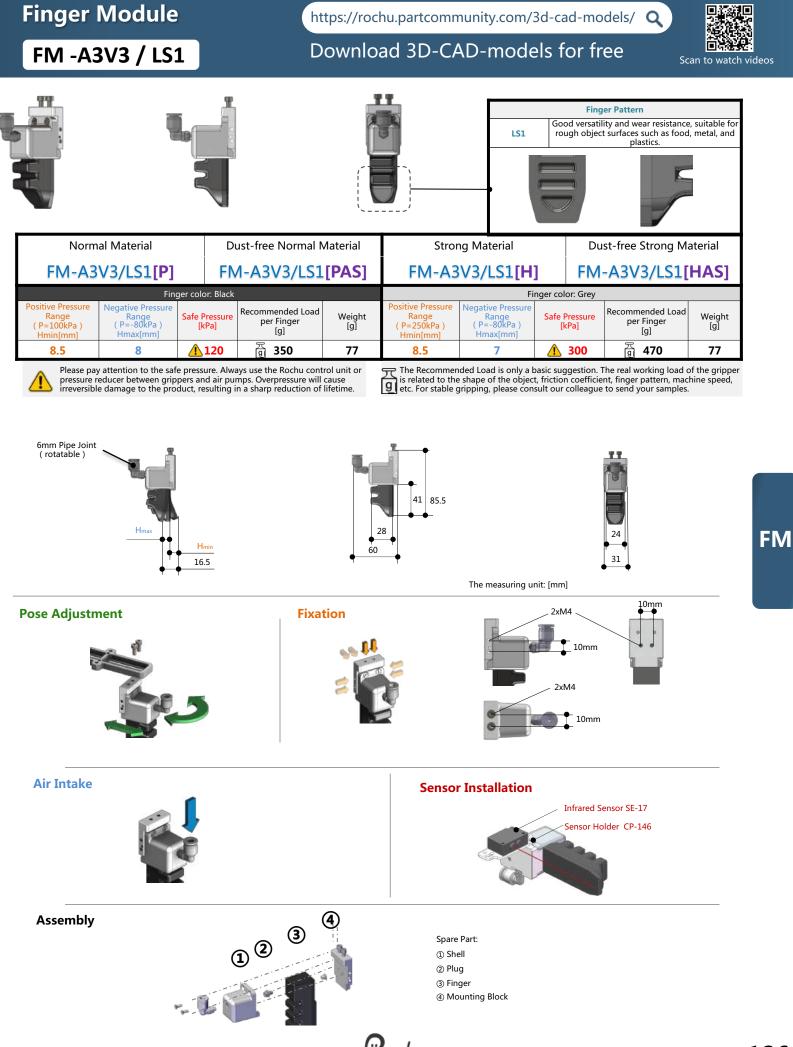
page. 394	<b>P</b> <i>age. 395</i>	<b>V</b> page. 396	page. 397	page. 398	page. 399
FM-C5V1/LF1	FM-C5V2/LF1	FM-C5V3/LF1	FM-C5V4/LF1	FM-C5V5/LF1	F-C5T/LF1
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FM-C6V1/LS1	FM-C6V2/LS1	FM-C6V3/LS1	FM-C6V4/LS1	FM-C6V5/LS1	F-C6T/LS1
page. 406	page. 407	<b>V</b> page. 408	page. 409	page. 410	page. 411
FM-C7V1/LS1	FM-C7V2/LS1	FM-C7V3/LS1	FM-C7V4/LS1	FM-C7V5/LS1	F-C7T/LS1
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FM-C8V1/LS1	FM-C8V2/LS1	FM-C8V3/LS1	FM-C8V4/LS1	FM-C8V5/LS1	F-C8T/LS1

Rochu





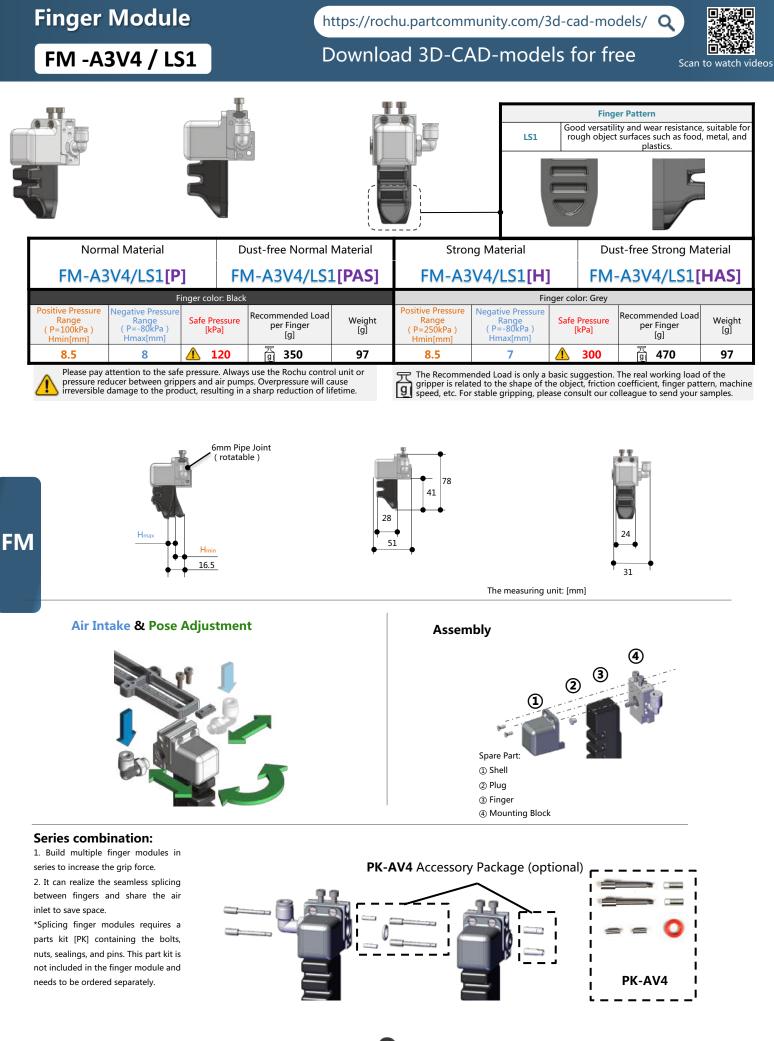
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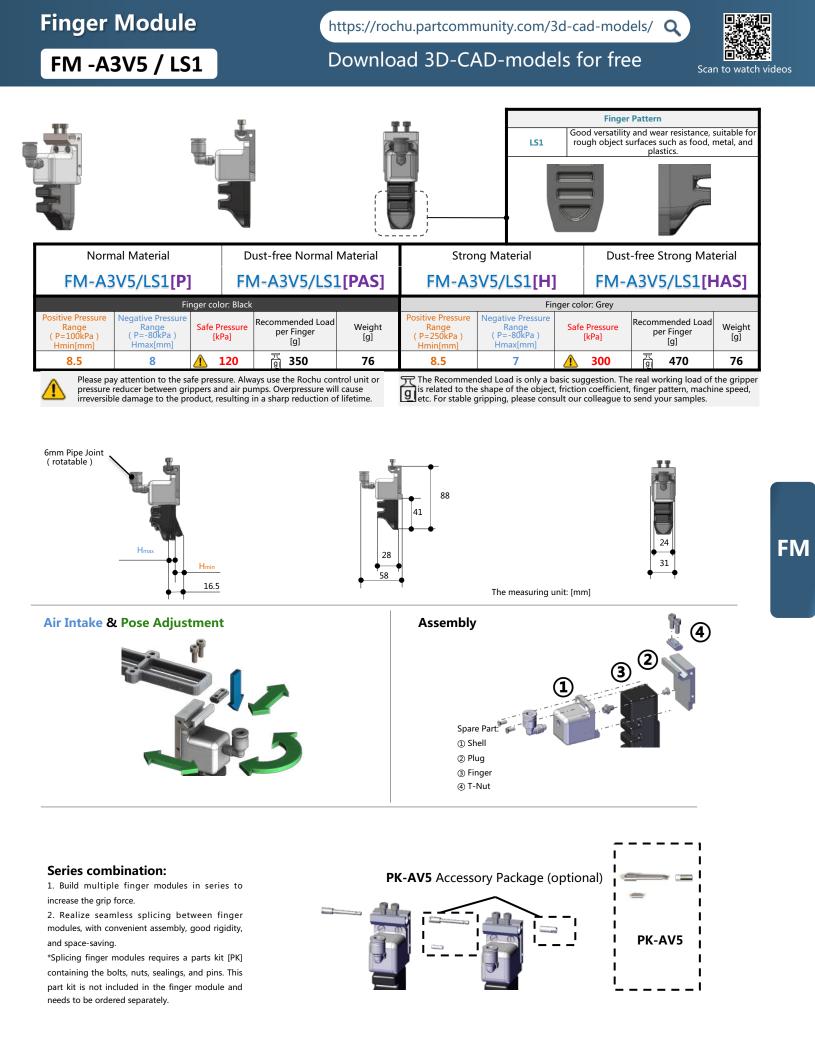
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Finger Module 126







Rochu

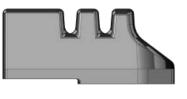
F -A3T / LS1

https://rochu.partcommunity.com/3d-cad-models/ Q

## Download 3D-CAD-models for free









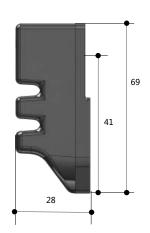
Finger	Pattern		Features						
LS1	Standard form	1	Good versatility	and wear res	istance, suitable for rough object surfaces such as food, metal, and plastics.				
Normal	Normal Material Dust-free Normal Material			Strong Material		Du	ust-free Strong Material		
F-A3T	F-A3T/LS1[P]		-A3T/LS1[ <b>P</b> /	AS]	F-A3T/LS1[H] F-A3T/LS1[HAS]		AS]		
	Fing	er color: Black			Finger color: Grey				
Positive Pressure Range (P=100kPa) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	ner Finder		Positive Pressure Range (P=250kPa) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]
8.5	8	<u>120</u>	L20 🛱 350 33		8.5	7	<u>}</u> 300	품 <b>470</b>	33

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

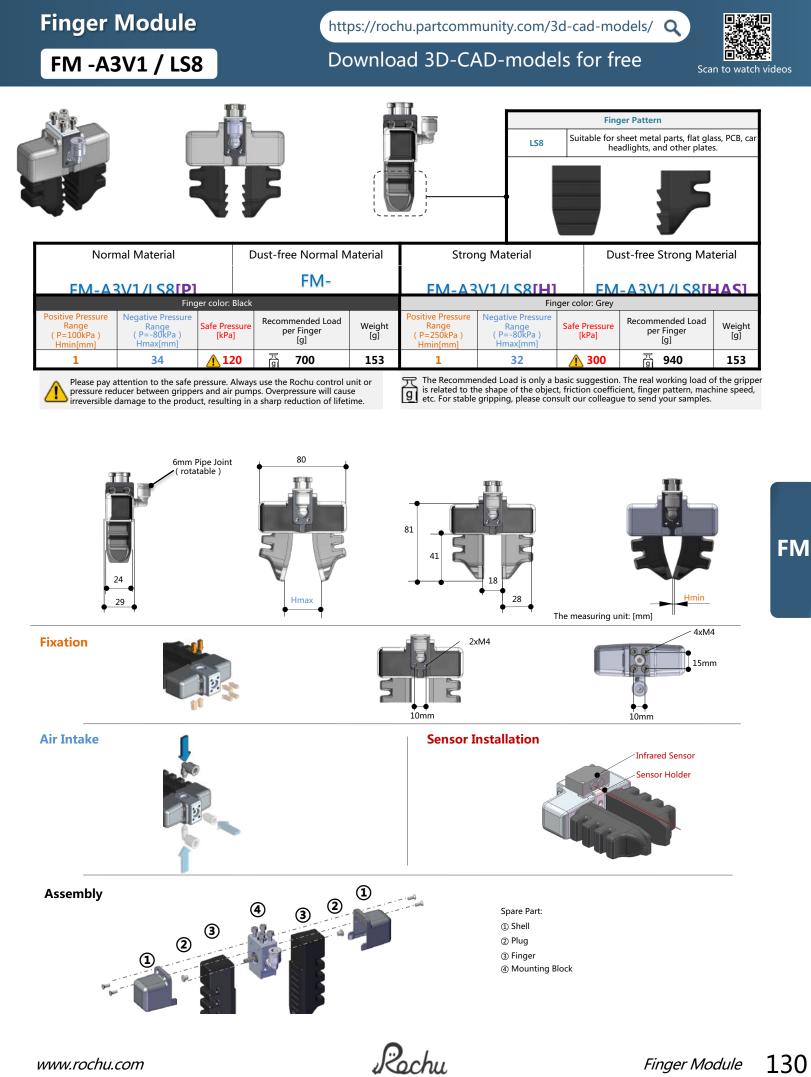
The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

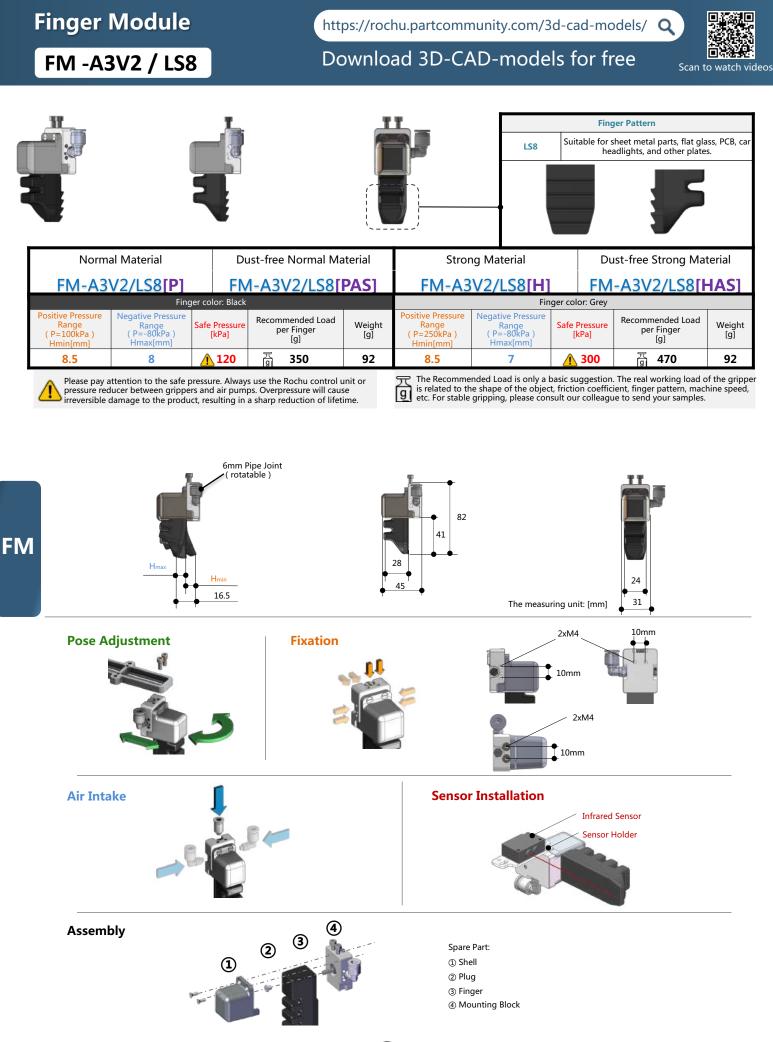
# FM Dimension Parameters



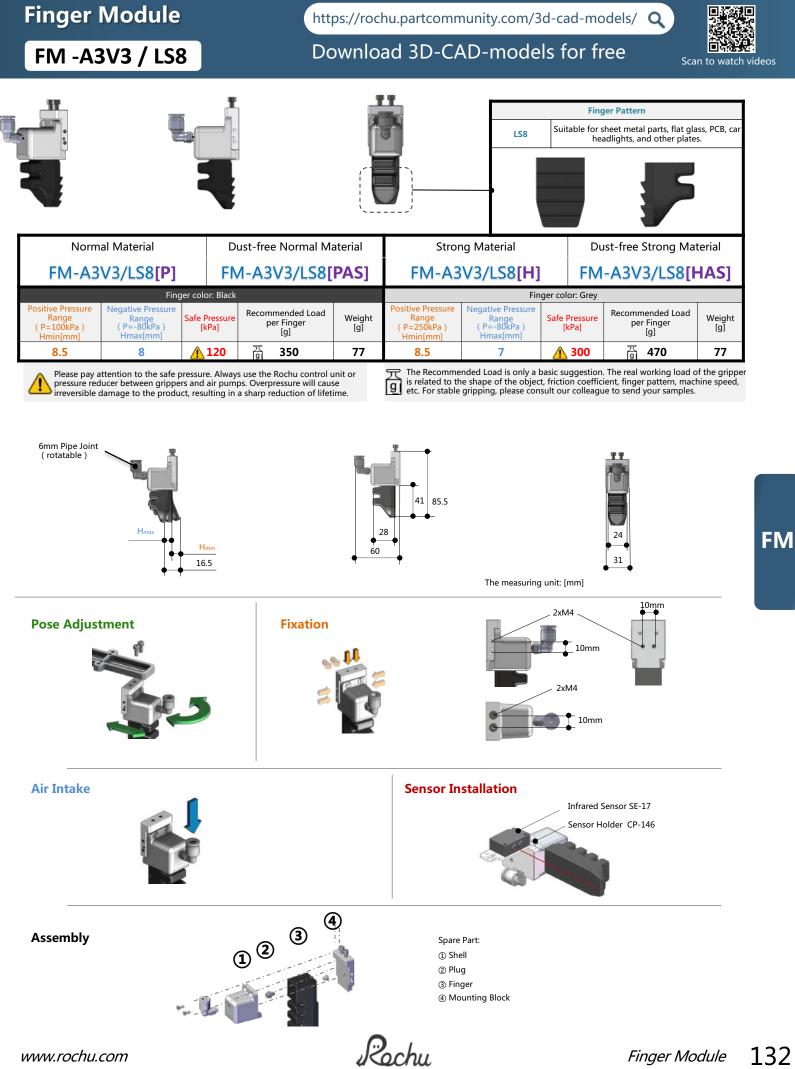


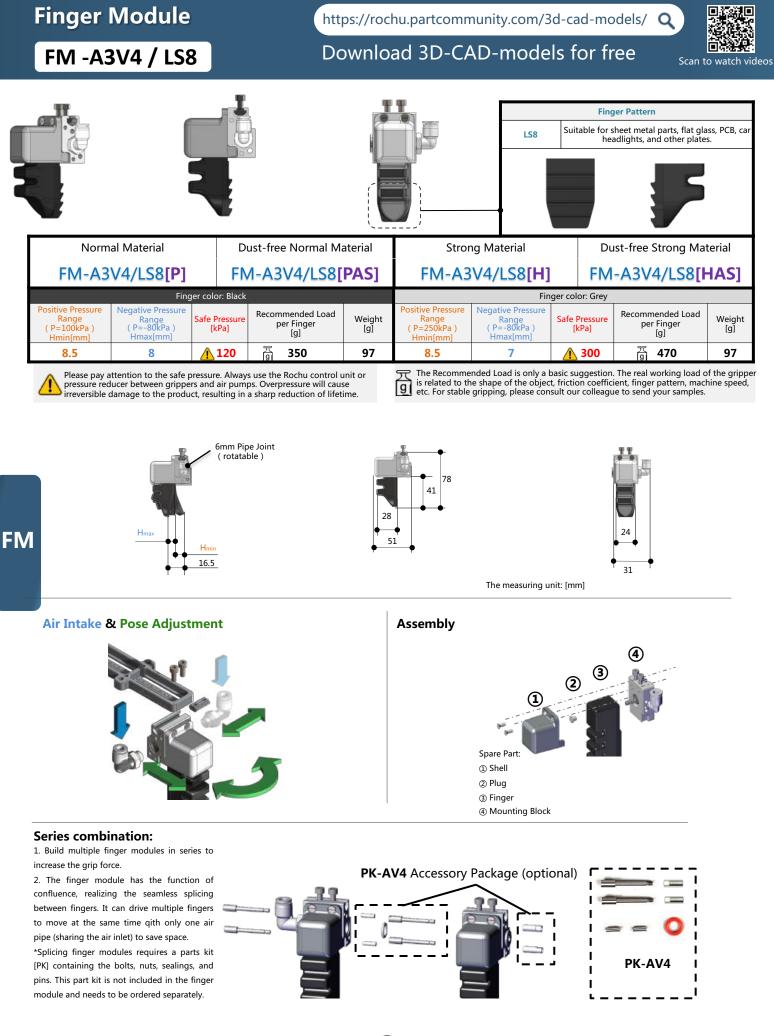




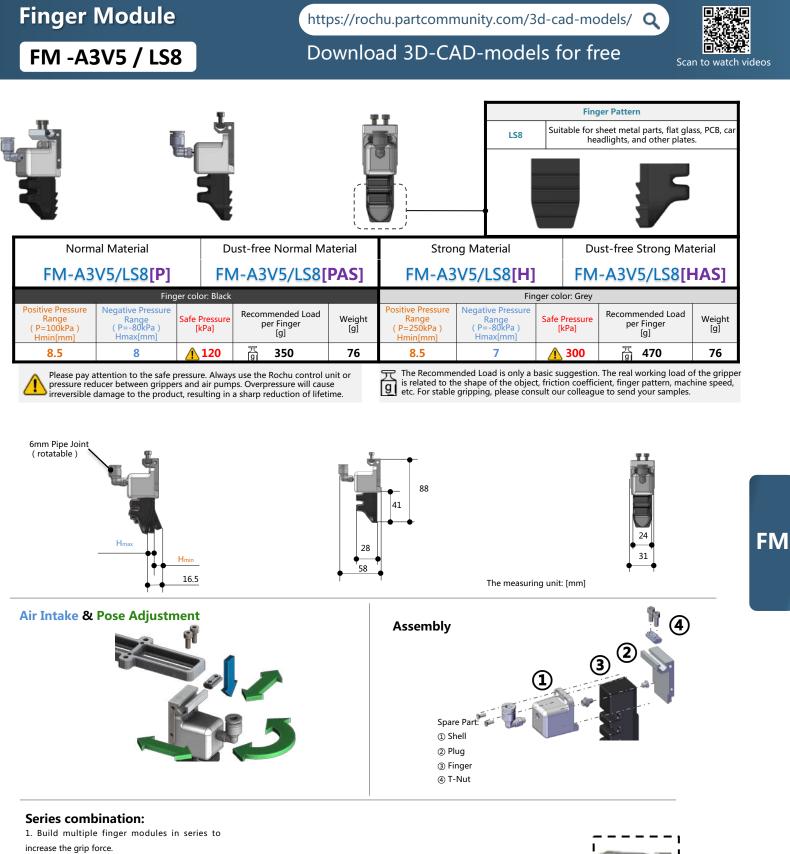


Rochu









2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Finger Module	https://rochu	.partcommunity.com/3d-ca	ad-models/ Q
F -A3T / LS8	Download	d 3D-CAD-models f	or free Scan to watch videos
			0
Finger Pattern		Features	
LS8 Special Form	Suitable for sh	eet metal parts, flat glass, PCB, car headlights,	;, and other plates.
Normal Material	Dust-free Normal Material	Strong Material	Dust-free Strong Material
F-A3T/LS8[P]	F-A3T/LS8[PAS]	F-A3T/LS8[H]	F-A3T/LS8[HAS]
	color: Black		r color: Grey
Positive Pressure         Negative Pressure           Range         Range           (P=100kPa)         Hmax[mm]	fe Pressure Recommended Load per Finger [g] Weight [g]	Positive Pressure Range         Negative Pressure Range         Sa           (P=250kPa)         (P=-80kPa)         Sa           Hmin[mm]         Hmax[mm]         Hmax[mm]	afe Pressure Recommended Load per Finger [g] Weight [g]

33

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

120

즙

350

8

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

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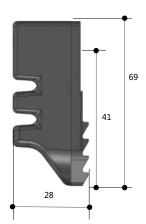
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7

# FM Dimension Parameters

8.5





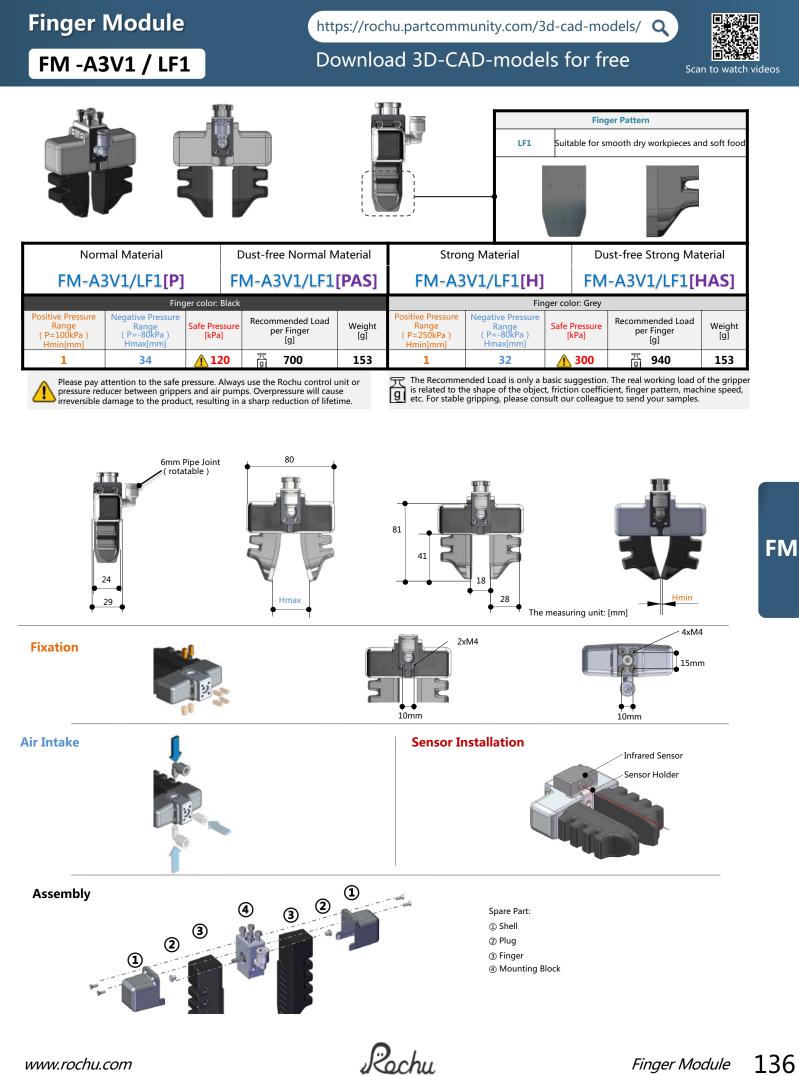
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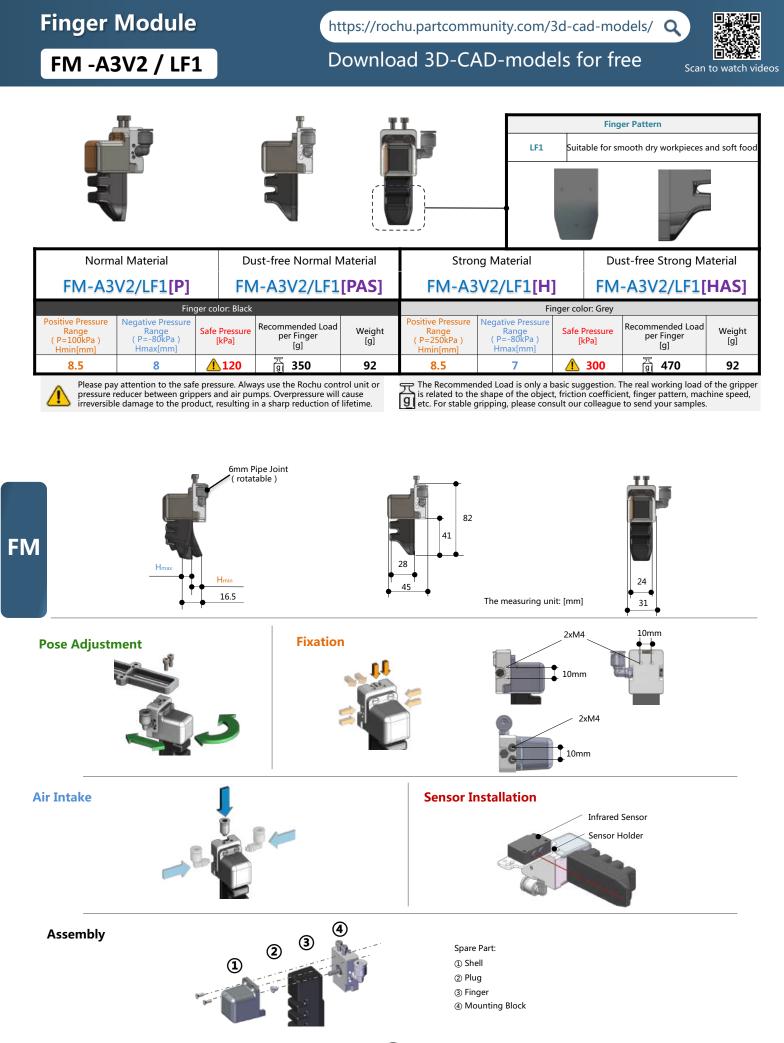


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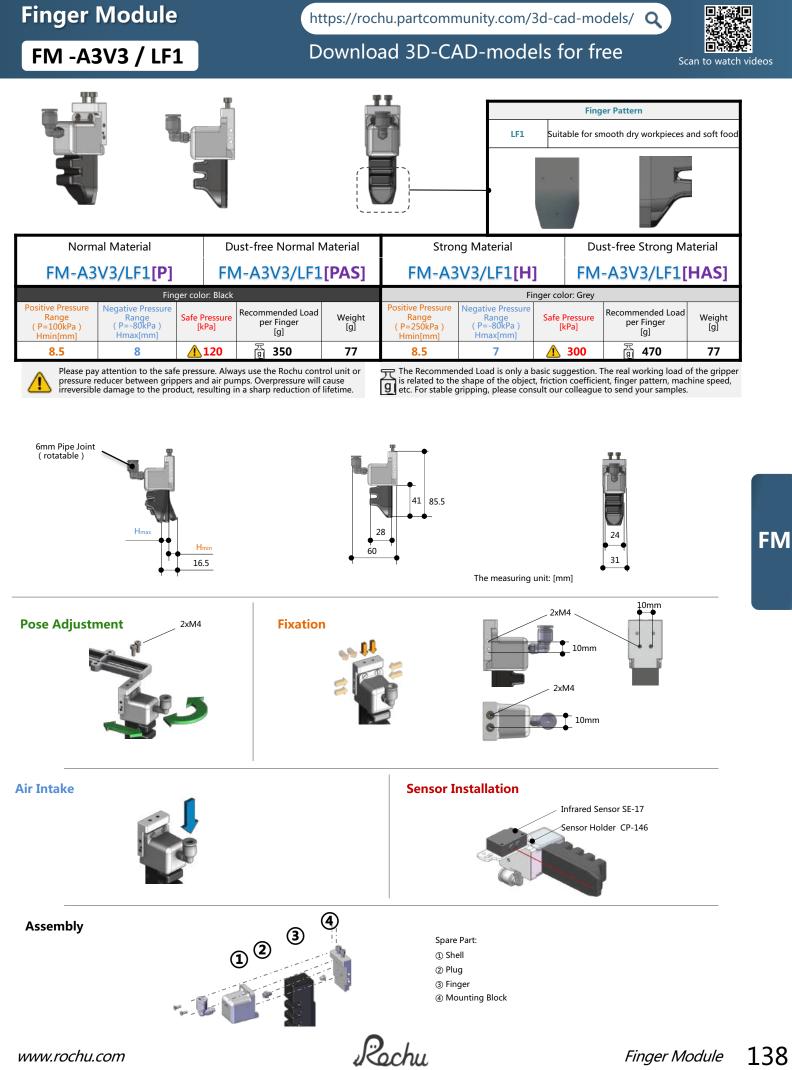
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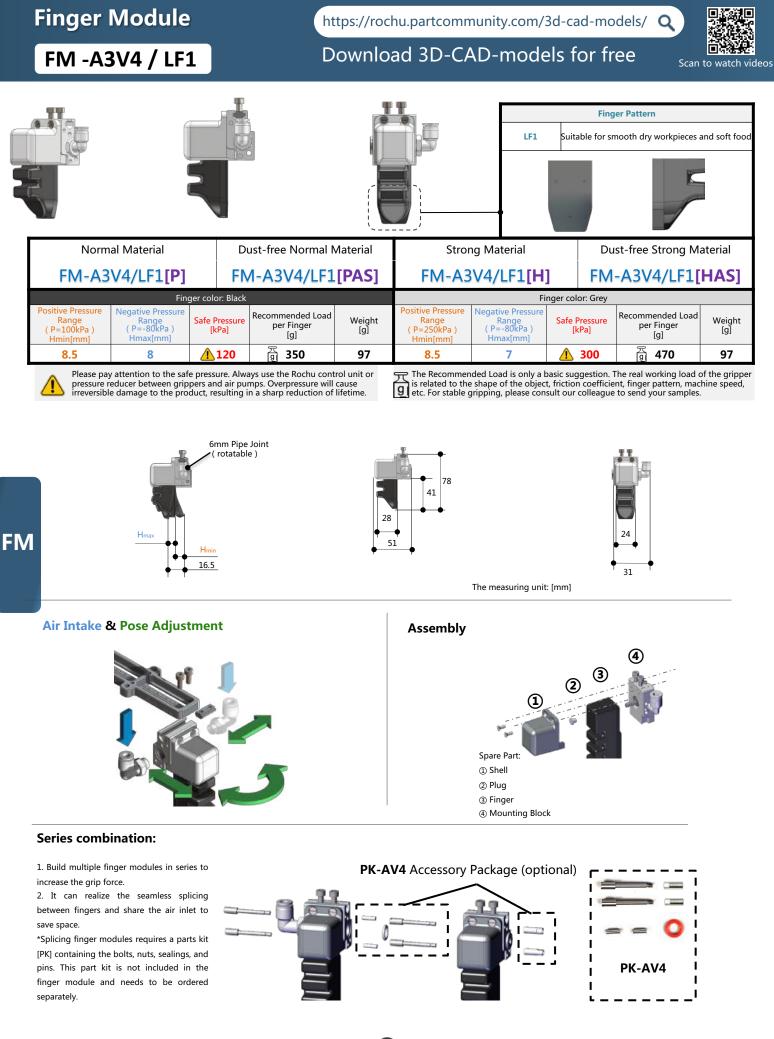




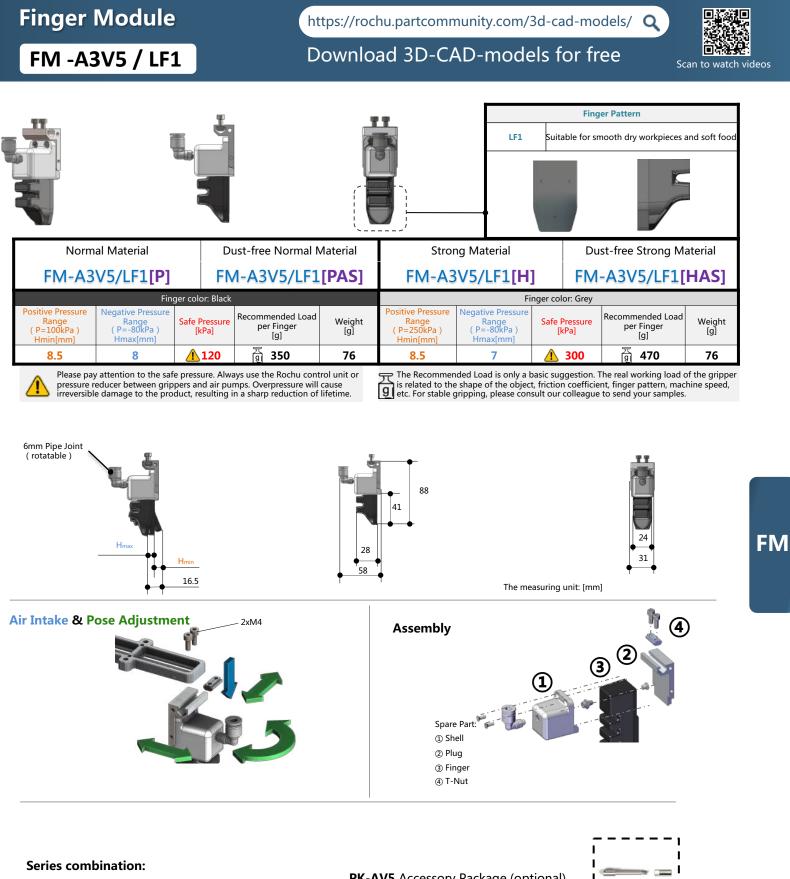


Rochu





Rochu



1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-AV5 Accessory Package (optional)



Finger Module	https://rochu	.partcommunity.com/3d-cad	-models/ Q	
F -A3T / LF1	Download	Download 3D-CAD-models for free Scan to watch videos		
Finger Pattern	Features			
LF1 Special Form	Suitable for smooth dry workpieces and soft food.			
Normal Material	Dust-free Normal Material         Strong Material         Dust-free Strong Material			
F-A3T/LF1[P]	F-A3T/LF1[PAS]	F-A3T/LF1[H]	F-A3T/LF1[HAS]	
Finger color: Black		Finger color: Grey		
	Pressure [kPa] Recommended Load per Finger [g] Weight [g]		Pressure [kPa] Recommended Load per Finger [g] Weight [g]	

33

8.5

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

斎 350

<u>120</u>

The Recommended Load is only a basic suggestion. The real working load of the gripper gives is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

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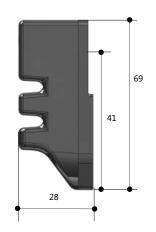
7

300

# FM Dimension Parameters

8





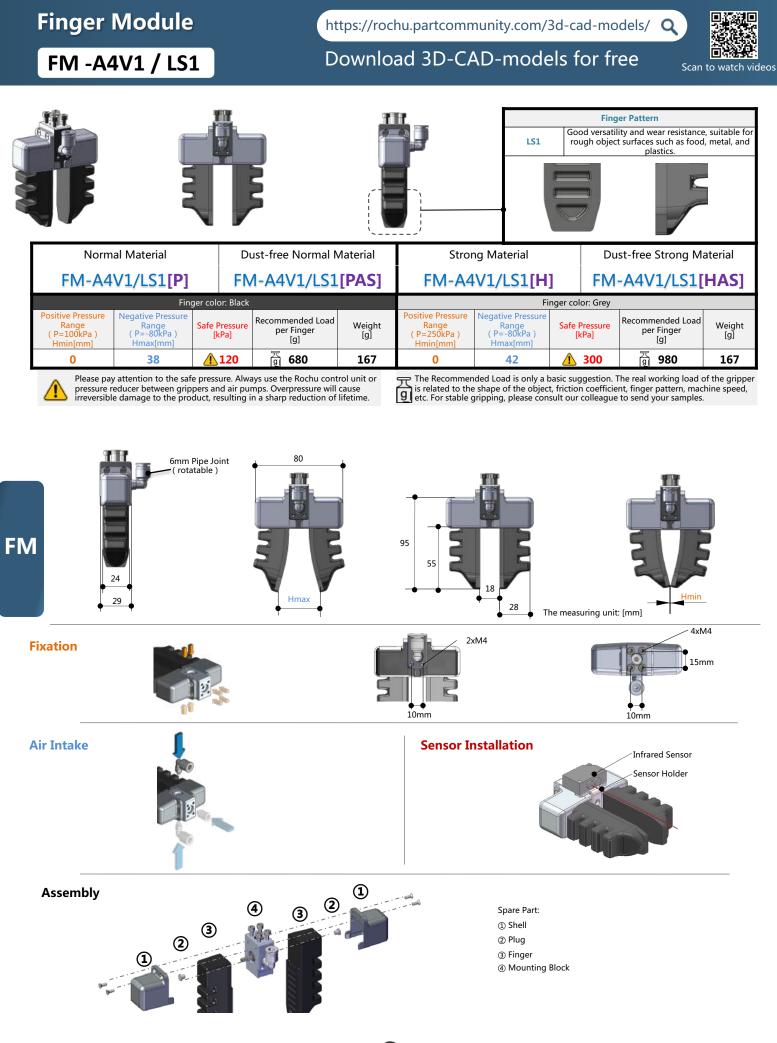
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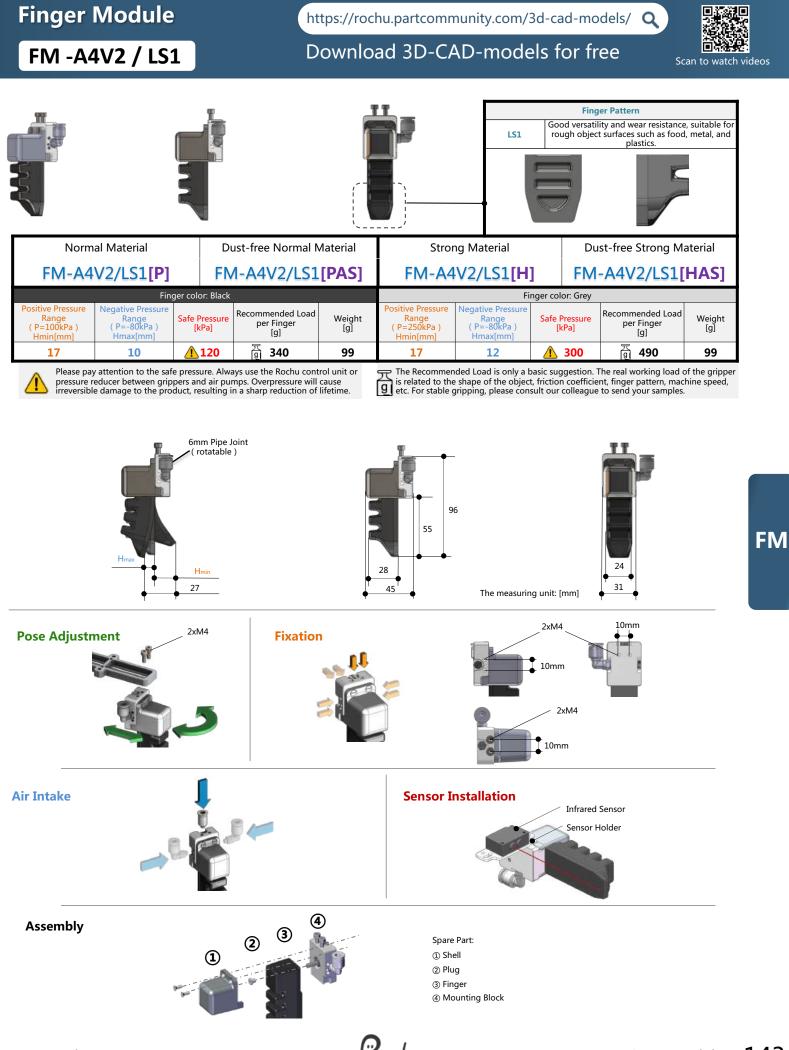
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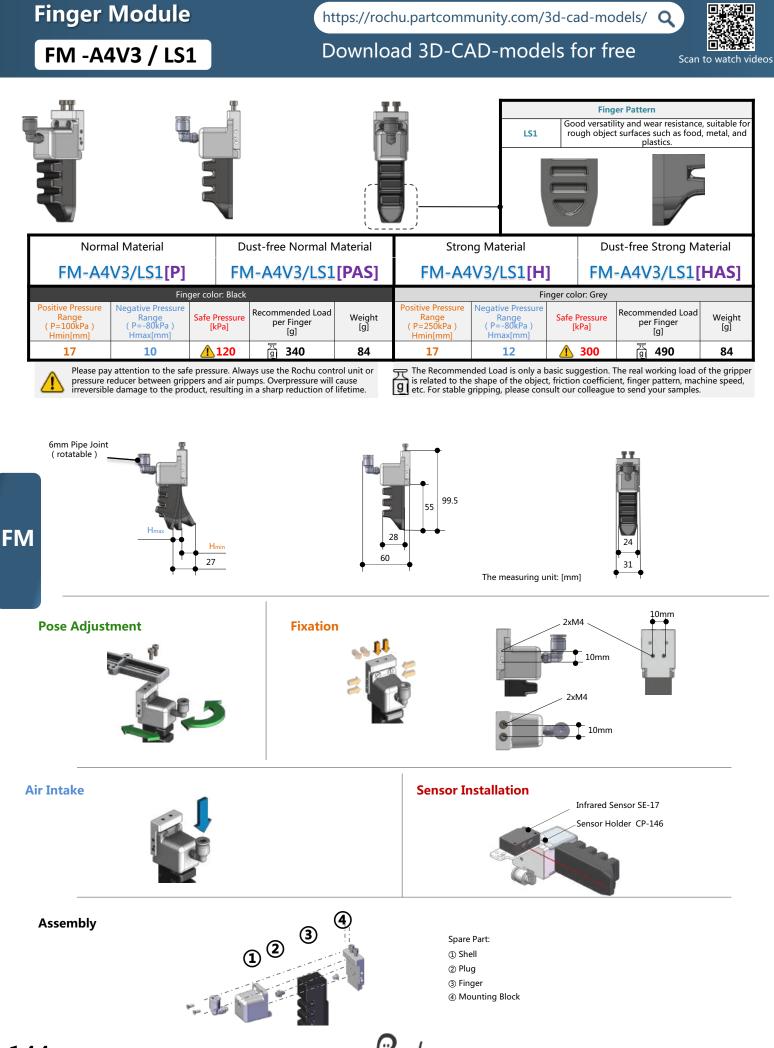




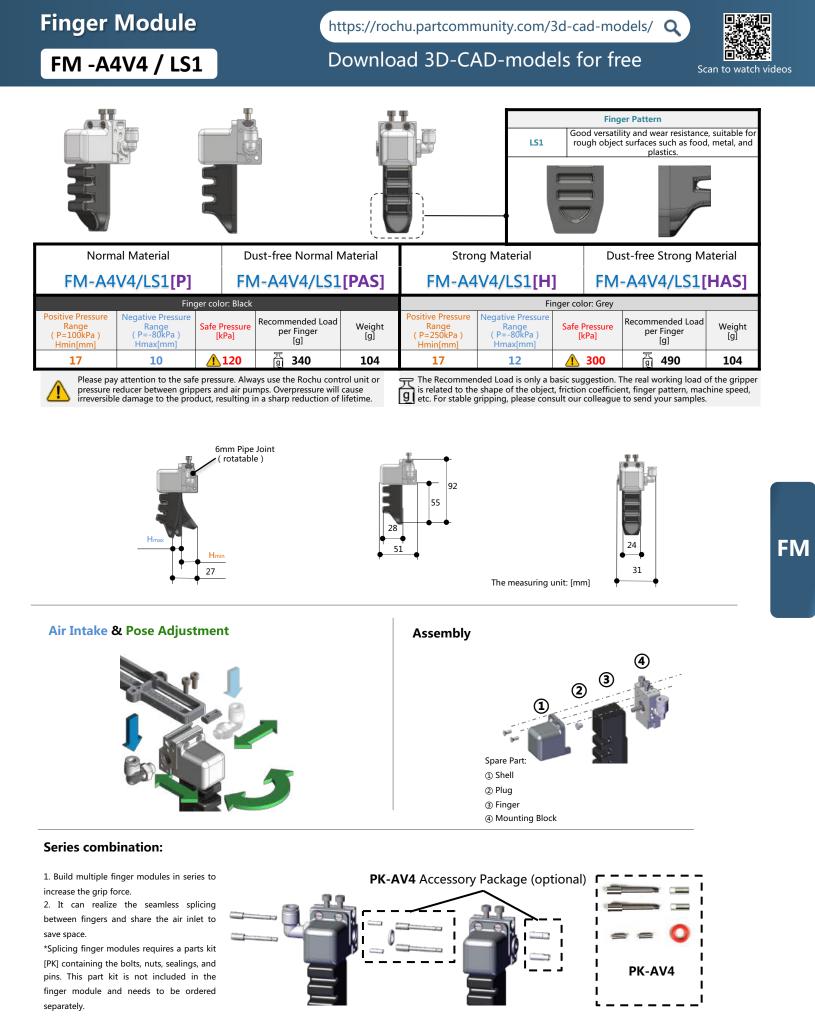
Rochu



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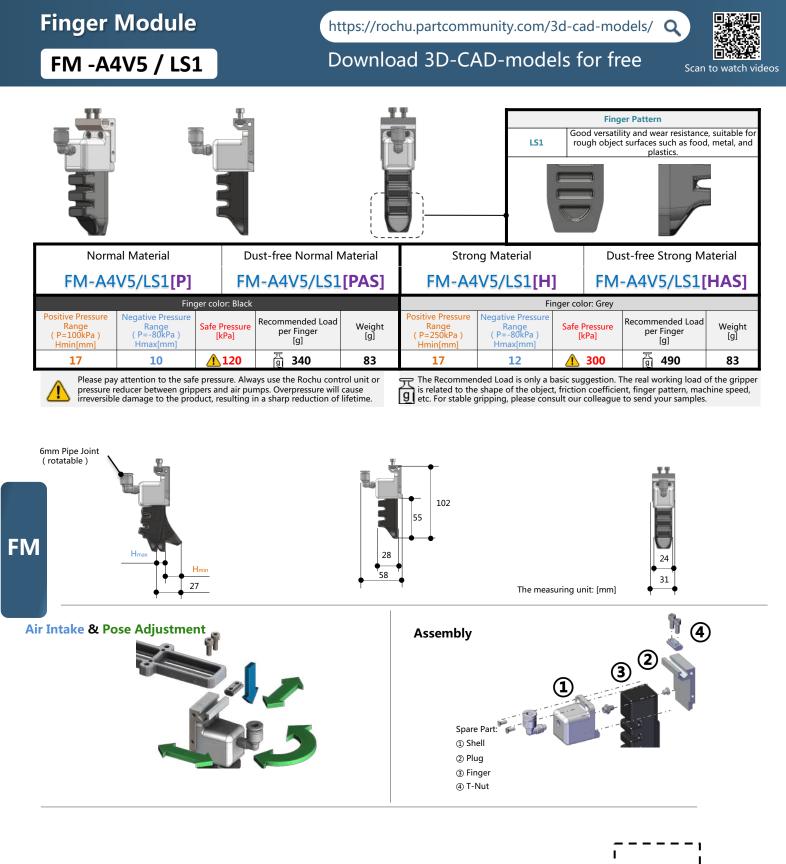


Rochu



Pochu







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Finger M	odule	h	ttps://rocl	chu.partcommunity.com/3d-cad-models/ Q					
F -A4T /	LS1	D	ownloa	ad 3D-CAD-models for free					
			<u>uu</u>						
Finger Pa	attern			Fe	atures				
LS1	Standard form	Good versatil	lity and wear res	sistance, suitable for	rough object surface	es such as food, m	netal, and plastics.		
Normal M	aterial	Dust-free Normal N	Vaterial	Strong Material		Du	Dust-free Strong Material		
		1. Contract (10, 1255)	LS1[PAS] F-A4T/LS1[H] F-A4T/LS1					aterial	
F-A4T/L	S1[P]	F-A4T/LS1[F	PAS]	F-A4	T/LS1[H]	F-	-A4T/LS1[H		
	Finger col		PAS]		Fi	F-	A4T/LS1[H		
Positive Pressure Range (P=100kPa) (	Finger col gative Pressure Range Safe		Weight	F-A4 Positive Pressure Range (P=250kPa) Hmin[mm]			Recommended Load per Finger [g]		

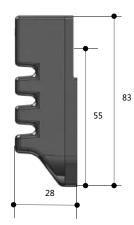
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Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

## **Dimension Parameters**





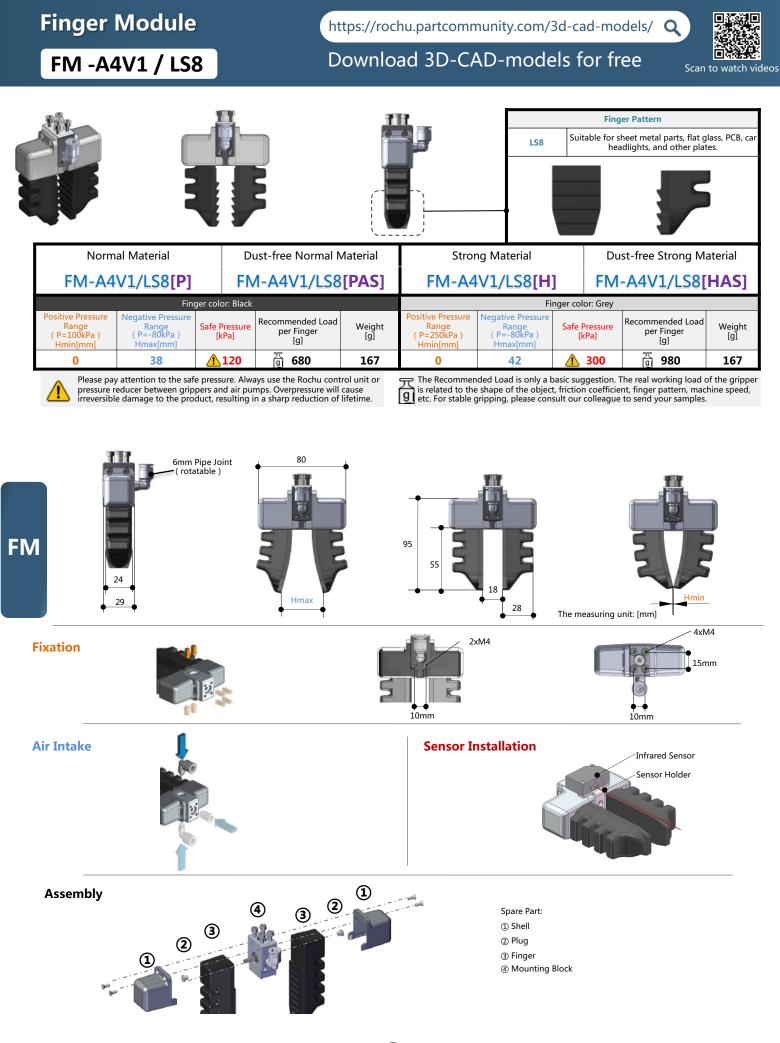


Finger Module

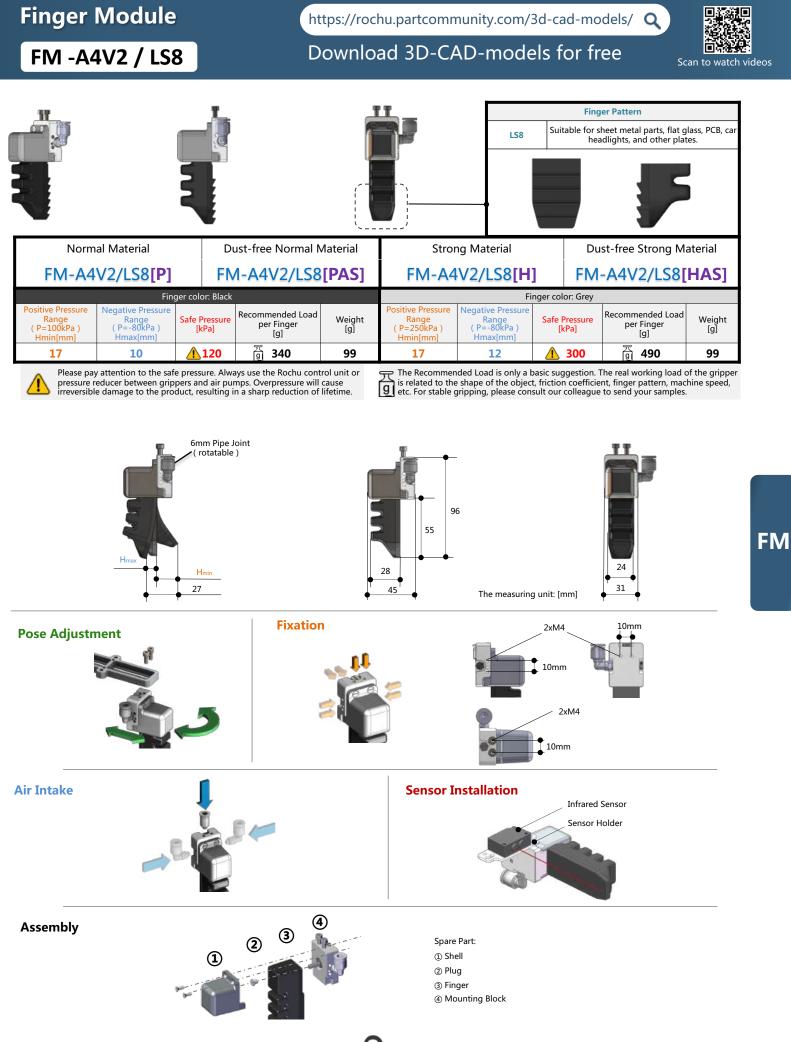
147



FM

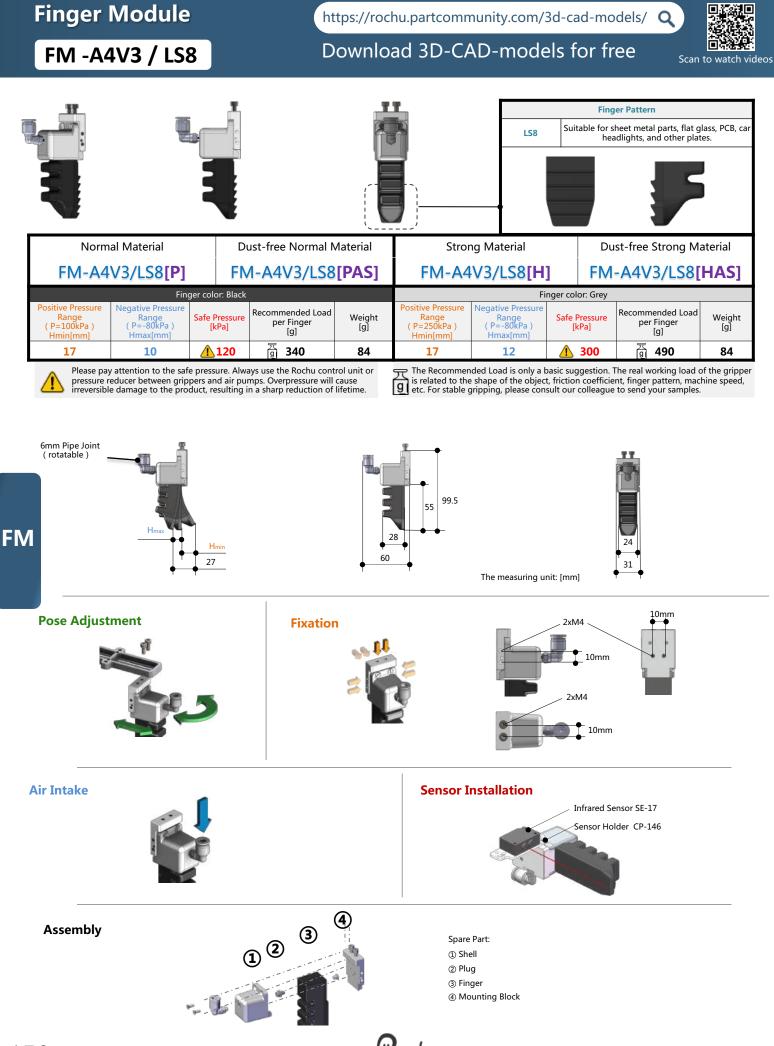


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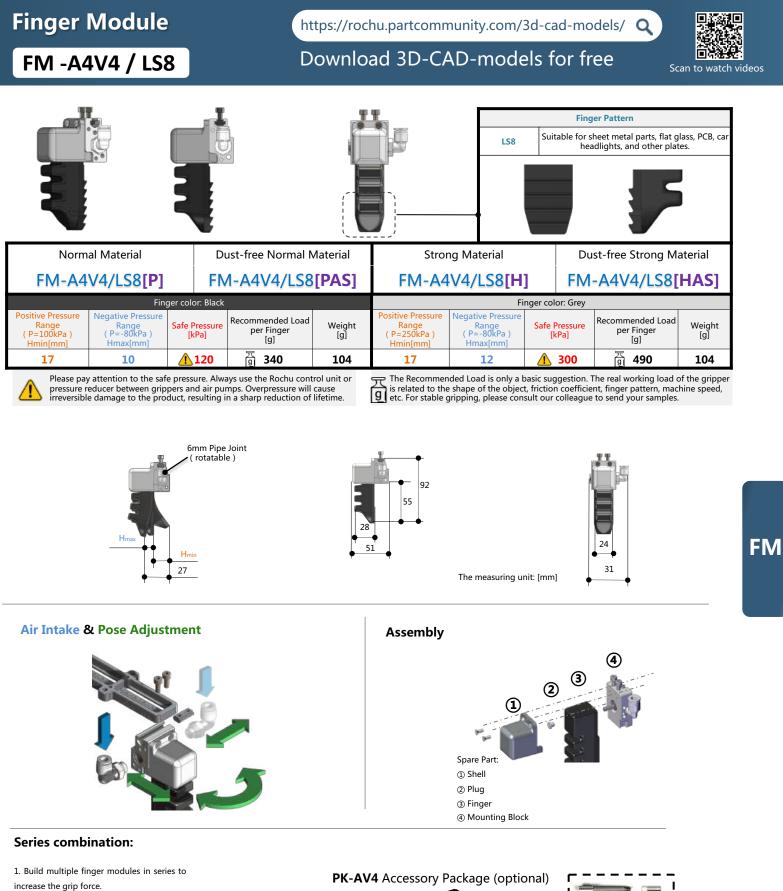


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Finger Module 149

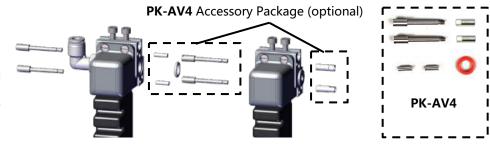


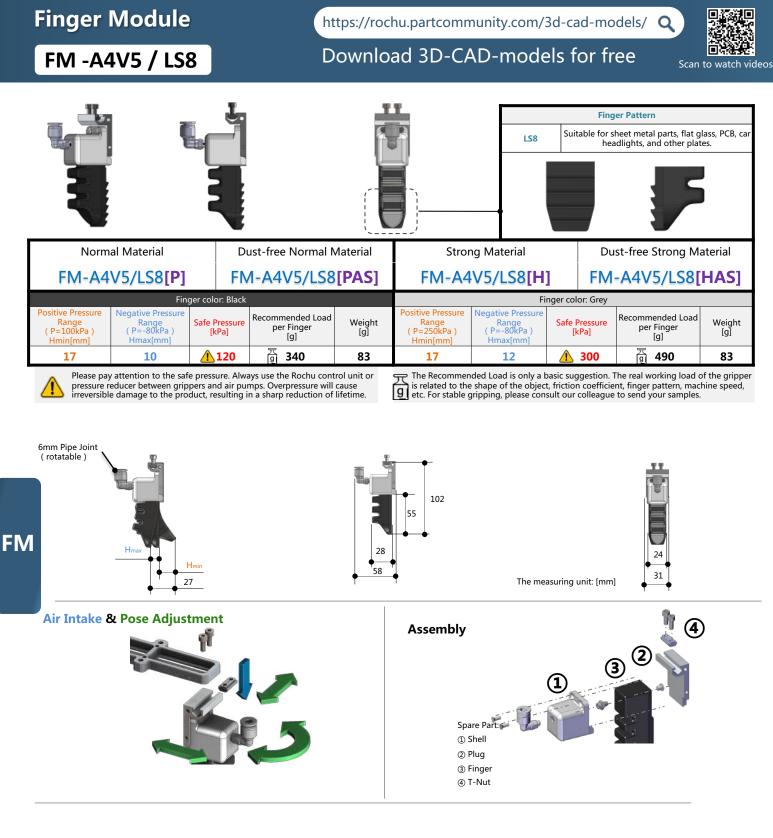
Rochu



2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.







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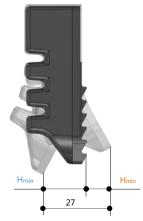


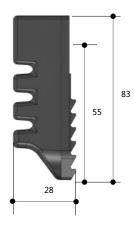


Finger	Module	https://r	ochu.partcommunity	y.com/3d-cad-mc	odels/ Q	
F -A4T	/ LS8	Down	oad 3D-CAD-ı	models for fr	ree <sub>s</sub>	can to watch
				•		
Finge	er Pattern		Feature	25		
Finge	er Pattern Special Form	Suitable fo	Feature		plates.	
LS8		Suitable fo Dust-free Normal Material		B, car headlights, and other p	<sup>plates.</sup> ust-free Strong M	laterial
LS8 Norm	Special Form		sheet metal parts, flat glass, PCE	B, car headlights, and other p		
LS8 Norm	Special Form nal Material <b>T/LS8[P]</b> Finger co	Dust-free Normal Material	sheet metal parts, flat glass, PCB Strong Mat F-A4T/LS	B, car headlights, and other p terial Du S8[H] F Finger color: Grey	ust-free Strong M	
LS8 Norm	Special Form nal Material T/LS8[P] Finger cc Negative Pressure Range Safe	Dust-free Normal Material F-A4T/LS8[PAS]	sheet metal parts, flat glass, PCB Strong Mat F-A4T/LS Positive Pressure Range (P=250kPa)	B, car headlights, and other p terial Du \$8[H] F	ust-free Strong M	IAS]

Please pay attention to the safe pressure. Always use the kochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime. The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

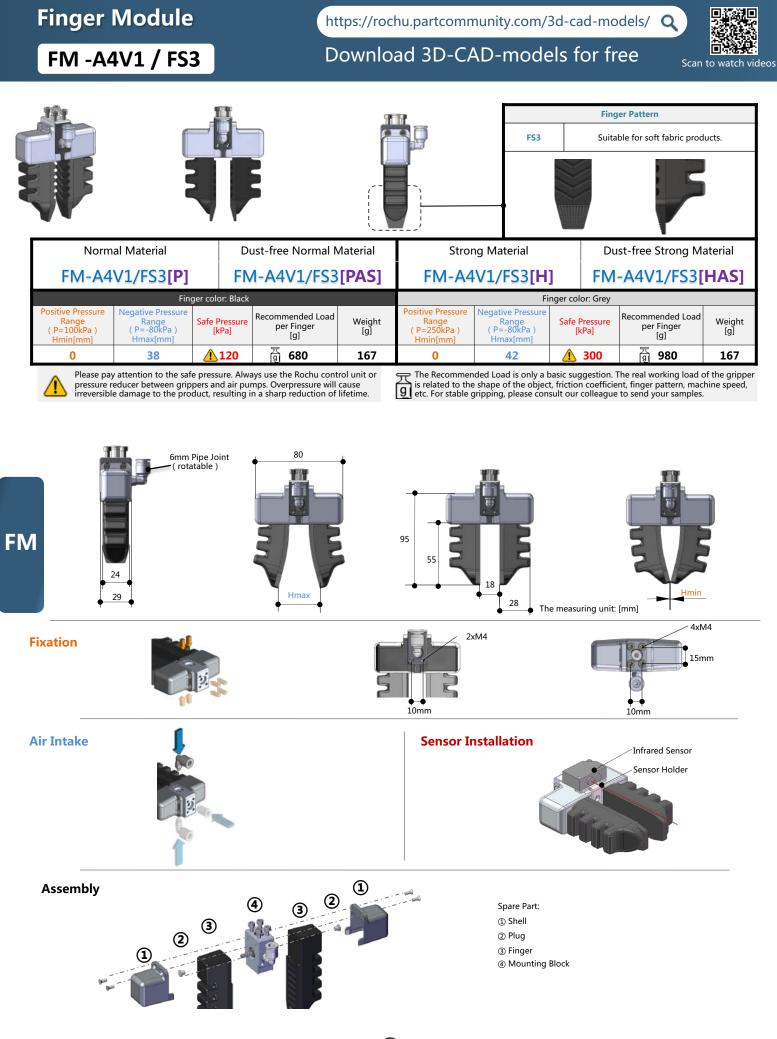
# **Dimension Parameters**



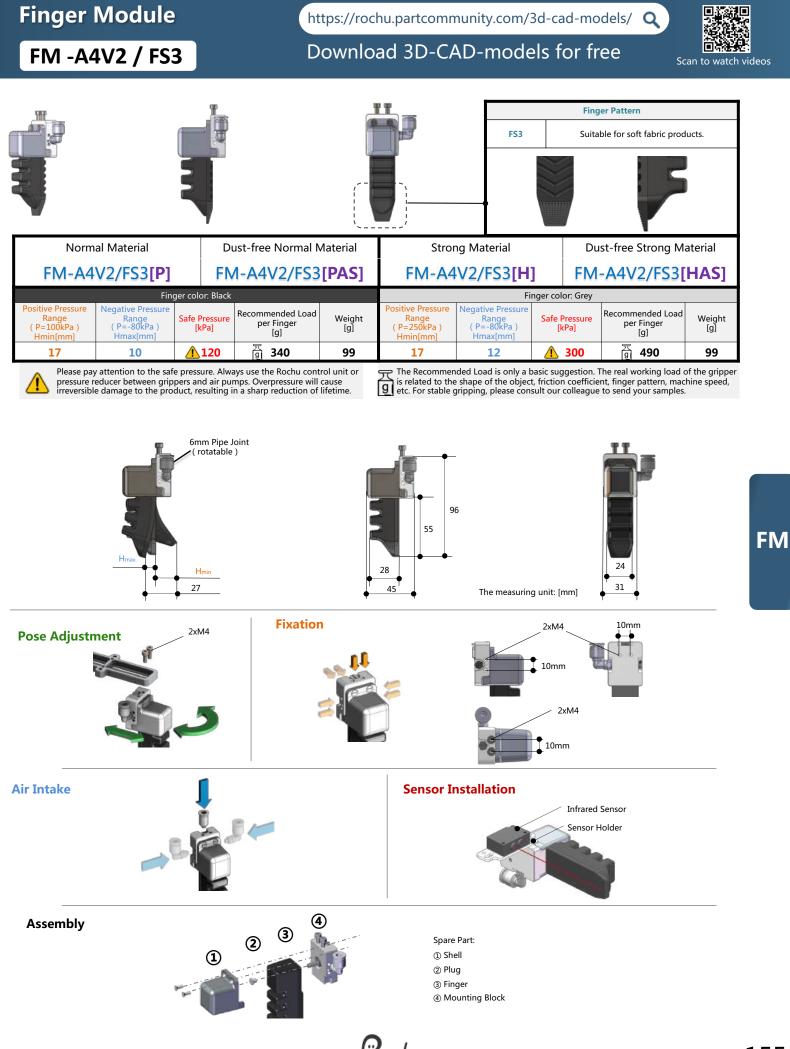




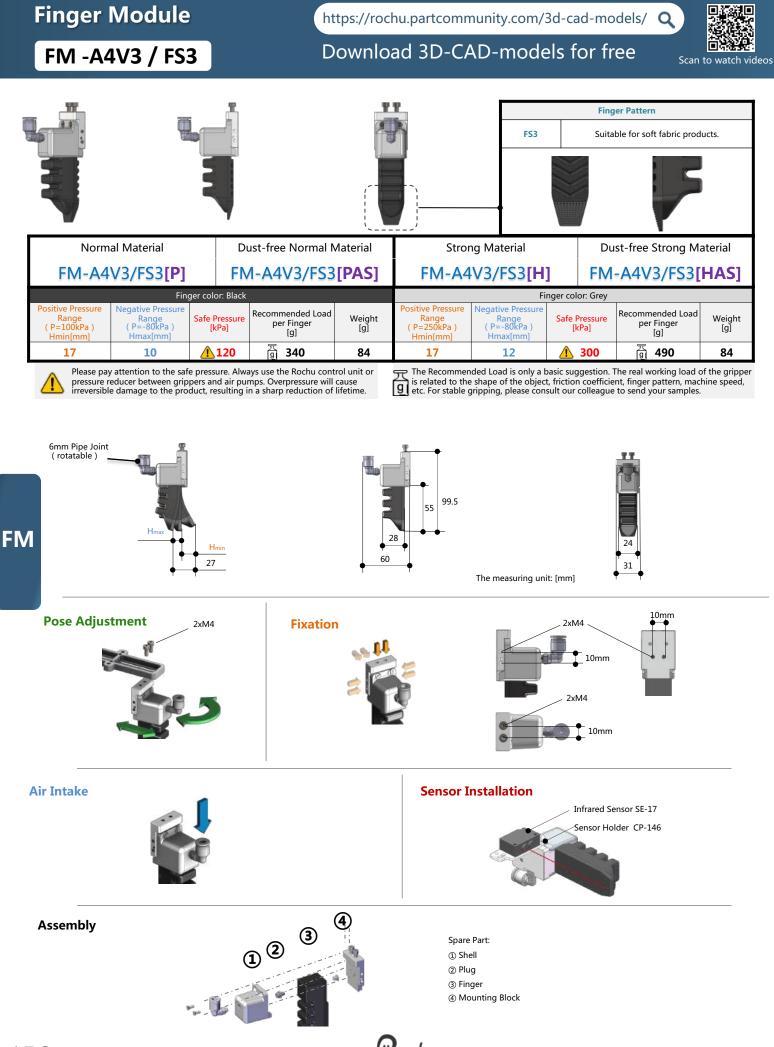
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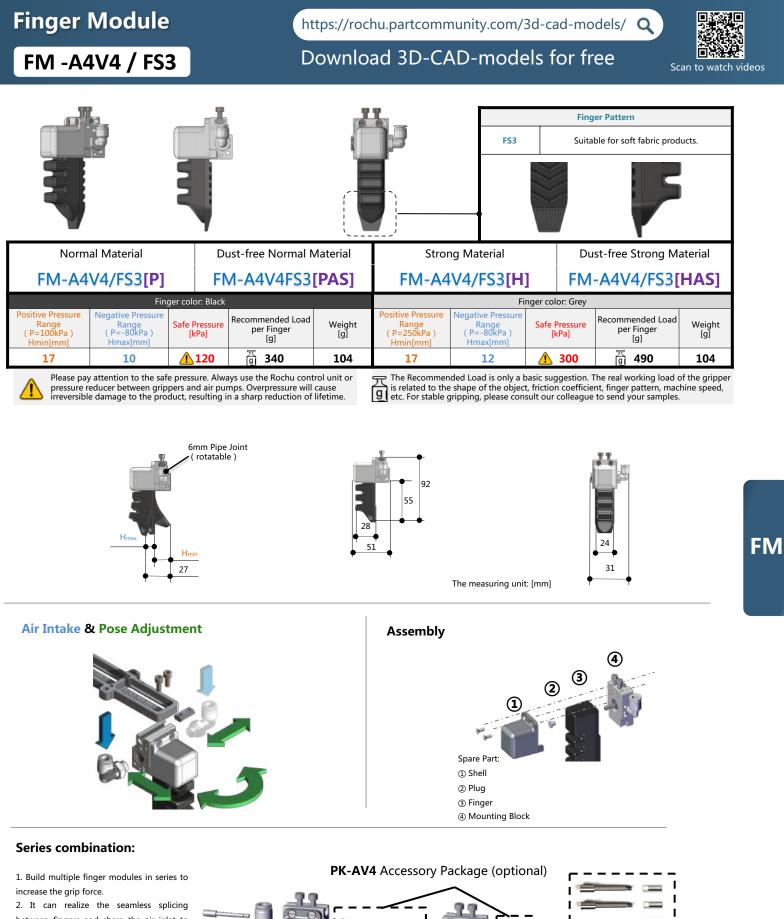
Rochu



Rochu

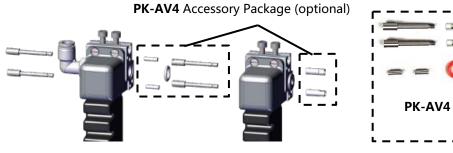


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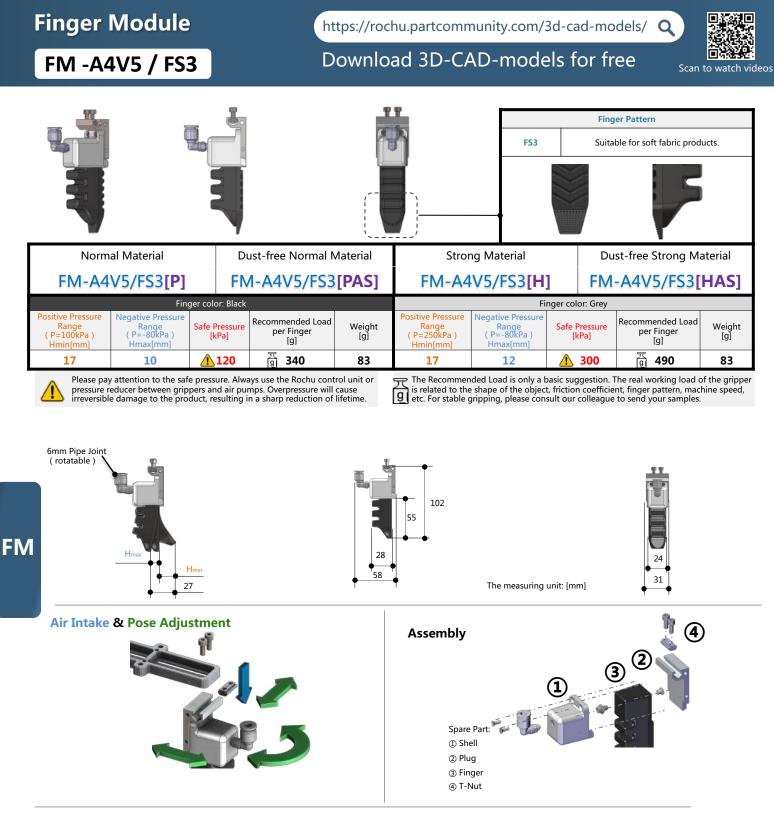


between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu



#### Series combination:

1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

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Finger I	inger Module https://rochu.partcommunity.com/3d-cad-models/ Q								
F -A4T	/ FS3		D	ownloa	ad 3D-CA	D-mode	els for fi	ree <sub>so</sub>	an to watch videos
				W	5				
Finger	r Pattern				Fe	atures			
FS3	Special Form				Suitable for s	oft fabric products.			
Norma	Normal Material		ust-free Normal N	Strong Material			Dust-free Strong Material		
F-A4T	F-A4T/FS3[P]			PAS]	F-A4T/FS3[H] F-A4T/F				AS]
	Fing	ger color: Black			Finger color: Grey				
Positive Pressure	Negative Pressure			Positive Pressure per Finger [g]     Positive Pressure Range (P=250kPa)     Negative Pressure Range (P=-80kPa)     Safe Pressure [kPa]     Recommended Load per Finger [g]					

17

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

120

집 340

The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

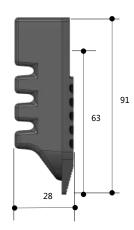
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12

### **Dimension Parameters**

10





17

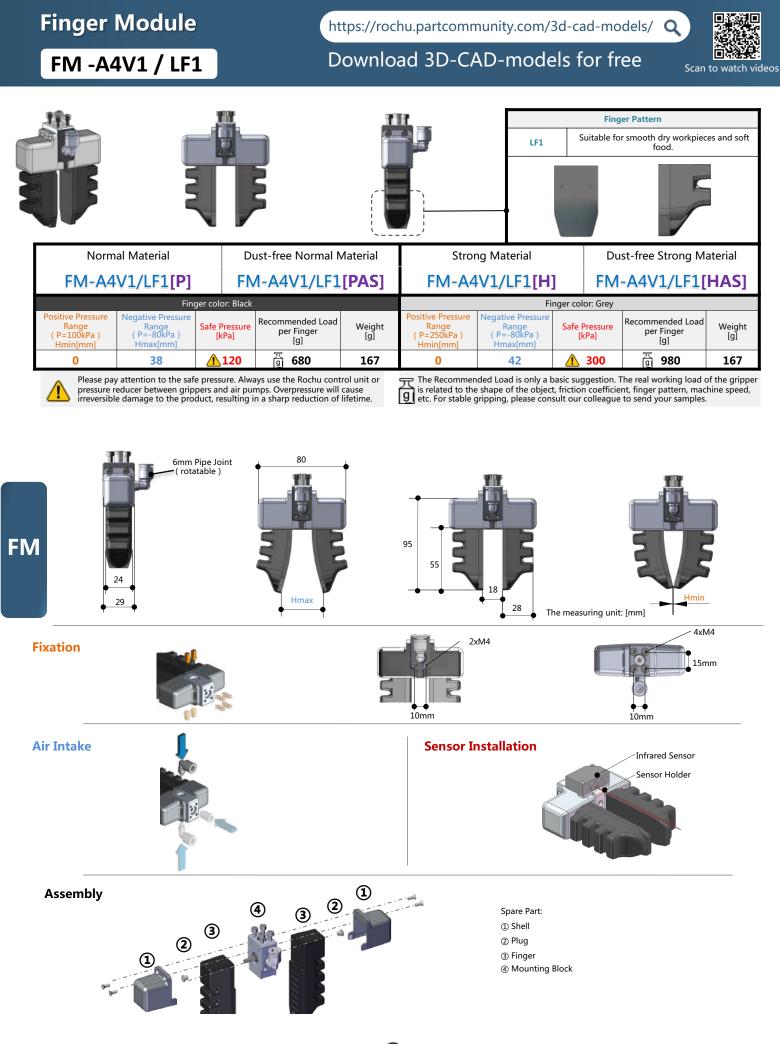
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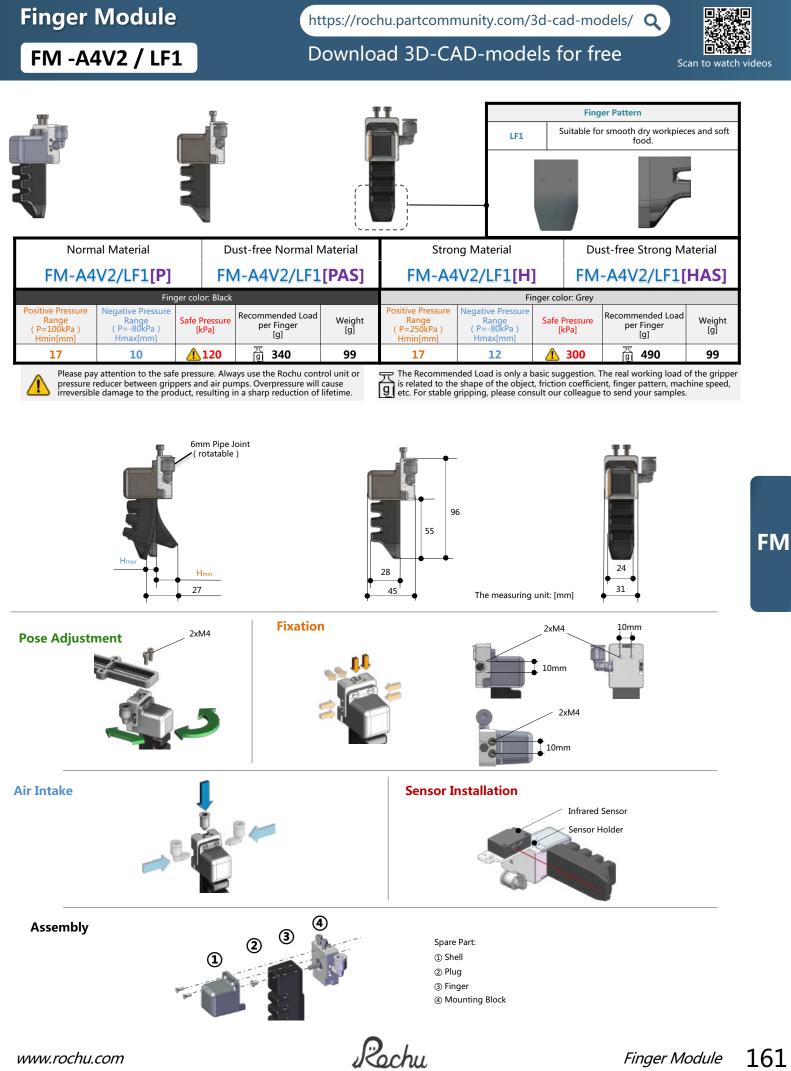
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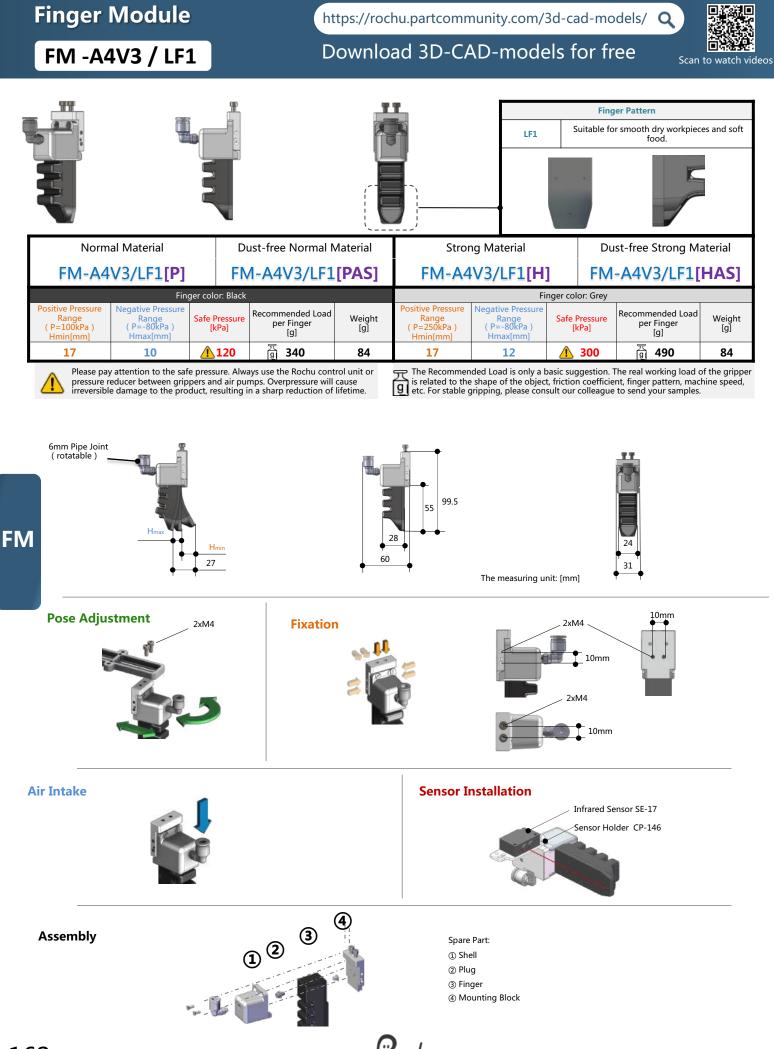
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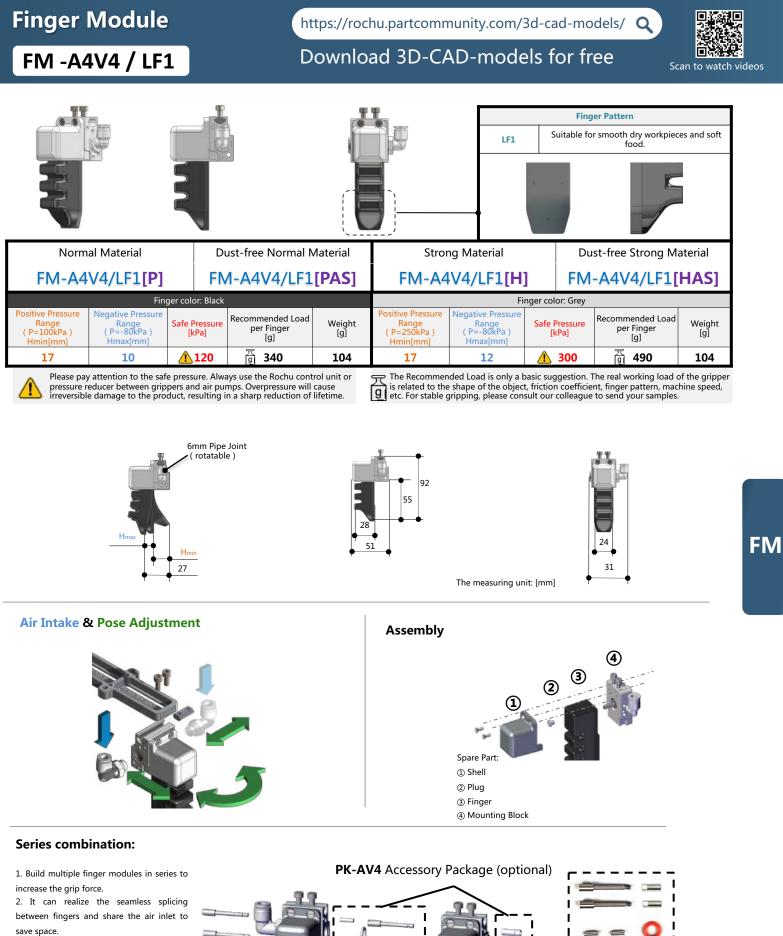




161 Finger Module



Rochu

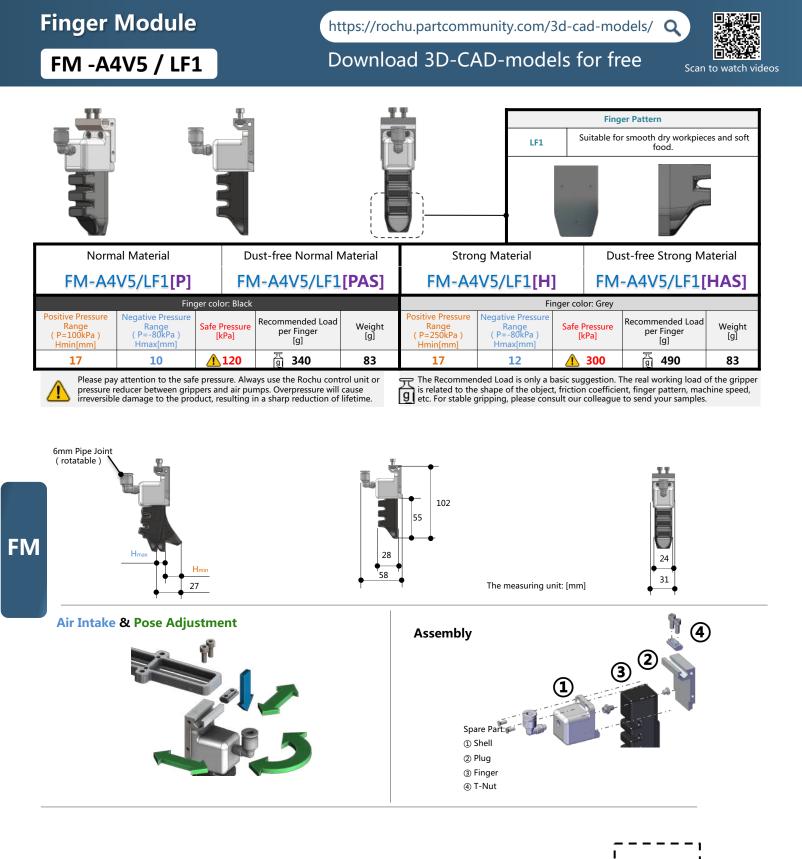


\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu







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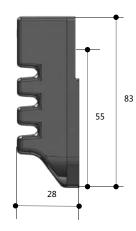
Filiger	Module	h	ttps://rocl	hu.partcomn	nunity.com/	3d-cad-mo	odels/ Q	
F -A4T	/ LF1	C	Downloa	ad 3D-CA	AD-mode	els for fr	ee <sub>so</sub>	an to watch video
						· · ·		
						-		
Finge	r Pattern	•		Fe	atures			
Finge	r Pattern Special Form		S		ratures Iry workpieces and s			
LF1		Dust-free Normal		uitable for smooth c		oft food.	st-free Strong M	aterial
LF1 Norma	Special Form	Dust-free Normal Dust-f	Material	uitable for smooth o	dry workpieces and s	oft food.	st-free Strong M	
LF1 Norma F-A41	Special Form al Material [/LF1[P] Finger c		Material	uitable for smooth o Stron F-A4	Iry workpieces and s ng Material <b>T/LF1[H]</b> Fi	oft food.		
LF1 Norma	Special Form al Material <b>[/LF1[P]</b> Finger c Negative Pressure	F-A4T/LF1[I	Material PAS]	uitable for smooth o	dry workpieces and s ng Material T/LF1[H]	oft food.		

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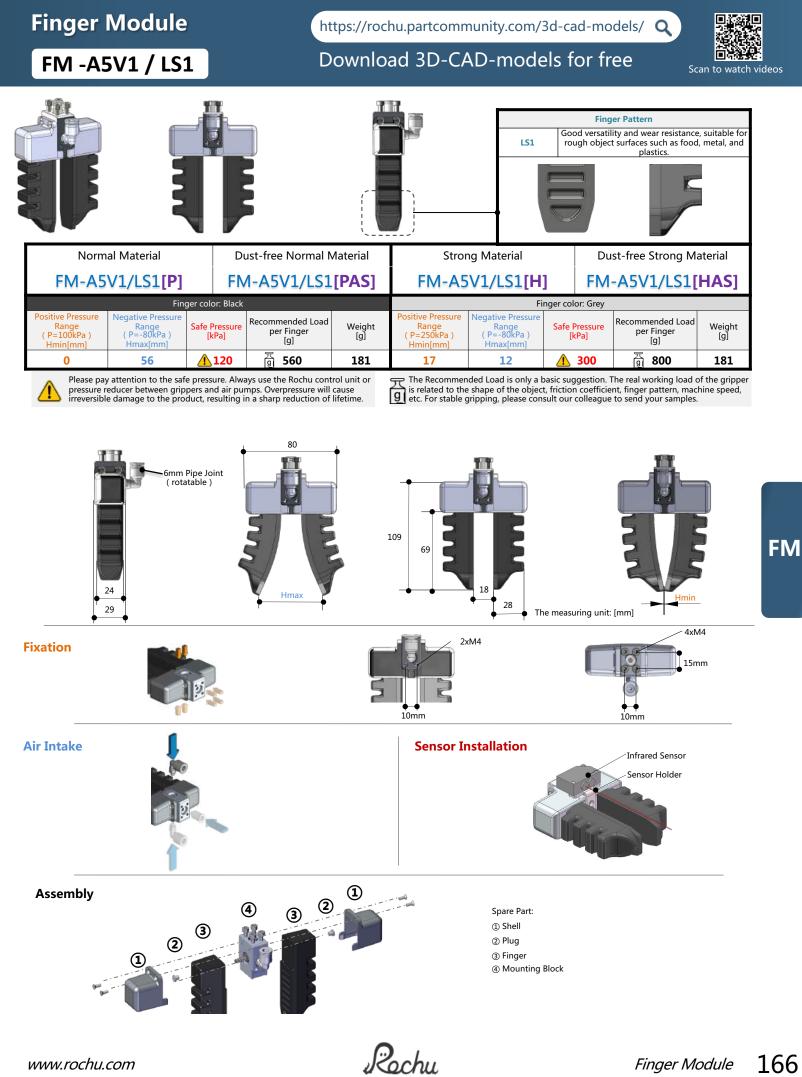
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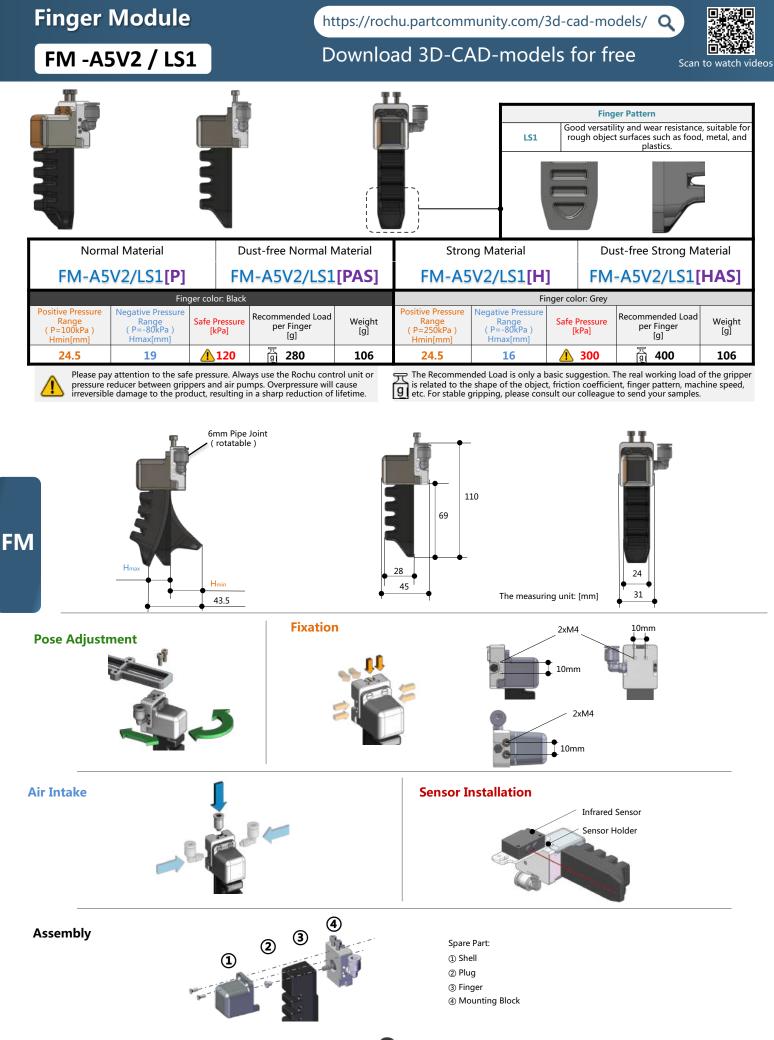
## **Dimension Parameters**



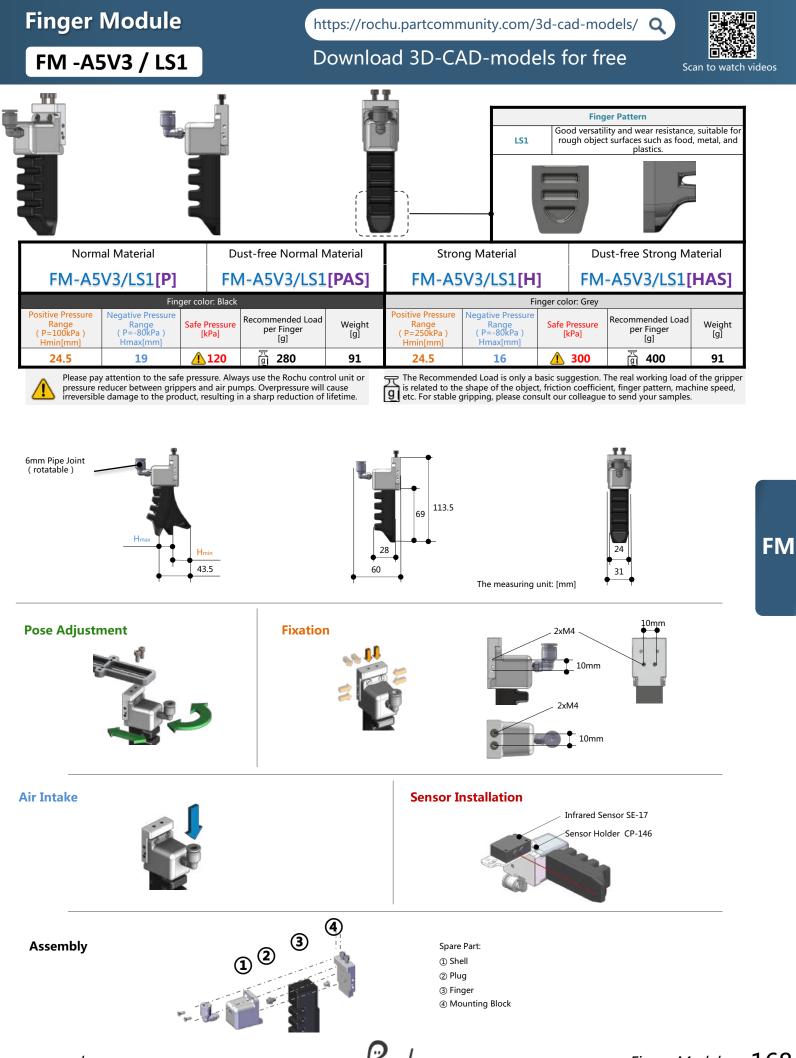




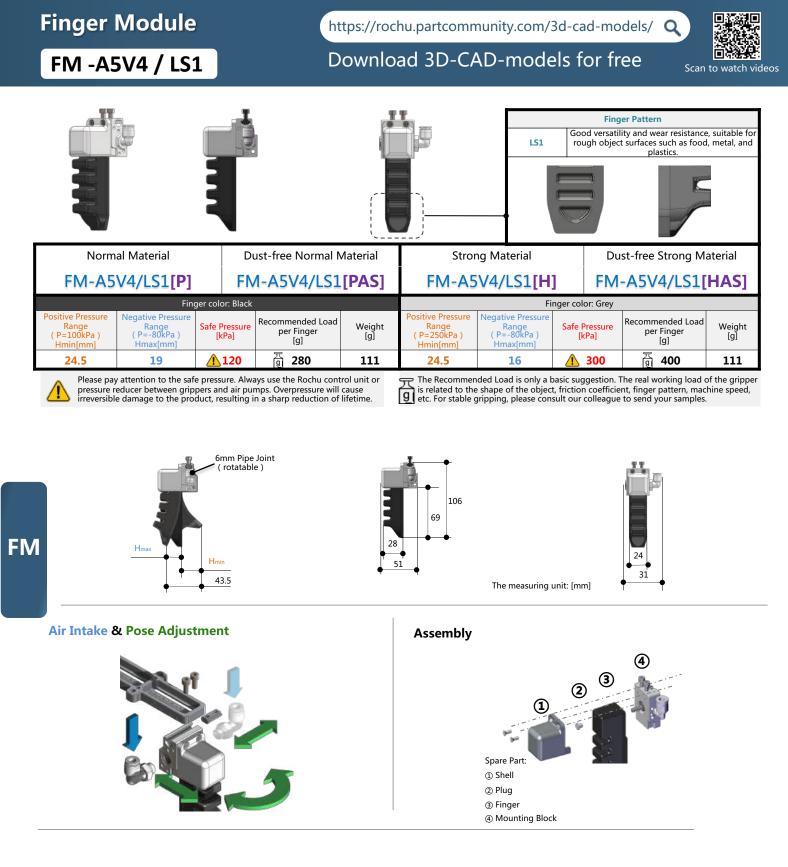




Rochu



Rochu

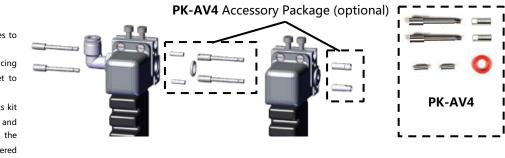


#### Series combination:

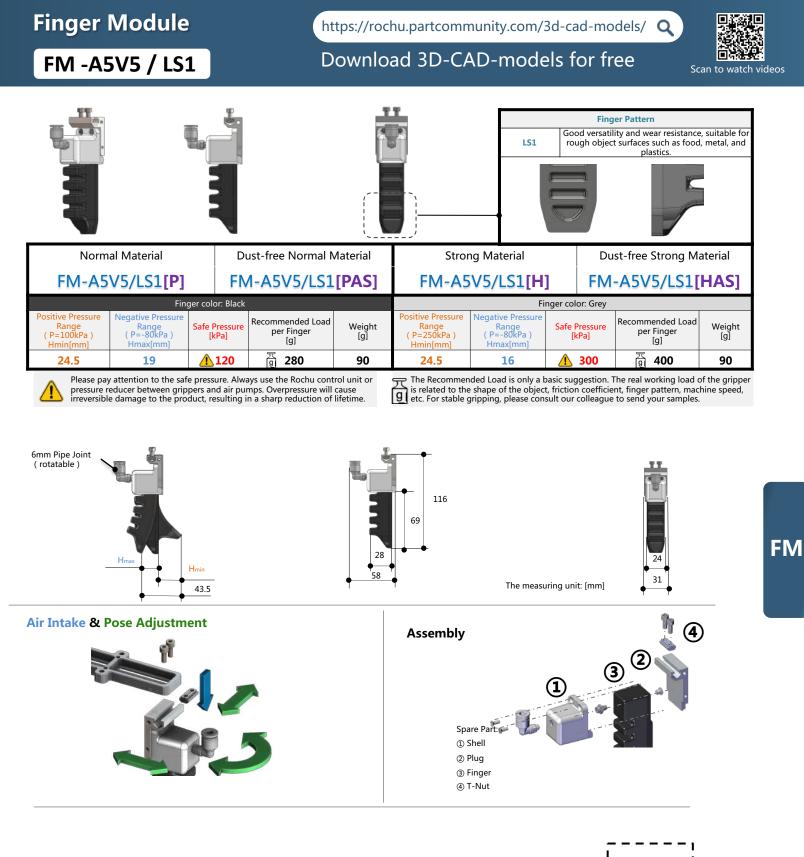
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2. It can realize the seamless splicing between fingers and share the air inlet to save space.

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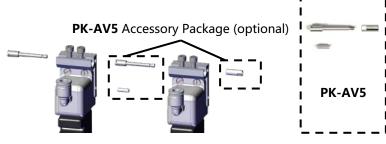




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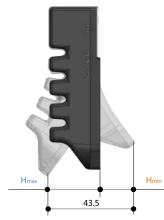


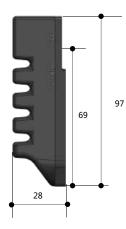
Finger Module       https://rochu.partcommunity.com/3d-cad-models/ Q       Image: Comparison of the second									日本部に
<b>F -A5T / LS1</b> Download 3D-CAD-models for free								ee so	can to watch v
Finger	Pattern			·	Fe	eatures			
Finger	Pattern Standard form		Good versatil	lity and wear res	Fe		tes such as food, r	netal, and plastics.	
LS1		Du	Good versatil ust-free Normal N		sistance, suitable for			netal, and plastics. Ist-free Strong M	aterial
LS1 Norma	Standard form			Material	sistance, suitable for Stroi	rough object surfac	Du		
LS1 Norma F-A5T	Standard form I Material /LS1[P] Finger		ust-free Normal N -A5T/LS1[F	Material	sistance, suitable for Stroi F-A5	rough object surfac ng Material <b>T/LS1[H]</b> Fi	Du	ist-free Strong M	
LS1 Norma F-A5T	Standard form I Material (/LS1[P] Finger Negative Pressure	F	ust-free Normal N -A5T/LS1[F	Material PAS]	sistance, suitable for Stroi	rough object surfac ng Material <b>T/LS1[H]</b>	Du F-	ist-free Strong M	

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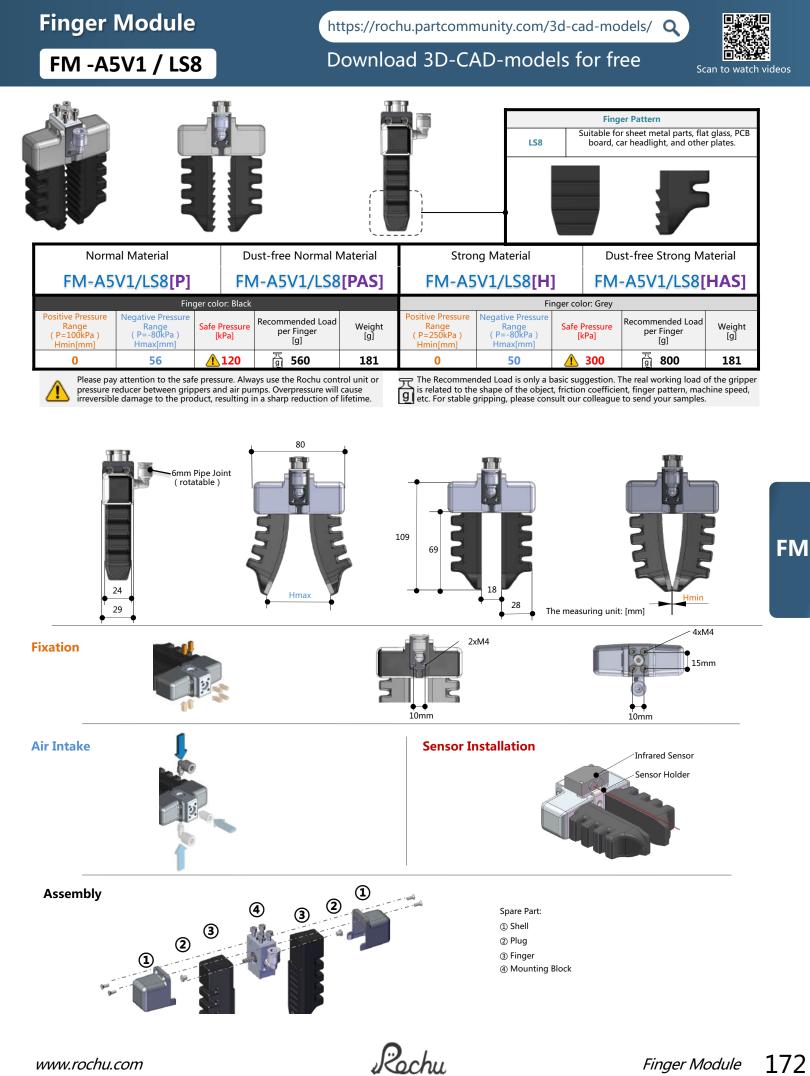
# **Dimension Parameters**

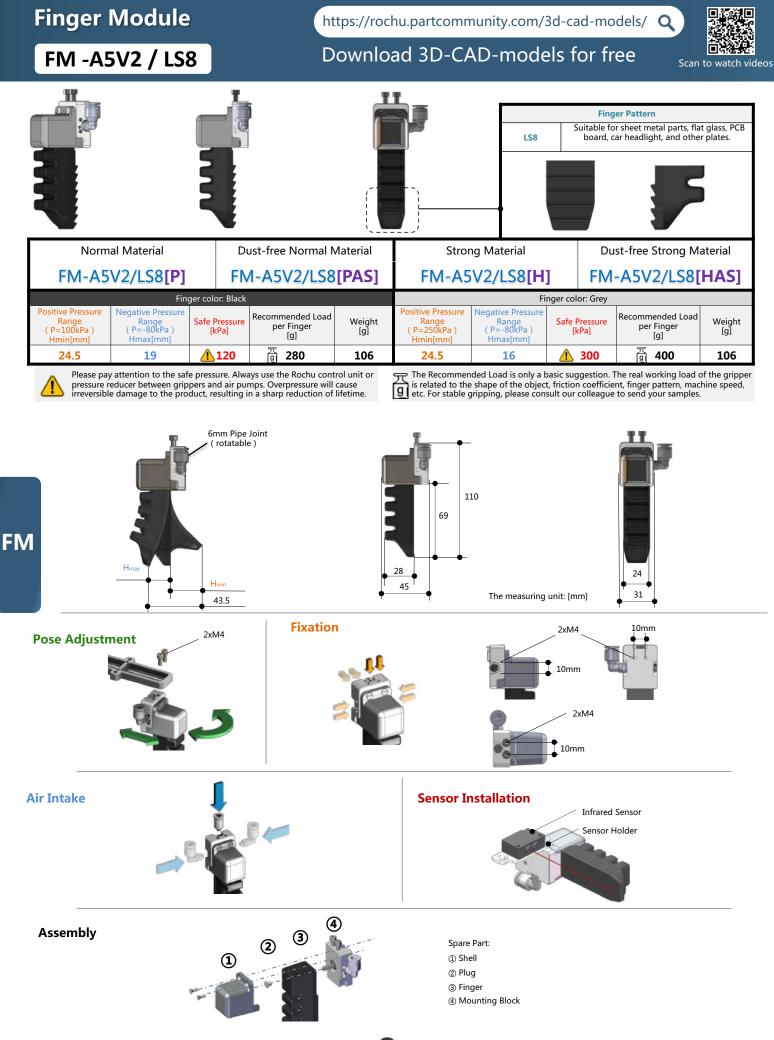




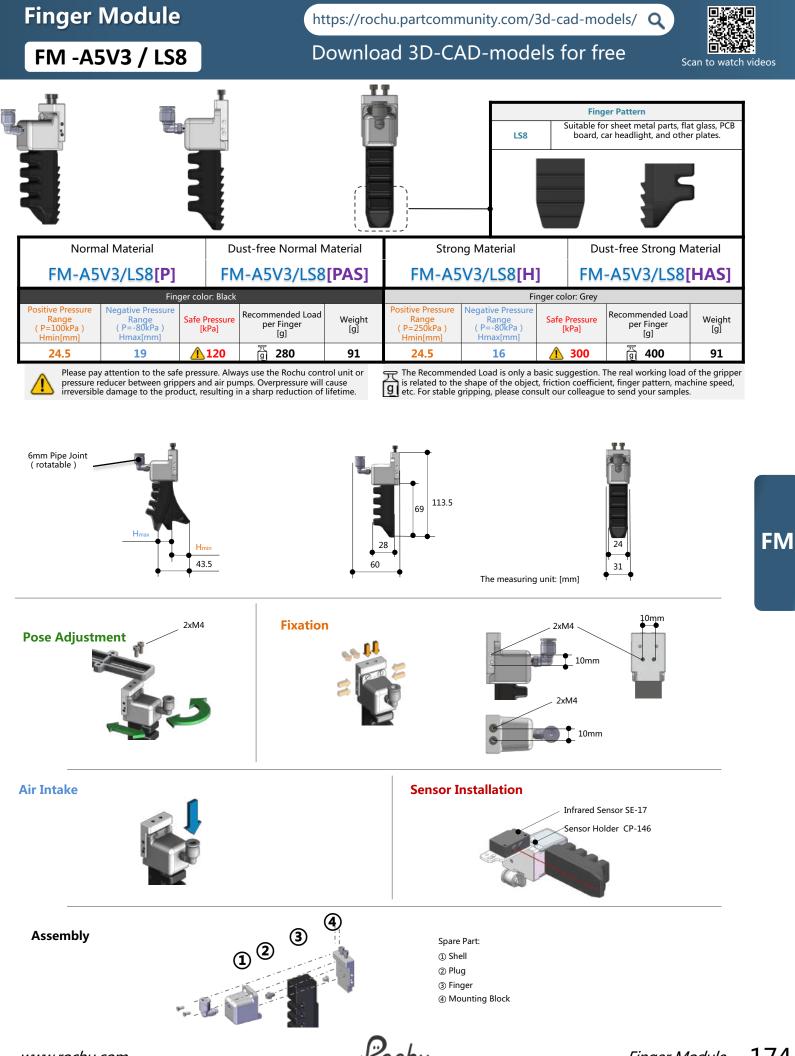


FM



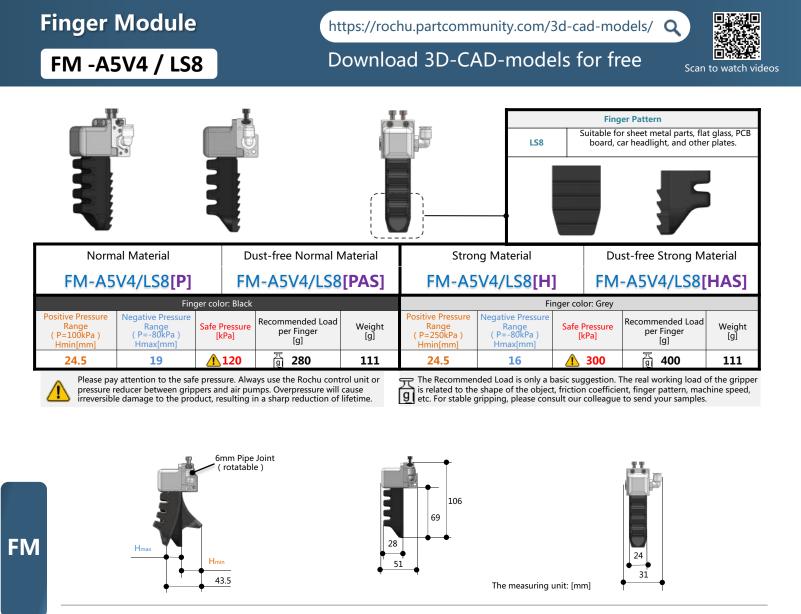


Pochu

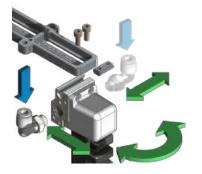


Rochu

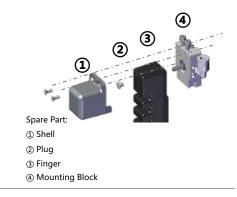
174 Finger Module



Air Intake & Pose Adjustment



Assembly

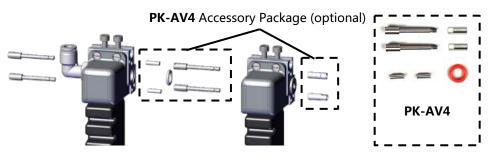


#### Series combination:

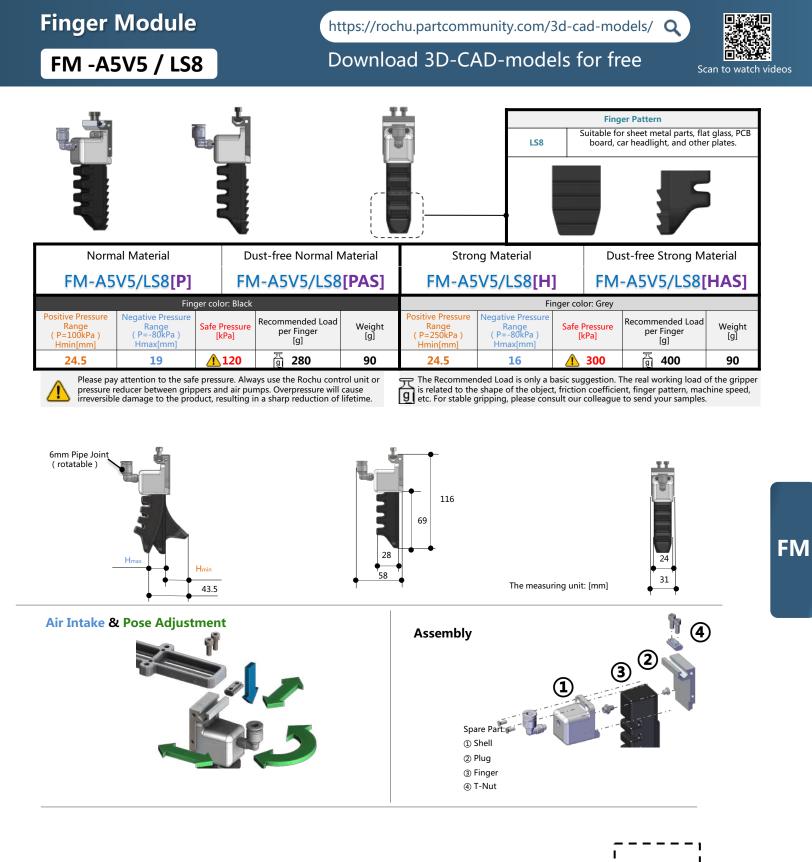
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.









1. Build multiple finger modules in series to increase the grip force.

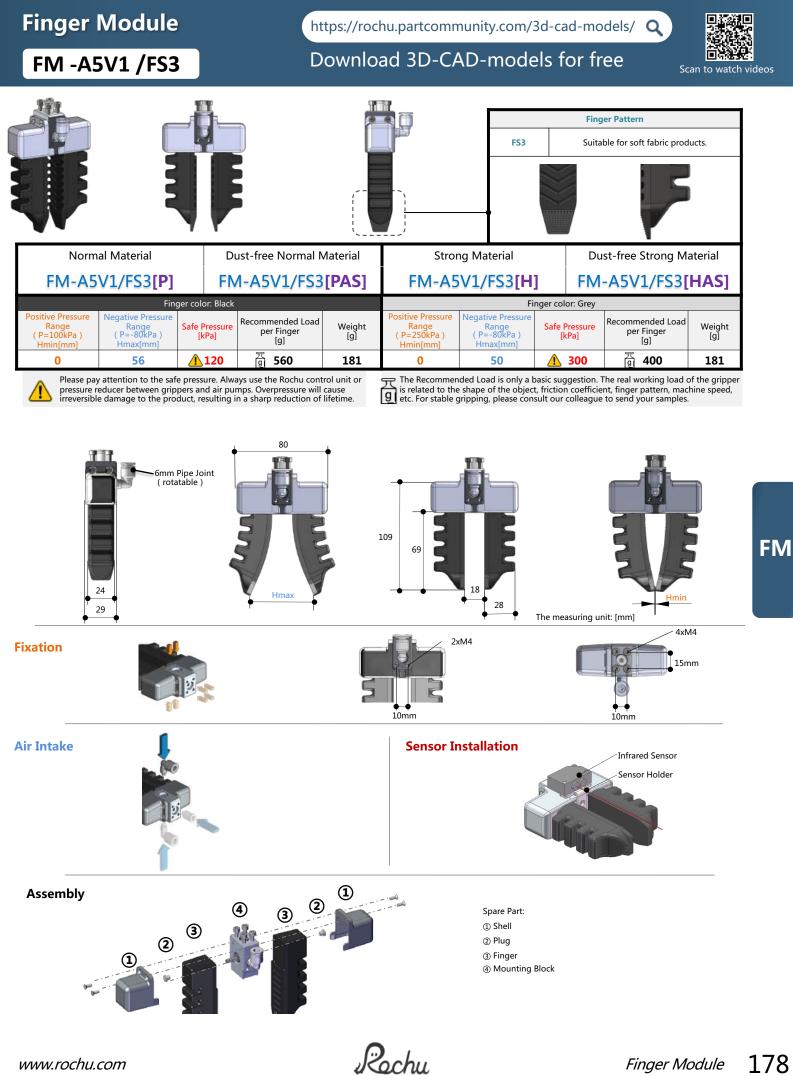
2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

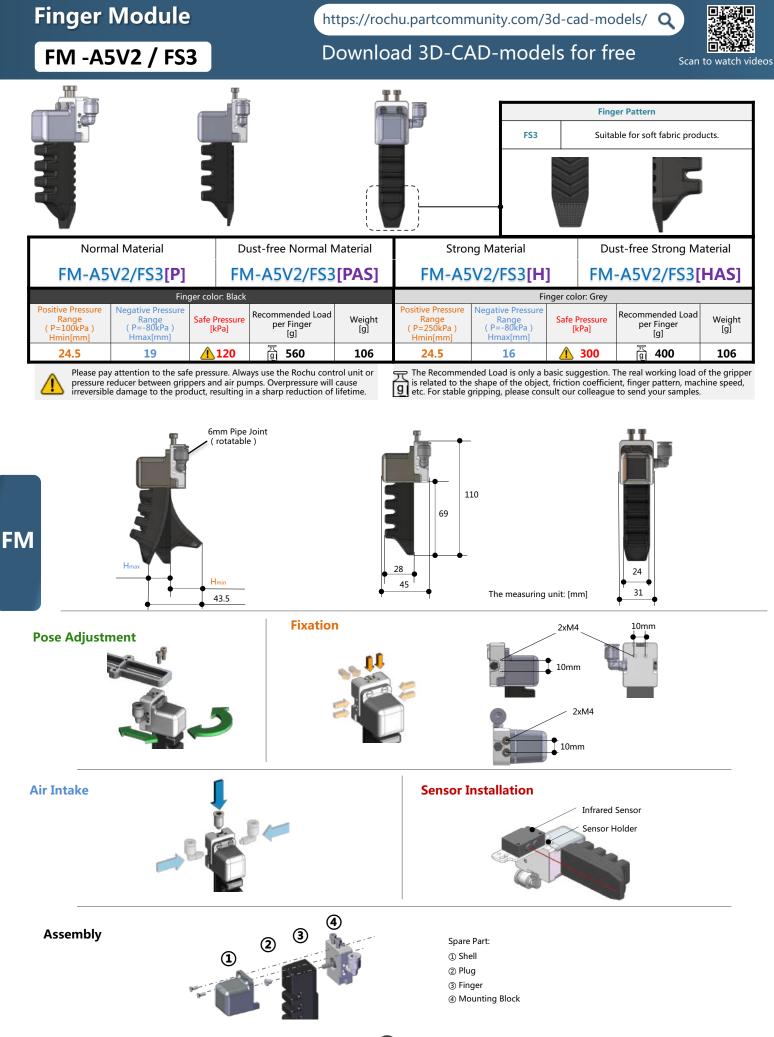
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-AV5 Accessory Package (optional)



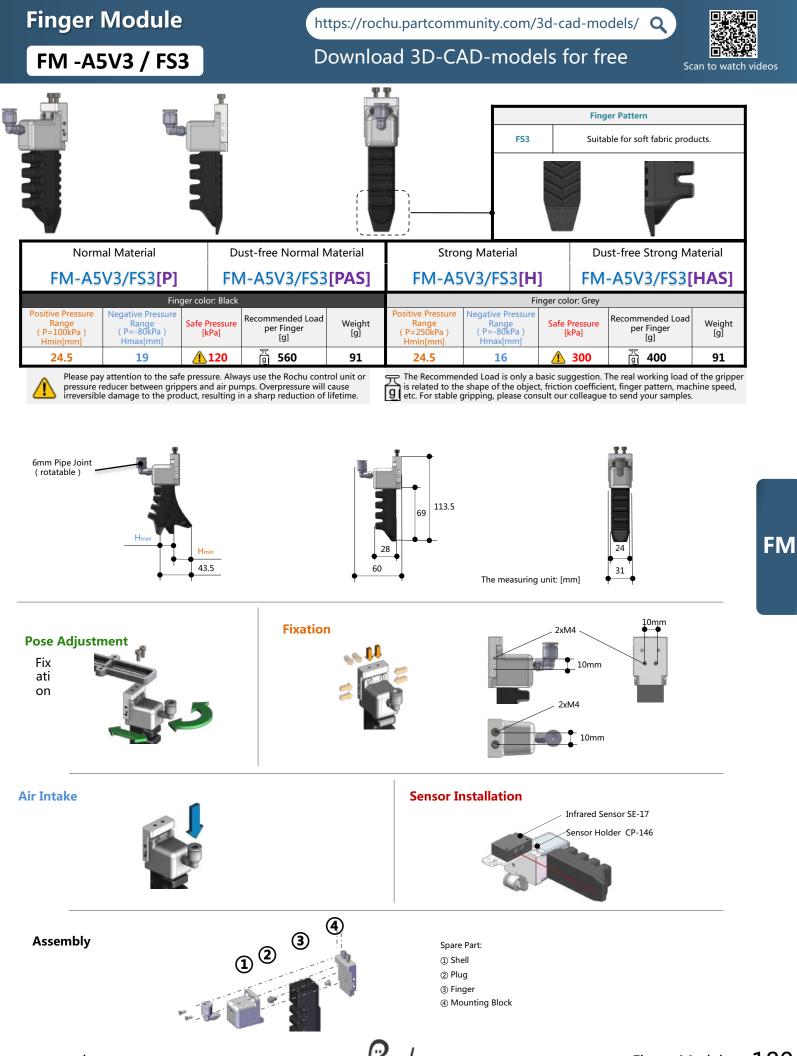
	nger Mo -A5T / I				-	oartcommun 3D-CAD	-			
			1					•	Scan to w	atch videos
	Finge	r Pattern				Fe	eatures			
	LS8	Special Form		Su	uitable for sheet	t metal parts, flat gla	ss, PCB board, car he	eadlight, and othe	er plates.	
	Norma	al Material	D	ust-free Normal I	Material	Stroi	ng Material	Du	ust-free Strong M	aterial
	F-A51	[/LS8[ <b>P</b> ]	I	-A5T/LS8[	PAS]	F-A5	T/LS8[H]	F	-A5T/LS8[H	AS]
	Positive Pressure	Fing Negative Pressure	ger color: Black	1		Positive Pressure	Fin Negative Pressure	nger color: Grey		
	Range (P=100kPa) Hmin[mm]	Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Range (P=250kPa) Hmin[mm]	Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]
	24.5	19	<u>^120</u>	ज ज़ 280	47	24.5	16	1 300	页 <b>400</b>	47
FM	Dimensio	educer between grip	ers and air pu duct, resulting	ays use the Rochu con mps. Overpressure wil in a sharp reduction of	l cause f lifetime.	etc. For stable of	ided Load is only a b e shape of the object gripping, please con: 	pasic suggestion. t, friction coefficie sult our colleague	The real working load ent, finger pattern, may e to send your samples	or the gripper chine speed,

Rochu



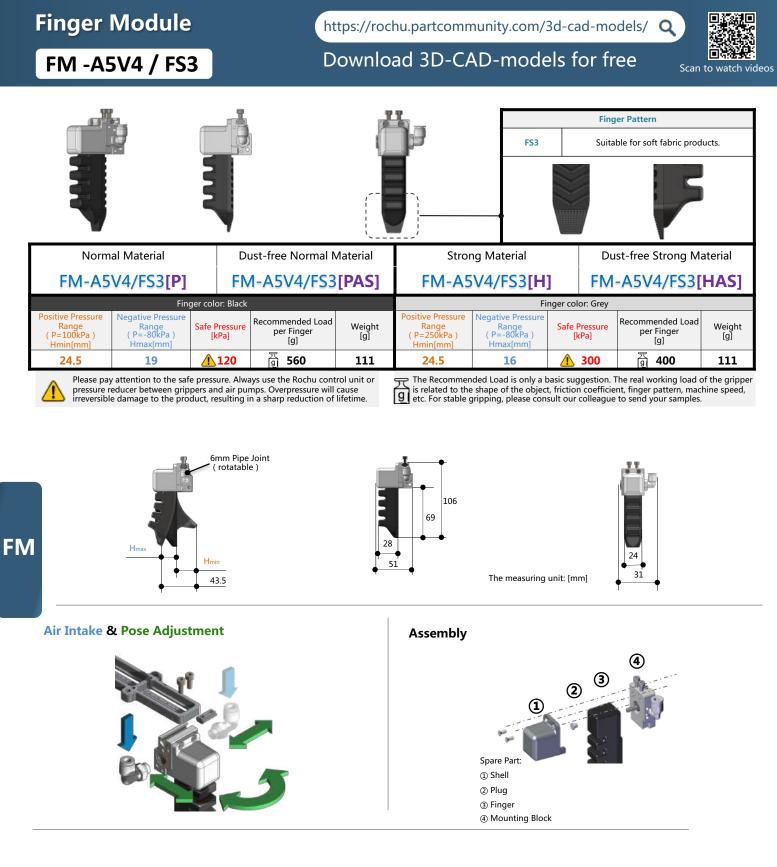


Rochu



Rochu

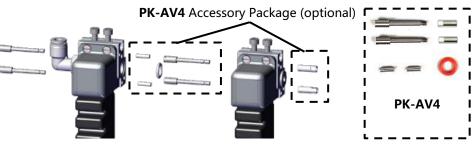
180 Finger Module



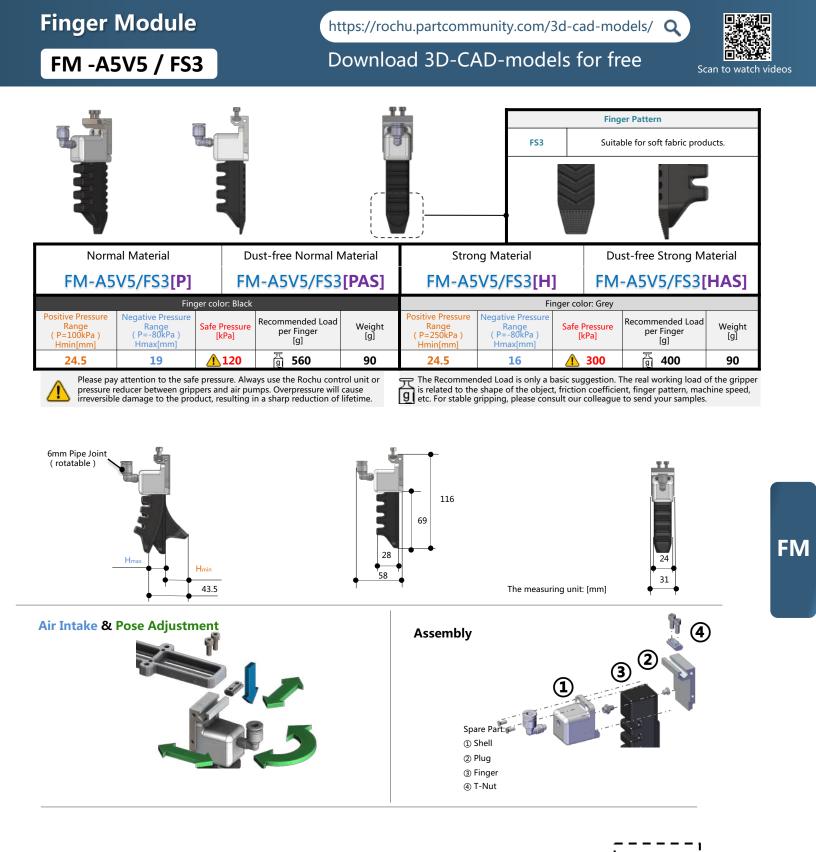
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.







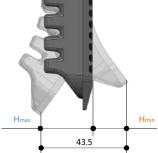
1. Build multiple finger modules in series to increase the grip force.

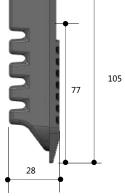
2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-AV5 Accessory Package (optional)

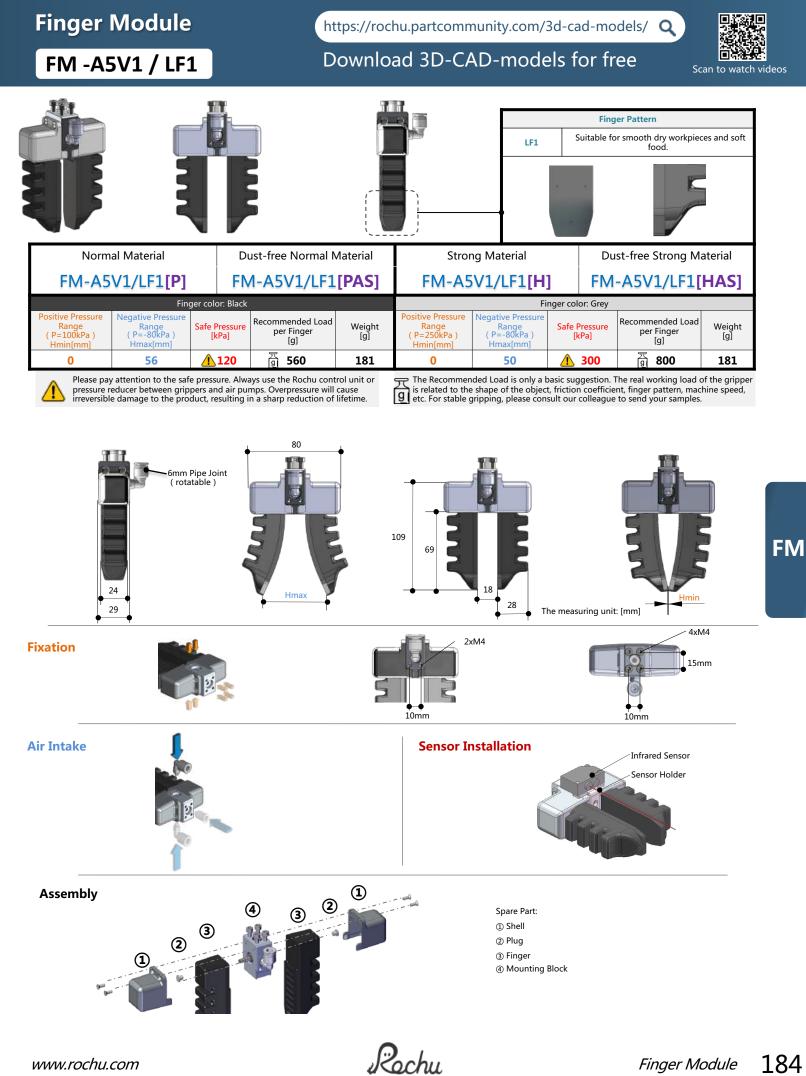


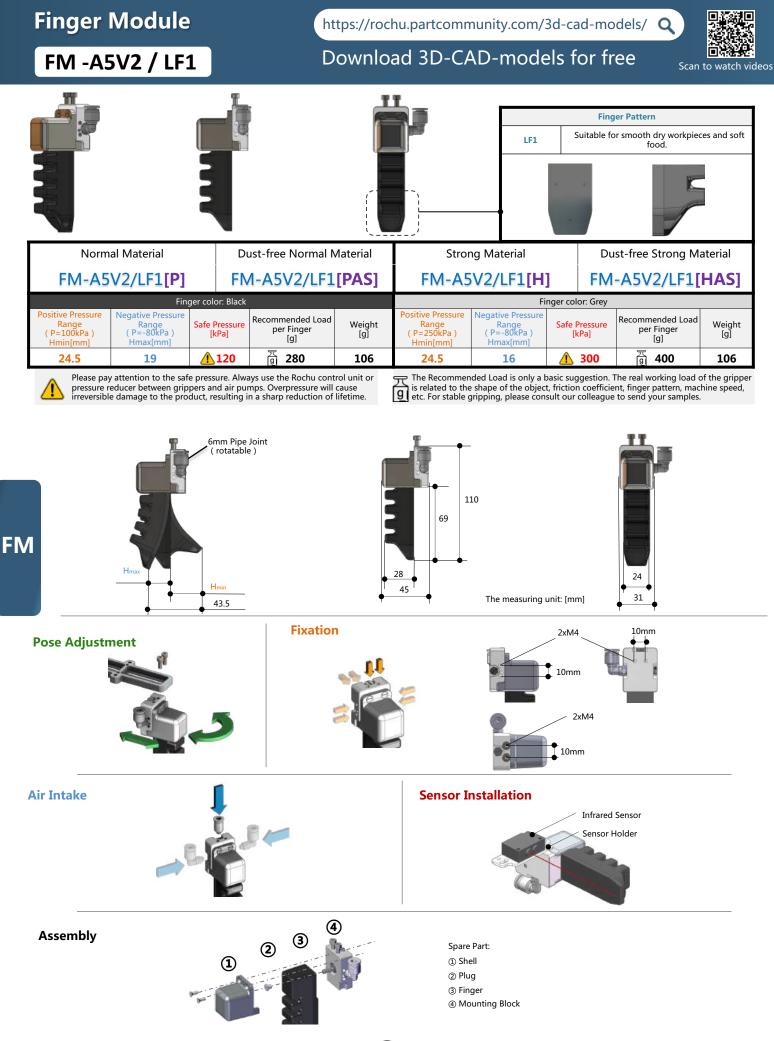
Fi	inger Mo	odule		https://rochu.partcommunity.com/3d-cad-models/ Q										
	F -A5T / I	FS3		Download 3D-CAD-models for free Scan to watch vio										
	Finge	r Pattern		Features										
	FS3	Special Form				Suitable for s	oft fabric products.							
	Norma	l Material	Du	ust-free Normal N	/laterial	Stror	ng Material		Du	st-free Strong	Material			
	F-A5T	/FS3[ <b>P</b> ]		-A5T/FS3[F	F-A5T/FS3[H]			F-A5T/FS3[HAS]						
	Positive Pressure Range	Negative Pressure	r color: Black Safe Pressure	Recommended Load	Weight	Positive Pressure Range	Negative Pressure	nger color Safe Pre		Recommended Lo	ad Weight			
	( P=100kPa ) Hmin[mm]	Range ( P=-80kPa ) Hmax[mm]	[kPa]	per Finger [g]	[g]	( P=250kPa ) Hmin[mm]	Range (P=-80kPa) Hmax[mm]	[kP		per Finger [g]	[g]			
	24.5 Please pay	19	120	g <b>280</b> ays use the Rochu cont	47	24.5	<b>16</b> ded Load is only a b		300 Jestion. T	be real working lo	47			
	// pressure re	educer between grippe	ers and air pu	mps. Overpressure will in a sharp reduction of	cause lifetime.	is related to the etc. For stable g	shape of the object pripping, please con	t, friction of sult our co	coefficier olleague	nt, finger pattern, r to send your samp	nachine speed, lles.			
FM	Dimensio	n Paramete	ers			+	_		J.L.	0				



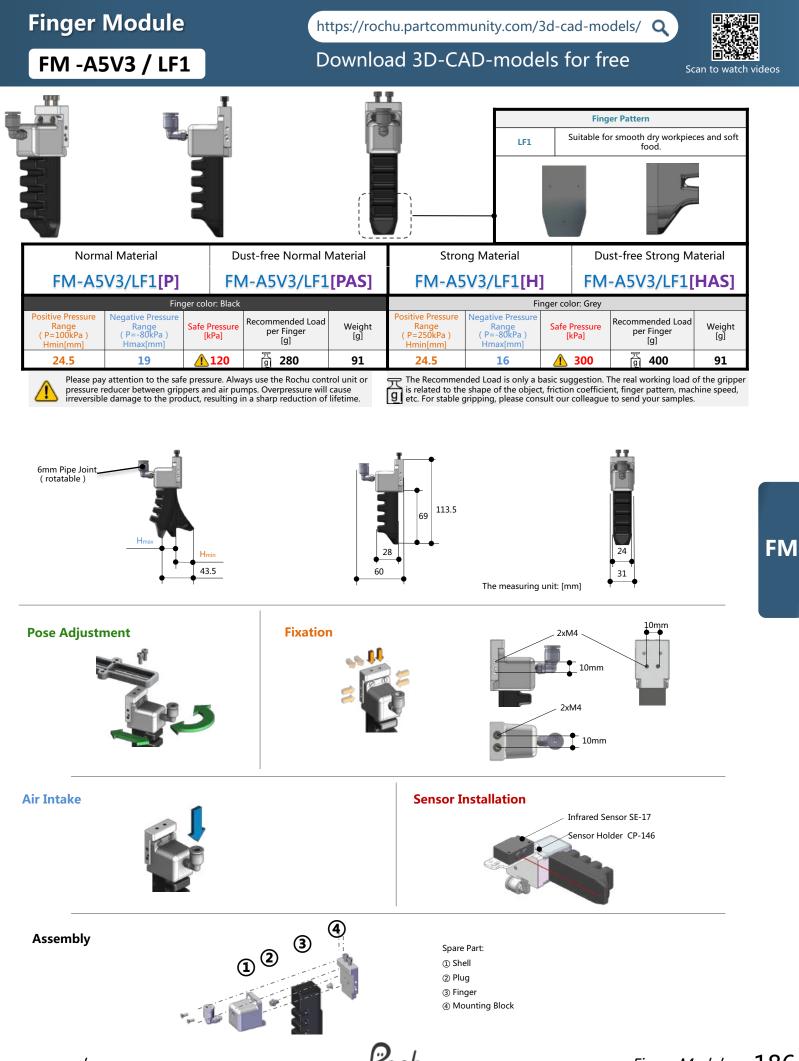






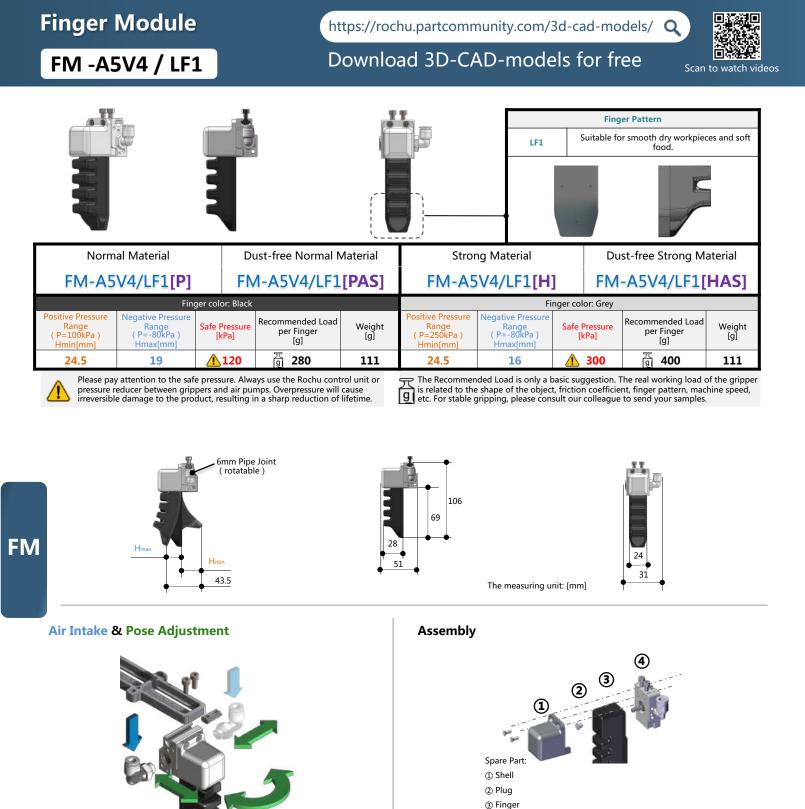






Rochu

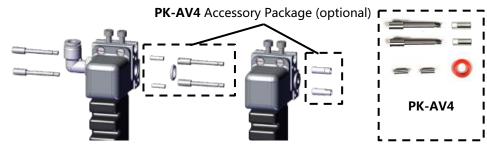
186 Finger Module



1. Build multiple finger modules in series to increase the grip force.

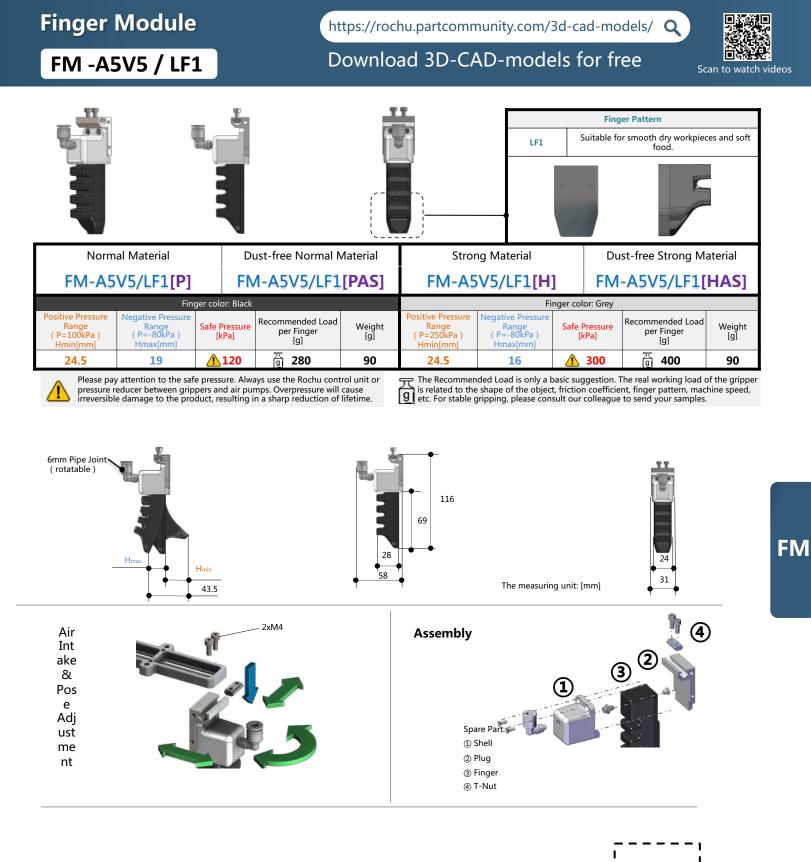
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



④ Mounting Block

Rochu





**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.

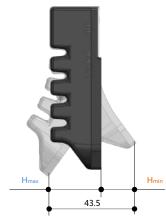


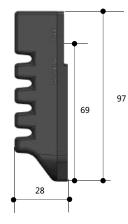
Finger Module 188

Rochu

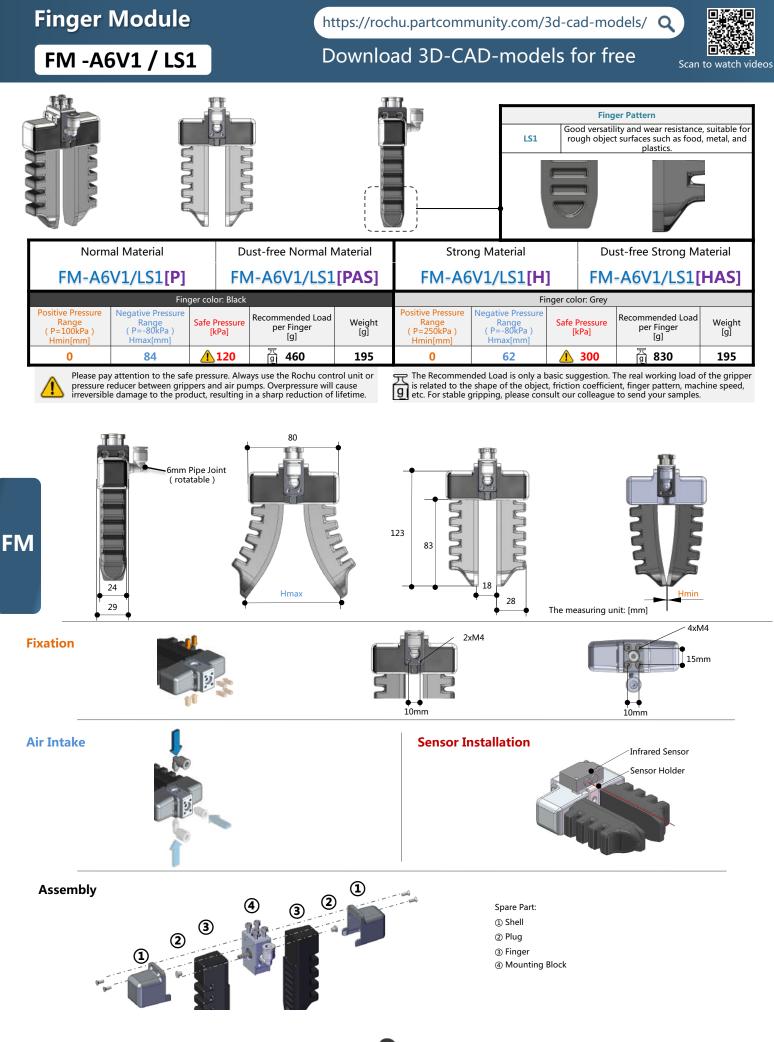
inger m	odule	https://rochu.partcommunity.com/3d-cad-models/ Q									
F -A5T /	LF1	Download 3D-CAD-models for free Scan to watch vide									
Finge	er Pattern		Fea	atures							
LF1	Special Form		Suitable for smooth d	Iry workpieces and soft for	od.						
						Dust-free Strong Material					
Norm	al Material	Dust-free Normal Materia	al Stron	ng Material	Dus	st-free Strong Ma	terial				
	al Material T/LF1[P]	Dust-free Normal Materia F-A5T/LF1[PAS]		ng Material T/LF1[H]		st-free Strong Ma					
F-A5	T/LF1[P] Finger c	F-A5T/LF1[PAS]	F-A5	T/LF1[H]	F-	A5T/LS1[H/					
F-A5 Positive Pressure Range (P=100kPa)	T/LF1[P] Finger c Negative Pressure Range (P=-80KPa)	F-A5T/LF1[PAS]	Positive Pressure Range (P=250kPa)	T/LF1[H] Finger of Negative Pressure Range (P=-80kPa)	F-						
F-A5 Positive Pressure Range	T/LF1[P] Finger c Negative Pressure Range (P=-80kPa) Hmax[mm]	F-A5T/LF1[PAS] olor: Black e Pressure (kbal Per Finger Wei	ght ] Positive Pressure Range ( P=250kPa ) Hmin[mm]	T/LF1[H] Finger co Negative Pressure Range	F- color: Grey e Pressure [kPa]	A5T/LS1[H/ Recommended Load per Finger	<b>AS]</b> Weight				
F-A5 Positive Pressure Range (P=100kPa) Hmin[mm] 24.5 Please pa pressure	T/LF1[P] Finger c Regative Pressure (P=-80KPa) Hmax[mm] 19 y attention to the safe pre- reducer between grippers	e Pressure [kPa] Recommended Load per Finger [g] Wei	ght Positive Pressure Range (P=250kPa) Hmin[mm] 7 24.5	T/LF1[H] Finger of Negative Pressure Range (P=-80kPa) Hmax[mm]	F- olor: Grey e Pressure [kPa] 300	AST/LS1[HA Recommended Load per Finger [g] J 400 he real working load of	AS] Weight [g] 47				



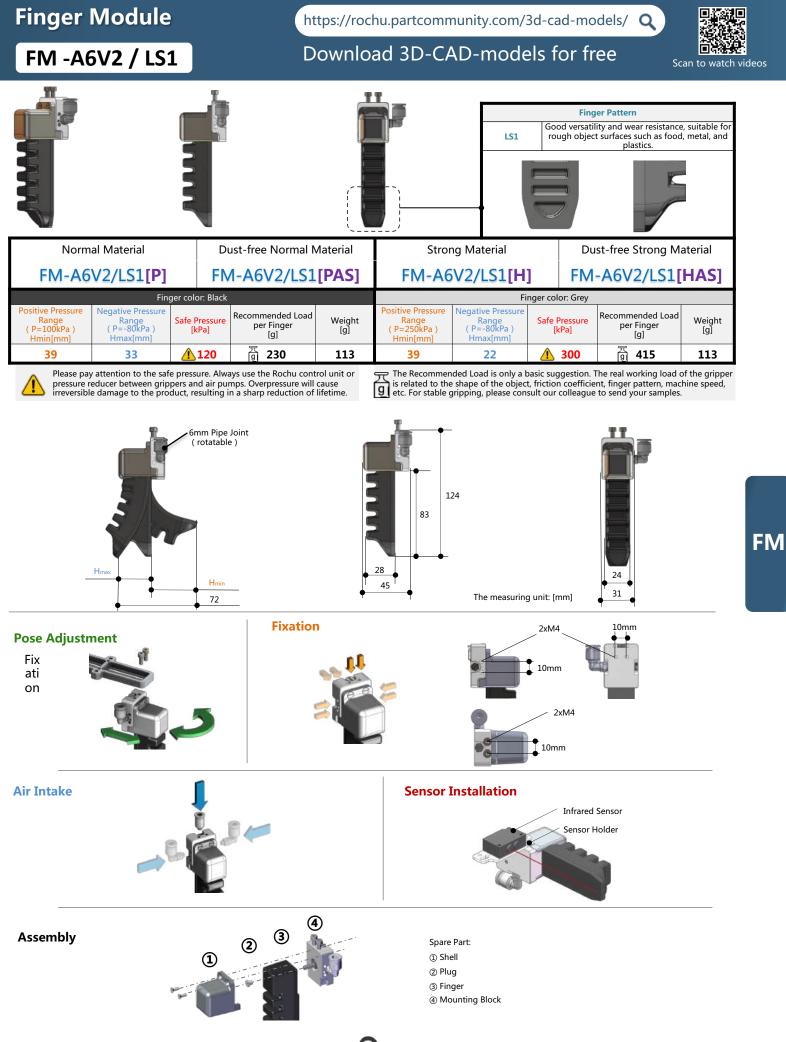




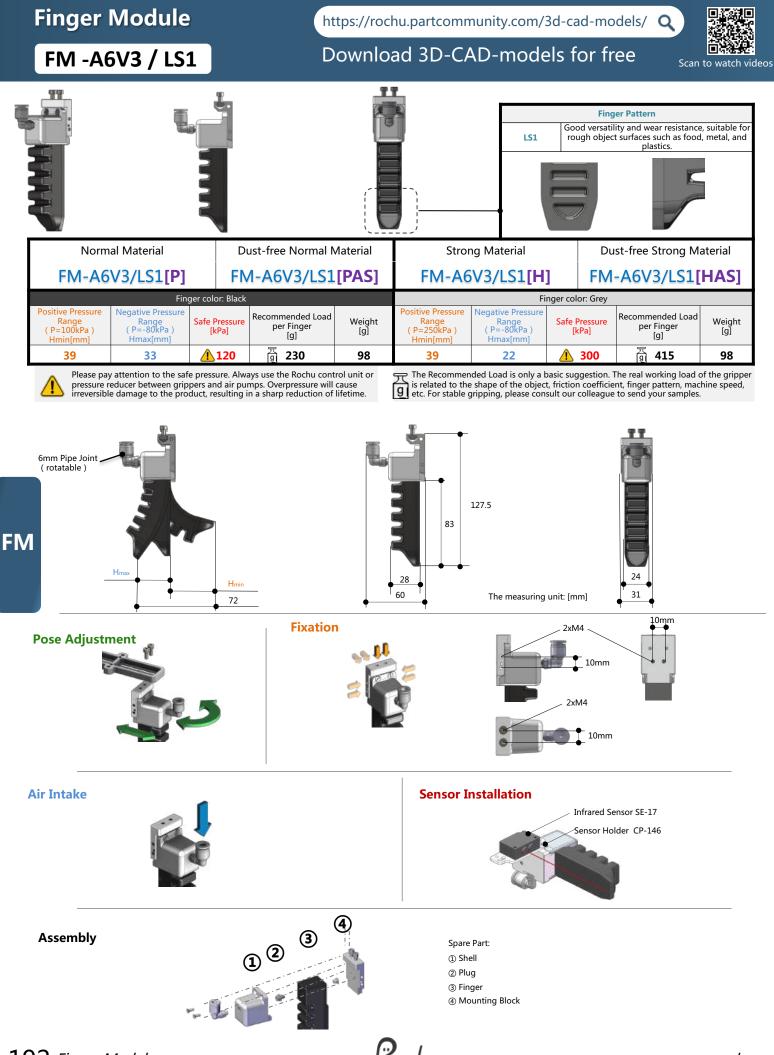




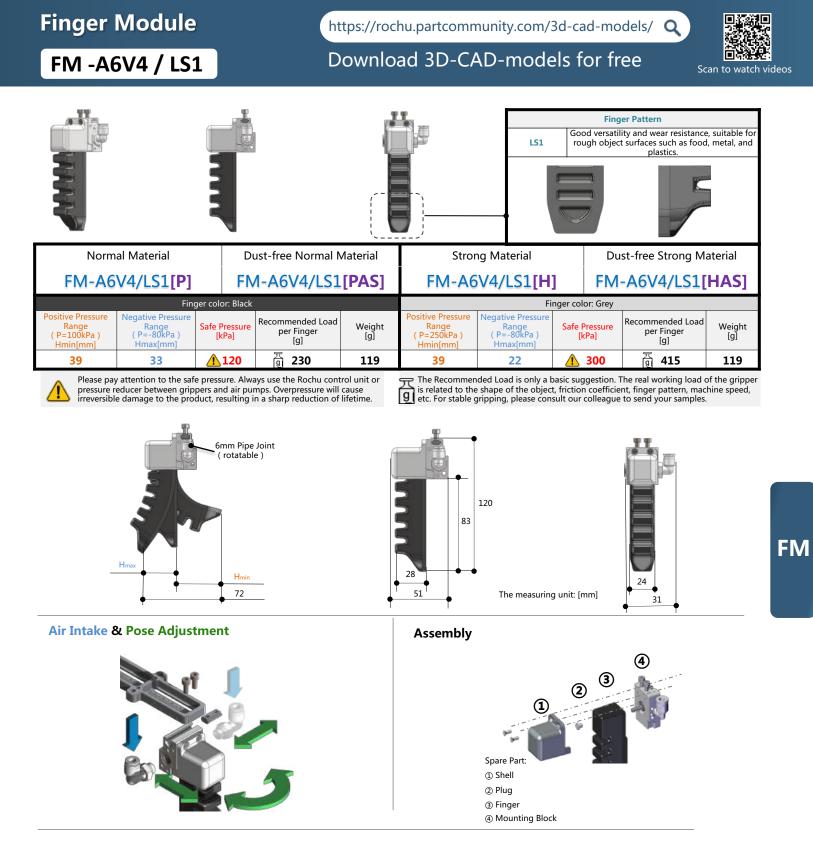
Rochu



Pochu



Rochu



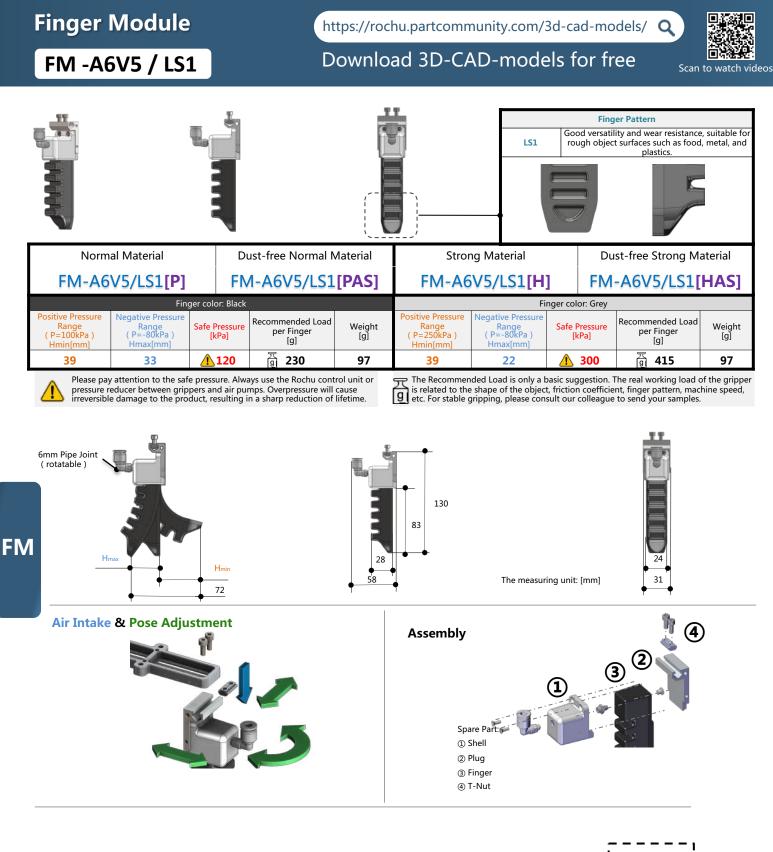
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu



194 Finger Module

1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.

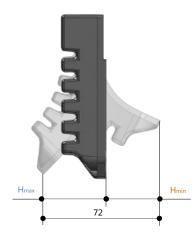


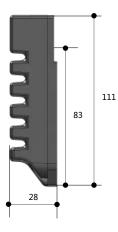
Finger <b>N</b>	Module		https://rochu.partcommunity.com/3d-cad-models/ Q								
F -A6T	/ LS1		Download 3D-CAD-models for free								
				,							
Finger	Pattern		Features								
LS1	LS1 Standard form			ity and wear res	sistance, suitable for rough object surfaces such as			as food, metal, and plastics.			
Norma	Dı	ust-free Normal N	Aaterial	Strong Material D			oust-free Strong Material				
F-A6T	F	-A6T/LS1[F	PAS]	F-A6	-A6T/LS1[H	IAS]					
Positive Pressure	Negative Pressure	olor: Black	Recommended Load		Finger colo Positive Pressure Negative Pressure			Recommended Load			
Range ( P=100kPa ) Hmin[mm]		e Pressure [kPa]	per Finger [g]	Weight [g]	Range ( P=250kPa ) Hmin[mm]	Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	per Finger [g]	d Weight [g]		
39	33 🧹	120	<u> ፴</u> 230	55	39	22	<u> 1</u> 300	<u>ଲ</u> 415	55		

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

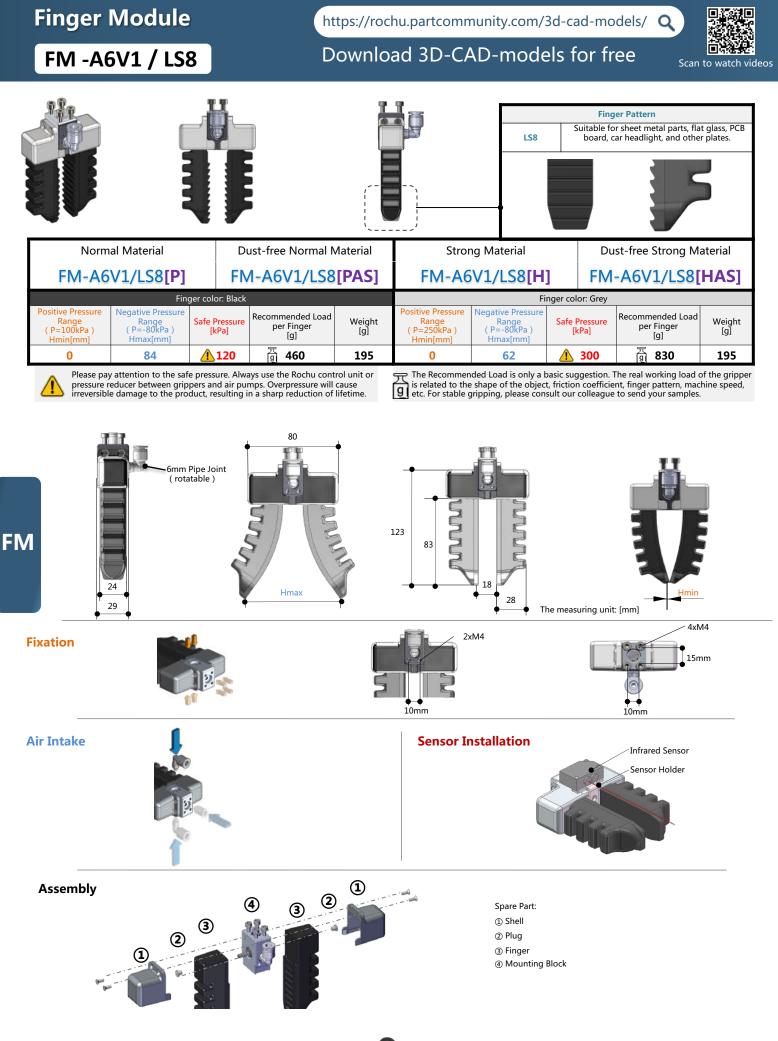
## **Dimension Parameters**



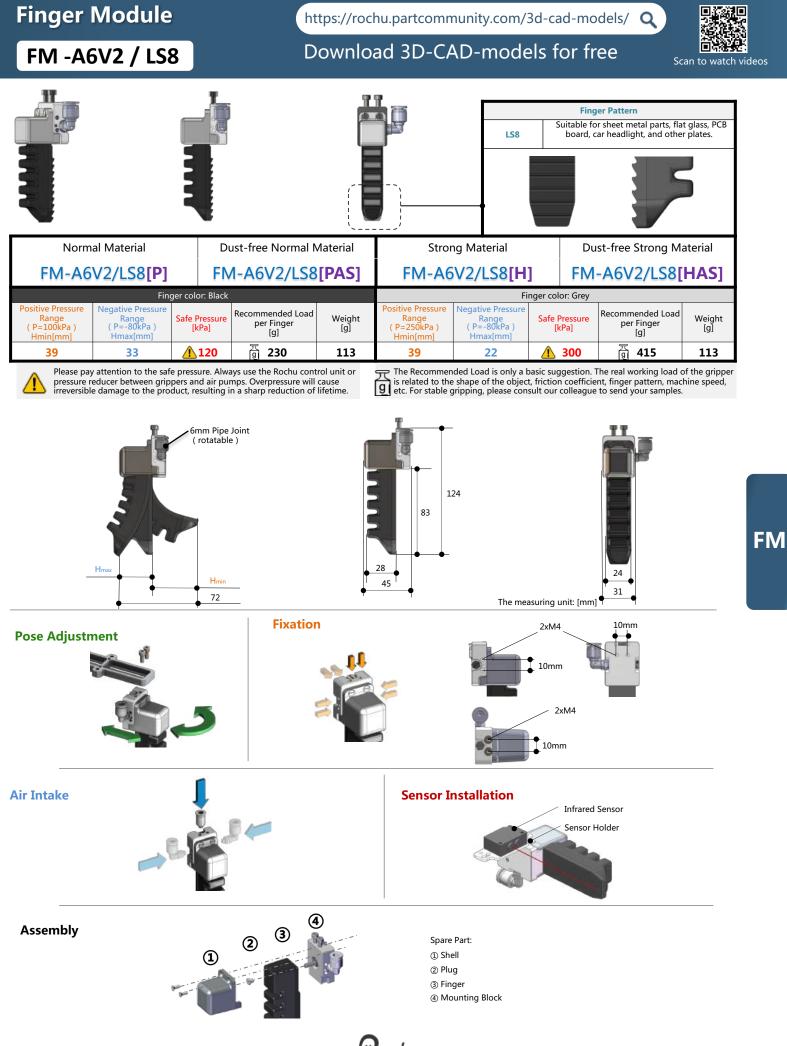




FM

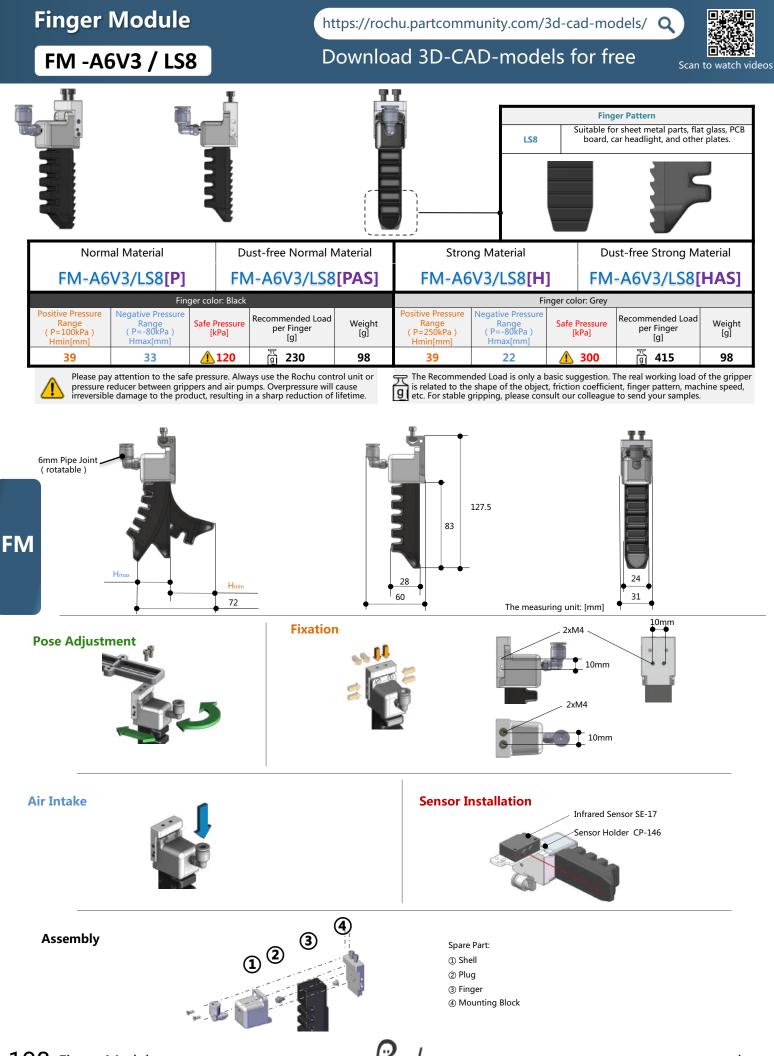


Rochu

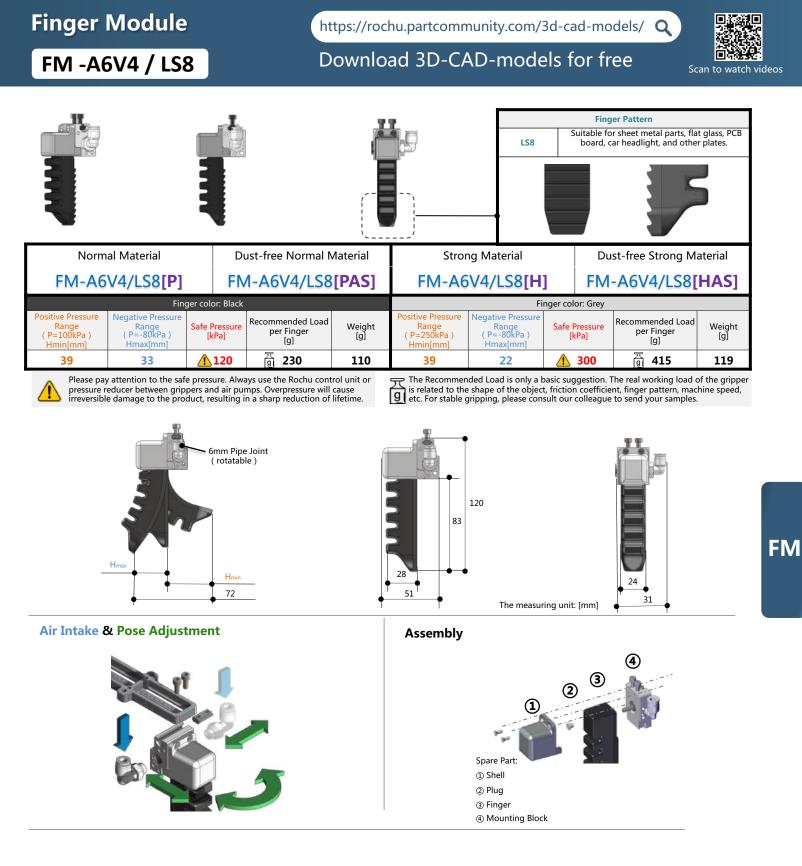


Pochu

Finger Module 197



Rochu



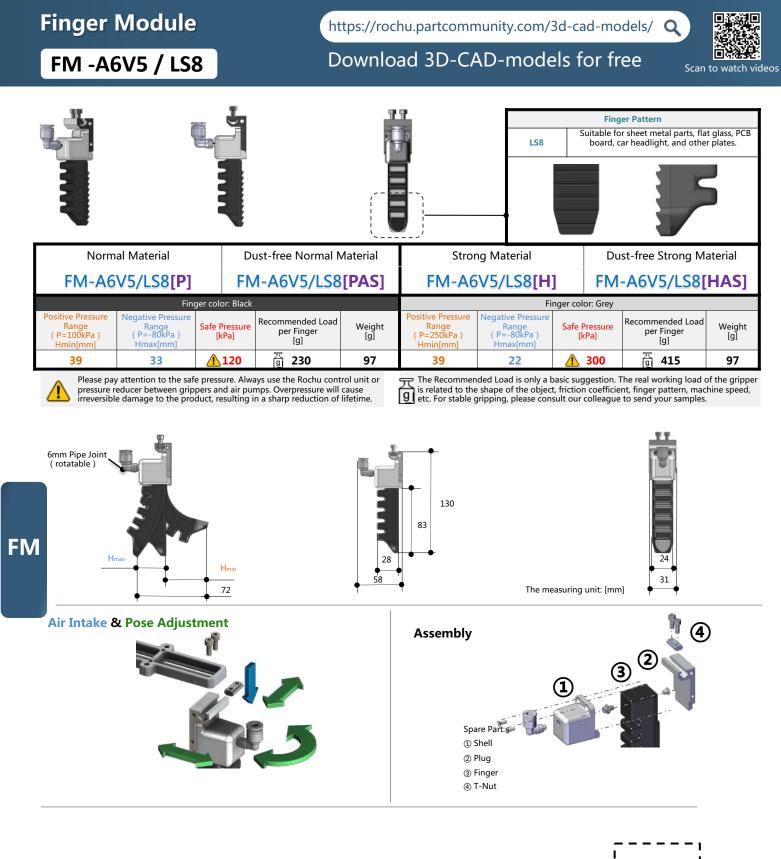
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu





**1**. Build multiple finger modules in series to increase the grip force.

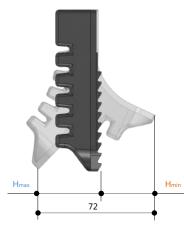
2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

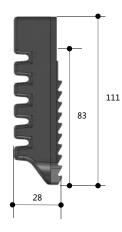
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



inger I	vlodule		https://rochu.partcommunity.com/3d-cad-models/ Q									
F -A6T	/ LS8		Download 3D-CAD-models for free Scan to wa									Can to wate
	in the second se								•			
Finger	Pattern					Fe	eatures					
Finger	Pattern Special Form			Su	uitable for shee	<b>Γε</b> t metal parts, flat gla		eadlight	, and other	r plates.		
LS8		Dust	t-free N	Su Normal N		t metal parts, flat gla		eadlight	- 	•	Strong M	faterial
LS8 Normal	Special Form				Vaterial	t metal parts, flat gla	ss, PCB board, car he	eadlight	Du	st-free	Strong M	
LS8 Normal	Special Form I Material /LS8[P] Finger co			Normal N	Vaterial	t metal parts, flat gla Stro F-A6	ss, PCB board, car he ng Material T/LS8[H] Fi	inger co	Du	st-free	, in the second s	
LS8 Normal	Special Form I Material /LS8[P] Finger cc Negative Pressure Range Safe	F=	-A6T/ Recommer per Fi	Normal N	Material PAS]	t metal parts, flat gla	ss, PCB board, car he ng Material	inger co	Du F-	st-free -A6T, Recomm	, in the second s	IAS]

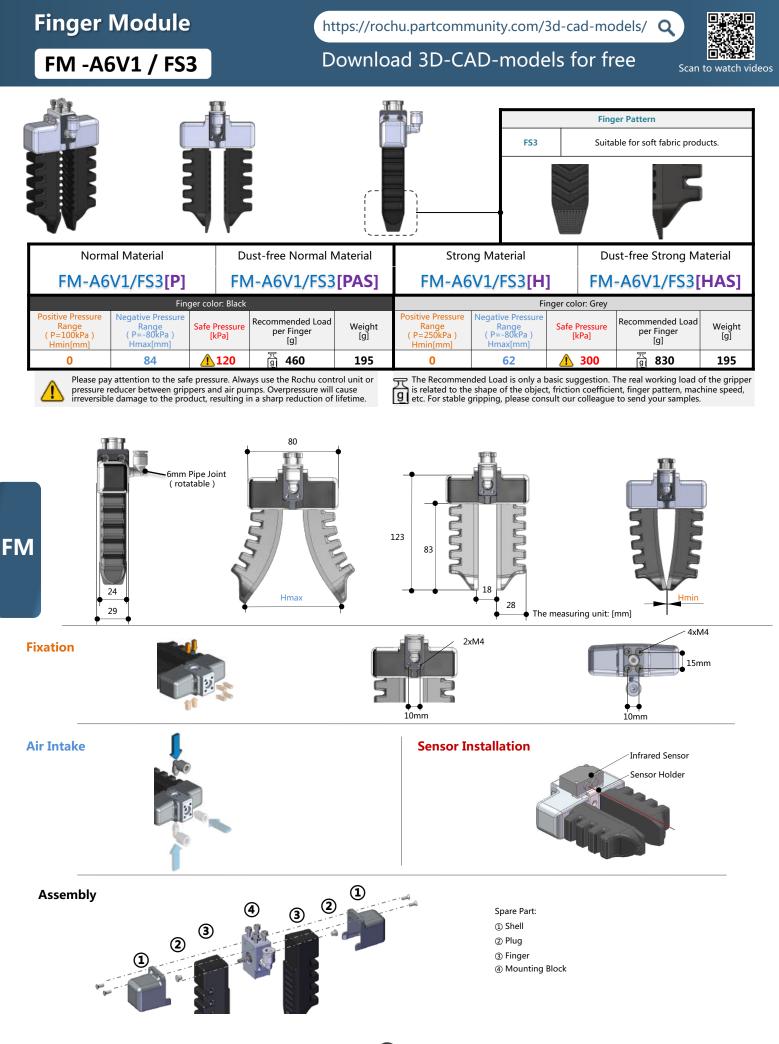
**Dimension Parameters** 

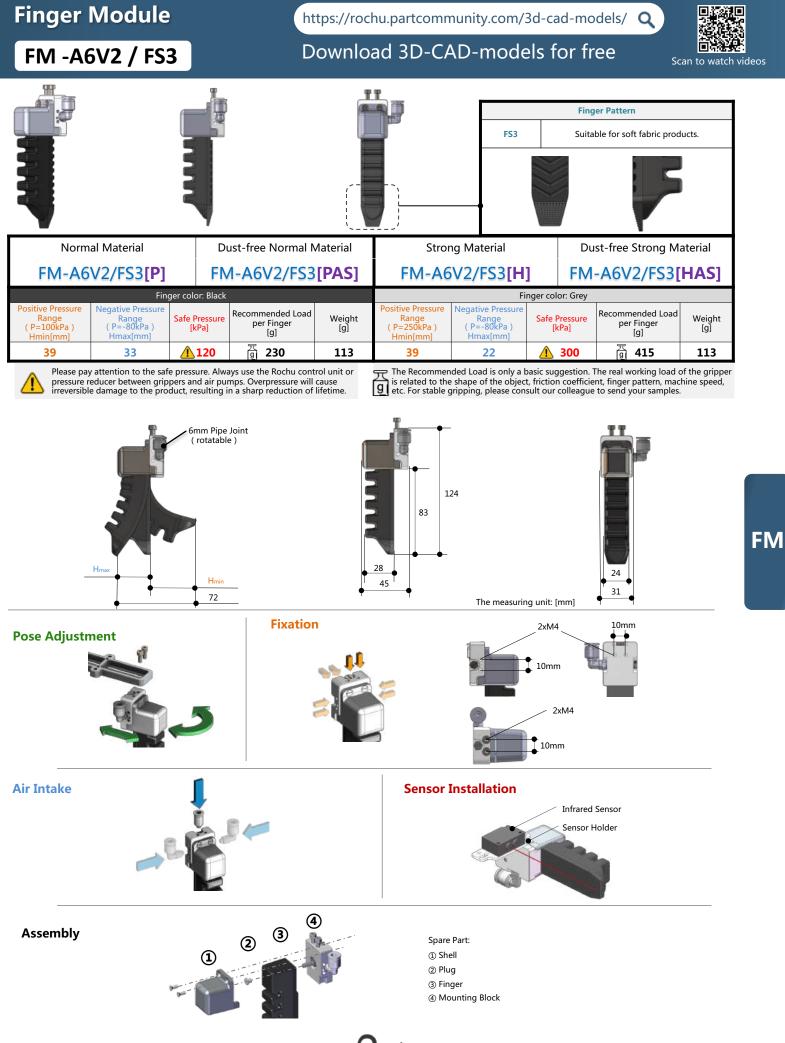




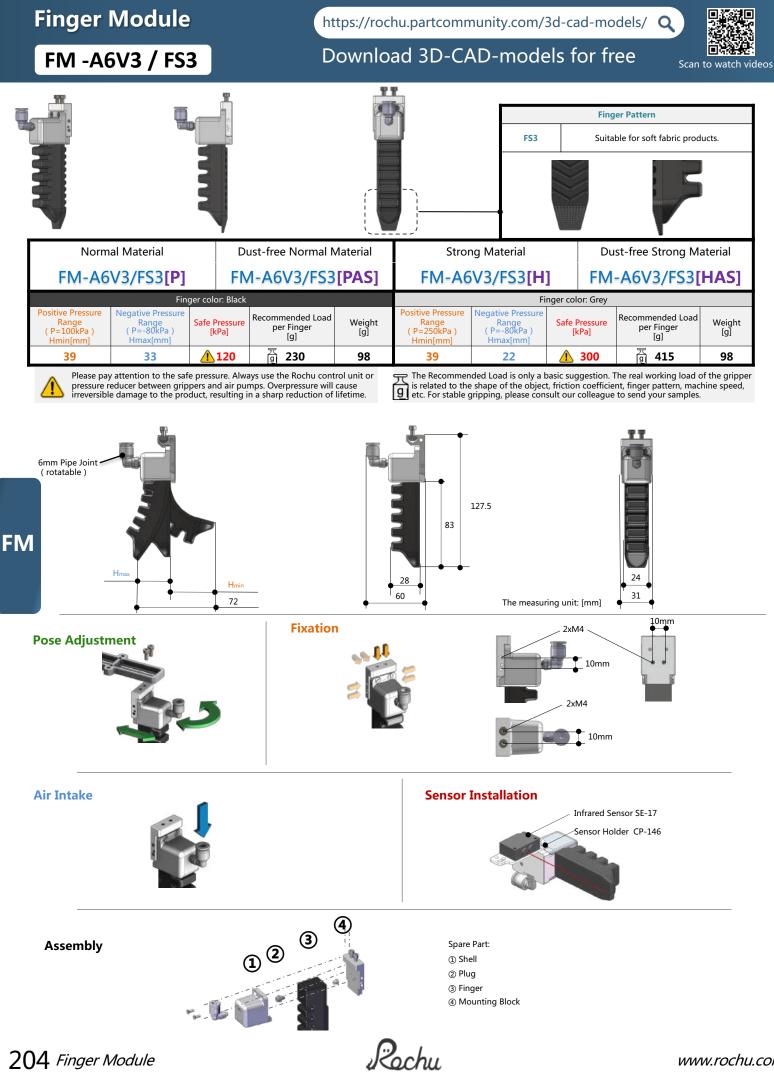


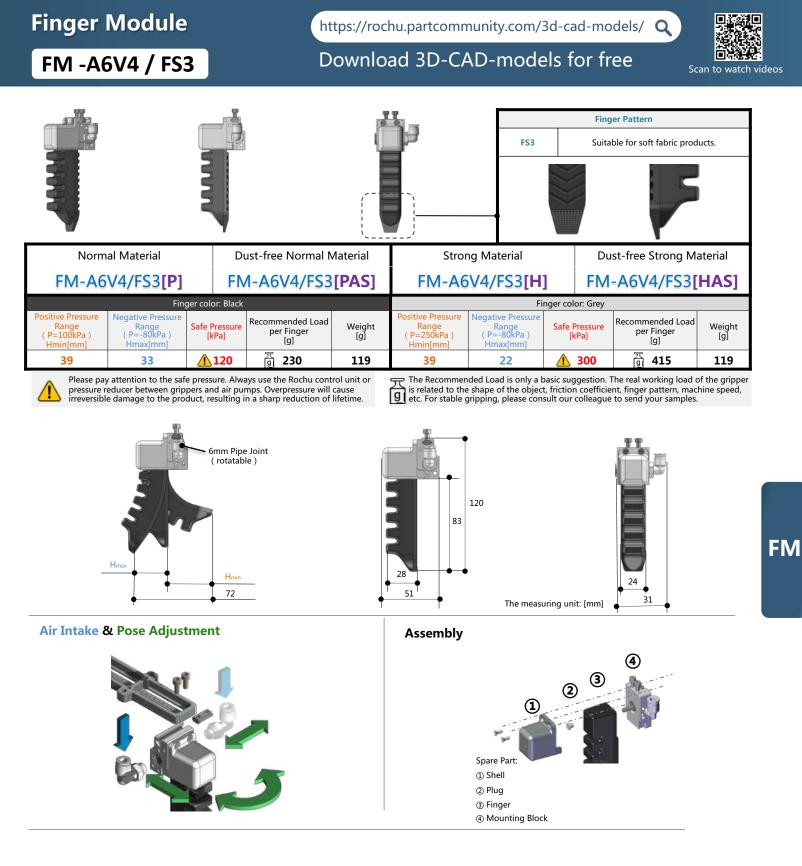
FM





Rochu



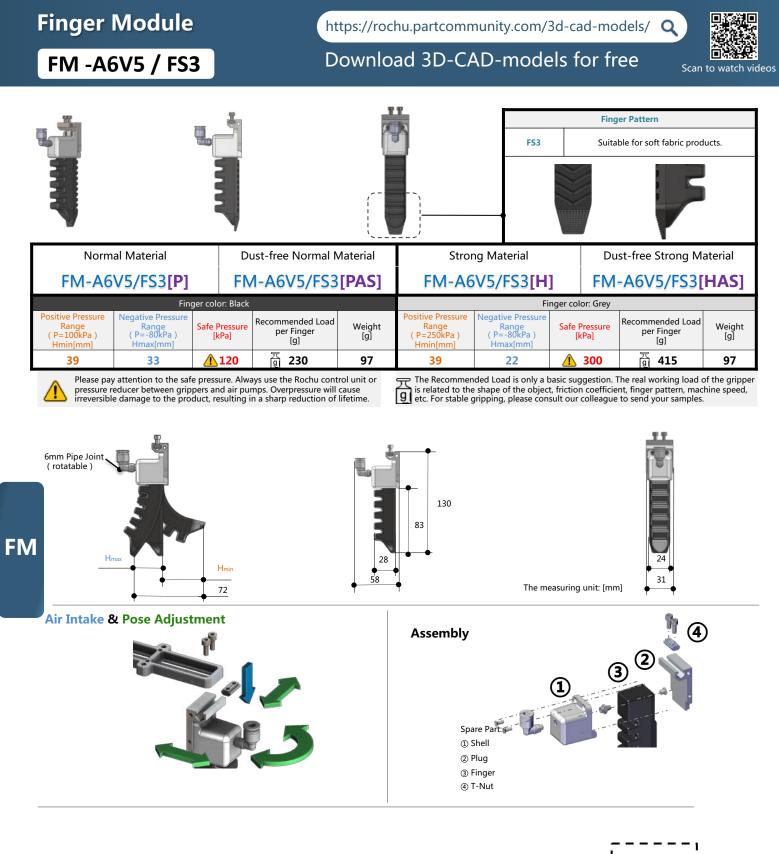


1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



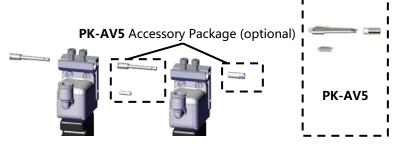


206 Finger Module

**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



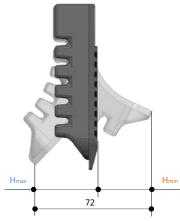
Finger Modu		https://rochu.partcommunity.com/3d-cad-models/ Q										
F -A6T / FS3			Download 3D-CAD-models for free									
	3			nn								
Finger Pattern			Features									
FS3 Specia	al Form				Suitable for s							
Normal Material	Du	st-free Normal N	/laterial	Strong Material		Du	Dust-free Strong Mat					
F-A6T/FS3[P	]	F	-A6T/FS3[ <b>F</b>	PAS]	F-A6T/FS3[H]			-A6T/FS3[ <b>HAS</b> ]				
	Finger co	lor: Black					nger color: Grey	color: Grey				
		Pressure [kPa]	Recommended Load per Finger	Weight [g]	Positive Pressure Range (P=250kPa)	Negative Pressure Range (P=-80kPa)	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]			
				_	Hmin[mm]	Hmax[mm]		」 资 <b>415</b>	[3]			

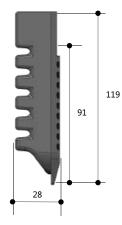
 $\wedge$ 

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

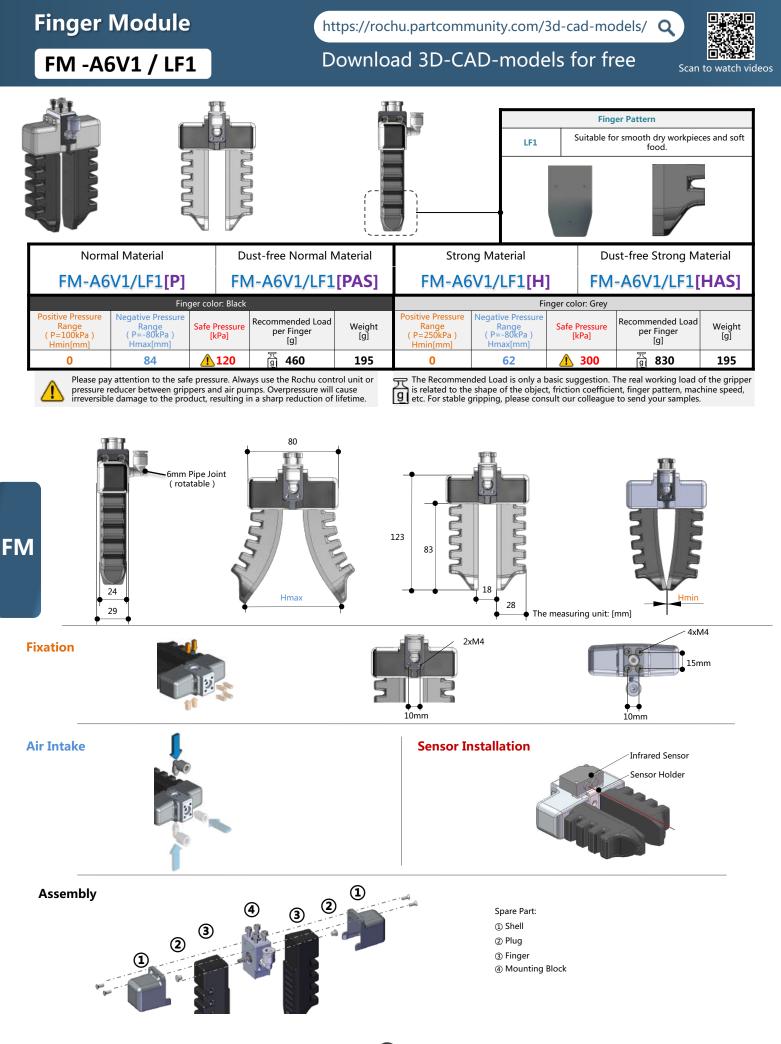
# **Dimension Parameters**



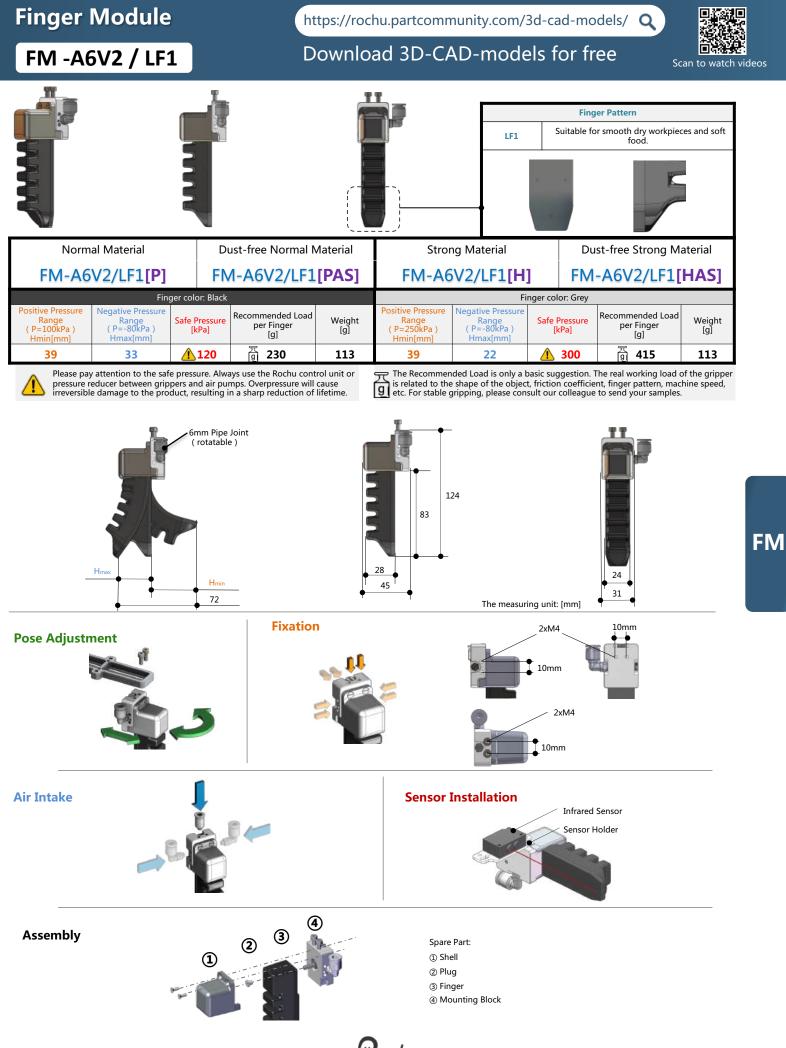




FM

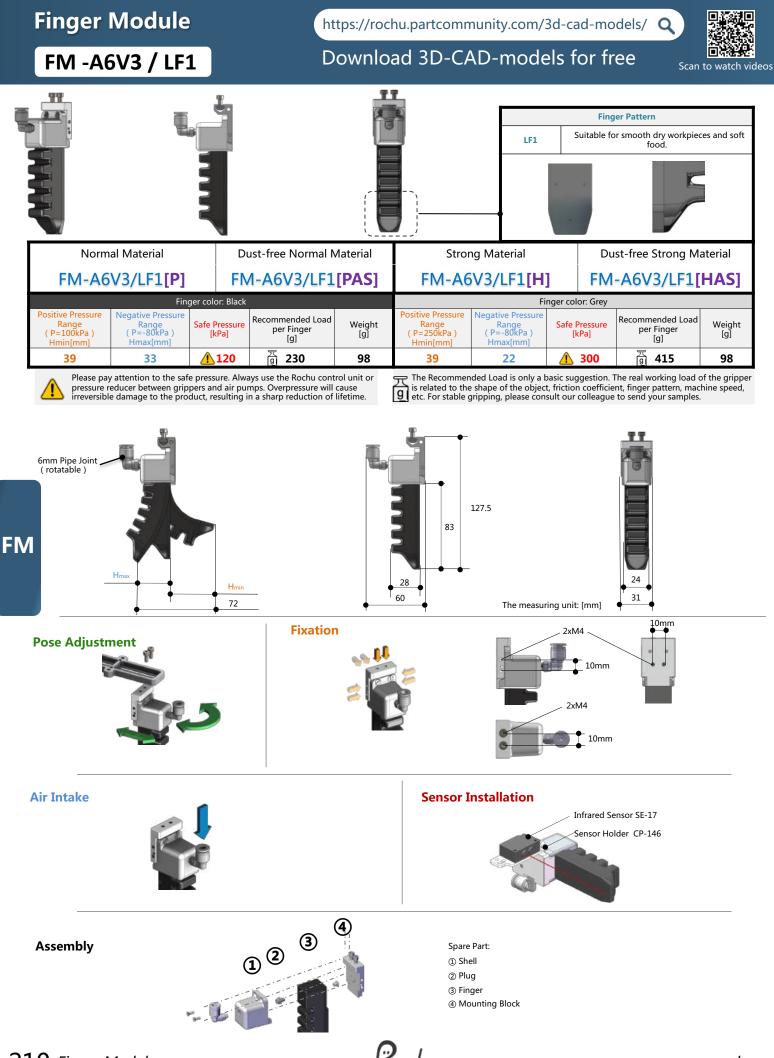


Rochu

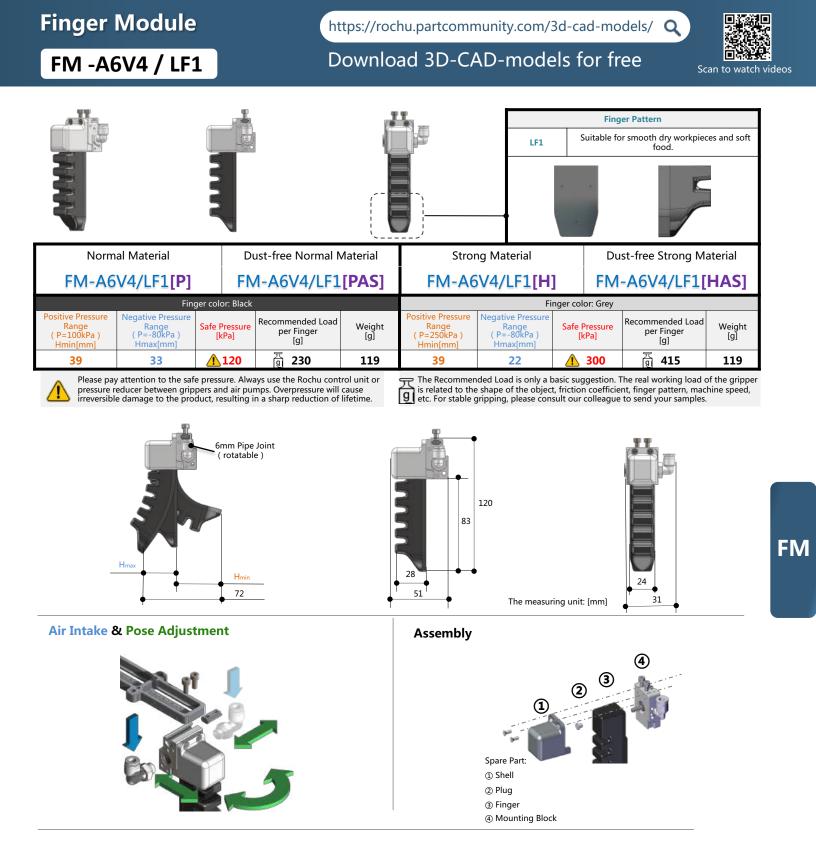


Pochu

Finger Module 209



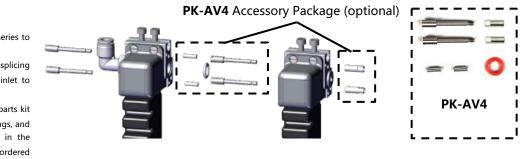
Rochu



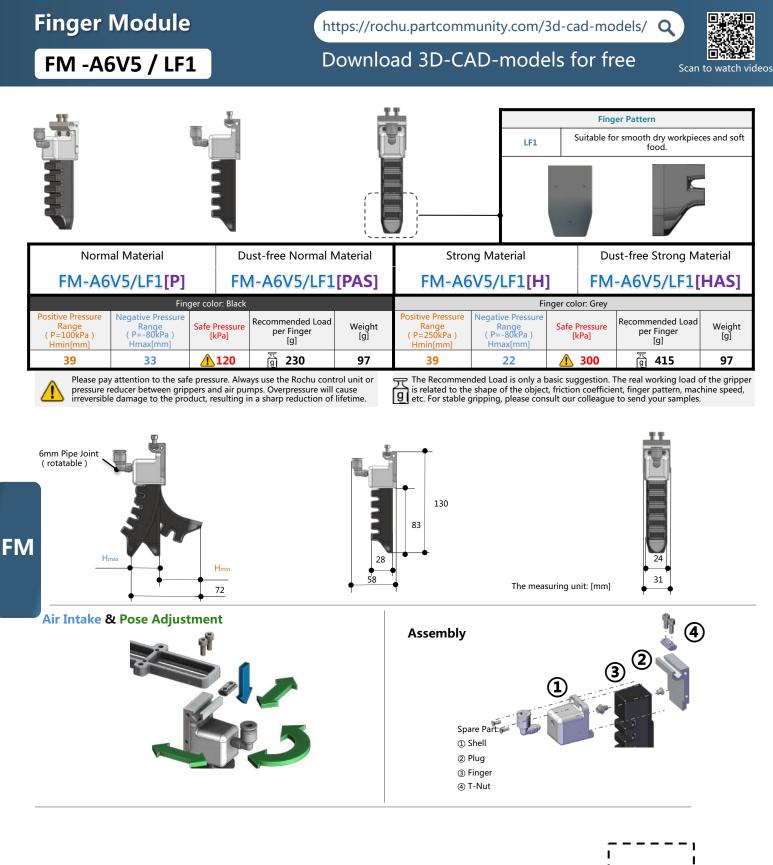
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu





1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-AV5 Accessory Package (optional)



Finger N	Module		https://rochu.partcommunity.com/3d-cad-models/ Q								
F -A6T	/ LF1		Download 3D-CAD-models for free								
				,	M						
Finger	Pattern				Fe	atures					
LF1			S	uitable for smooth o	dry workpieces and s	soft food.					
Normal	Normal Material			/laterial	Strong Material		Du	Dust-free Strong Material			
F-A6T	/LF1[P]	F	-A6T/LF1[F	PAS]	F-A6T/LF1[H]			F-A6T/LF1[HAS]			
	2	er color: Black			Finger color						
Positive Pressure Range Range Safe P		Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range (P=250kPa) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]		

55

39

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

<u>^</u>120

岡 230

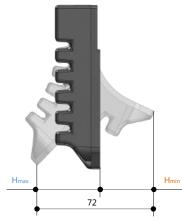
The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

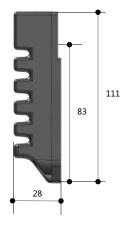
 $\Lambda$ 300

22

## **Dimension Parameters**

33





39

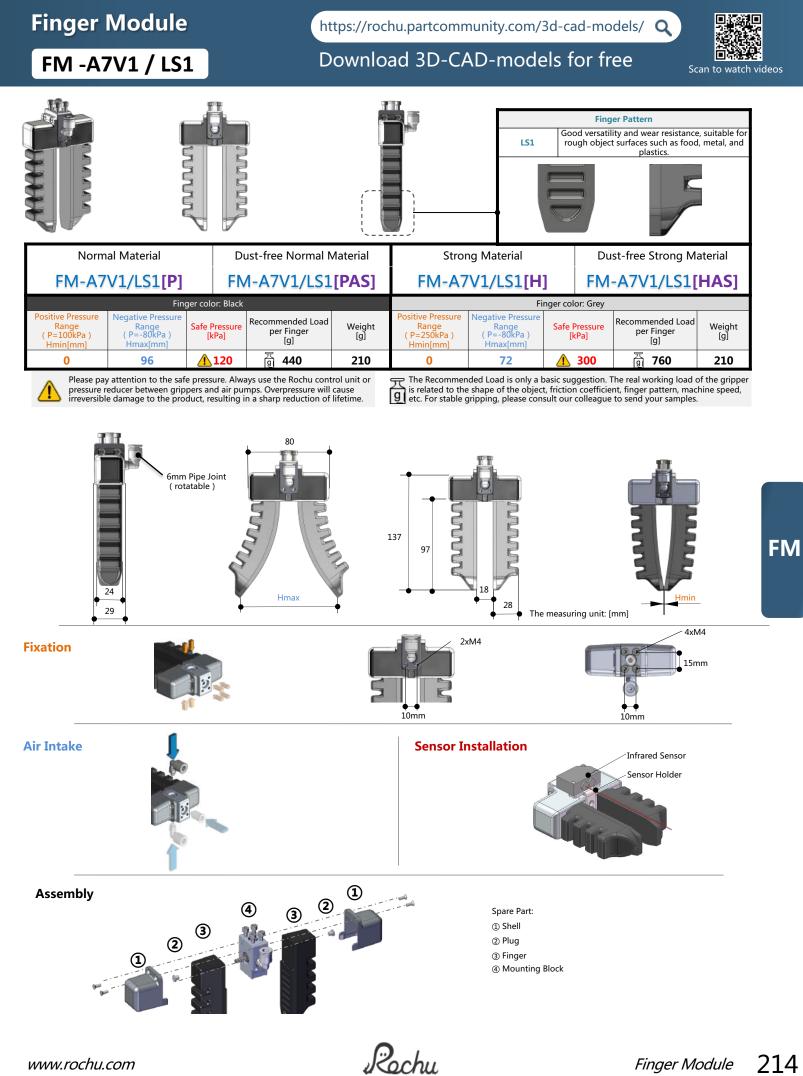


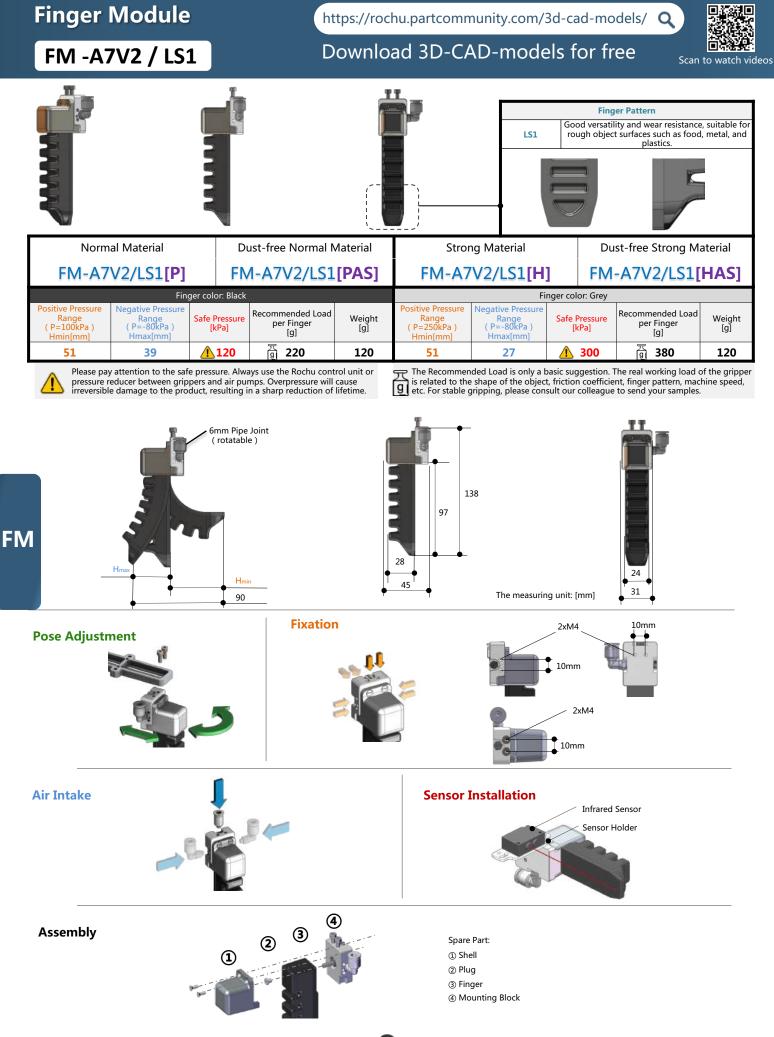
គ

415

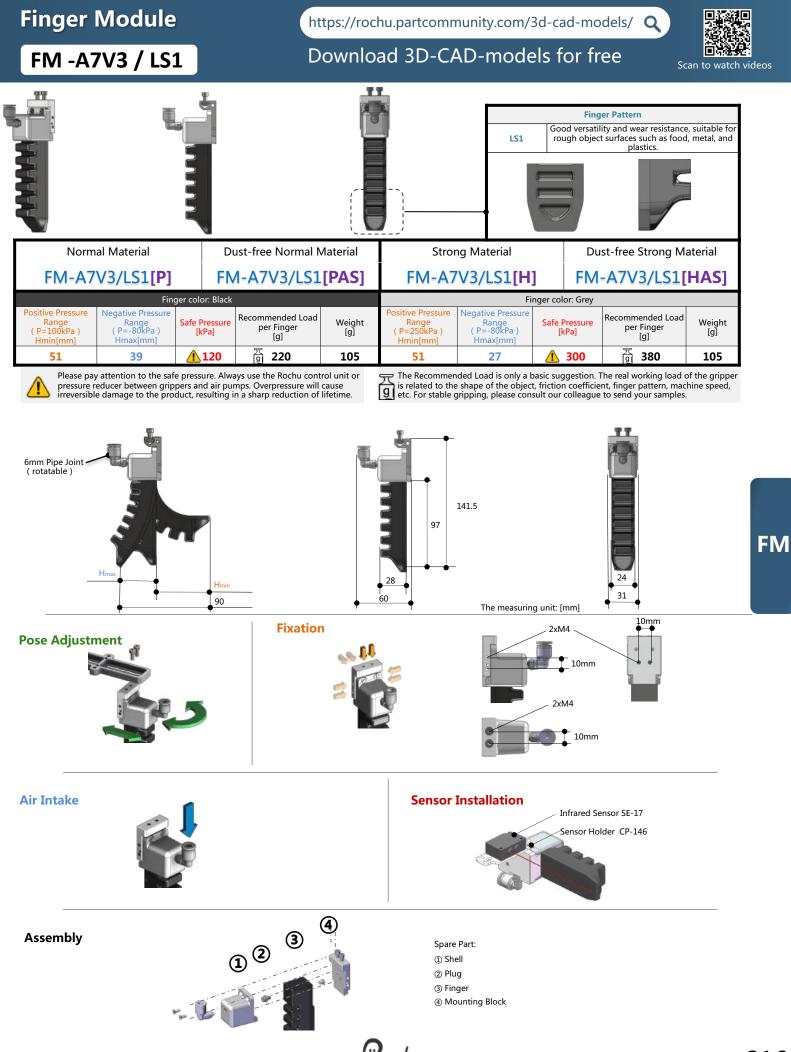
55

FM



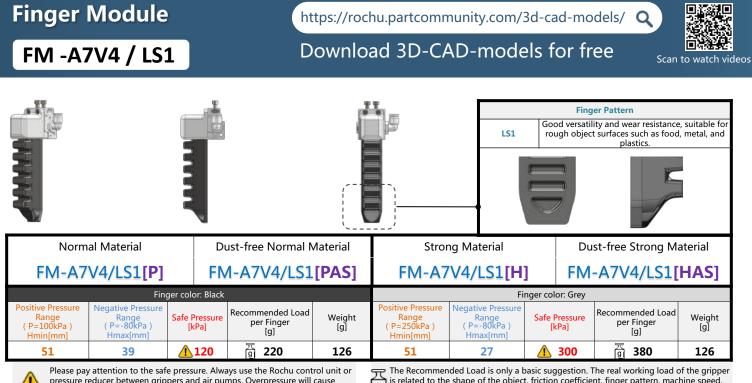


Pochu



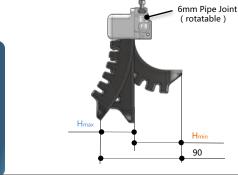
Rochu

Finger Module 216



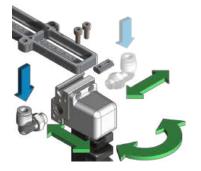
pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.



FM

# Air Intake & Pose Adjustment



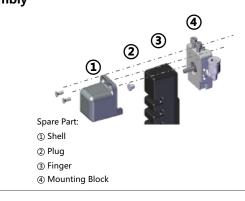
# Assembly

28

51

134

97



The measuring unit: [mm]

24

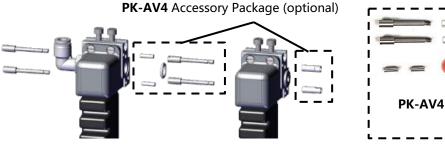
31

## Series combination:

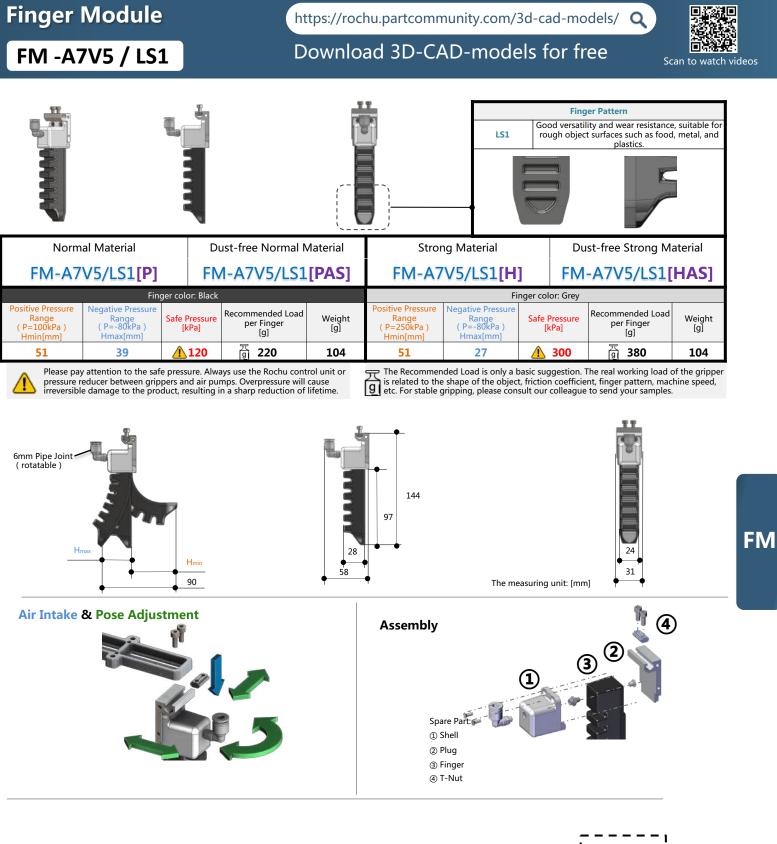
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.







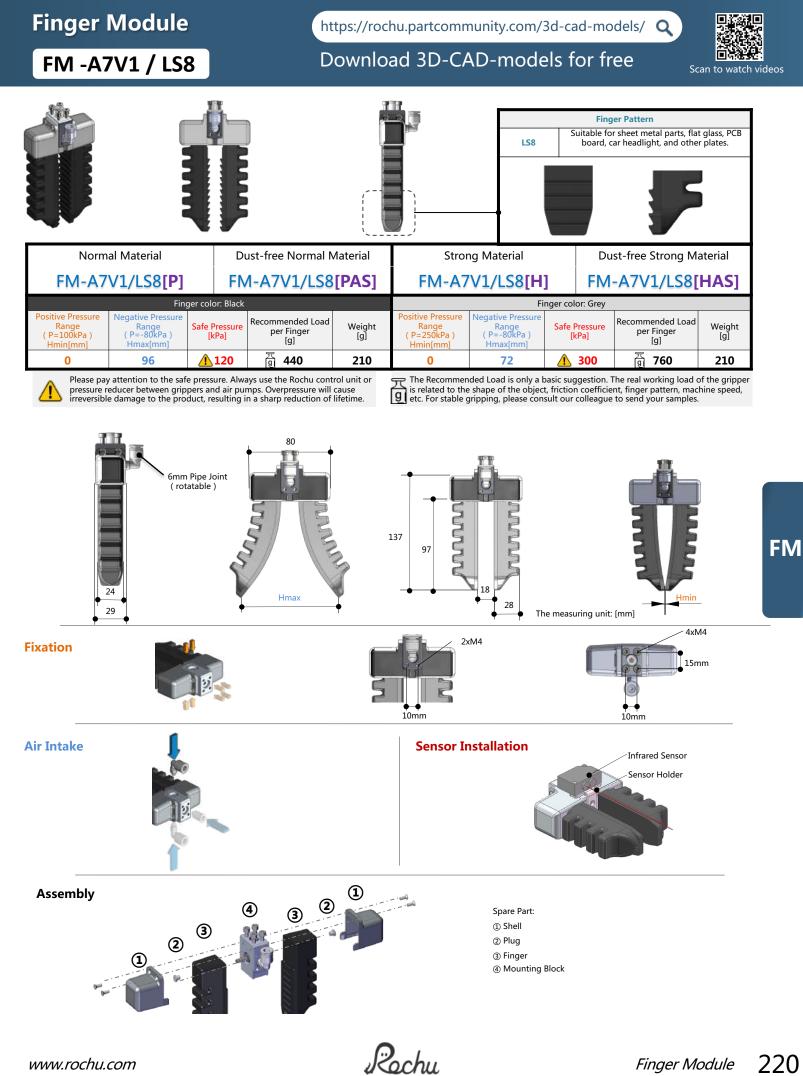
## Series combination:

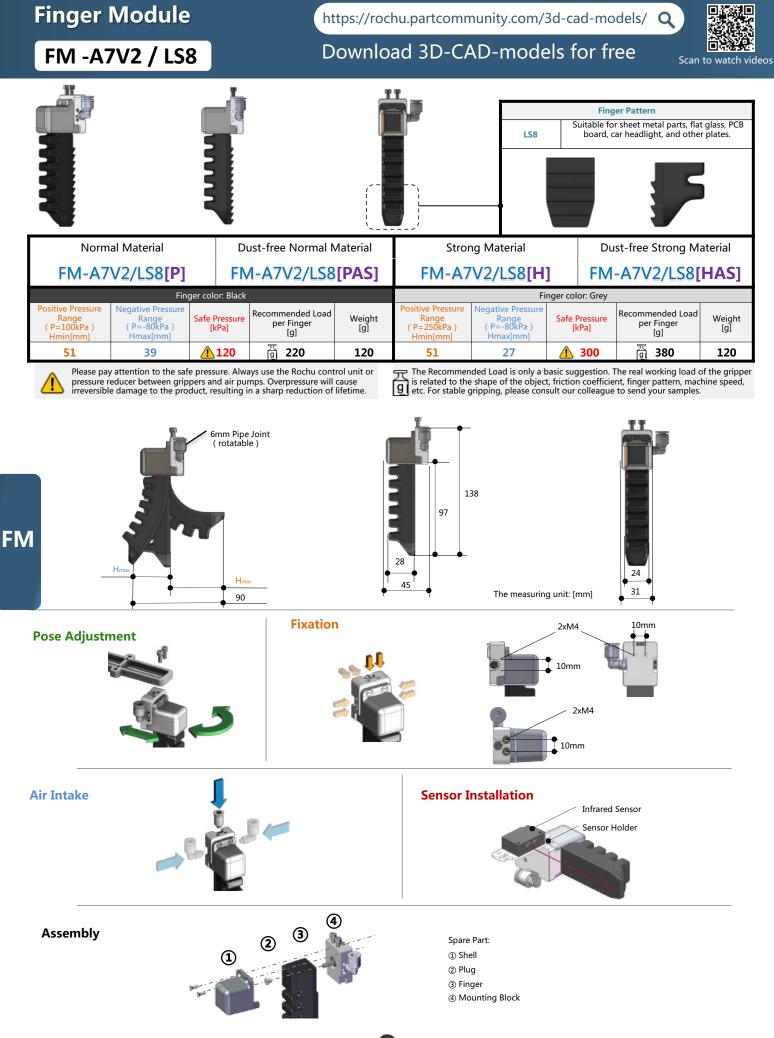
1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-AV5 Accessory Package (optional)

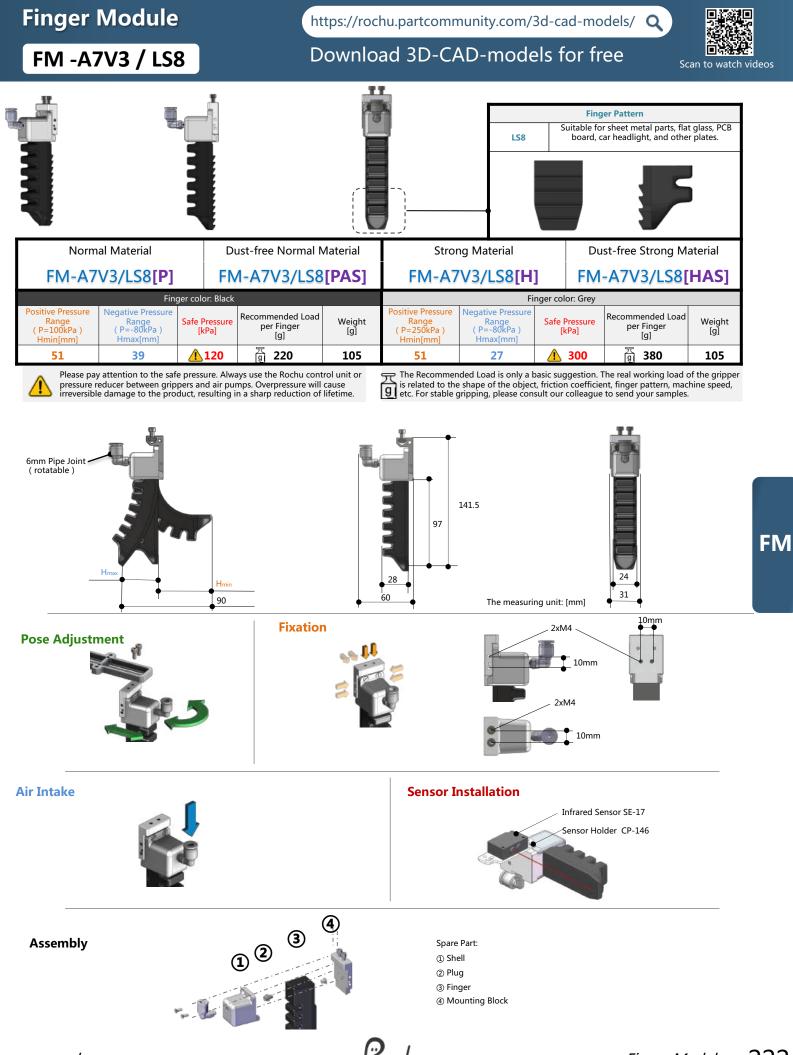
Finger M	Finger Module       https://rochu.partcommunity.com/3d-cad-models/ Q								
F -A7T /	F-A7T / LS1     Download 3D-CAD-models for free								
Finge	r Pattern			Fe	atures				
LS1	Standard form	Good ve	rsatility and wear re	es such as food, metal, and plastics.					
	al Material	Dust-free Norm			ng Material		Dust-free Strong Material		
F-A7	<b>[/LS1[P]</b> Finger c	F-A7T/LS	L[PAS]	F-A7T/LS1[H] F-A7T/LS			-A7T/LS1[H		
Positive Pressure Range ( P=100kPa ) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	fe Pressure [kPa] Recommended L per Finger [g]	Pal per Finger [a]		Positive Pressure Range (P=250kPa) Hmin[mm]		Safe Pressure [kPa] Recommended Load per Finger [g]		
51		<u>120</u> ☐ 220	62	51	27	<u> 300</u>	ज ब्रा <b>380</b>	62	
	educer between grippers	essure. Always use the Rochu s and air pumps. Overpressure t, resulting in a sharp reduction <b>rs</b>	e will cause	9 etc. For stable of the stabl	snape of the object, gripping, please cons	, meton coefficie sult our colleague	The real working load of ent, finger pattern, mac e to send your samples	nine speed.	



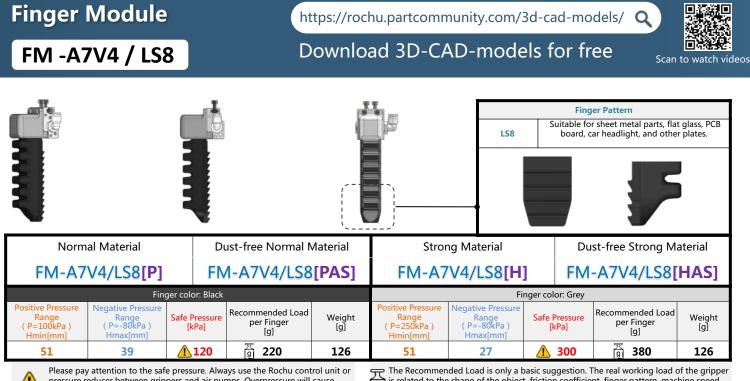


221 Finger Module

Pochu

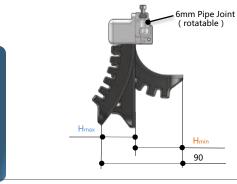


Rochu



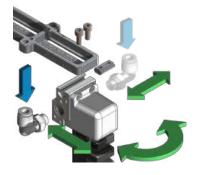
pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

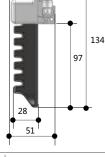
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

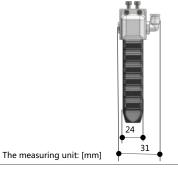


# Air Intake & Pose Adjustment

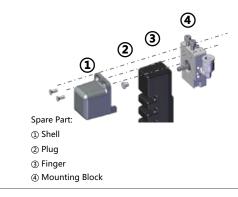
FM







Assembly

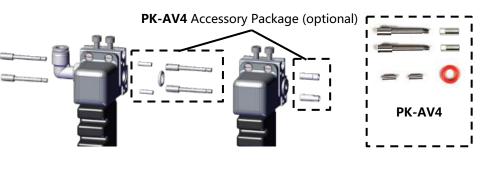


## Series combination:

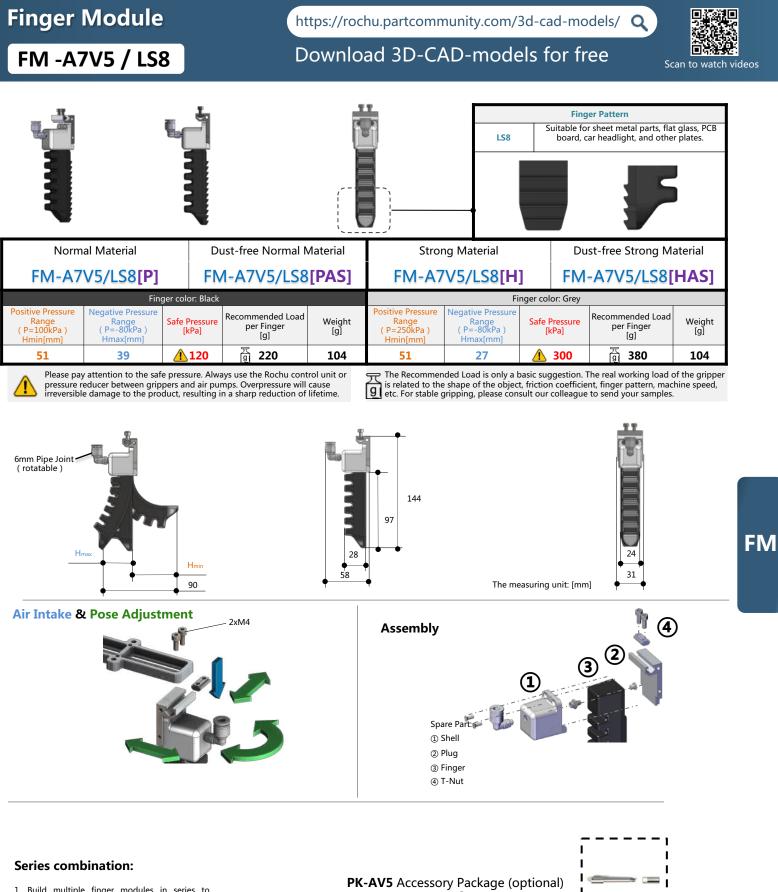
1. Build multiple finger modules in series to increase the grip force.

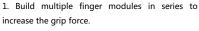
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.









2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

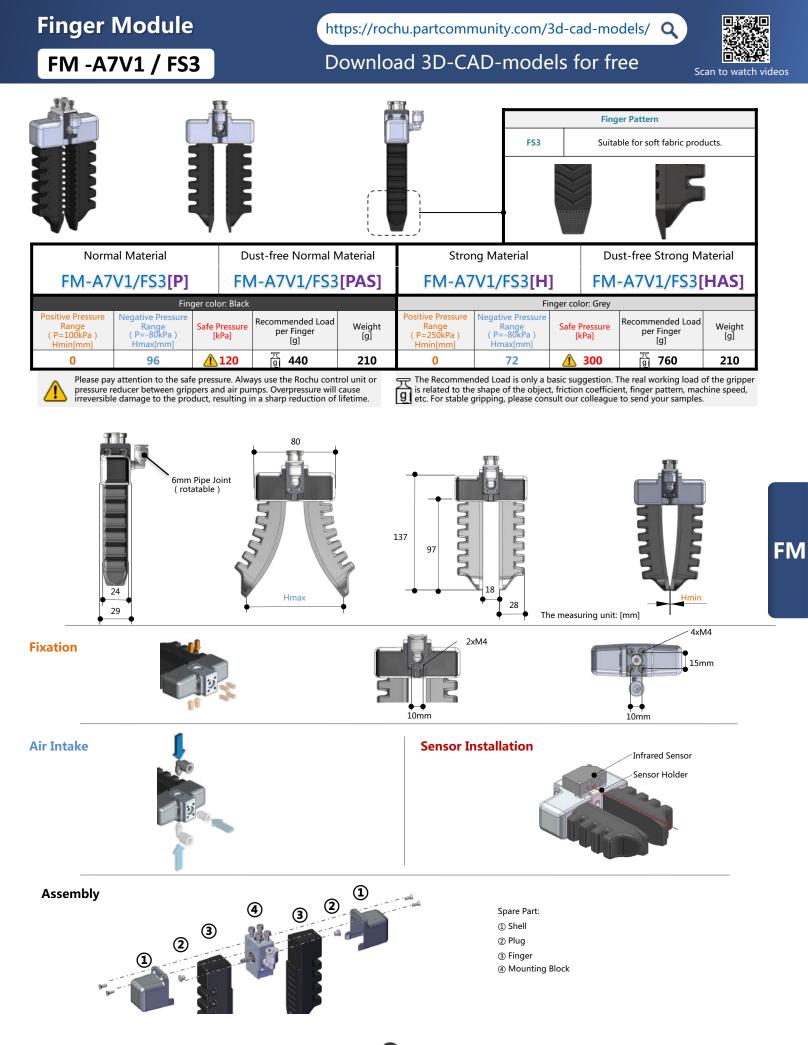
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.

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н PK-AV5

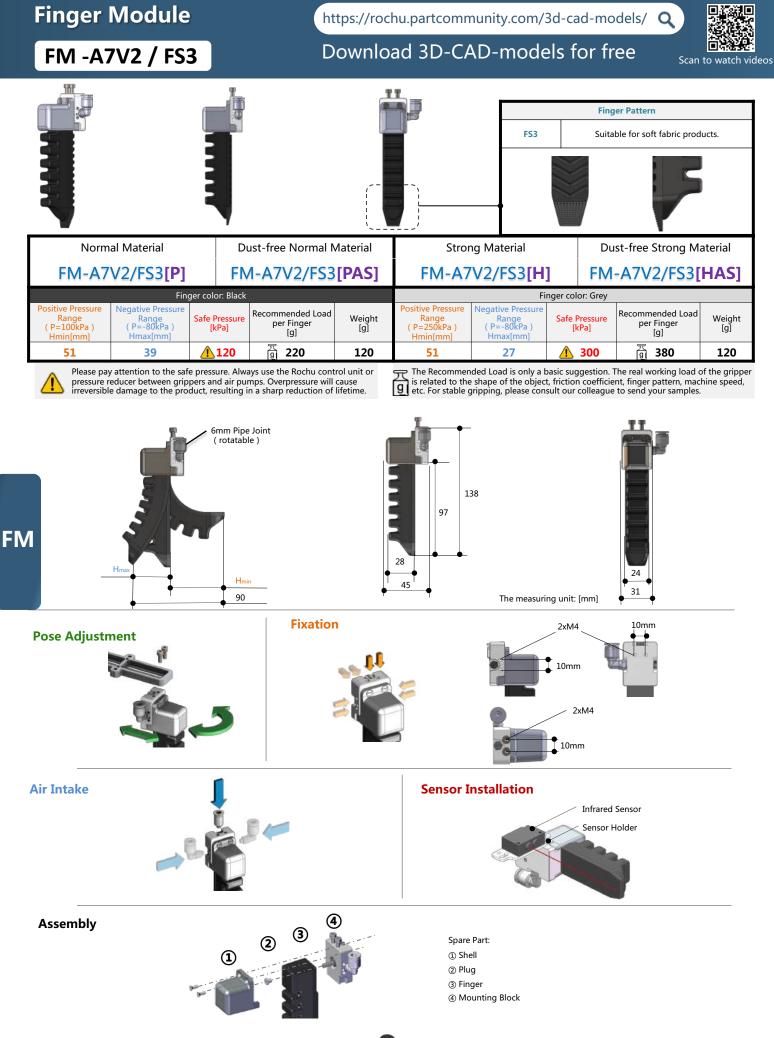


	Finger Mo	odule	http	os://rochu.µ	partcommun	ity.com/3d-c	ad-models	s/ ۹ 📲	
	F -A7T / I	LS8	Do	wnload	3D-CAD	-models	for free	Scan to w	atch videos
							0		
	Finge	r Pattern				eatures			
	LS8	Special Form				ss, PCB board, car hea	-		
		al Material	Dust-free Normal Material F-A7T/LS8[PAS]		Strong Material F-A7T/LS8[H]		Dust-free Strong Mat		
	Positive Pressure Range (P=100kPa) Hmin[mm] <b>51</b>	Negative Pressure Range (P=-80kPa) Hmax[mm]	Pressure [kPa]     Recommended Loa per Finger [g]       120     T	ad Weight [g] 62	Positive Pressure Range (P=250kPa) Hmin[mm] 51	Fir Negative Pressure Range (P=-80kPa) Hmax[mm] 27	safe Pressure [kPa]	Recommended Load per Finger [g] (g) <b>380</b>	Weight [g] 62
	Please pay pressure re	attention to the safe pres educer between grippers a	ssure. Always use the Rochu co and air pumps. Overpressure v resulting in a sharp reduction	ontrol unit or vill cause	元 The Recommer	nded Load is only a b	asic suggestion. T	he real working load on t, finger pattern, mac to send your samples	of the gripper
FM	Dimension	n Parameters	S Hmin		97 125 8	5		24	



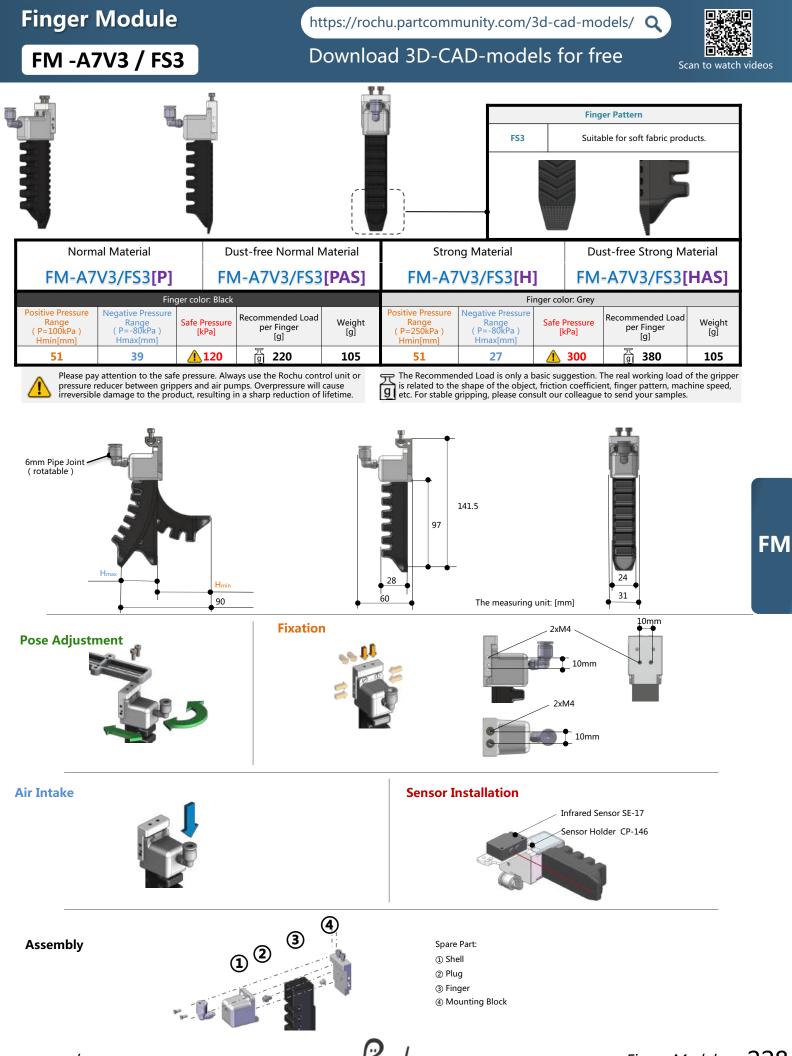
Rochu

Rochu soft Finger 226

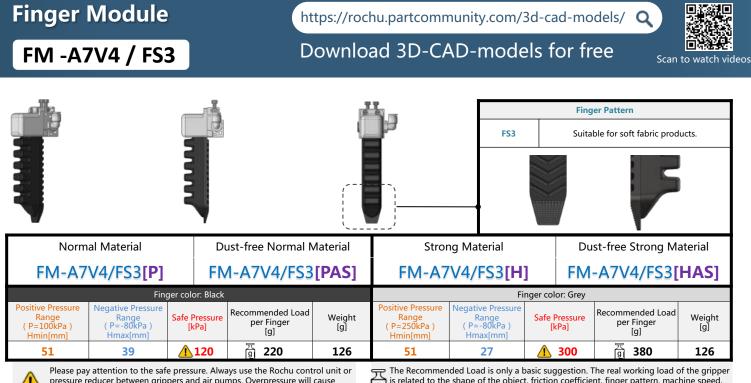


227 Finger Module

Pochu

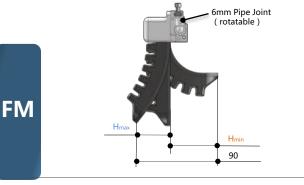


Rochu

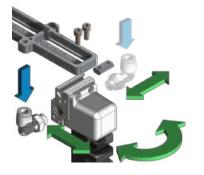


pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.



# Air Intake & Pose Adjustment



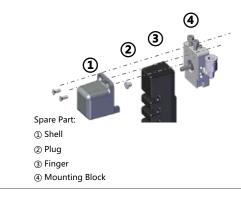


134

97



Assembly



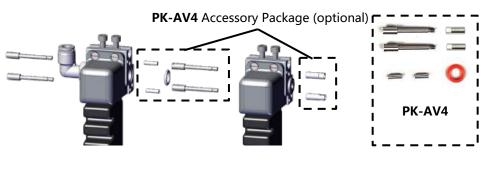
The measuring unit: [mm]

## Series combination:

1. Build multiple finger modules in series to increase the grip force.

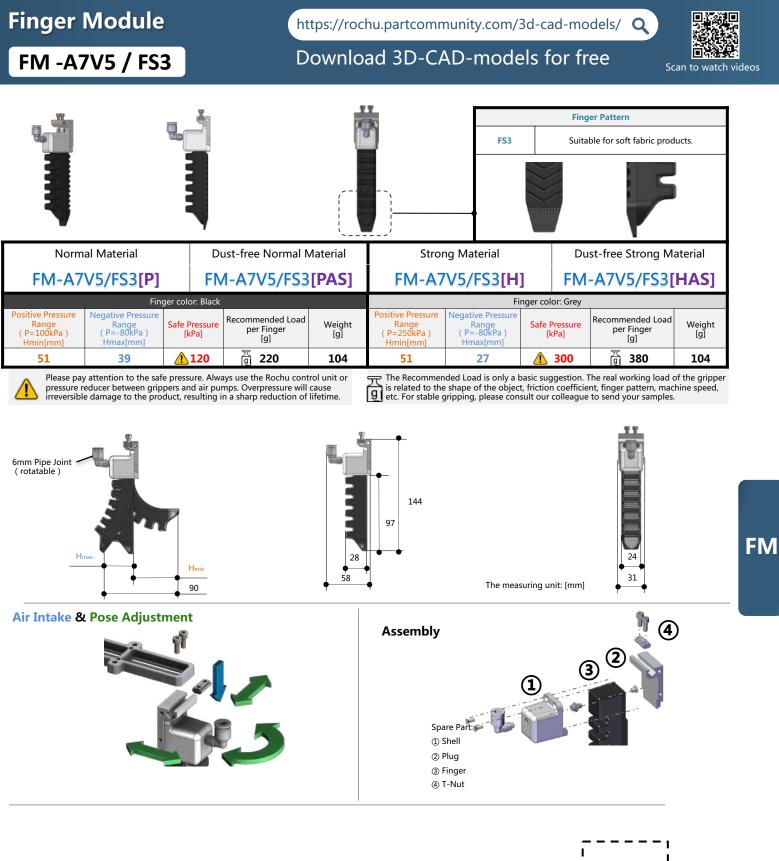
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.









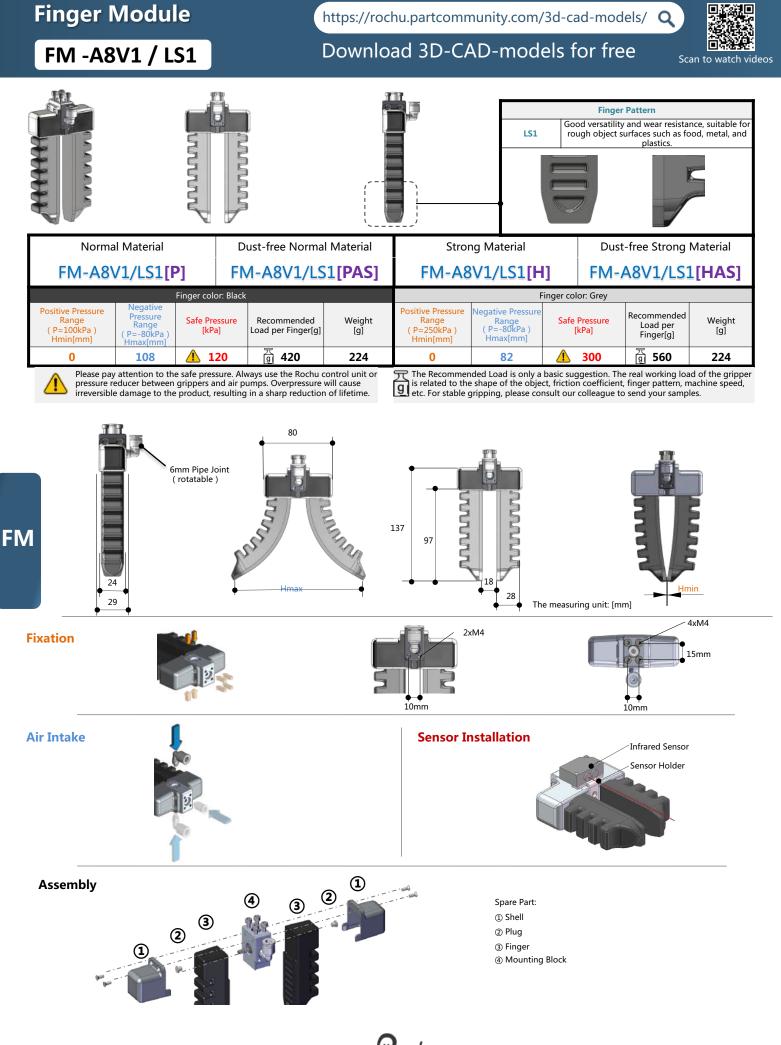
# Series combination:

1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

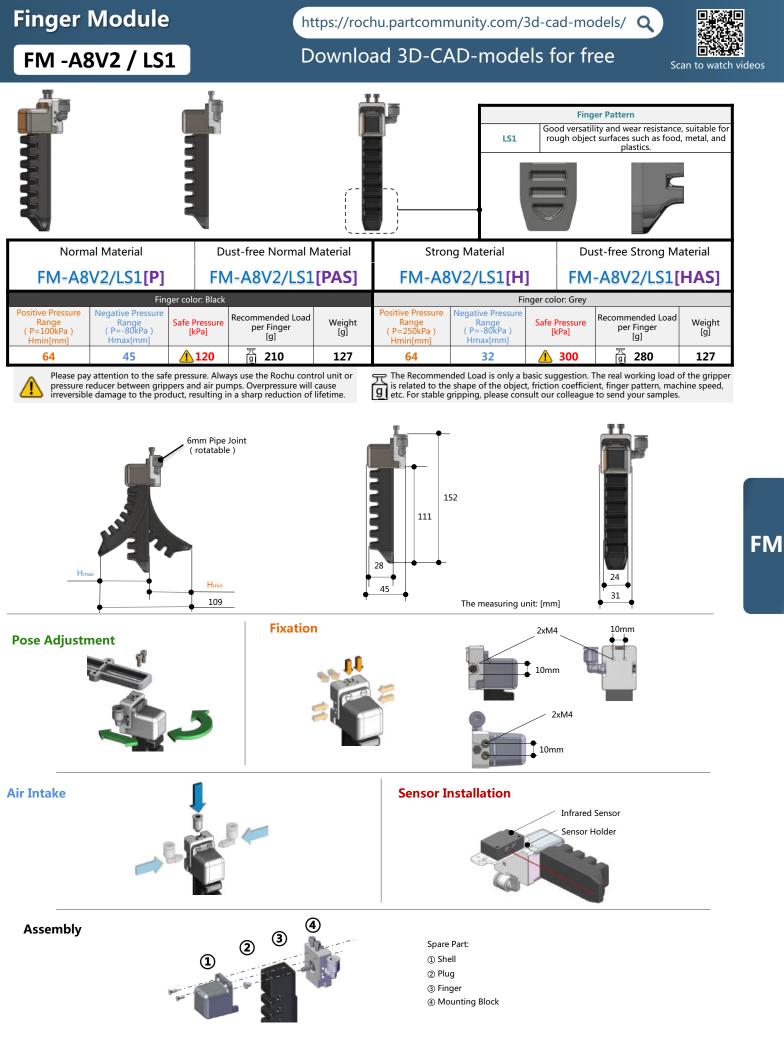
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-AV5 Accessory Package (optional)

Fi	Finger Module				//rochu.p	partcommun	ity.com/3d-c	ad-model	s/ Q		
	F -A7T / I	<b>-S3</b>		Dow	nload	3D-CAD	-models t	for free	Scan to w	atch videos	
					vvv	<b>~</b>					
	Finger	r Pattern				Fe	atures				
	FS3	Special Form					soft fabric products.				
		l Material		Dust-free Normal Material F-A7T/FS3[PAS]		Strong Material F-A7T/FS3[H]		Dust-free Strong Mater F-A7T/FS3[HAS			
	Positive Pressure Range         Negative Pressure Range         Safe I [F=100kPa )           (P=100kPa )         (P=-80kPa )         [Hmax[mm]]		er color: Black Safe Pressure [kPa]	Recommended Load per Finger [g] 220	Weight [g] <b>62</b>	Positive Pressure Range (P=250kPa) Hmin[mm] <b>51</b>	Fin Negative Pressure Range ( P=-80kPa ) Hmax[mm] 27	safe Pressure [kPa]	Recommended Load per Finger [g] Tg <b>380</b>	Weight [g] 62	
FM	pressure re irreversible	educer between gripp	ers and air pur uct, resulting i	ays use the Rochu cont mps. Overpressure will n a sharp reduction of	cause	9 etc. For stable	e shape of the object, gripping, please cons	, friction coefficie ult our colleague	The real working load of the real working load		



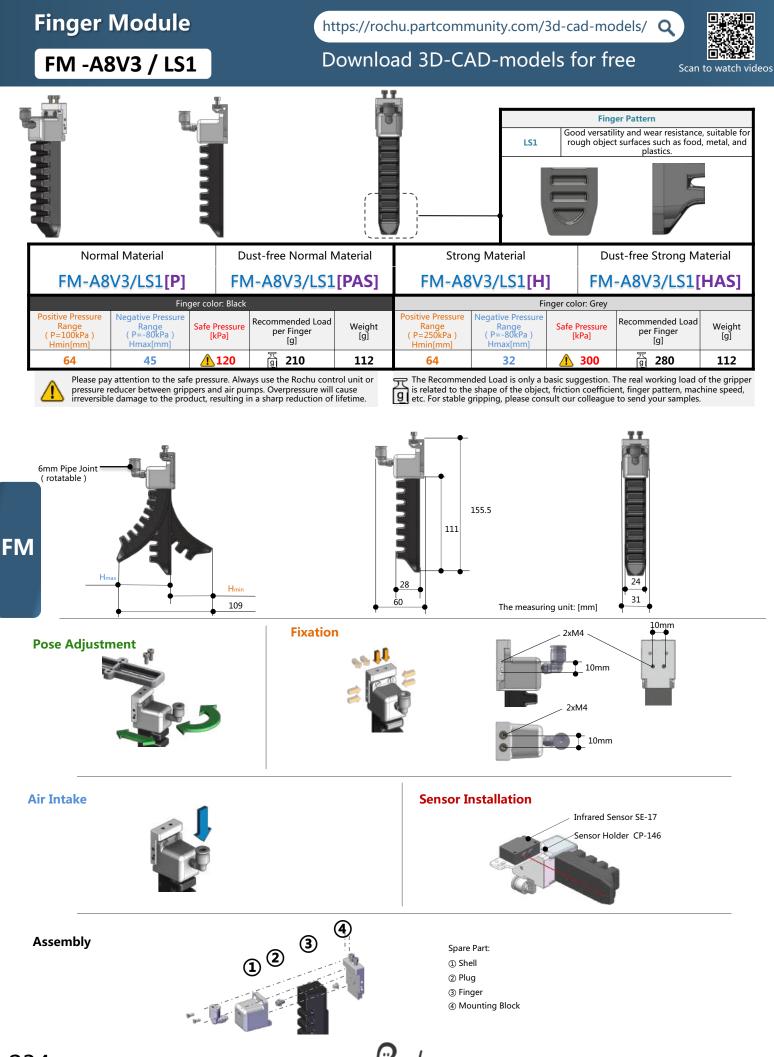
232 Finger Module





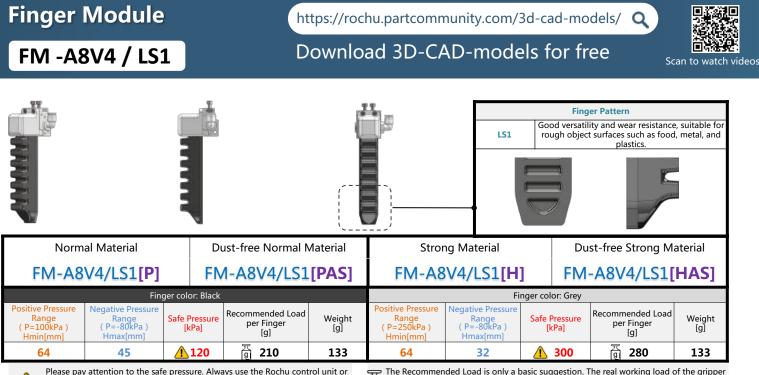
Pochu

Finger Module 233



234 Finger Module

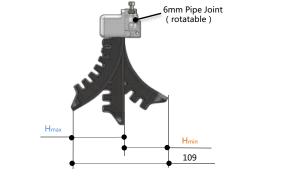
Rochu



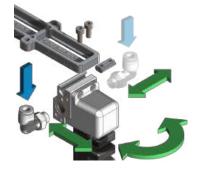
 $\Lambda$ 

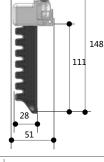
Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

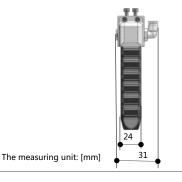
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.



# Air Intake & Pose Adjustment

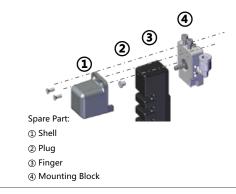






FM

Assembly

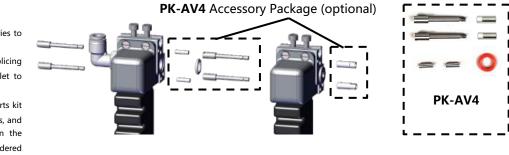


# Series combination:

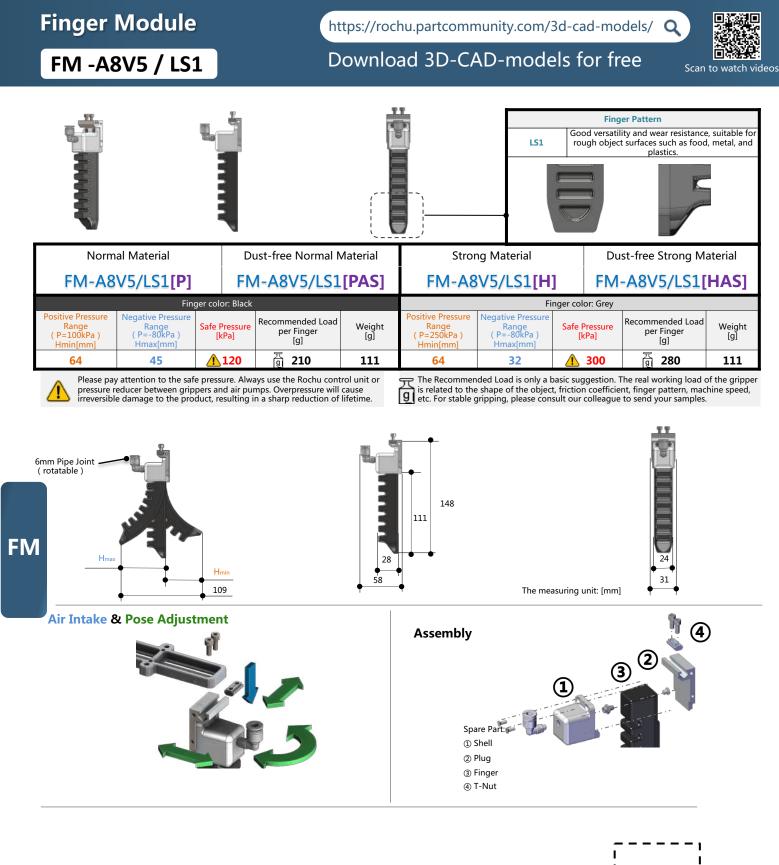
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.





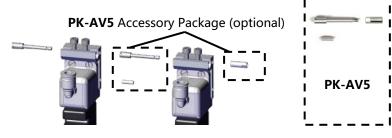




**1**. Build multiple finger modules in series to increase the grip force.

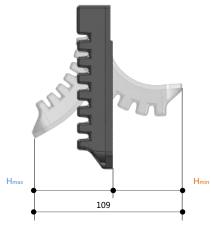
2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

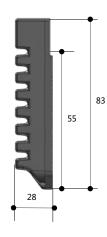
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



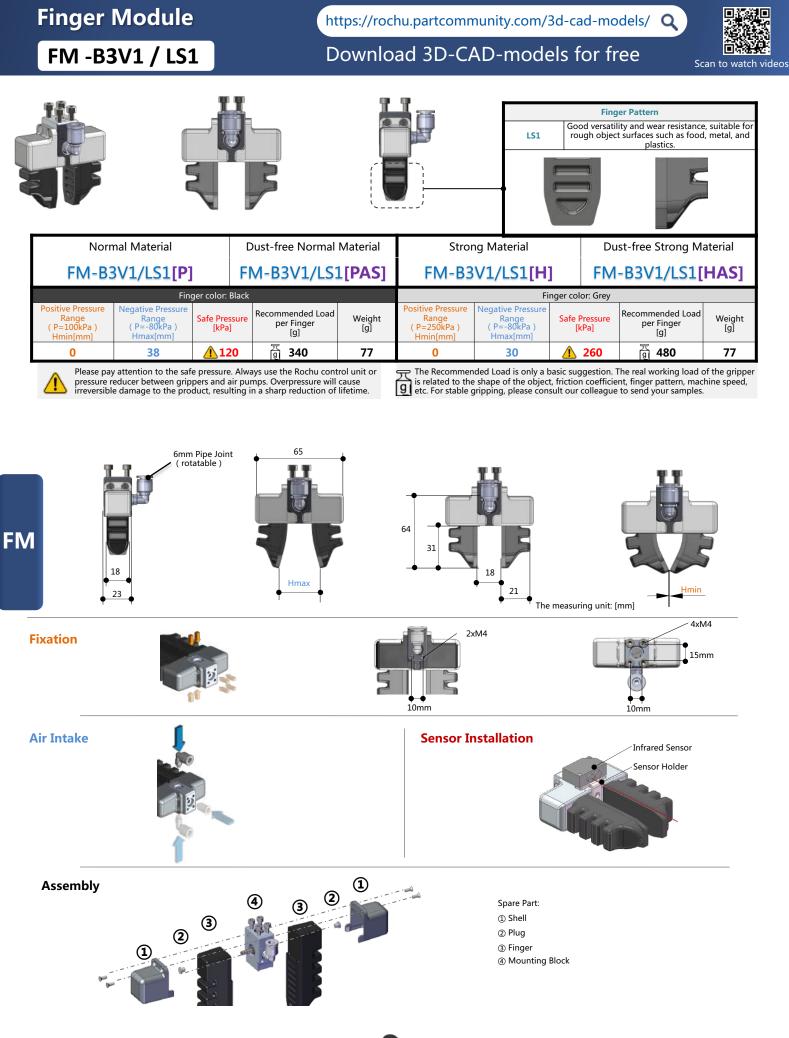
inger F -A8T	Module / LS1	•		•	chu.partcomr ad 3D-CA			ree	an to watch vide
				w	w				
Finge	r Pattern				Fe	atures			
LS1	Standard for	m	Good versatil	ity and wear re	esistance, suitable for	rough object surfac	es such as food, r	metal, and plastics.	
Norma	al Material	Di	ust-free Normal N	Aaterial	Stro	ng Material	Du	ust-free Strong Ma	aterial
F-A81	[/LS1[P]	F	-A8T/LS1[P	PAS]	F-A8	T/LS1[H]	F	-A8T/LS1[H	AS]
		ger color: Black					nger color: Grey	1	
Positive Pressure Range (P=100kPa) Hmin[mm]	Negative Pressure Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range (P=250kPa) Hmin[mm]	Negative Pressure Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]
64	45	<u>120</u>	页 <b>210</b>	69	64	32	<u> 300</u>	ਸ਼ੂ 280	69
	educer between grip	pers and air pu	ays use the Rochu cont mps. Overpressure will n a sharp reduction of	cause	The Recommer is related to the etc. For stable of	nded Load is only a b e shape of the object gripping, please cons	asic suggestion. , friction coefficies sult our colleague	The real working load o ent, finger pattern, mach e to send your samples.	f the gripper nine speed,

# **Dimension Parameters**

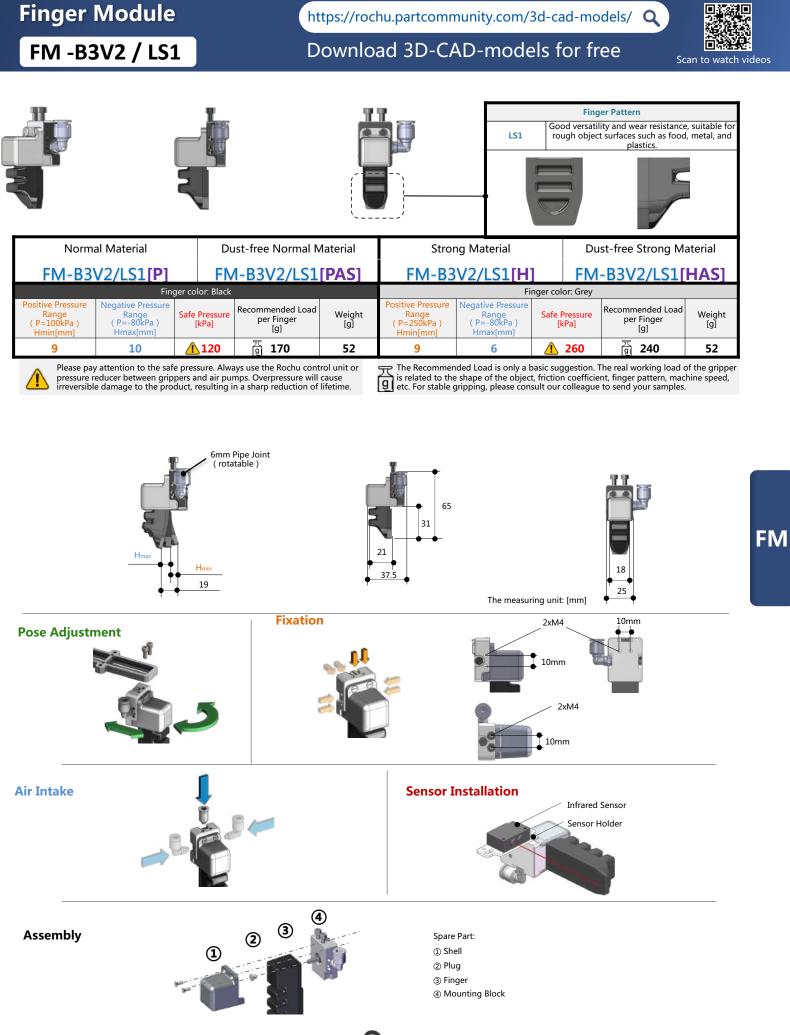




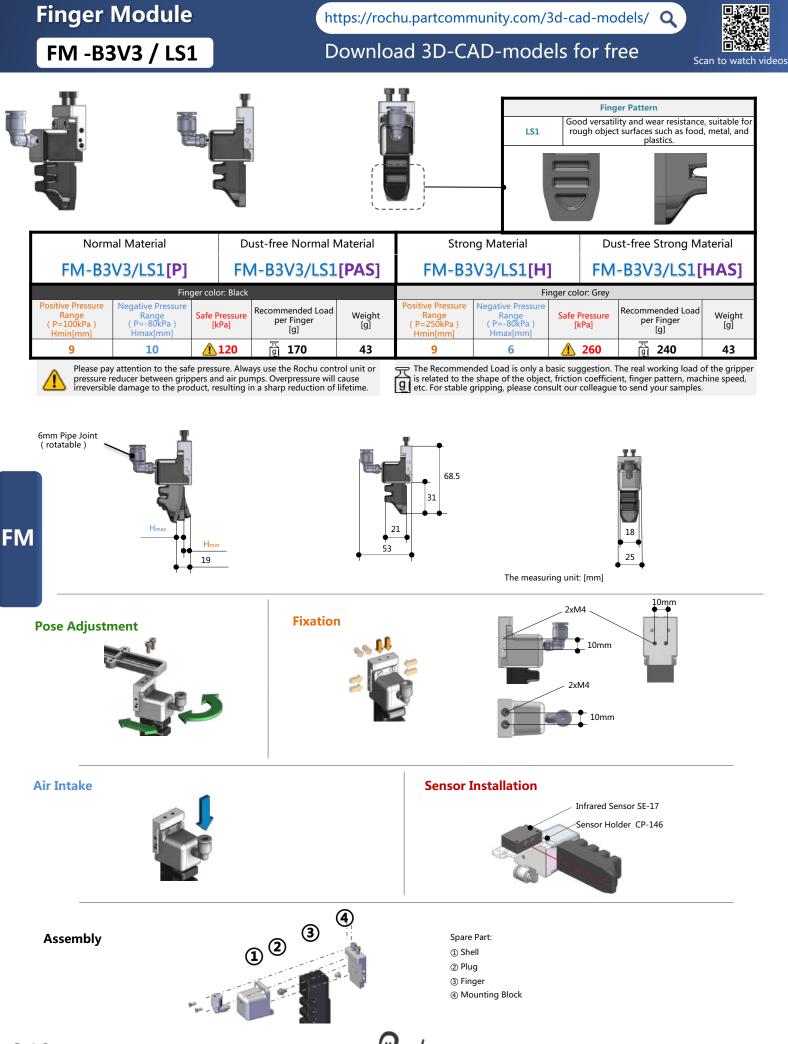




238 Rochu soft Finger

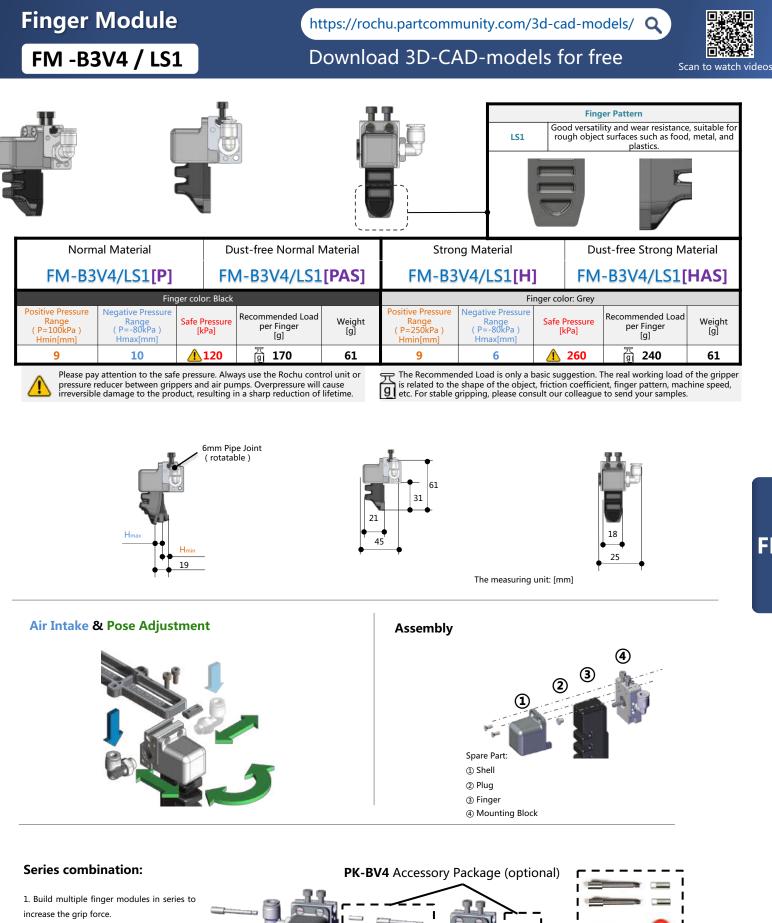


Rochu



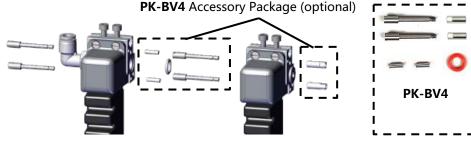
240 Rochu soft Finger

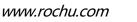
Rochu



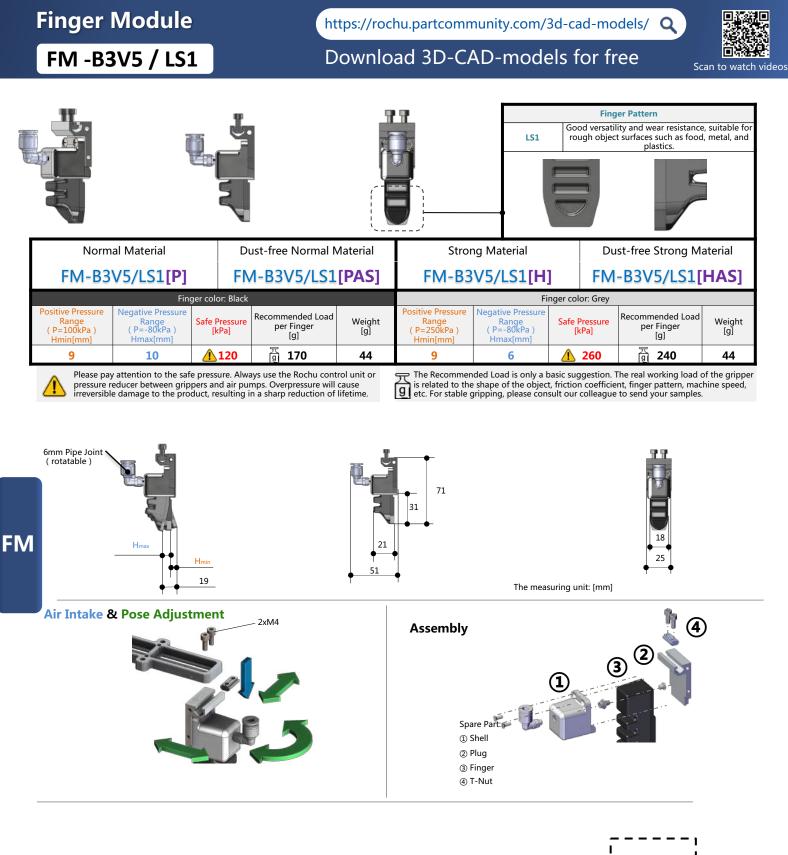
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.





FM





1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.

PK-BV5 Accessory Package (optional)



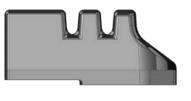
https://rochu.partcommunity.com/3d-cad-models/ Q

# Download 3D-CAD-models for free



Scan to watch videos







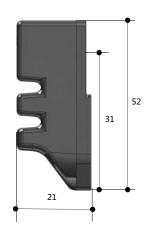
Finger Pattern					Features					
LS1	Standard forr	n	Good versatil	ity and wear re	esistance, suitable for rough object surfaces such as food, metal, and plastics.					
Norma	Normal Material Dust-free Normal Material			/laterial	Strong Material D			ust-free Strong Material		
F-B3T/LS1[P] F-B3T/LS1[PAS			PAS]	F-B3	T/LS1[H]	F	-B3T/LS1[H	AS]		
	Fing	ger color: Black			Finger color: Grey					
Positive Pressure Range (P=100kPa) Hmin[mm]	Negative Pressure Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range (P=250kPa) Hmin[mm]	Negative Pressure Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	
9	10	<u>120</u>	页 170	11	9	6	1 260	표 및 <b>240</b>	11	
A Please pay	attention to the saf	e pressure. Alwa	ays use the Rochu cont	trol unit or	元 The Recommer	nded Load is only a b	asic suggestion.	The real working load o	of the gripper	

rease pay attention of the safe pressure. Always use the focular of the of the focular of the pressure reducers between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

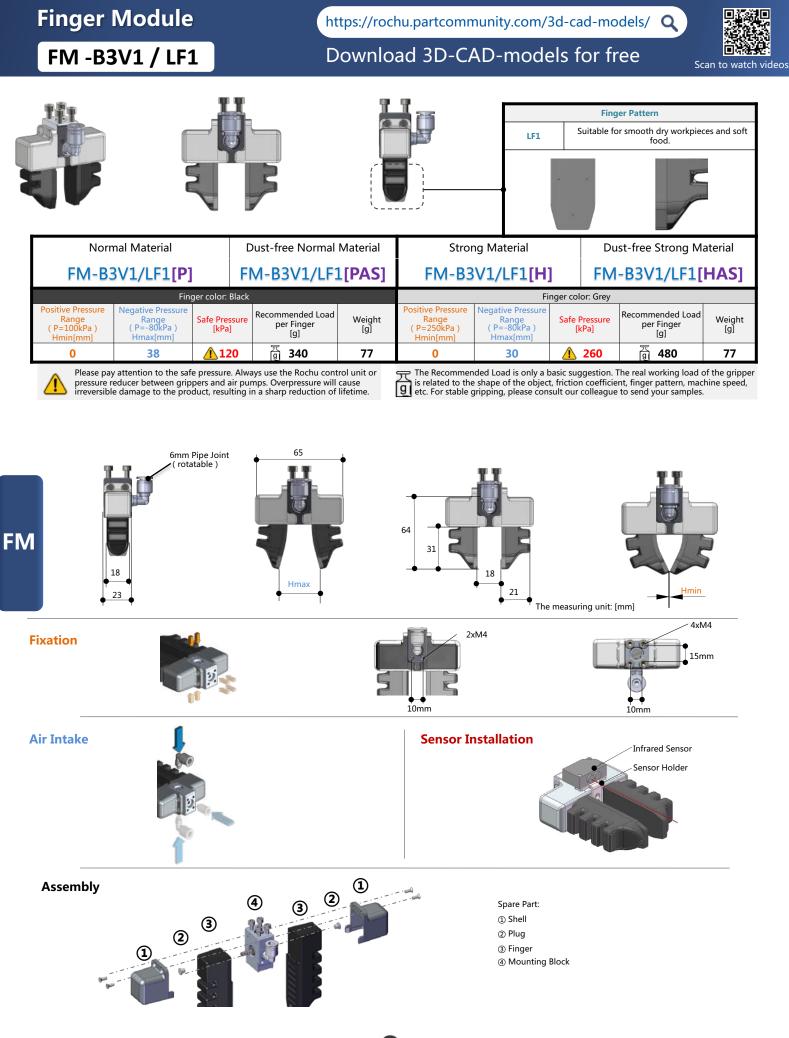
is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

# **Dimension Parameters**



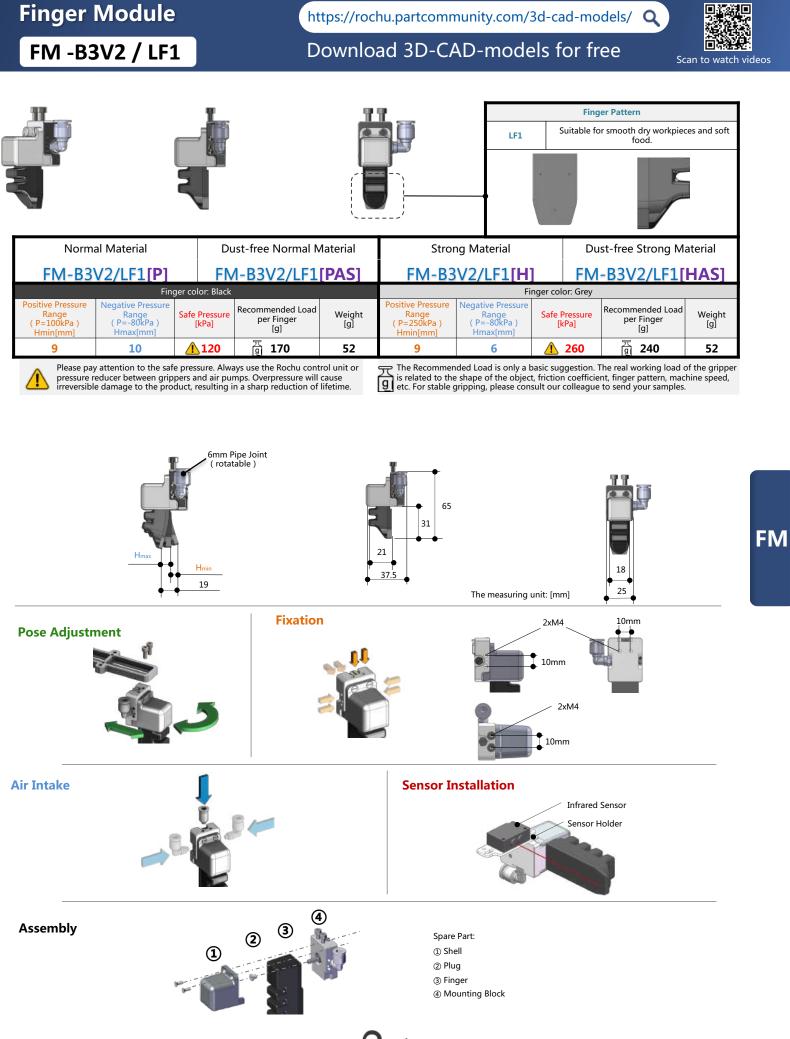






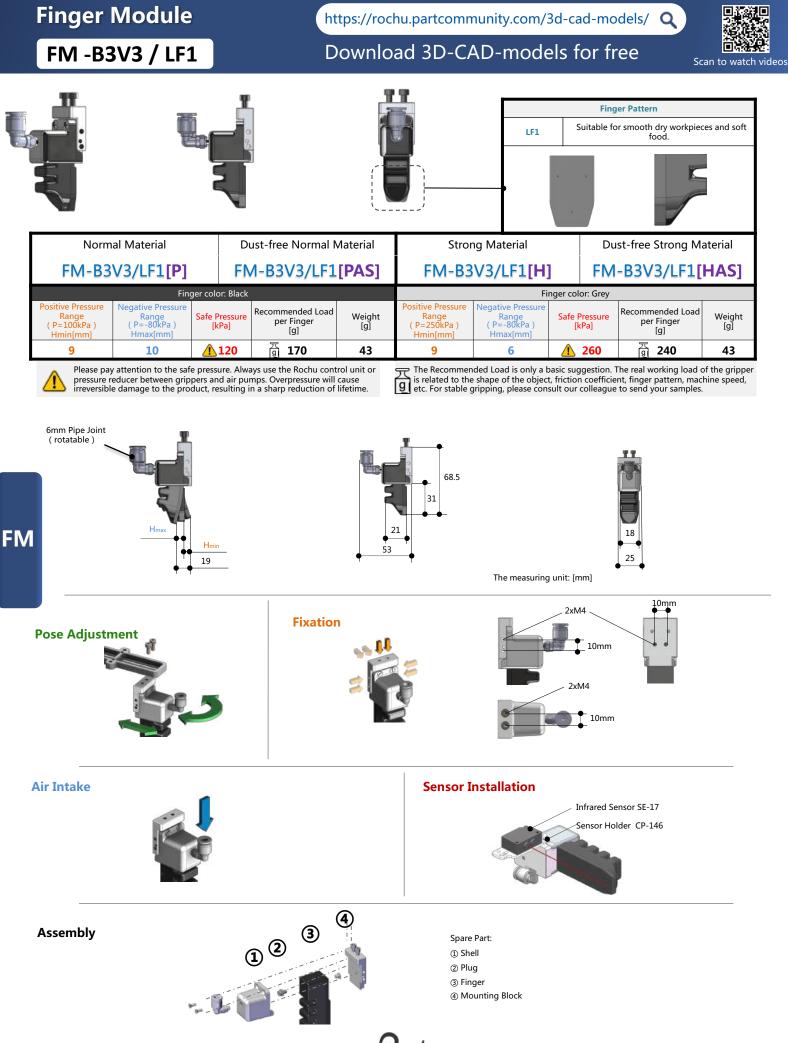
244 Rochu soft Finger





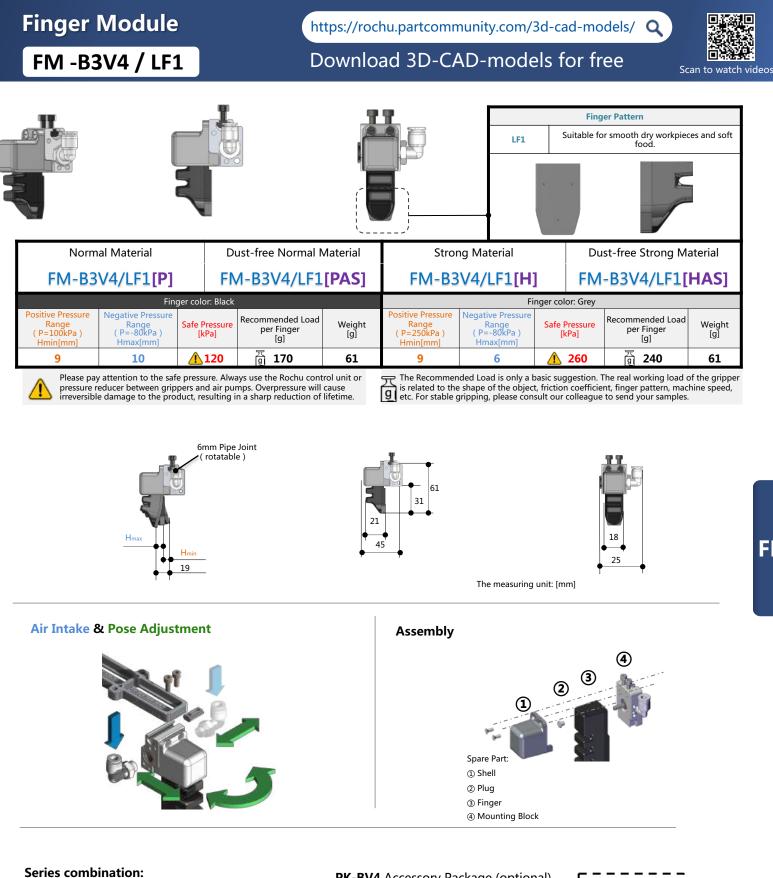
Rochu

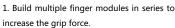
Rochu soft Finger 245



246 Rochu soft Finger

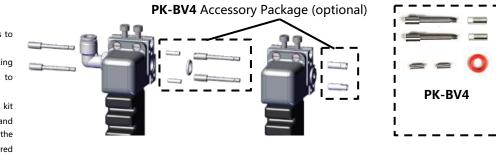
Rochu





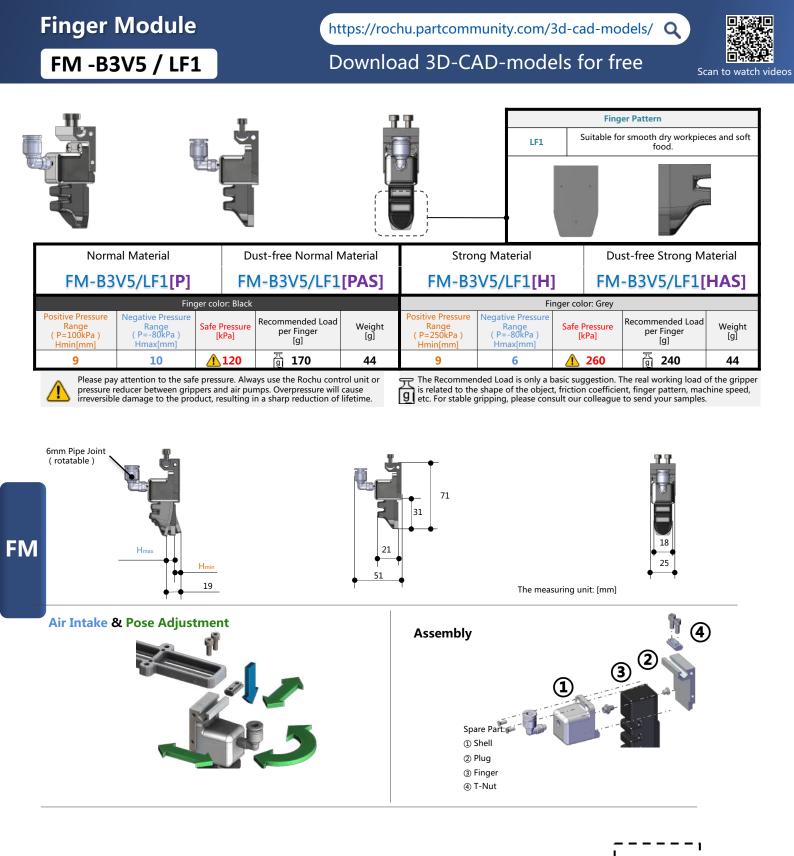
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.





FM



## Series combination:

**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu

Finger I	Module	https://rochu.partcommunity.com/3d-cad-models/ Q						
F -B3T ,	/ LF1	Download 3D-CAD-models for free Sca						
				•				
Finger	Pattern		Features					
LF1	Special Form	Suitable for smooth dry workpieces and soft food.						
Norma	Material	Dust-free Normal Material	Strong Material	Dust-free Strong Material				
F-B3T/LF1[P]		F-B3T/LF1[PAS]						

Positive Pressure Range (P=250kPa) Hmin[mm]

9

21

Weight [g]

11

Finger color: Grey

1 260

The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

Safe Pressure [kPa] Recommended Load

per Finger [g]

240

គ

18

Weight [g]

11

Negative Pressure Range ( P=-80kPa )

Hmax[mm]

6

52

31

Finger color: Black

Safe Pressure

[kPa]

120

Please pay attention to the safe pressure. Always use the Rochu control unit or

pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

Recommended Load

per Finger [g]

**斎 170** 

Hmin

Negative Pressure

Range (P=-80kPa)

Hmax[mm]

10

Hmax

19

**Dimension Parameters** 

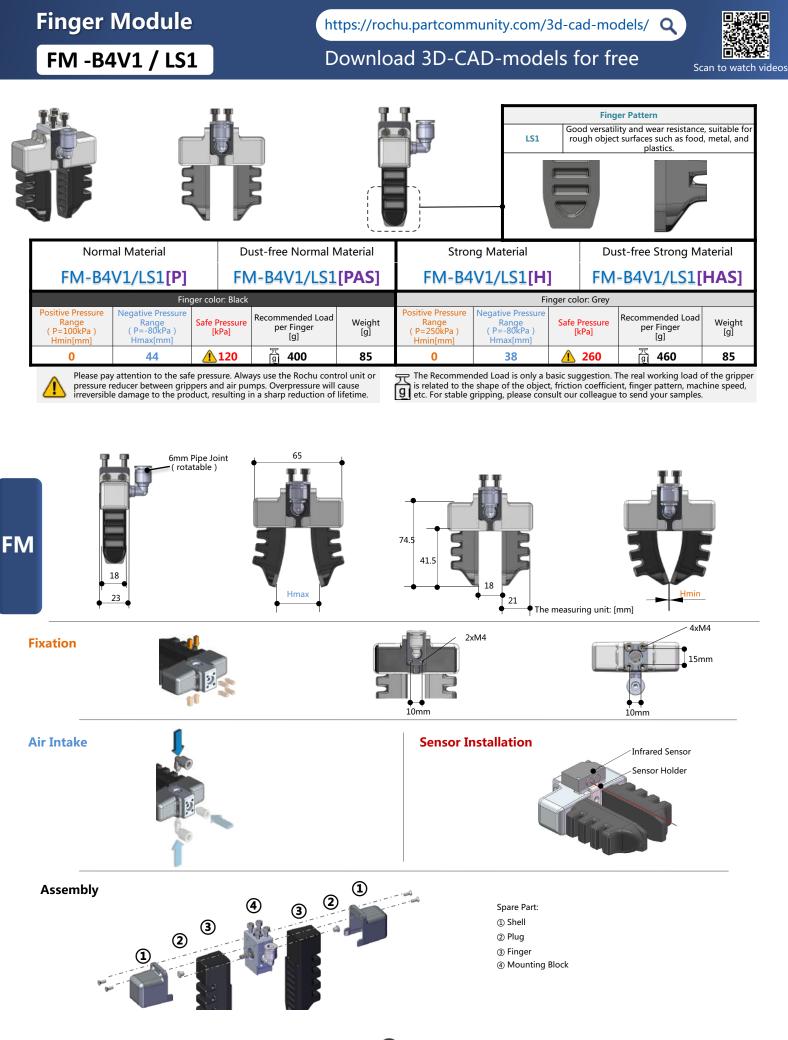
FM

/ideos

Positive Pressure Range (P=100kPa) Hmin[mm]

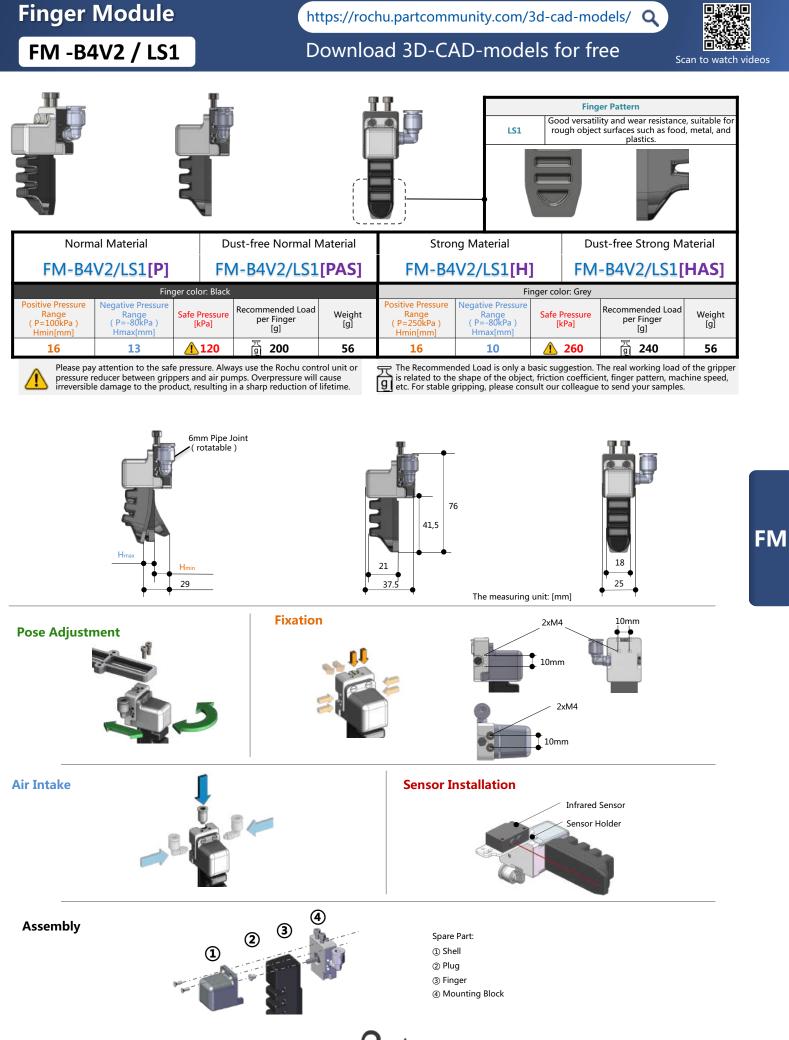
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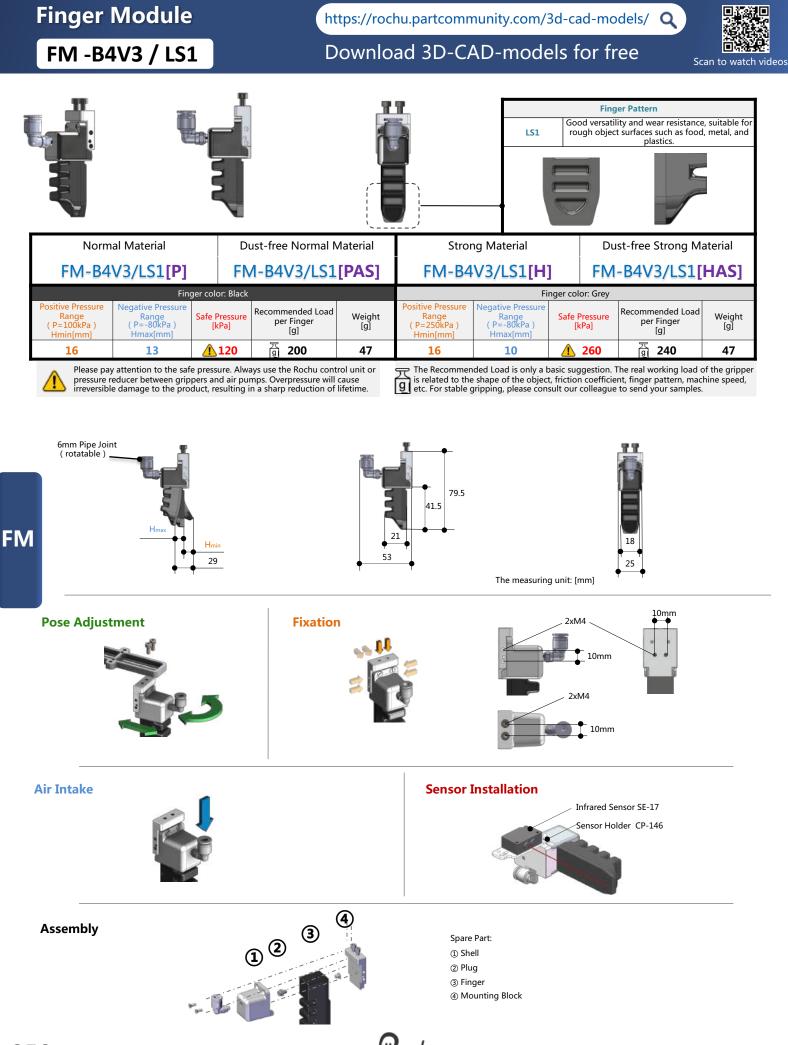
250 Rochu soft Finger

Rochu



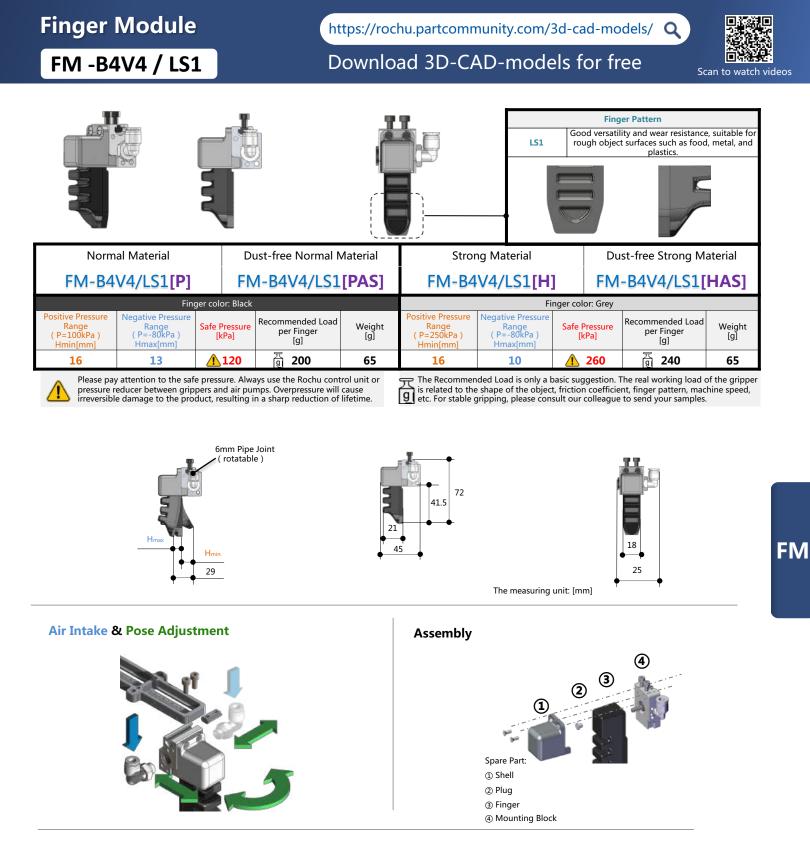
Rochu

Rochu soft Finger 251



252 Rochu soft Finger

Rochu



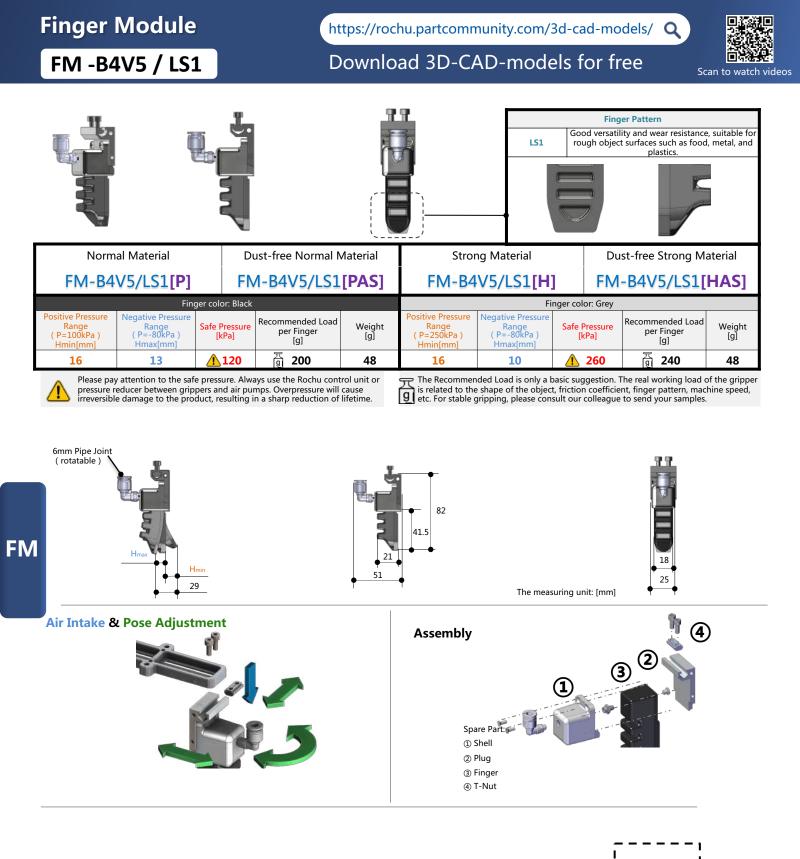
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu



**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



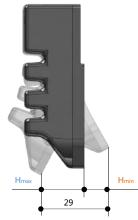
Finger	Module		ht	tps://rocl	hu.partcomm	nunity.com/3	3d-cad-mo	dels/ Q	
F-B4T	/ LS1		D	ownloa	ad 3D-CA	D-mode	els for fr	ee	an to watch vide
				UU ,					
Finge	er Pattern				Fe	atures			
LS1	Standard forr	n	Good versatil	ity and wear res	sistance, suitable for	rough object surfac	es such as food, m	netal, and plastics.	
Norma	al Material	Du	ust-free Normal N	/laterial	Stron	ng Material	Du	st-free Strong M	a travial
		i							aterial
F-B41	T/LS1[P]	F	-B4T/LS1[P	PAS]	F-B4	T/LS1[H]	F	-B4T/LS1[H	
Positive Pressure	Fing Negative Pressure	ger color: Black		-	Positive Pressure	Fin Negative Pressure	nger color: Grey		AS]
	Fin		Recommended Load per Finger [g] () () () () () () () () () () () () ()	Weight		Fi		Recommended Load per Finger [g]	

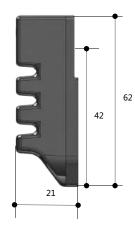
Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

# **Dimension Parameters**

www.rochu.com

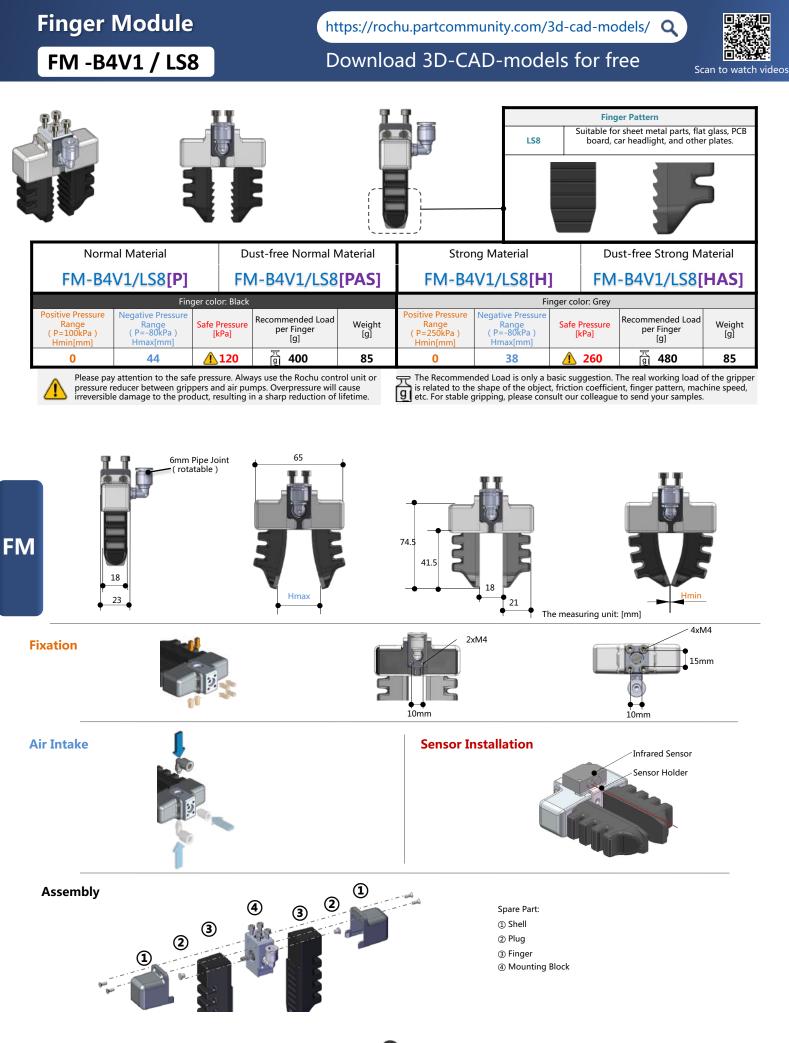




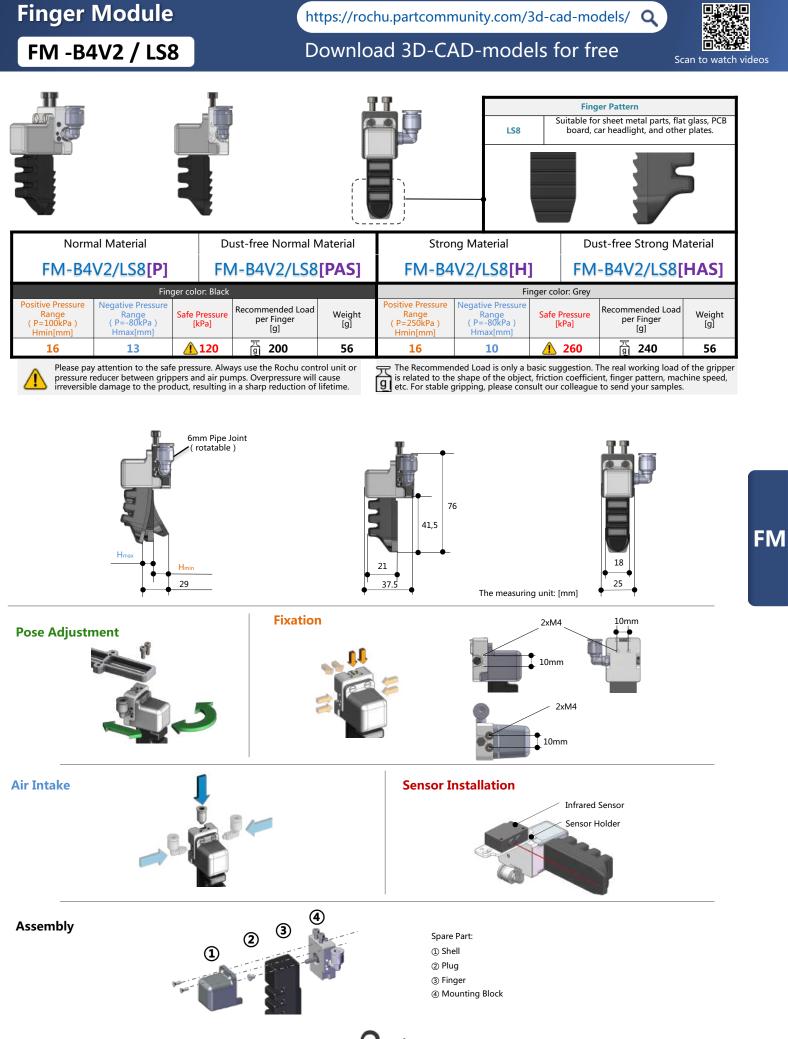
Rochu



FM

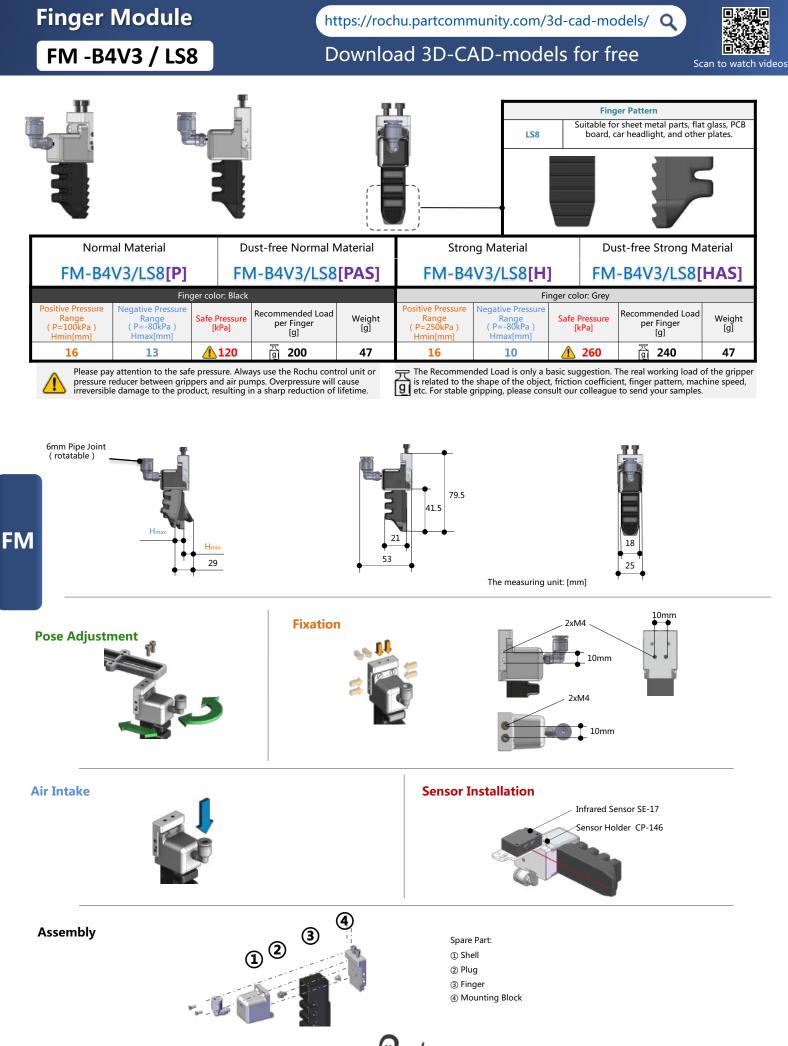


Rochu

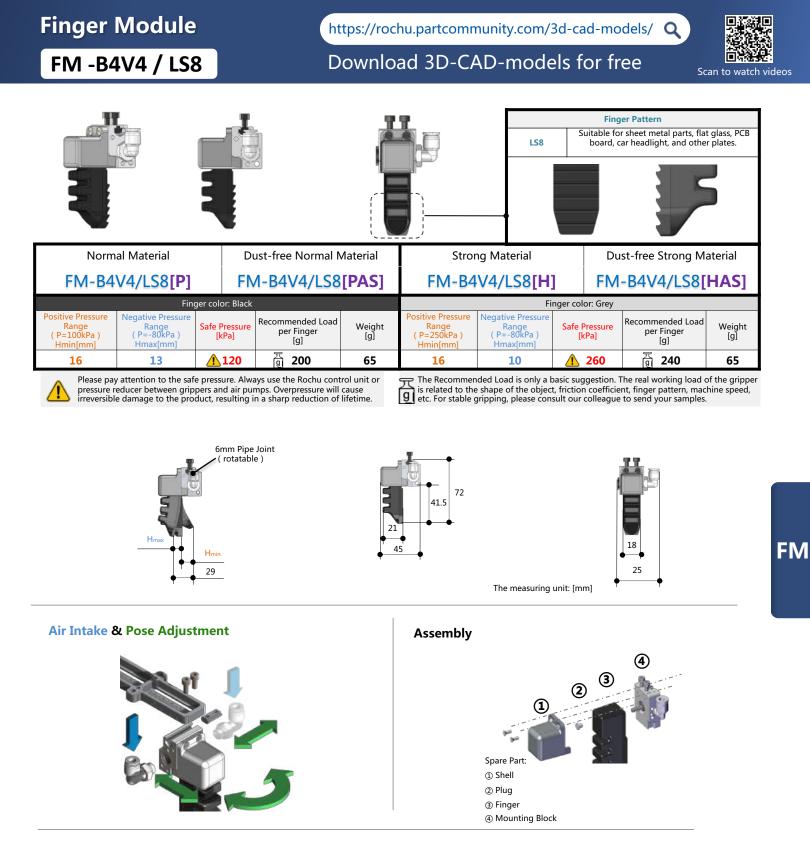


Rochu

Rochu soft Finger 257



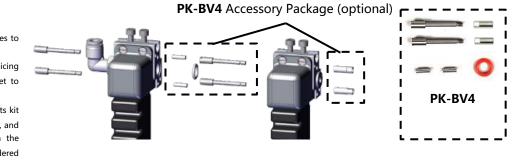
Rochu



1. Build multiple finger modules in series to increase the grip force.

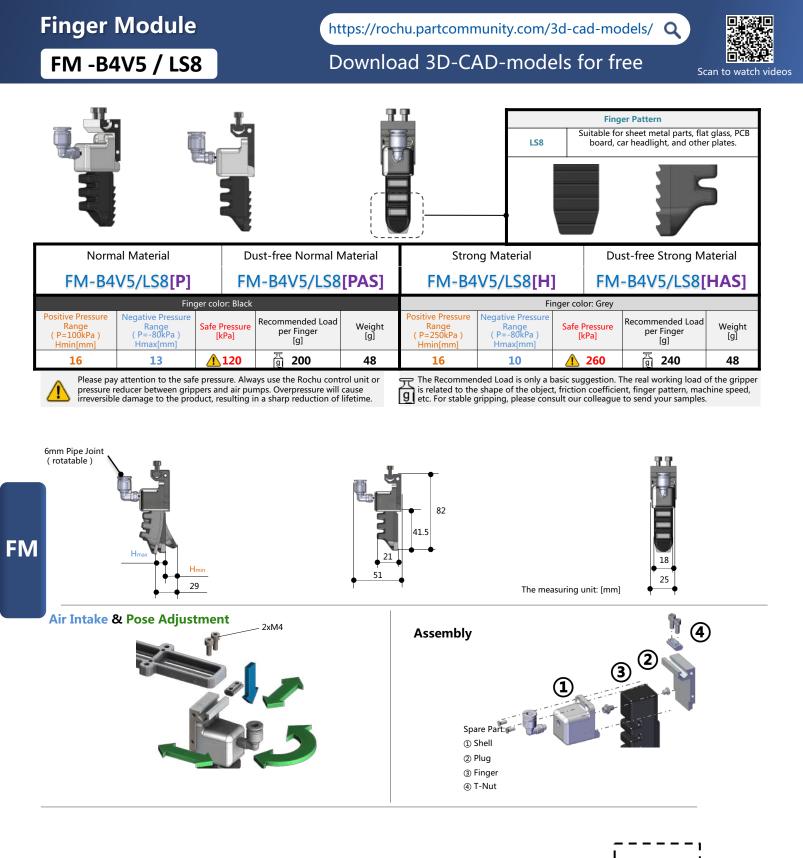
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.











**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

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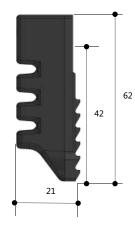
ringer	Module	http	ps://rocl	hu.partcomn	nunity.com/3	3d-cad-mc	odels/ Q		
F -B4T / LS8     Download 3D-CAD-models for free									
			<b>V</b>	L L		0			
Finge	r Pattern			Fe	atures				
Finge	r Pattern Special Form	Suita	able for sheet		s <b>atures</b> ss, PCB board, car he	adlight, and othe	r plates.		
LS8		Suita Dust-free Normal Ma		metal parts, flat glas			er plates. Ist-free Strong M	laterial	
LS8 Norma	Special Form		aterial	metal parts, flat glas	ss, PCB board, car he	Du	•		
LS8 Norma F-B41	Special Form al Material [/LS8[P] Finger co	Dust-free Normal Ma	aterial	metal parts, flat glas Stroi F-B4	ng Material T/LS8[H]	Du	ist-free Strong M		
LS8 Norma	Special Form al Material <b>[/LS8[P]</b> Finger co Negative Pressure	Dust-free Normal Ma	aterial	metal parts, flat glas	ng Material	Du	ist-free Strong M	IAS]	

Prease pay attention of the safe pressure. Always use the round of the of the pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

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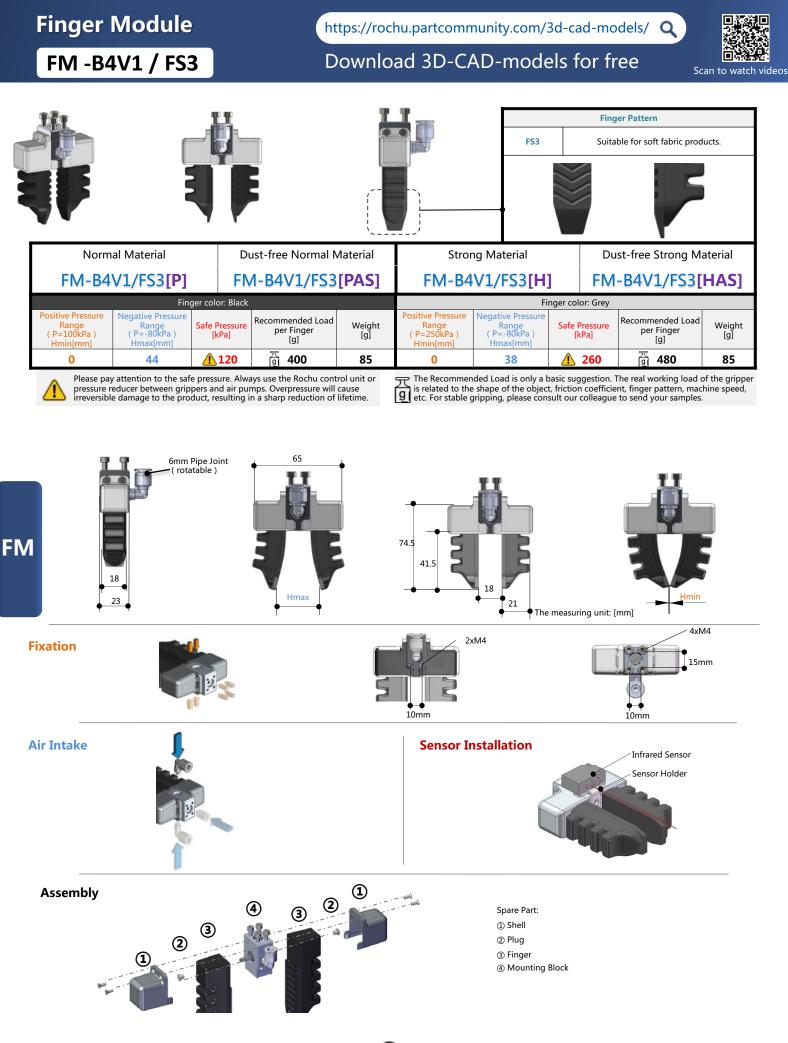
# **Dimension Parameters**



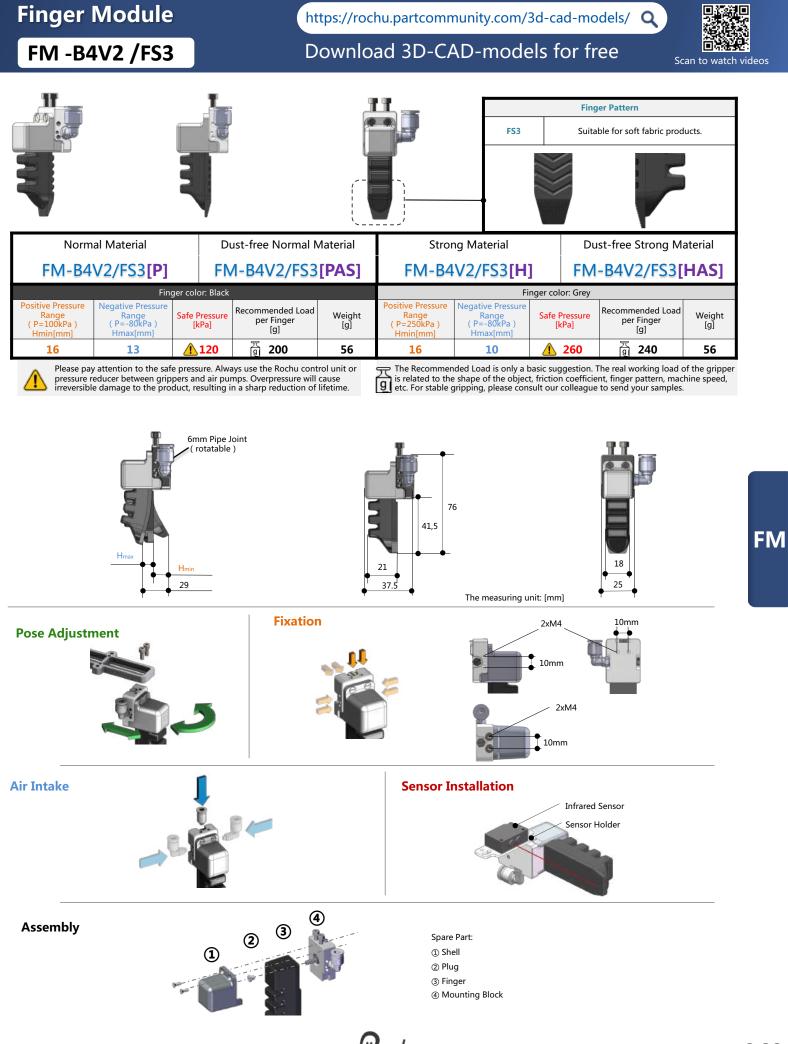




FM

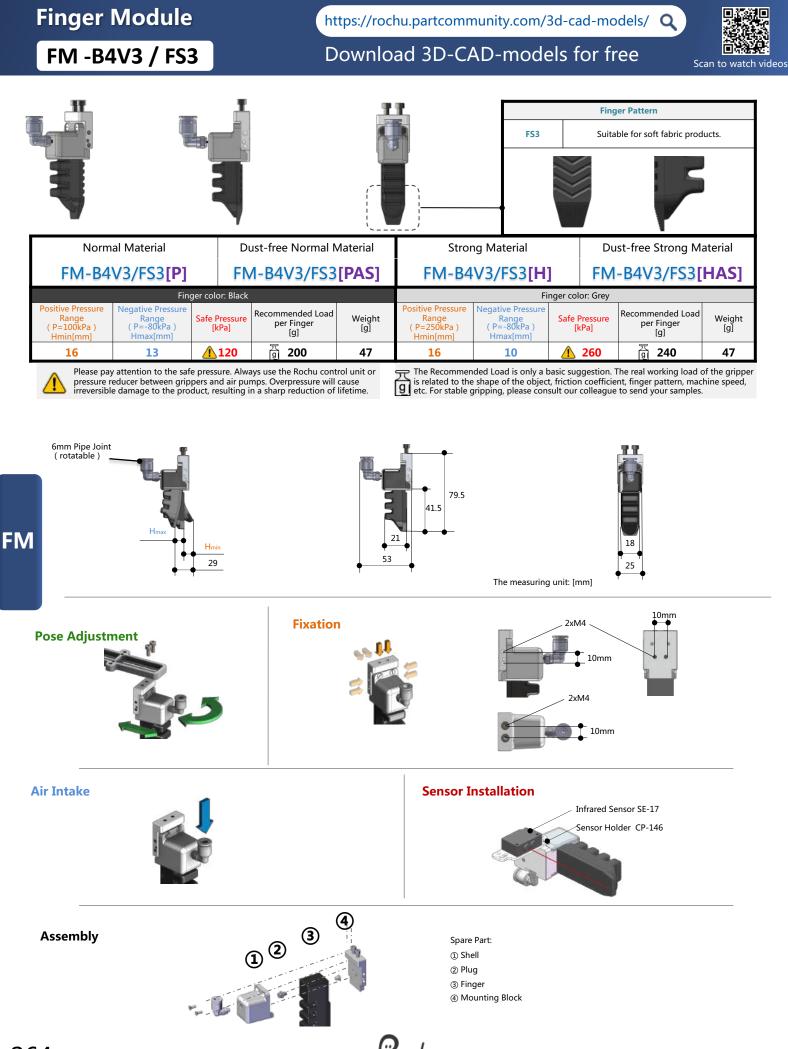


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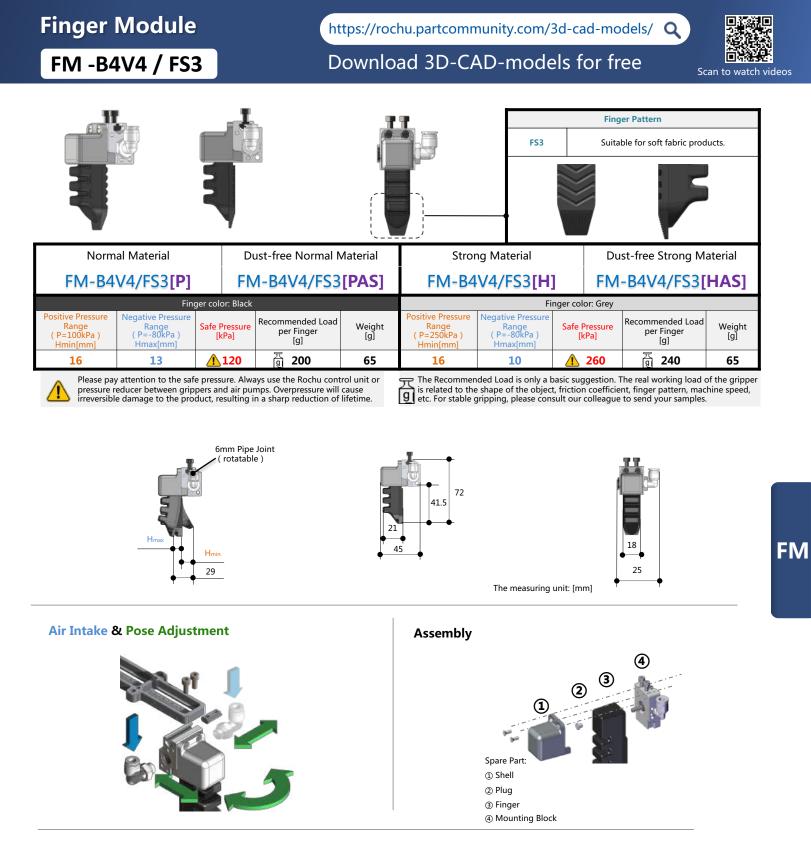


Rochu

Rochu soft Finger 263



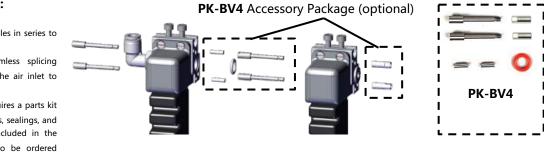
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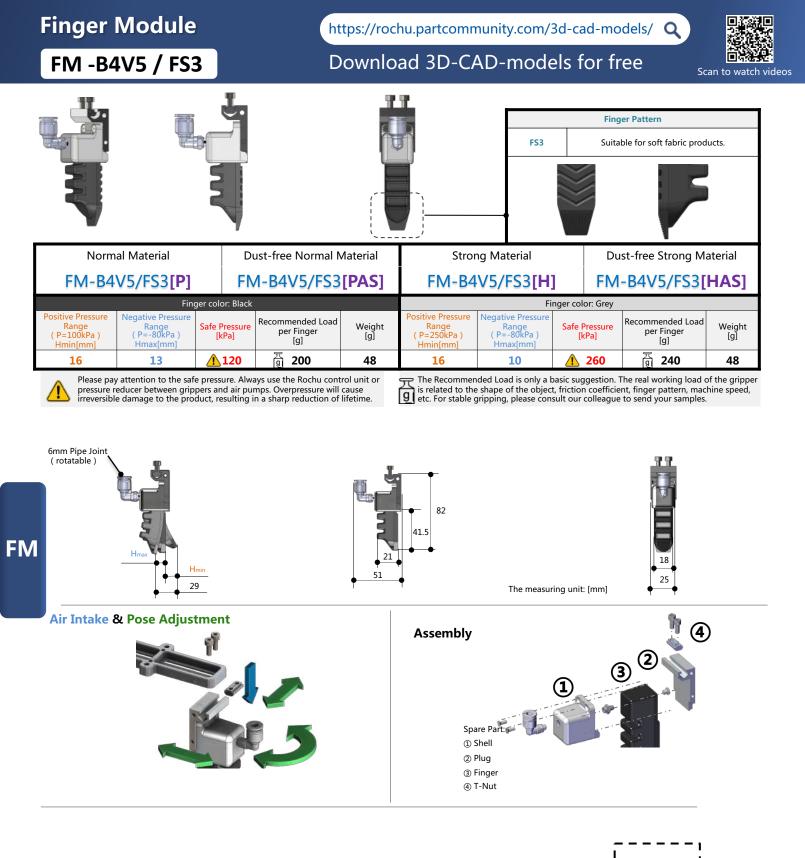
1. Build multiple finger modules in series to increase the grip force.

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Finger l	Module	https://rock	ad-models/ <b>Q</b>					
F-B4T	/ FS3	Download 3D-CAD-models for free Scan to watch video						
Finger	Pattern		Features					
FS3	Special Form		Suitable for soft fabric products.					
Norma	l Material	Dust-free Normal Material	Strong Material	Dust-free Strong Material				
F-B4T	/FS3[ <b>P</b> ]	F-B4T/FS3[PAS]	F-B4T/FS3[H]	F-B4T/FS3[HAS]				
	Finger col							

 
 Positive Pressure Range (P=100kPa) Hmin[mm]
 Negative Pressure Range (P=-80kPa) Hmax[mm]

 16
 13

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

Safe Pressure

[kPa]

120

Recommended Load

per Finger [g]

**斎 200** 

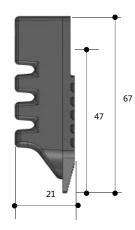
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

1 260

Safe Pressure [kPa]

## **Dimension Parameters**





Positive Pressure Range (P=250kPa) Hmin[mm]

16

Weight [g]

16

Negative Pressure Range ( P=-80kPa )

Hmax[mm]

10



Recommended Load

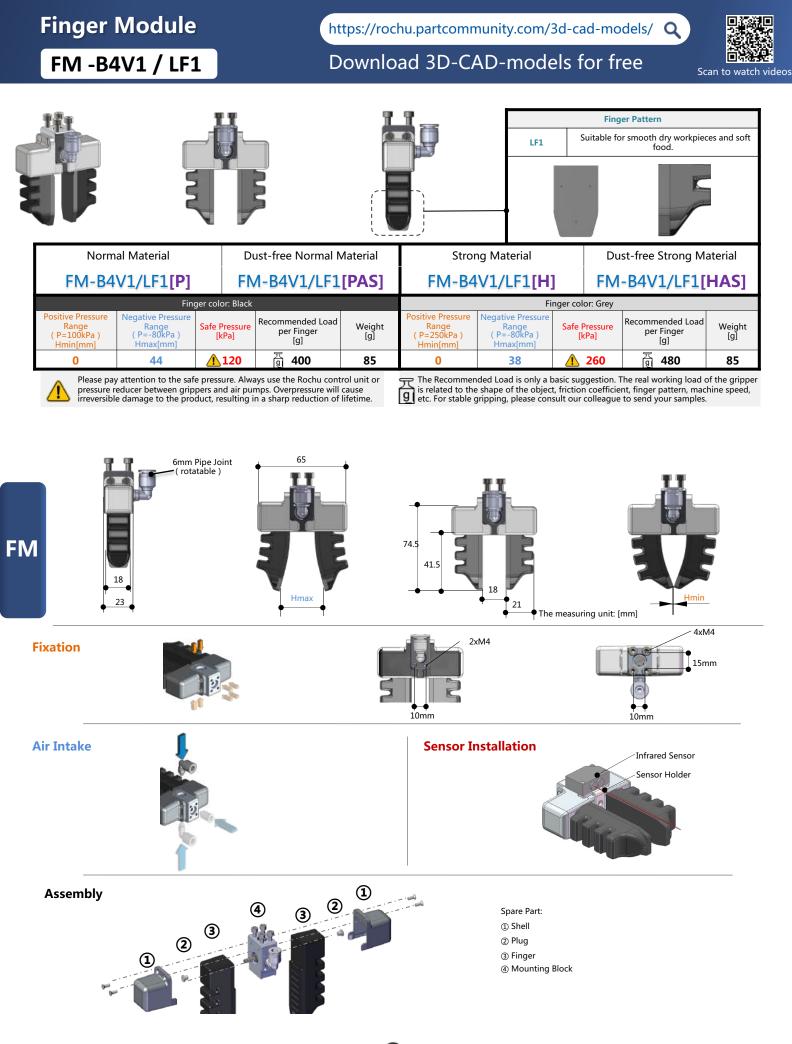
per Finger [g]

240

중

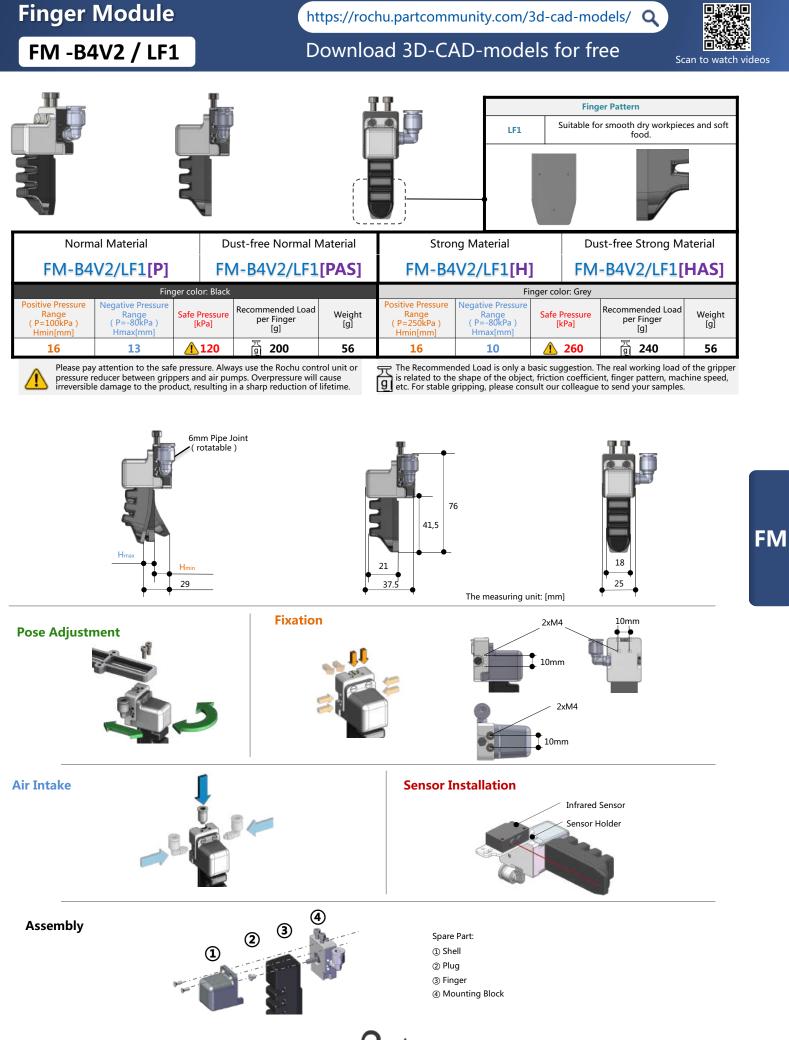
Weight [g]

16



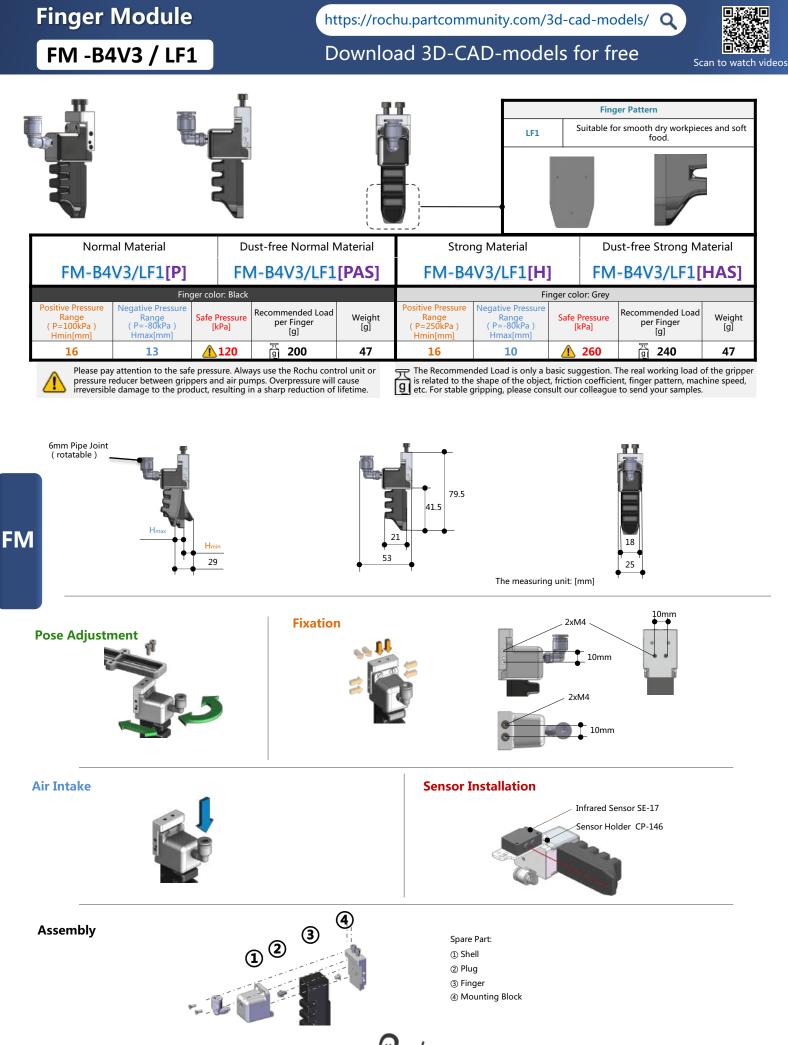
268 Rochu soft Finger



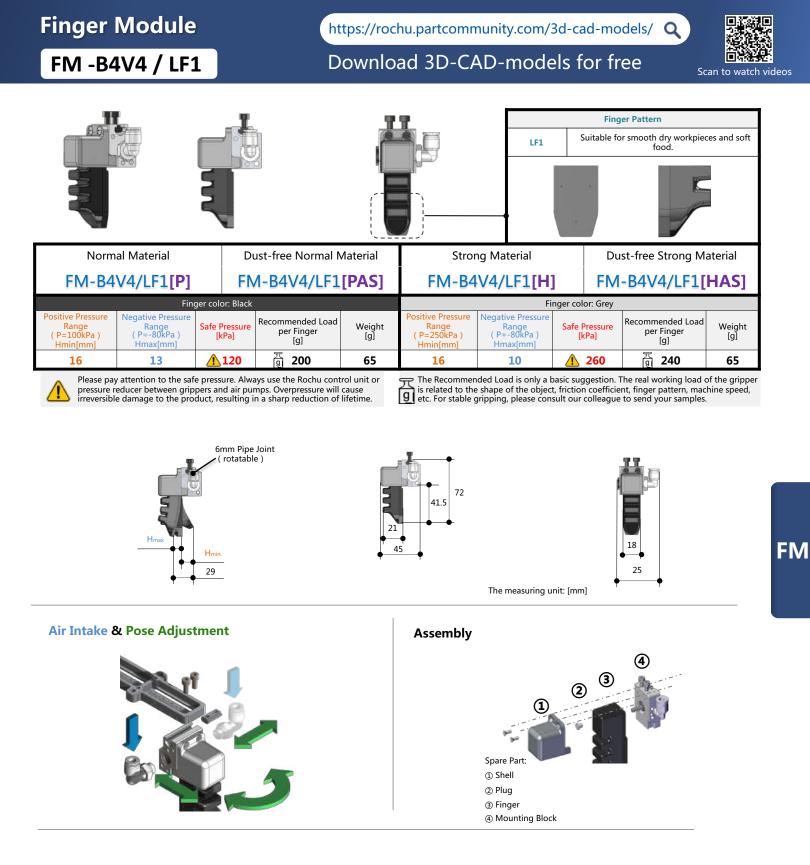


Rochu

Rochu soft Finger 269



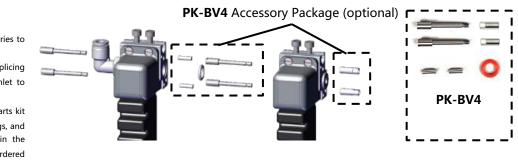
Rochu



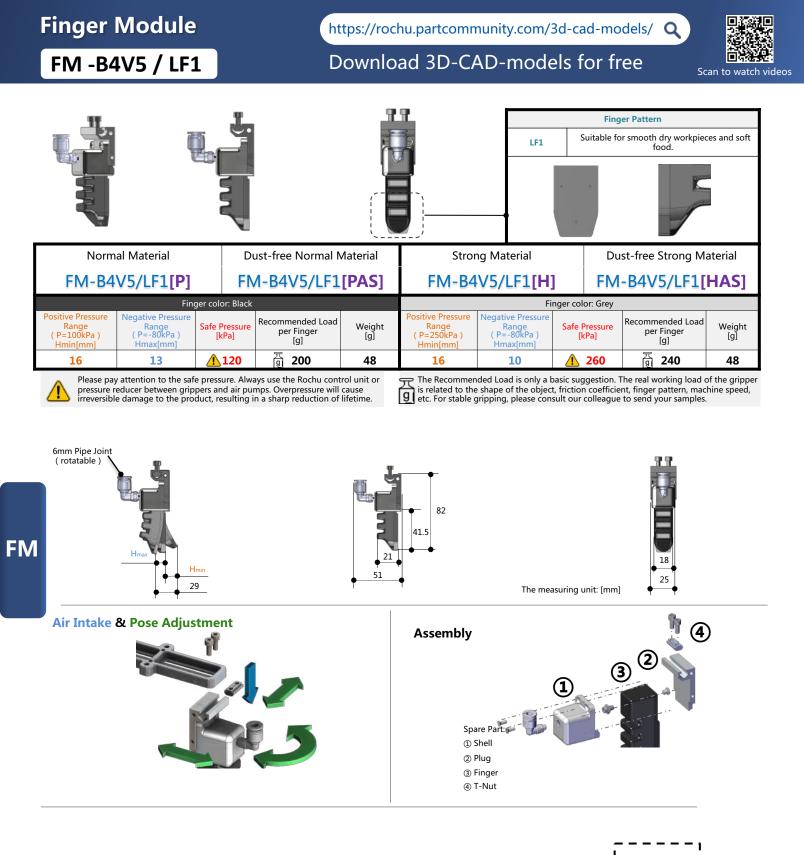
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Rochu





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Finger <b>N</b>	Module	)	ht	ttps://rocl	hu.partcomn	nunity.com/	3d-cad-mc	odels/ Q	
F -B4T	/ LF1		D	ownloa	ad 3D-CA	AD-mode	els for fr	ee so	can to watch vide
				<u>vv</u>					
Finger	Pattern				Fe	atures			
LF1	Special Form			S	uitable for smooth o	dry workpieces and s	soft food.		
Norma	Material	Du	ust-free Normal N	Aaterial	Stror	ng Material	Du	ist-free Strong M	aterial
F-B4T	/LF1[P]		F-B4T/LF1[PAS] F-B4T/LF1[H] F-B4T/LF1[HAS]					AS]	
		ger color: Black					nger color: Grey	1	
Positive Pressure Range (P=100kPa) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range (P=250kPa) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]



16

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

120

**斎 200** 

The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

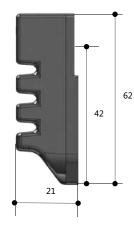
1 260

10

## **Dimension Parameters**

13





16

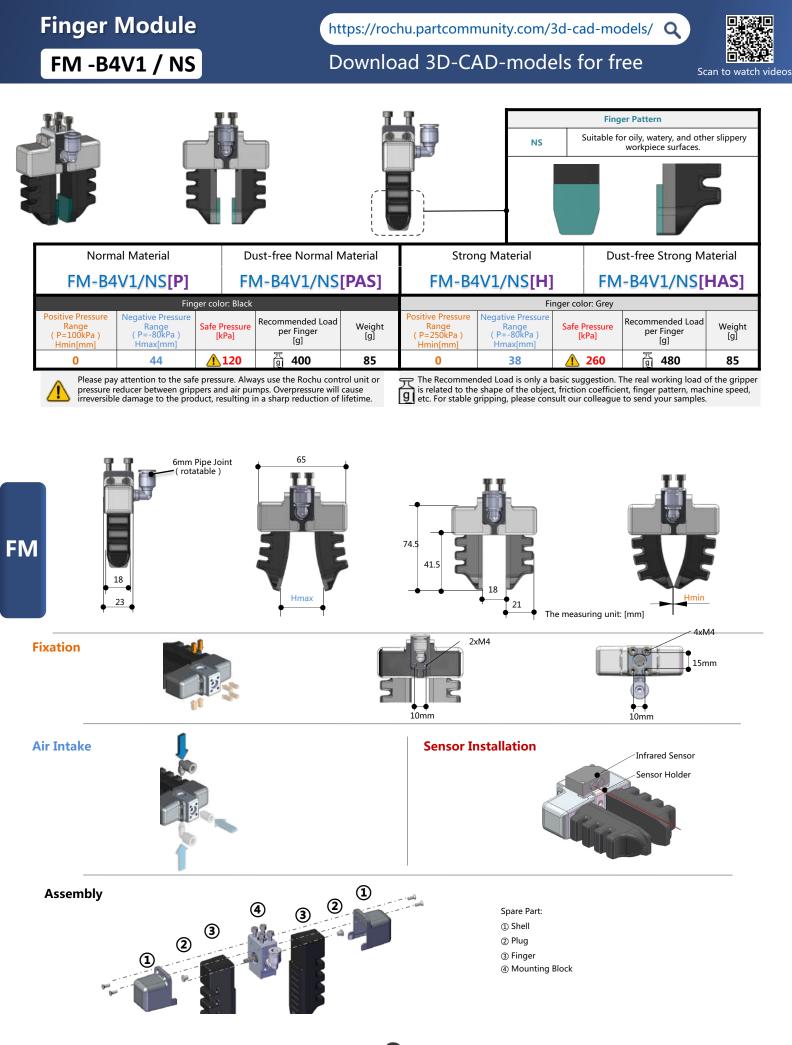
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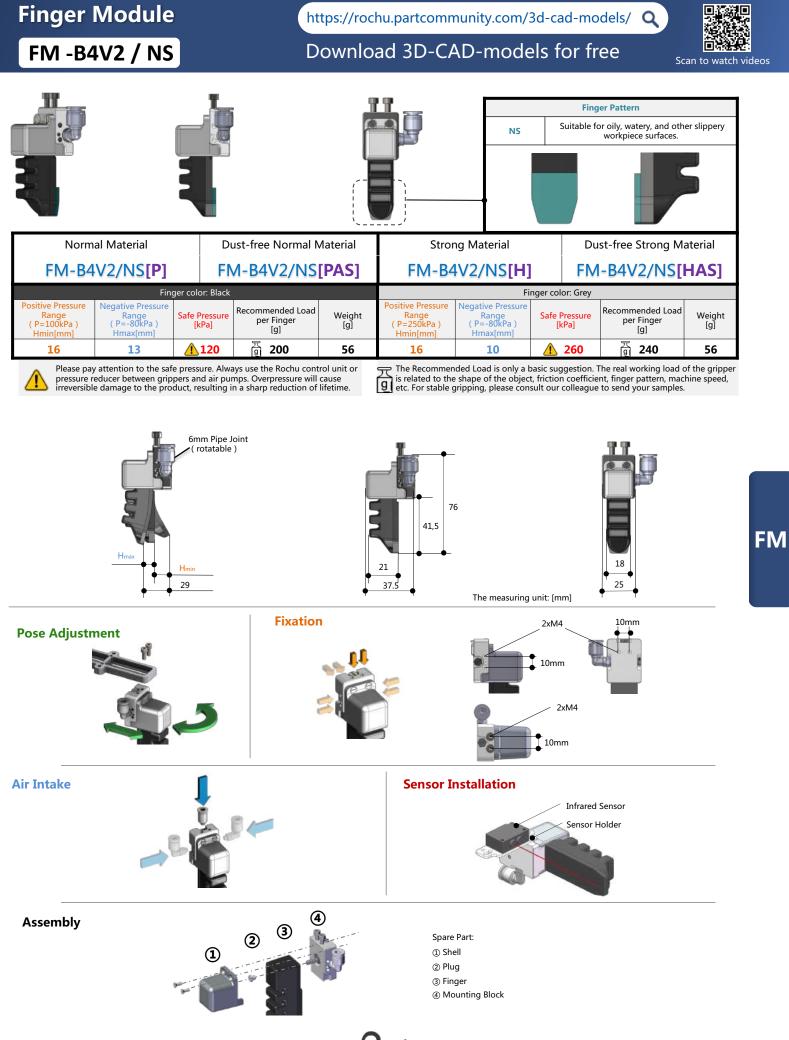
历

240

16

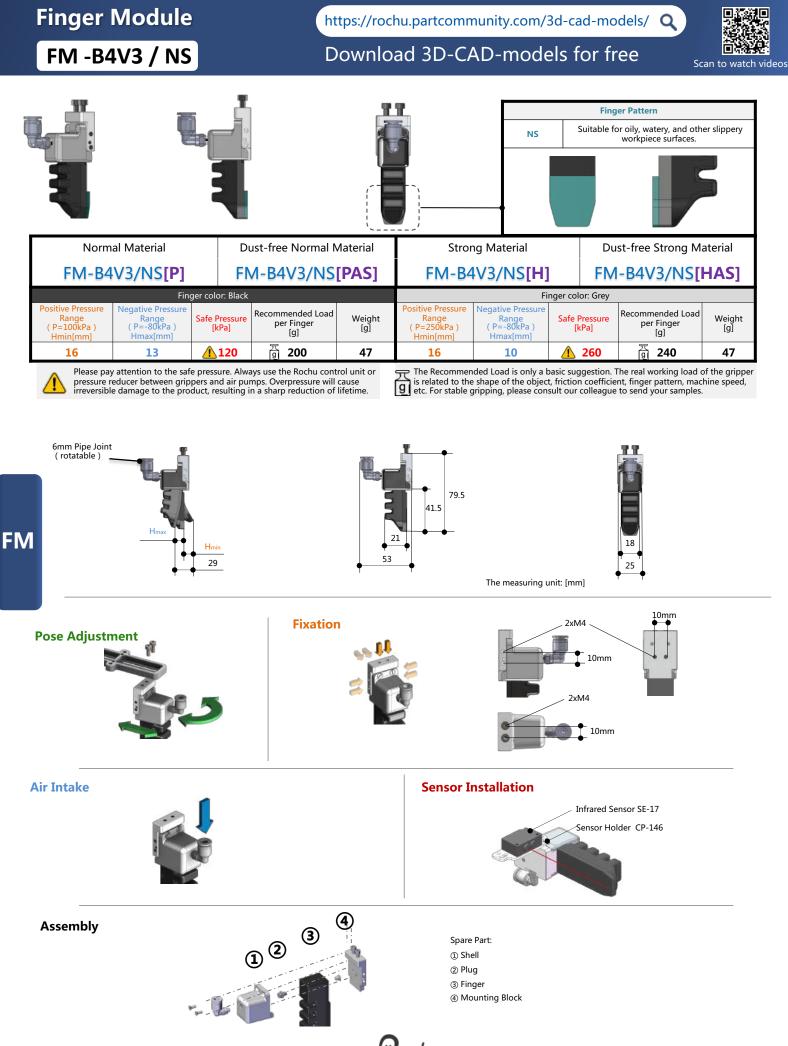




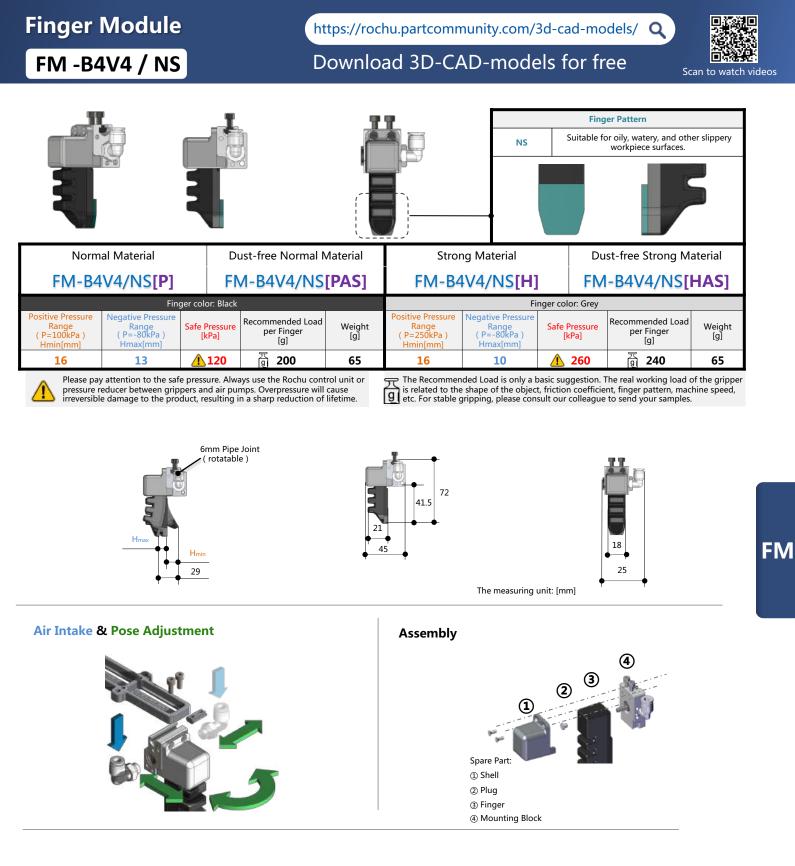


Rochu

Rochu soft Finger 275



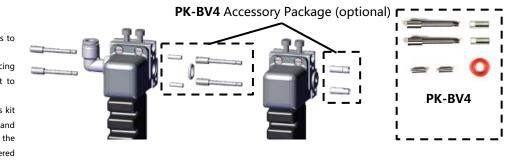
Rochu



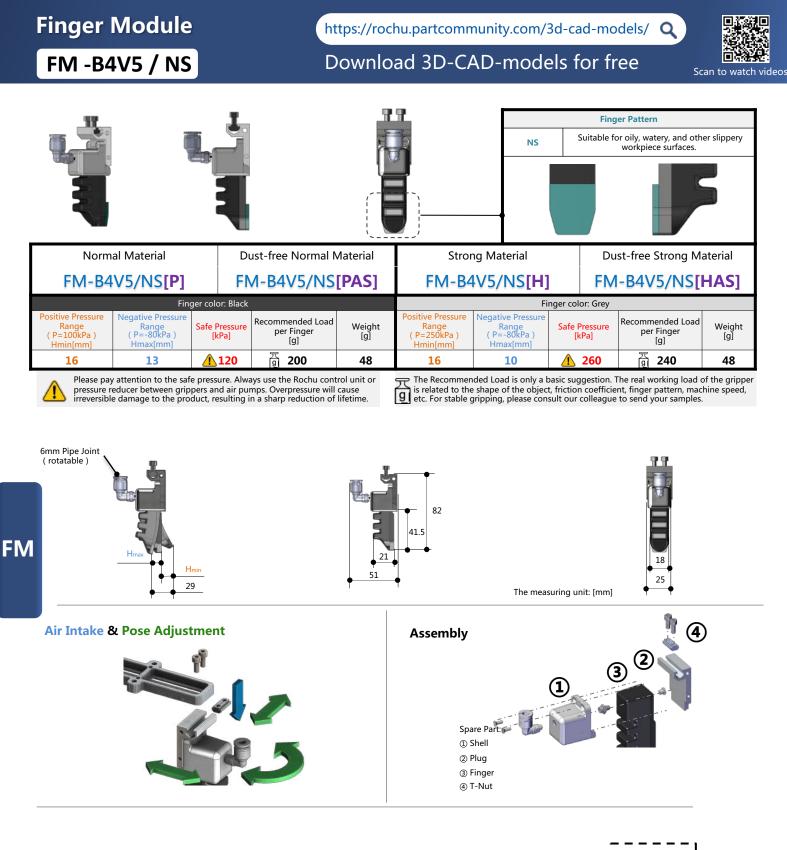
1. Build multiple finger modules in series to increase the grip force.

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Rochu



278 Rochu soft Finger

**1**. Build multiple finger modules in series to increase the grip force.

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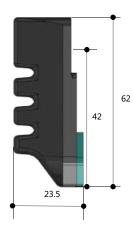


Finger	Module	https://re	ochu.partcommunity.com	/3d-cad-mo	odels/ Q	
F -B4T	/ NS	Downl	oad 3D-CAD-mod	els for fi	ree	can to watch v
Finge	er Pattern		Features			
Finge	er Pattern Special Form	Suit	Features able for oily, watery, and other slippery wo	orkpiece surfaces.		
NS		Suit			ust-free Strong N	laterial
NS Norma	Special Form		able for oily, watery, and other slippery wo	Du	ust-free Strong M -B4T/LS1[H	
NS Norma <b>F-B4</b> 1	Special Form al Material T/LS1[P] Finger co	Dust-free Normal Material F-B4T/LS1[PAS]	able for oily, watery, and other slippery wo Strong Material F-B4T/LS1[H]	Finger color: Grey	B4T/LS1[H	IAS]
NS Norma	Special Form al Material T/LS1[P] Finger cc Negative Pressure Range	Dust-free Normal Material F-B4T/LS1[PAS]	able for oily, watery, and other slippery wo Strong Material F-B4T/LS1[H] Positive Pressure Negative Pressure	Finger color: Grey	Ū.	IAS]

irreversible damage to the product, resulting in a sharp reduction of lifetime. - - |---,

# **Dimension Parameters**



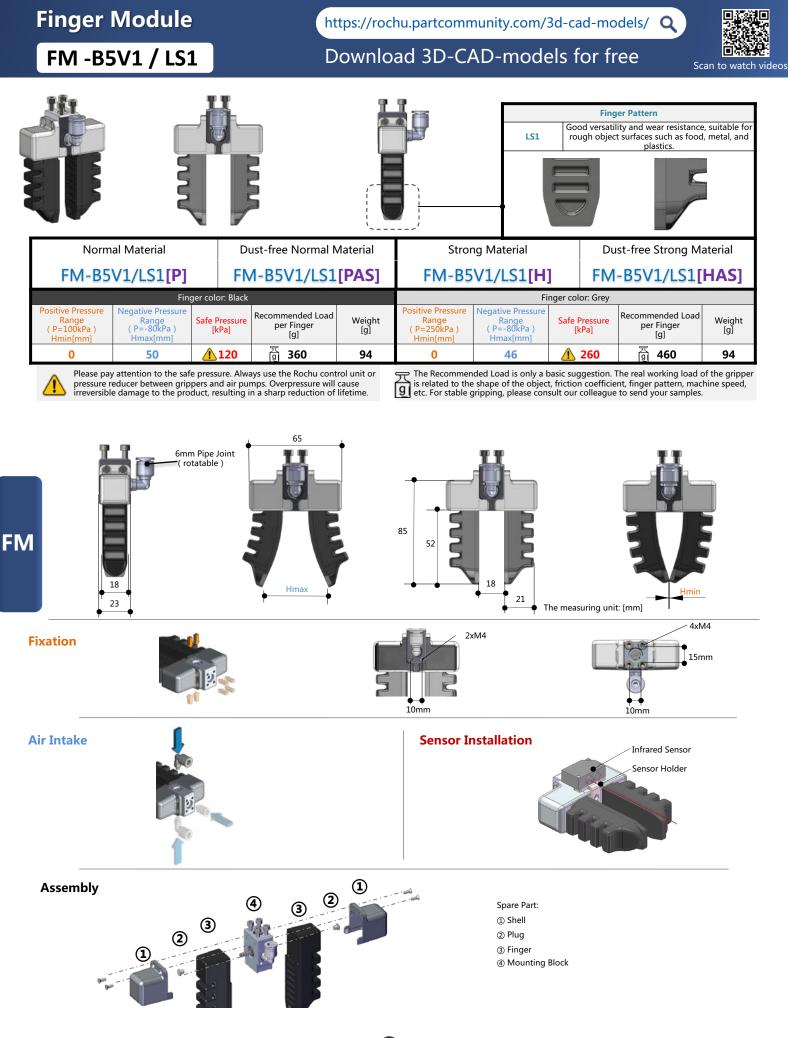




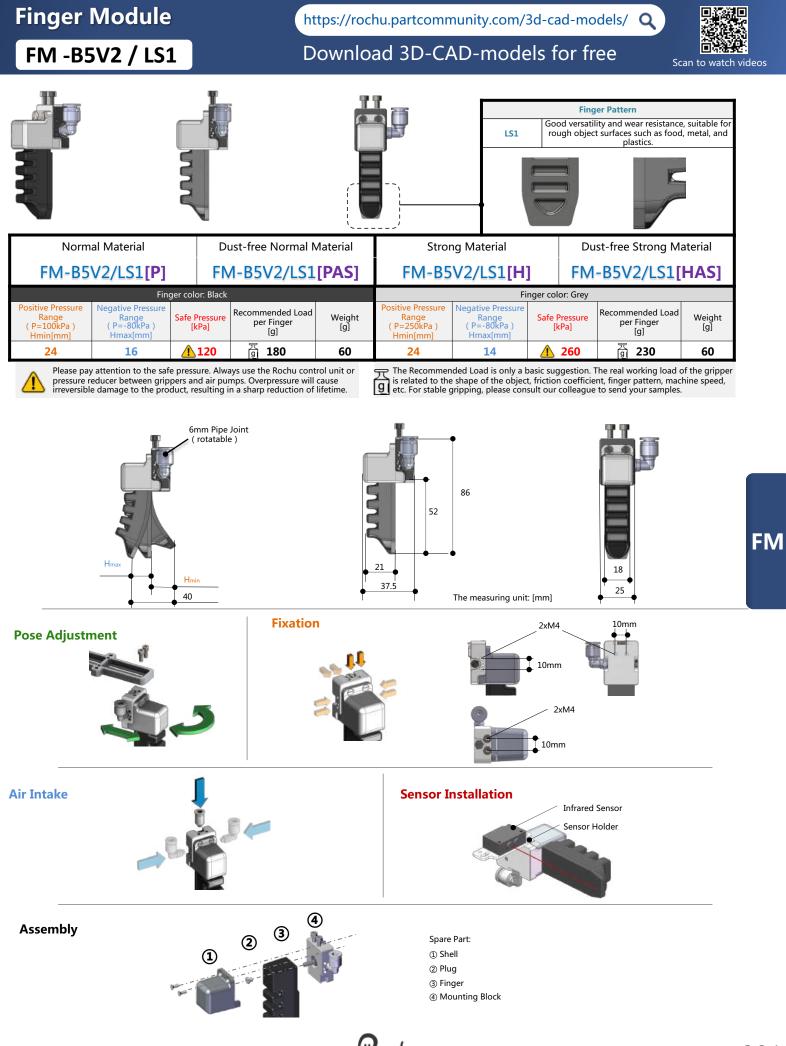
FM

eos



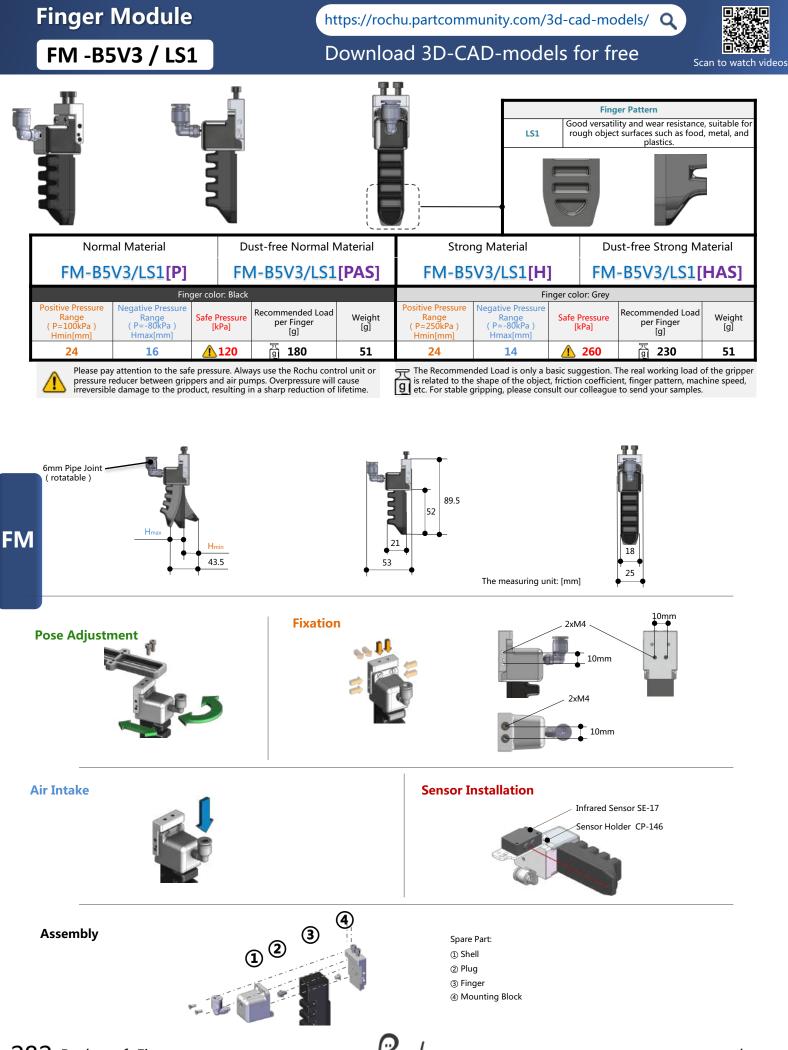


Rochu

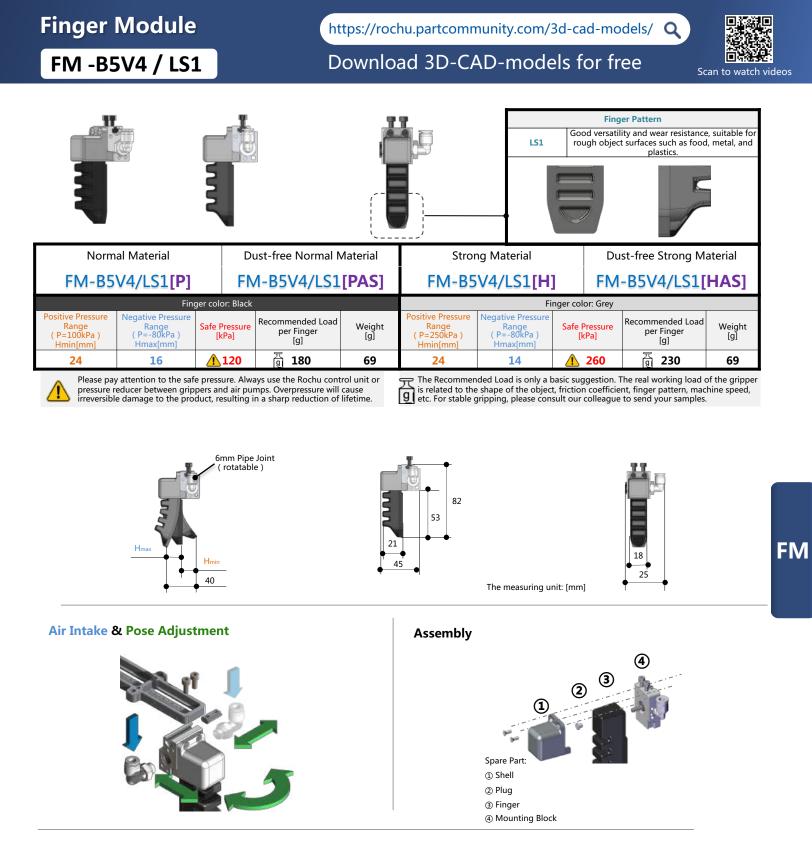


Rochu

Rochu soft Finger 281



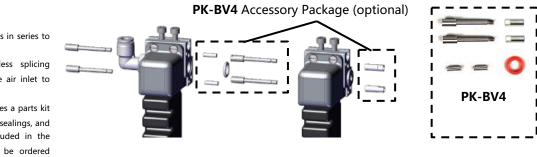
Rochu



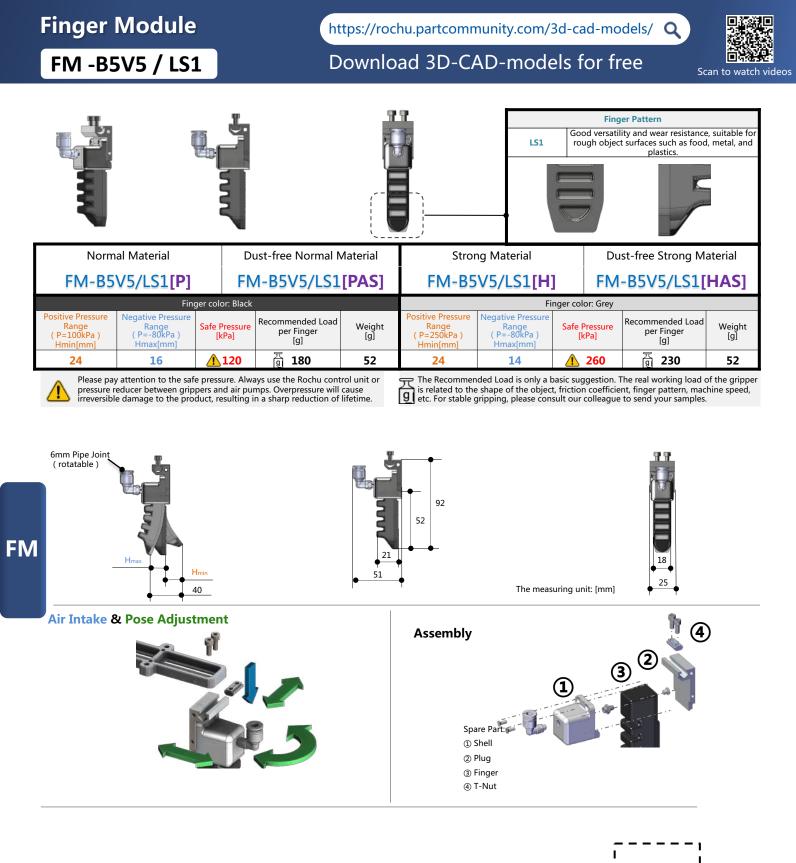
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Rochu





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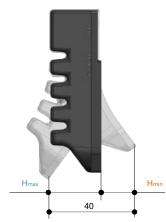
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-BV5 Accessory Package (optional)

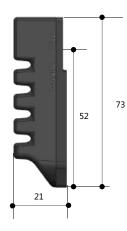
Rochu

Finger Module       https://rochu.partcommunity.com/3d-cad-models/ Q									
F -B5T	/ LS1		D	ownlo	ad 3D-CA	AD-mode	els for fr	ree <sub>s</sub>	can to watch vid
				,					
Finger	r Pattern				Fe	atures			
LS1	Standard for	n	Good versati	lity and wear res	sistance, suitable for	rough object surfac	tes such as food, ι	metal, and plastics.	
Norma	al Material	Dı	ust-free Normal N	Material	Stro	ng Material	Du	ust-free Strong N	laterial
F-B5T	/LS1[ <b>P</b> ]	F	F-B5T/LS1[F	PAS]	F-B5	T/LS1[H]	F	-B5T/LS1[H	AS]
		ger color: Black				1	nger color: Grey		
Positive Pressure Range	Negative Pressure	Safe Pressure	Recommended Load	Weight	Positive Pressure Range	Negative Pressure Range (P=-80kPa)	Safe Pressure	Recommended Load per Finger	Weight
(P=100kPa) Hmin[mm]	Range ( P=-80kPa ) Hmax[mm]	[kPa]	per Finger [g] 页 <b>180</b>	[g]	(P=250kPa) Hmin[mm]	(P=-80kPa) Hmax[mm]	[kPa]	[g] [g] [g] 230	[g]

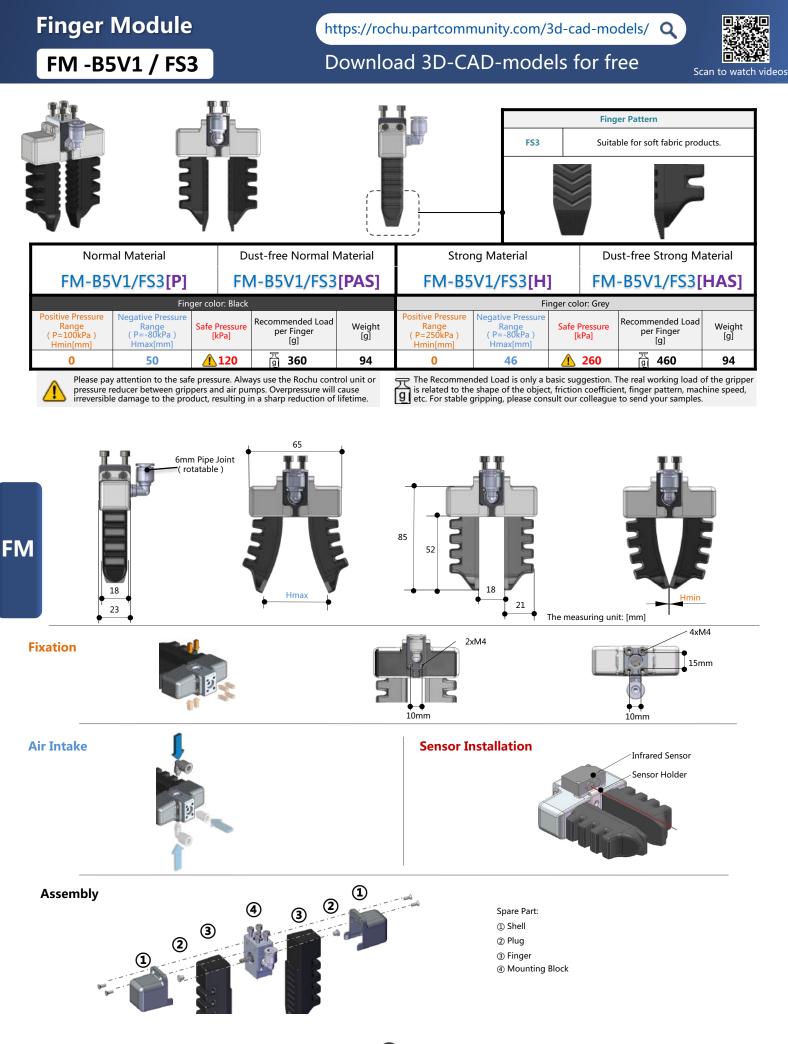
Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

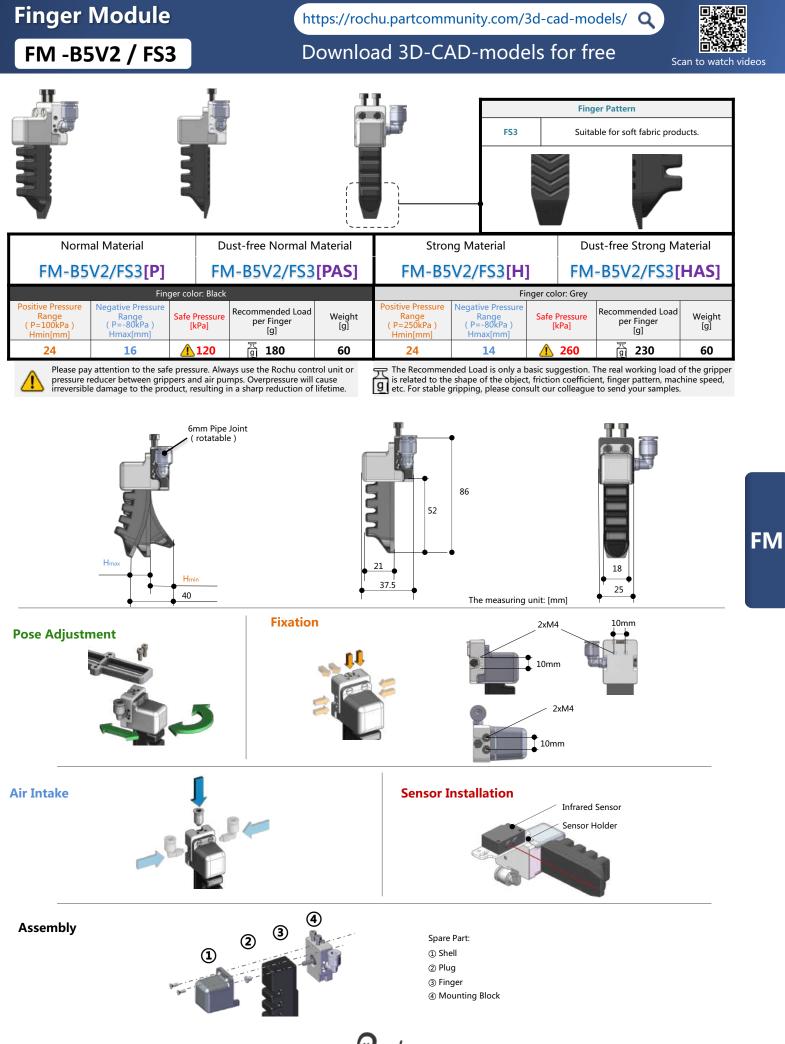
# **Dimension Parameters**





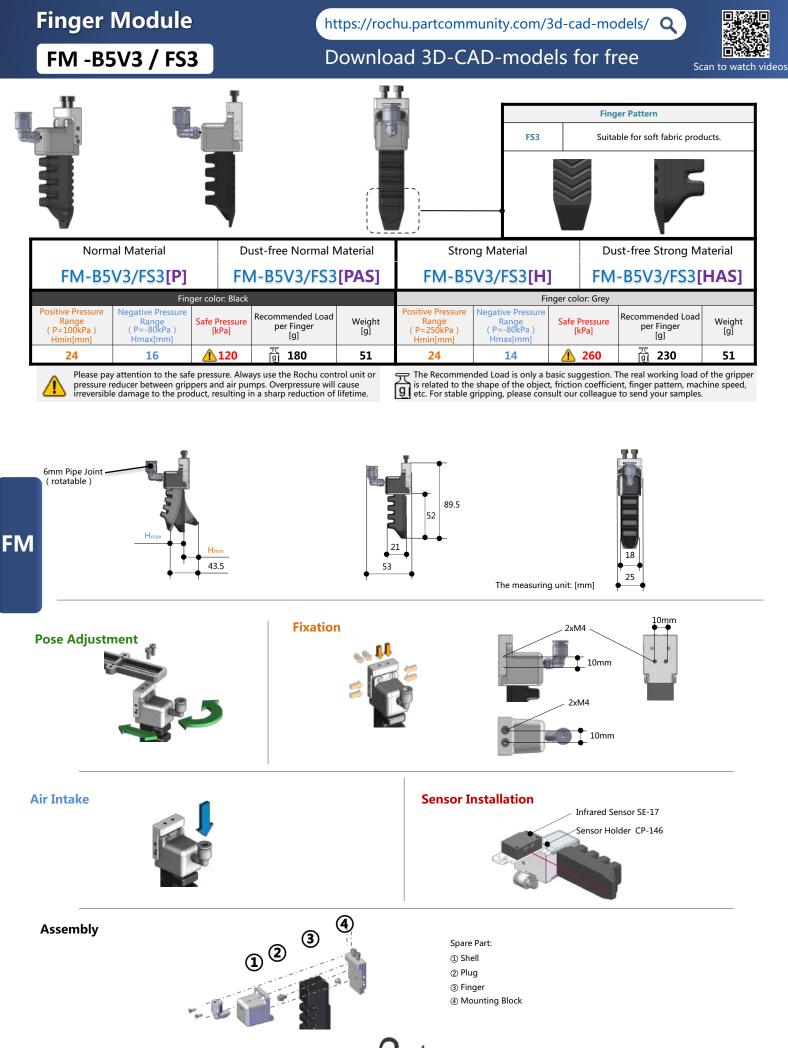




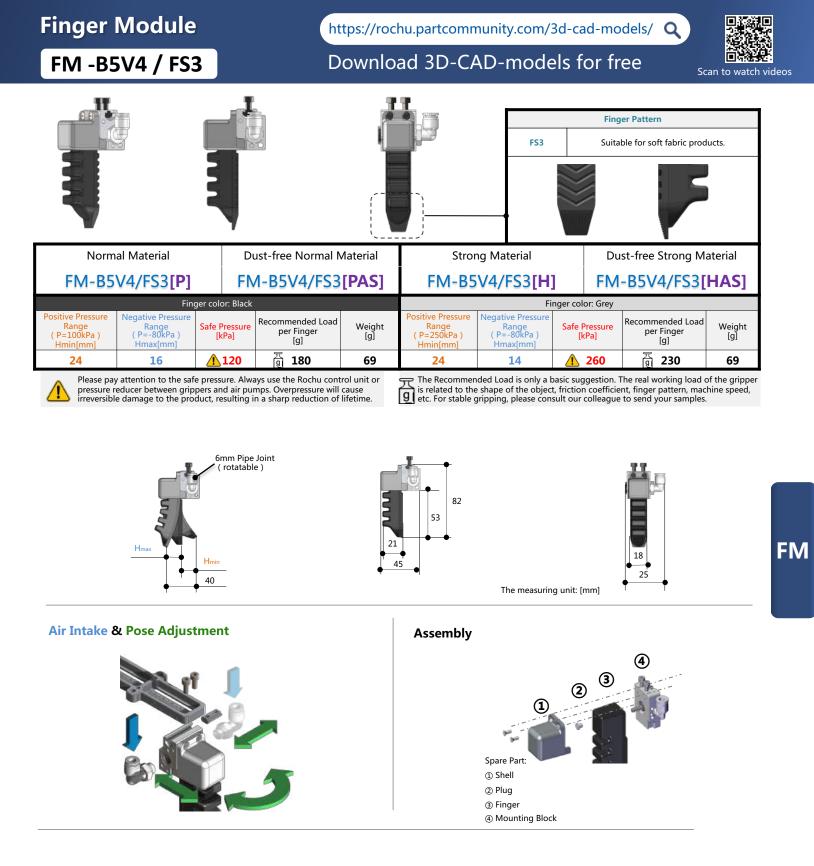


Pochu

Rochu soft Finger 287



Rochu

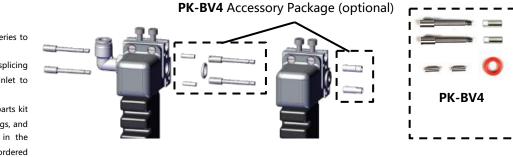


### Series combination:

1. Build multiple finger modules in series to increase the grip force.

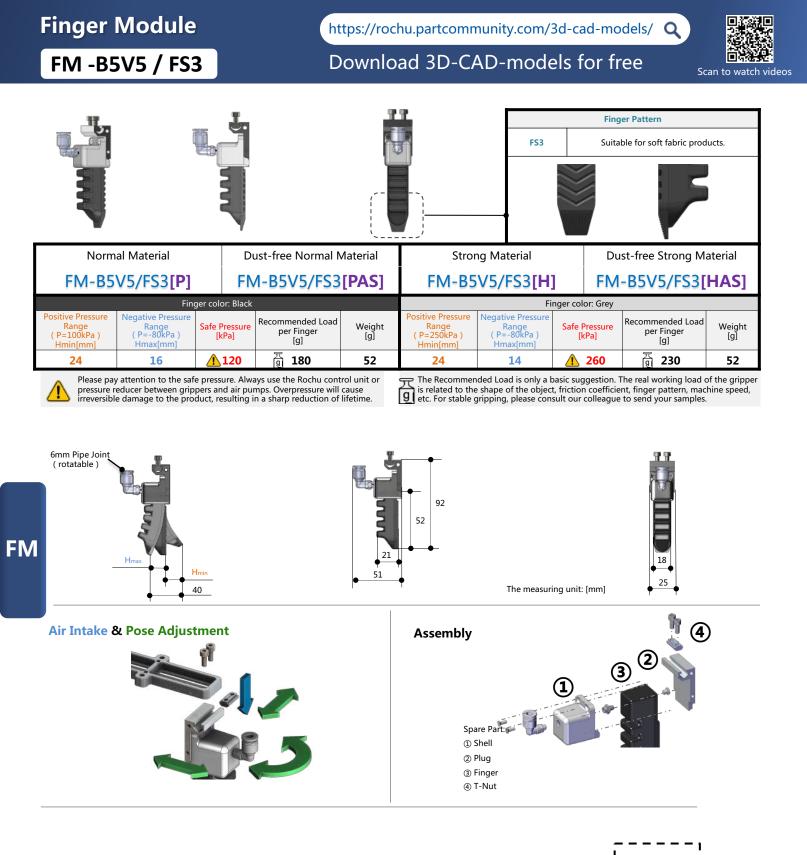
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.









#### Series combination:

290 Rochu soft Finger

**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.





Finger	Module		https://rochu.partcommunity.com/3d-cad-models/ Q							
F -B5T	/ FS3		D	ownloa	ad 3D-CA	D-mode	els for fr	ee so	an to watch video	
					N					
Finge	r Pattern				Fe	atures				
FS3	Special Form				Suitable for s	oft fabric products.				
Normal Material		Du	ust-free Normal N	Strong Material		Du	Dust-free Strong Material			
F-B5T	/FS3[ <b>P</b> ]	F	-B5T/FS3[P	F-B5T/FS3[H] F-			-B5T/FS3[H	AS]		
		er color: Black						lor: Grey		
Positive Pressure Range (P=100kPa)         Negative Pressure Range (P=-80kPa)         Safe Pressure [kPa]           Hmin[mm]         Hmax[mm]         Hmax[mm]         Safe Pressure [kPa]			Recommended Load Weight Positive Pressure Range Safe Pressure Recommended Load Destination Pressure Recommended Positive Po						Weight	

24

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

<u>120</u>

<u>–</u> 180 20

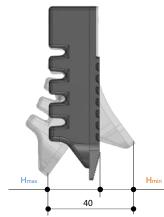
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

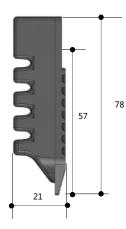
260

14

# **Dimension Parameters**

16





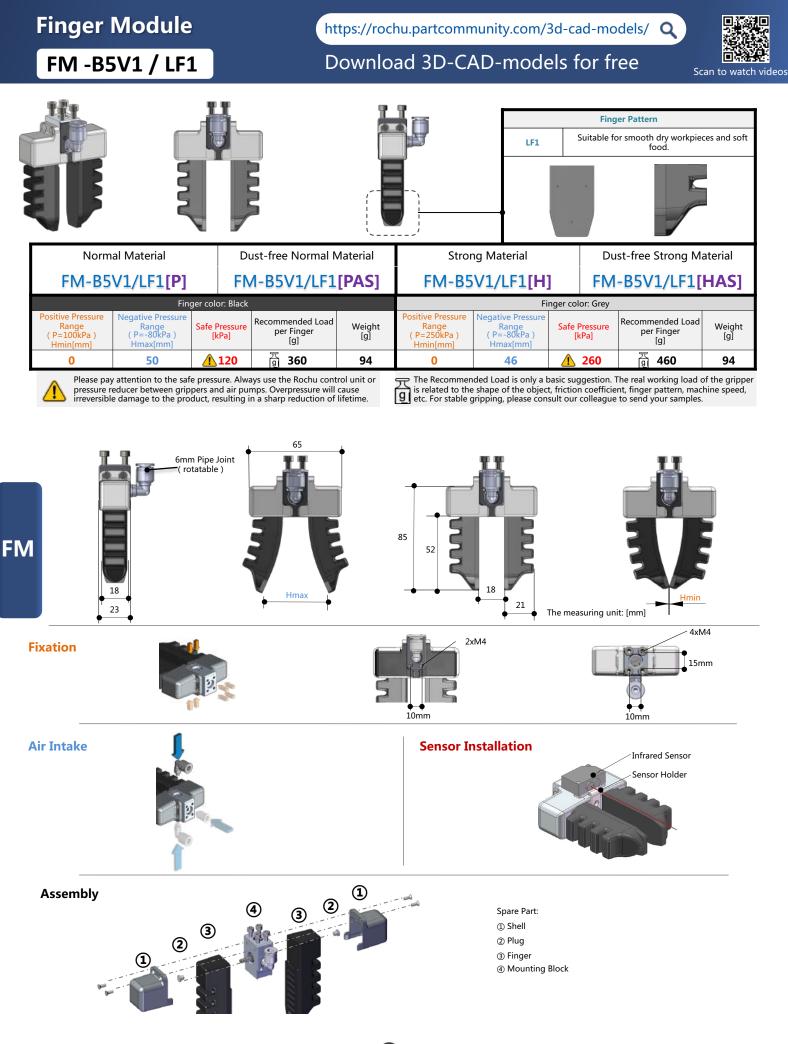
24



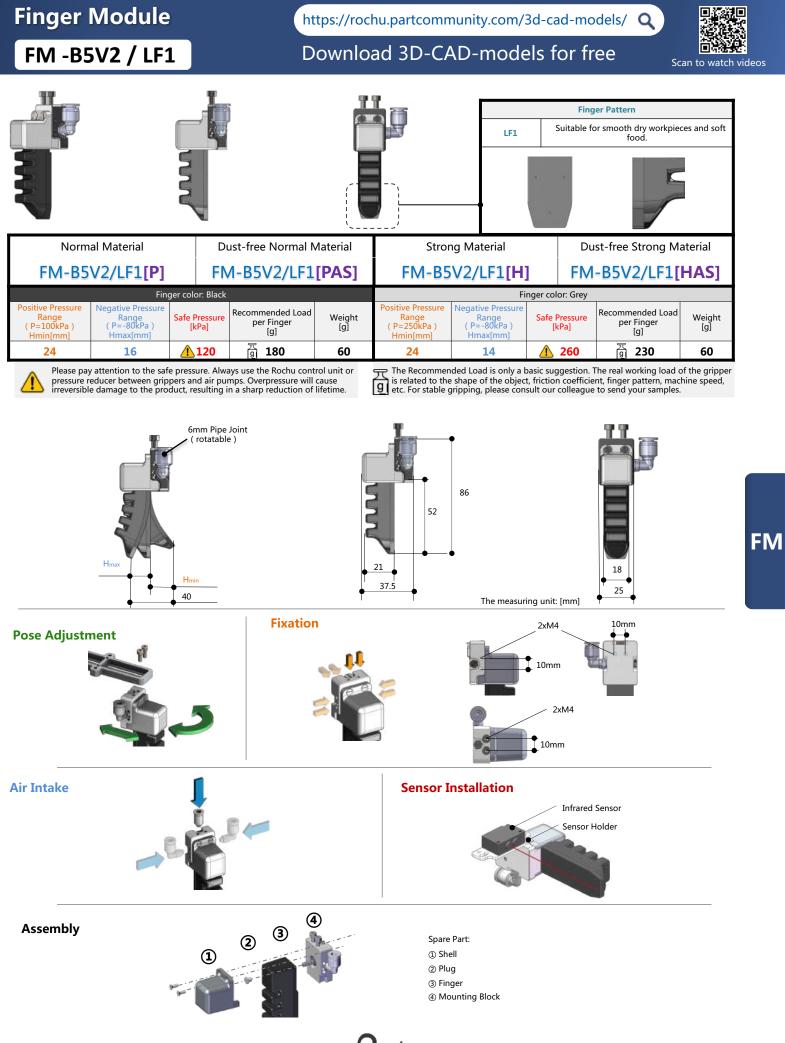
<u>គ</u> 230

20

FM



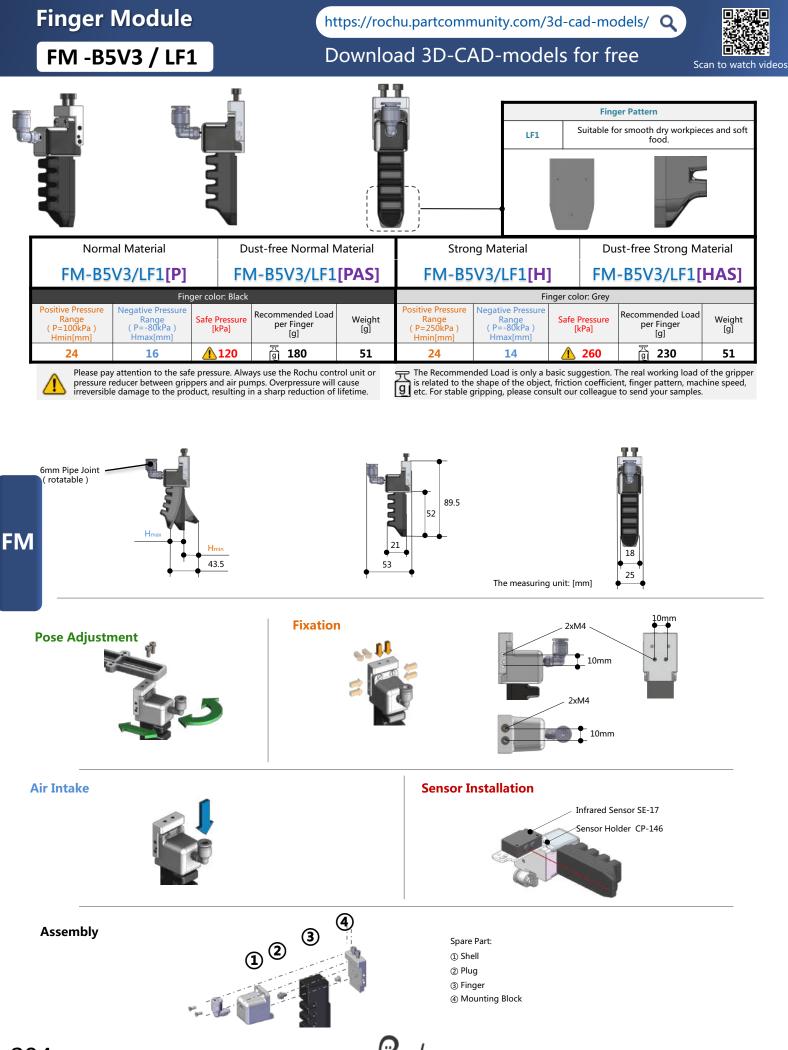
Rochu



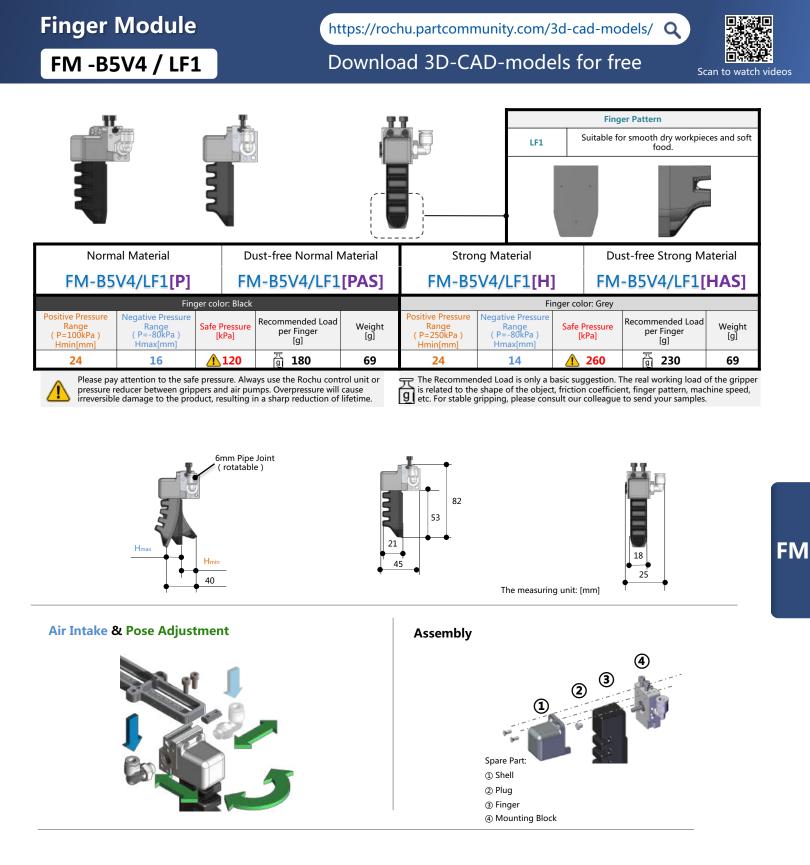
www.rochu.com

Rochu

Rochu soft Finger 293



Rochu

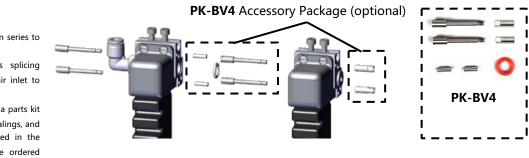


#### Series combination:

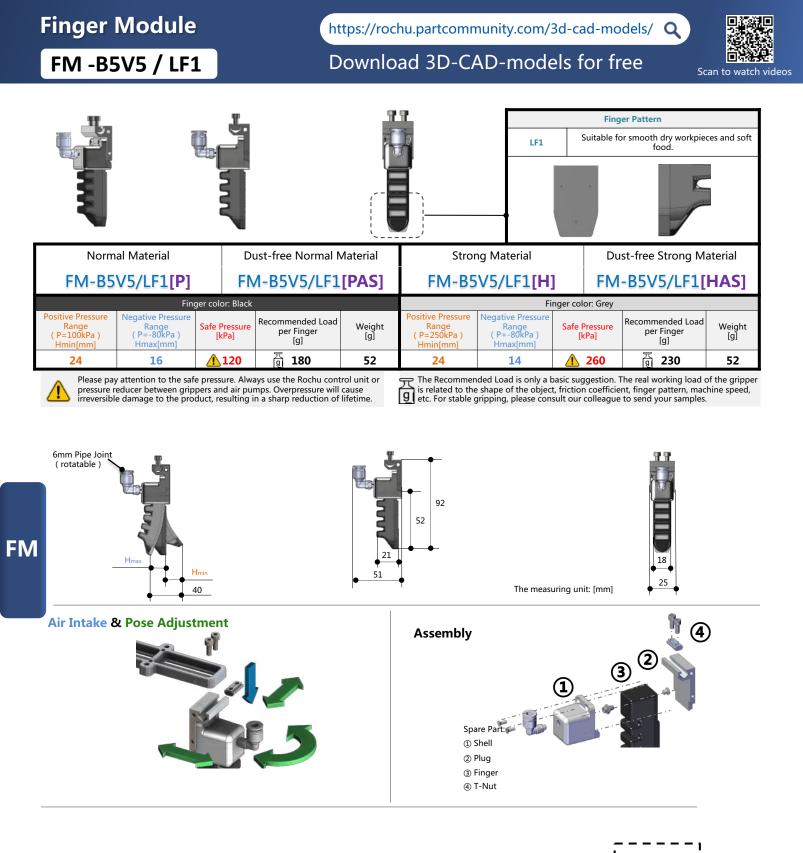
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu



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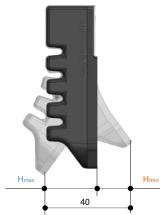


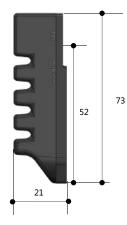


Finger I	Module	https://rock	nu.partcommunity.com/3d-	cad-models/ Q
F -B5T	/ LF1	Downloa	ad 3D-CAD-models	for free Scan to watch vide
Finger	r Pattern		Features	
LF1	Special Form	S	uitable for smooth dry workpieces and soft f	ood.
Norma	l Material	Dust-free Normal Material	Strong Material	Dust-free Strong Material
F-B5T	'/LF1[P]	F-B5T/LF1[PAS]	F-B5T/LF1[H]	F-B5T/LF1[HAS]
	Finger co	lor: Plack	Finger	color: Grov

Finger color: Black Finger color: Grey Positive Pressure Range (P=100kPa) Hmin[mm] Positive Pressure Range (P=250kPa) Hmin[mm] Negative Pressure Range ( P=-80kPa ) **Negative Pressure** Recommended Load Recommended Load Weight [g] Safe Pressure [kPa] Range (P=-80kPa) Hmax[mm] Safe Pressure per Finger [g] per Finger [g] [kPa] Hmax[mm] 중 24 16 집 180 24 14 120 20  $\wedge$ 260 Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime. The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

## **Dimension Parameters**







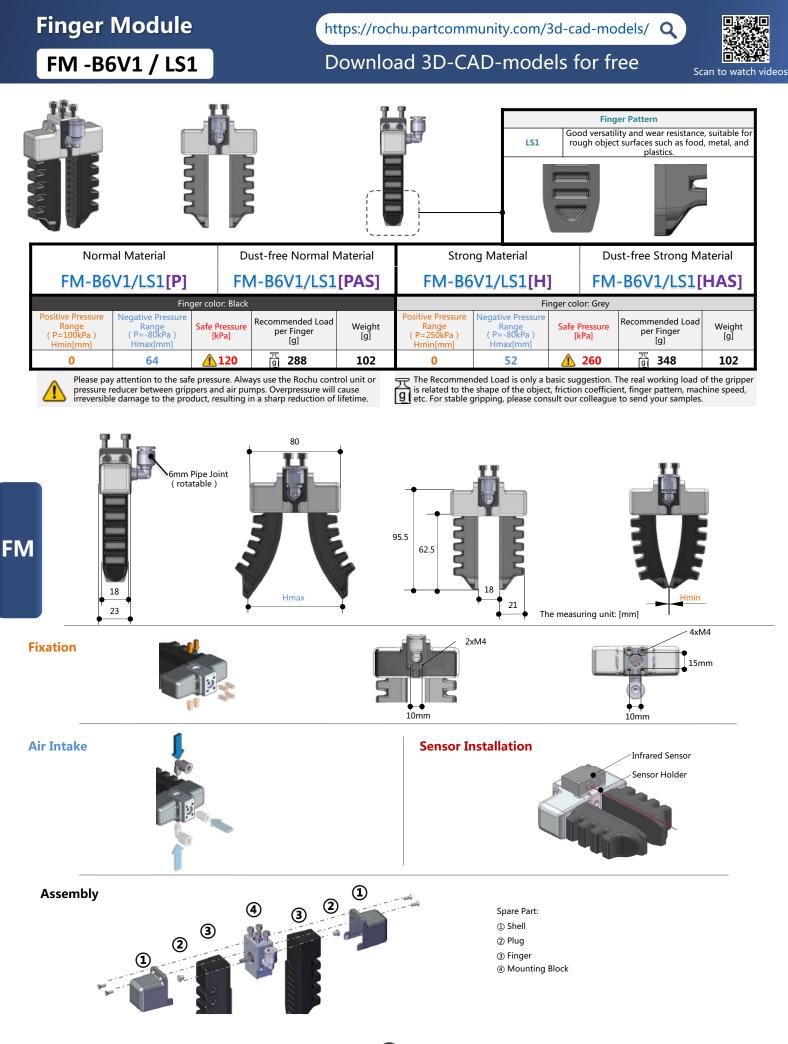
230

Weight [g]

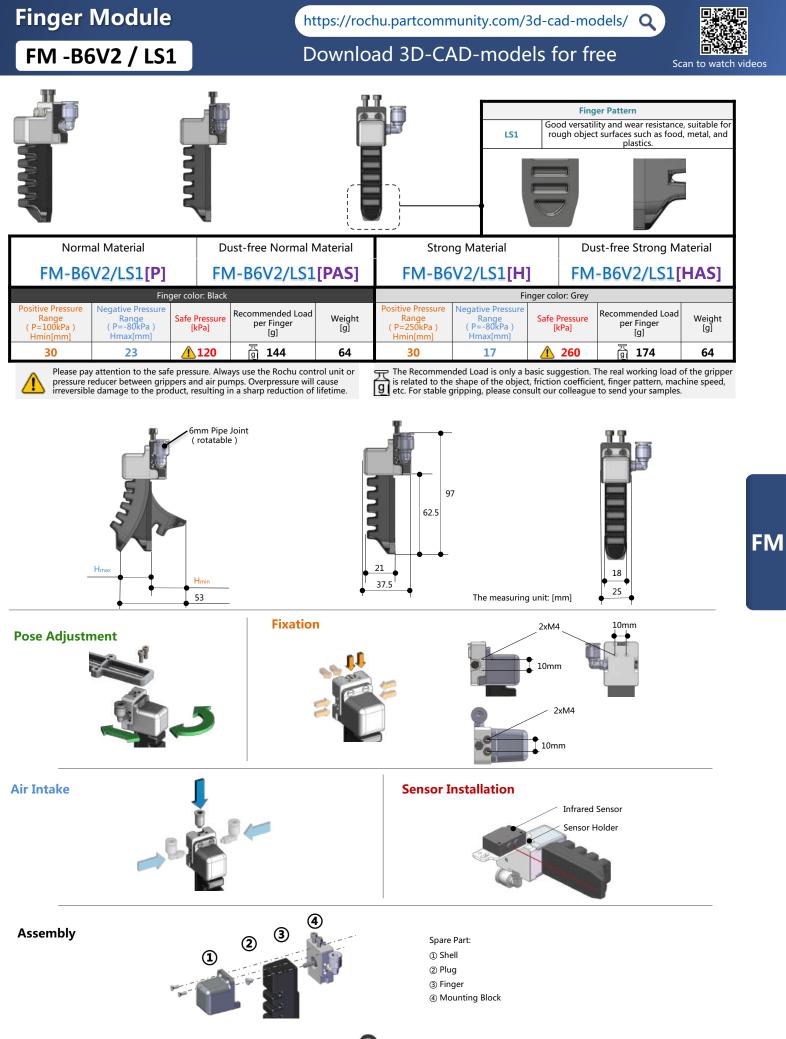
20

eos





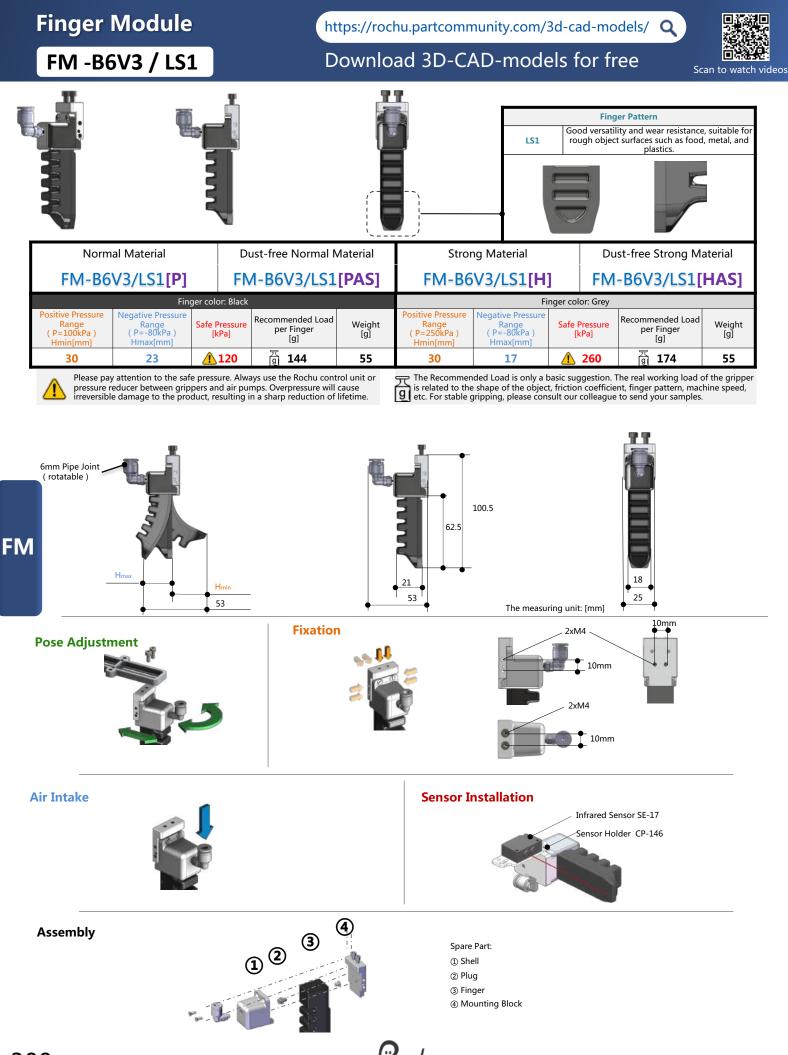
Rochu



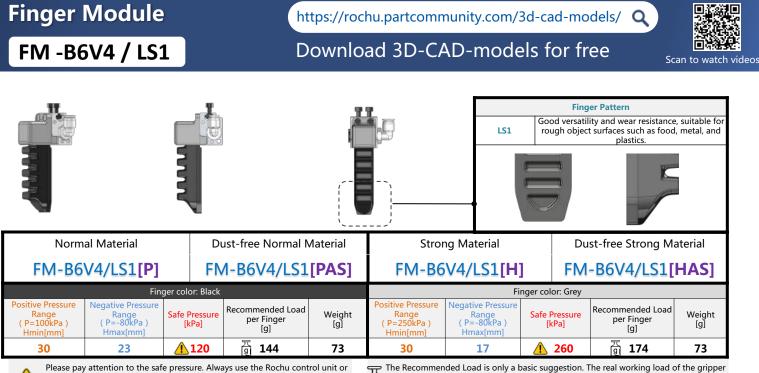
www.rochu.com

Rochu

Rochu soft Finger 299

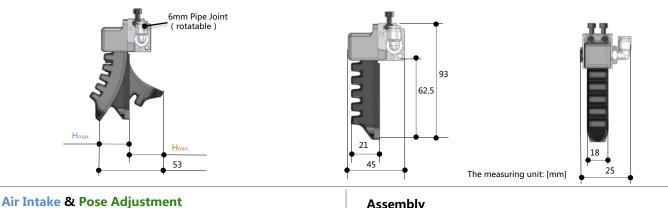


Rochu



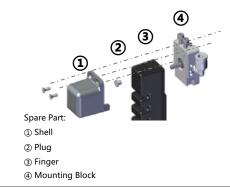
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Assembly

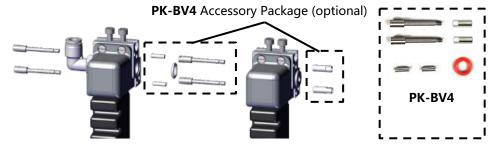


### Series combination:

1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

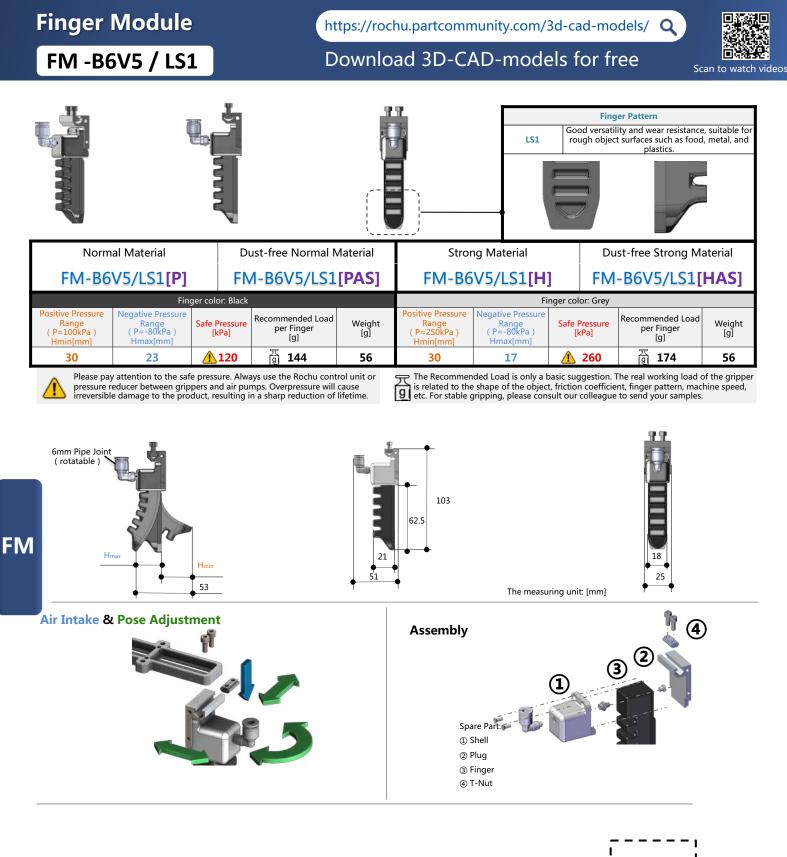
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.







FM



### Series combination:

1. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

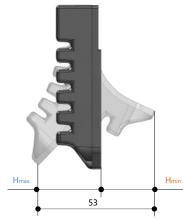
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-BV5 Accessory Package (optional)

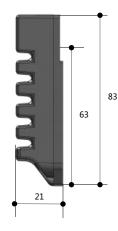
Finger	Module		ht	tps://rocl	hu.partcomn	nunity.com/	3d-cad-mo	dels/ Q	
F -B6T	/ LS1		D	ownlo	ad 3D-CA	AD-mode	els for fr	ee so	an to watch vide
				,					
Finge	r Pattern				Fe	atures			
LS1	Standard forr	n	Good versatil	ity and wear res	sistance, suitable for	rough object surfac	es such as food, n	netal, and plastics.	
Normal Material			ust-free Normal N	Strong Material Du			ust-free Strong Material		
F-B61	[/LS1[P]	F	F-B6T/LS1[PAS] F-B6T/LS1[H] F-B6T/LS1					-B6T/LS1[H	AS]
Positive Pressure	Fing Negative Pressure	ger color: Black			Positive Pressure	Fi Negative Pressure	nger color: Grey	Decommonded	
Range ( P=100kPa ) Hmin[mm]	Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Range ( P=250kPa ) Hmin[mm]	Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]
30	23	120	ត្តី <b>144</b>	24	30	17	1 260	员 174	24

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

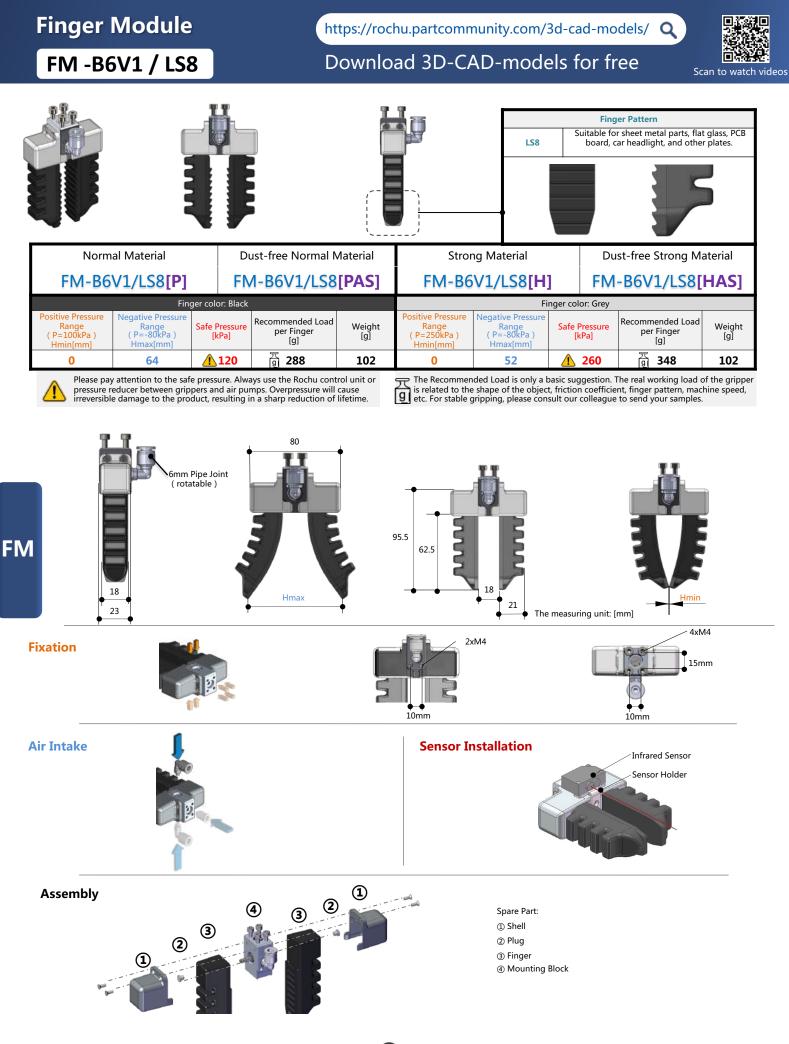
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

## **Dimension Parameters**

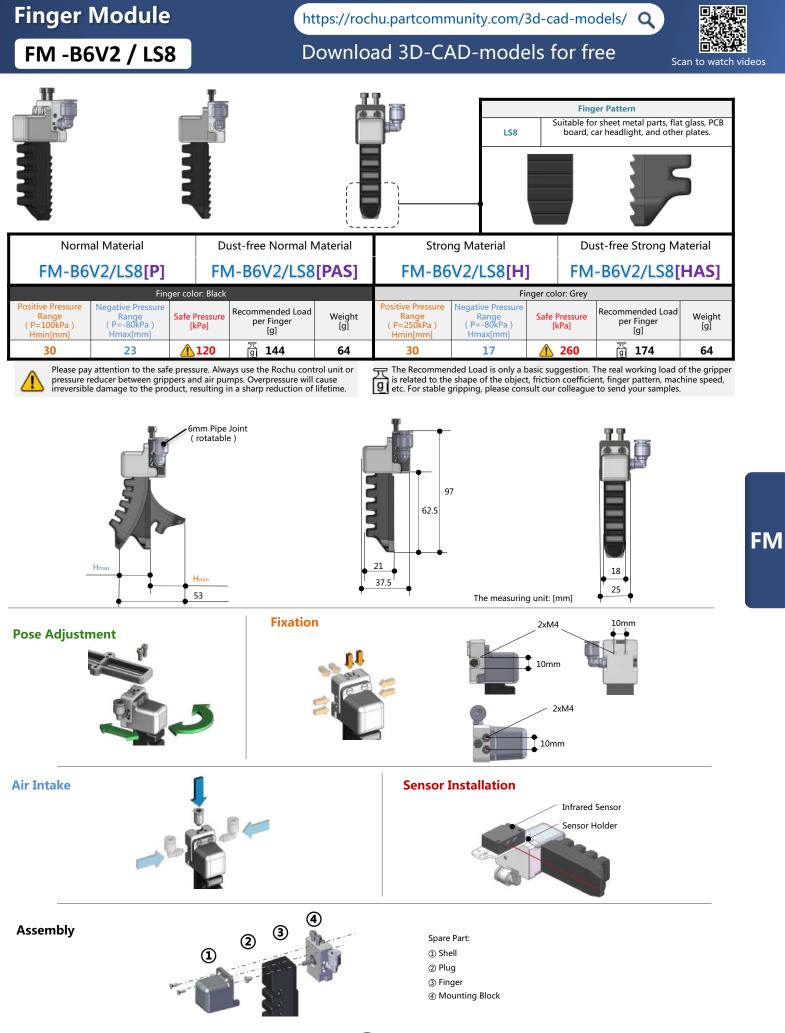








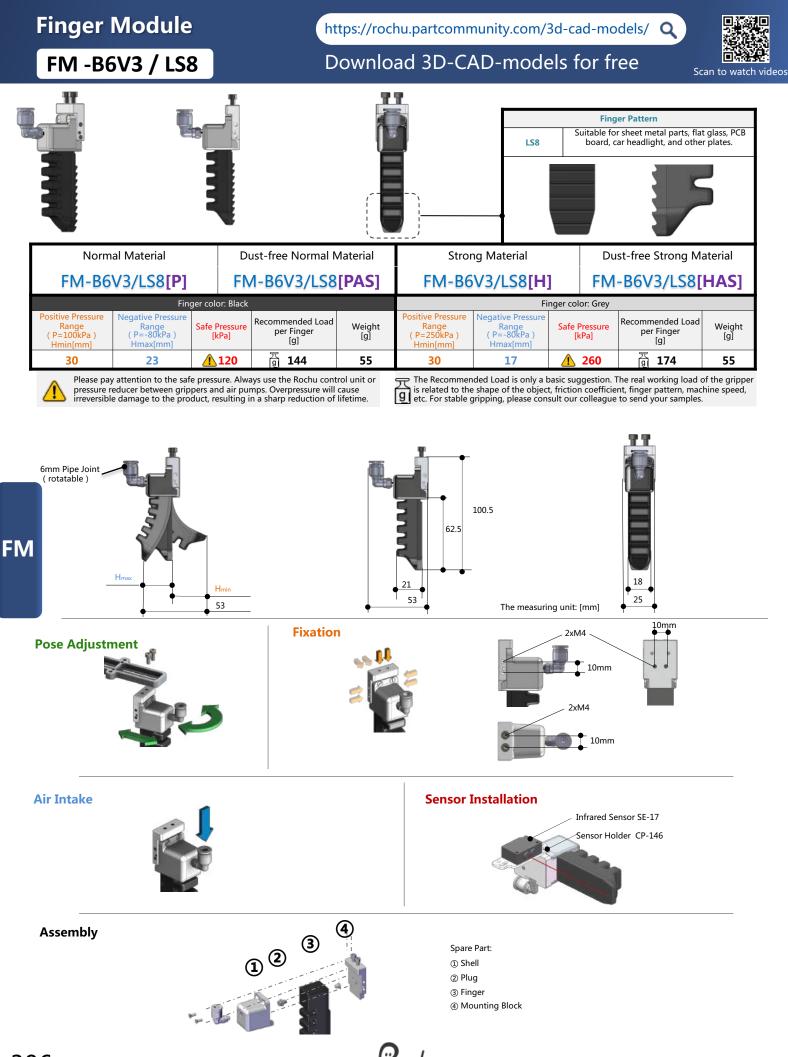
Rochu



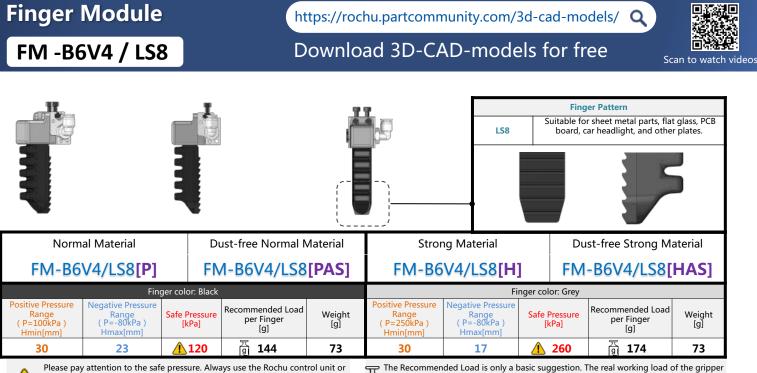
www.rochu.com

Pochu

Rochu soft Finger 305



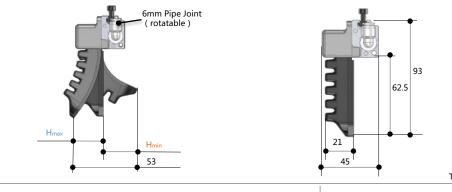
Rochu

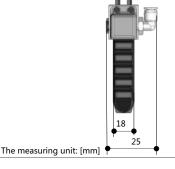




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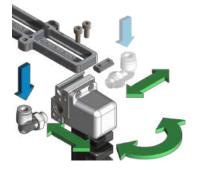
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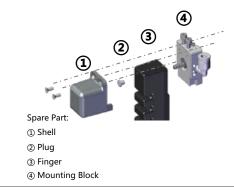


FM

Air Intake & Pose Adjustment



Assembly



### Series combination:

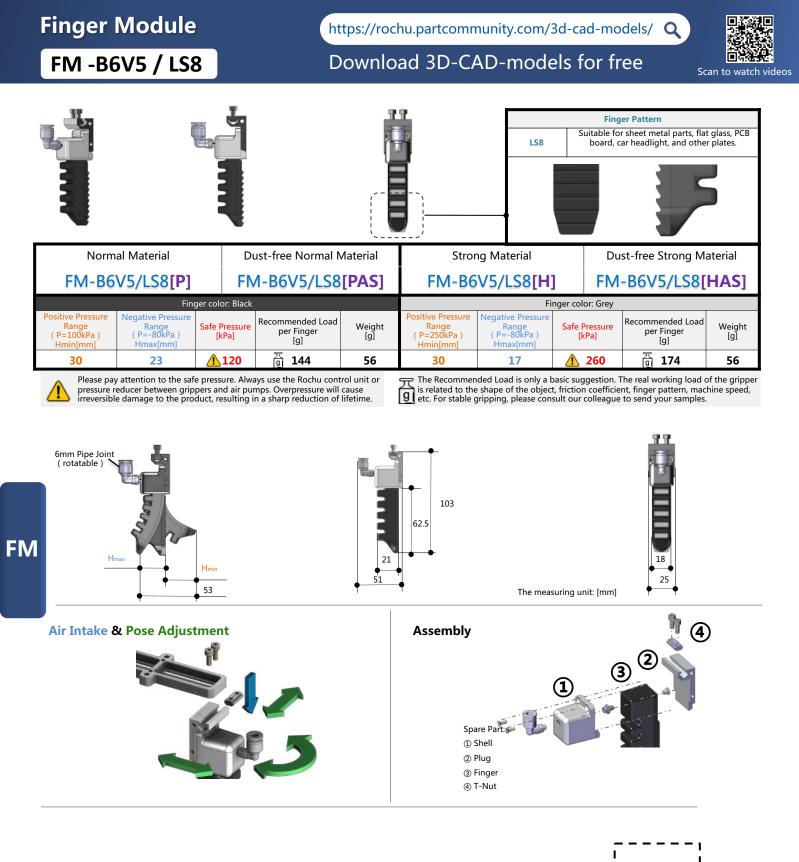
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.









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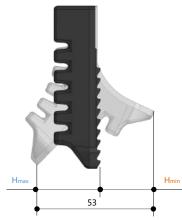
Finger N	Module	https://rochu	u.partcommunity.com/3d	d-cad-mod	els/ Q	旦後新 総統		
F -B6T	/ LS8	Download	Download 3D-CAD-models for free					
	LUG			D				
•								
Finger	Pattern		Features					
Finger	Pattern Special Form	Suitable for sheet me	<b>Features</b> etal parts, flat glass, PCB board, car headl	llight, and other p	lates.			
LS8		Suitable for sheet me Dust-free Normal Material			lates. :-free Strong Ma	aterial		
LS8 Normal	Special Form		etal parts, flat glass, PCB board, car headl	Dust				
LS8 Normal	Special Form I Material /LS8[P] Fing	Dust-free Normal Material F-B6T/LS8[PAS] color: Black	etal parts, flat glass, PCB board, car head Strong Material F-B6T/LS8[H] Finge	Dust	-free Strong Ma			
LS8 Normal	Special Form I Material /LS8[P]	Dust-free Normal Material F-B6T/LS8[PAS] color: Black afe Pressure Recommended Load Weight	etal parts, flat glass, PCB board, car head Strong Material F-B6T/LS8[H] Finge Positive Pressure Negative Pressure	Dust F-E er color: Grey	-free Strong Ma			

⚠

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

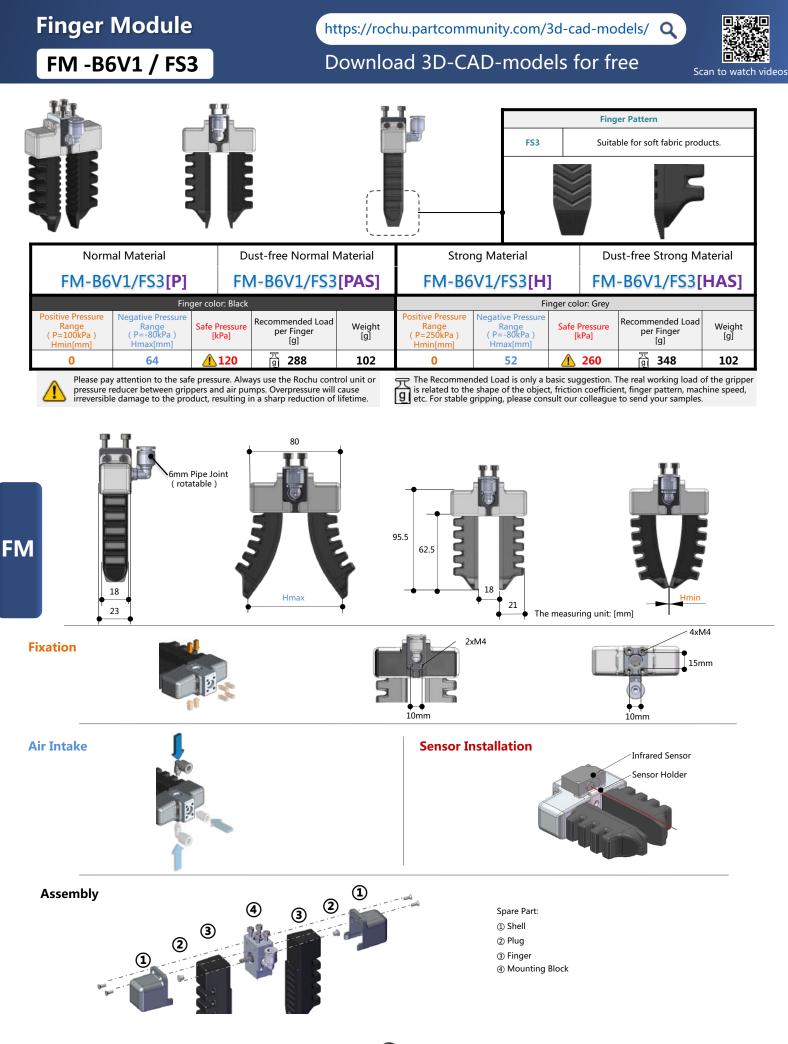
The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

## **Dimension Parameters**

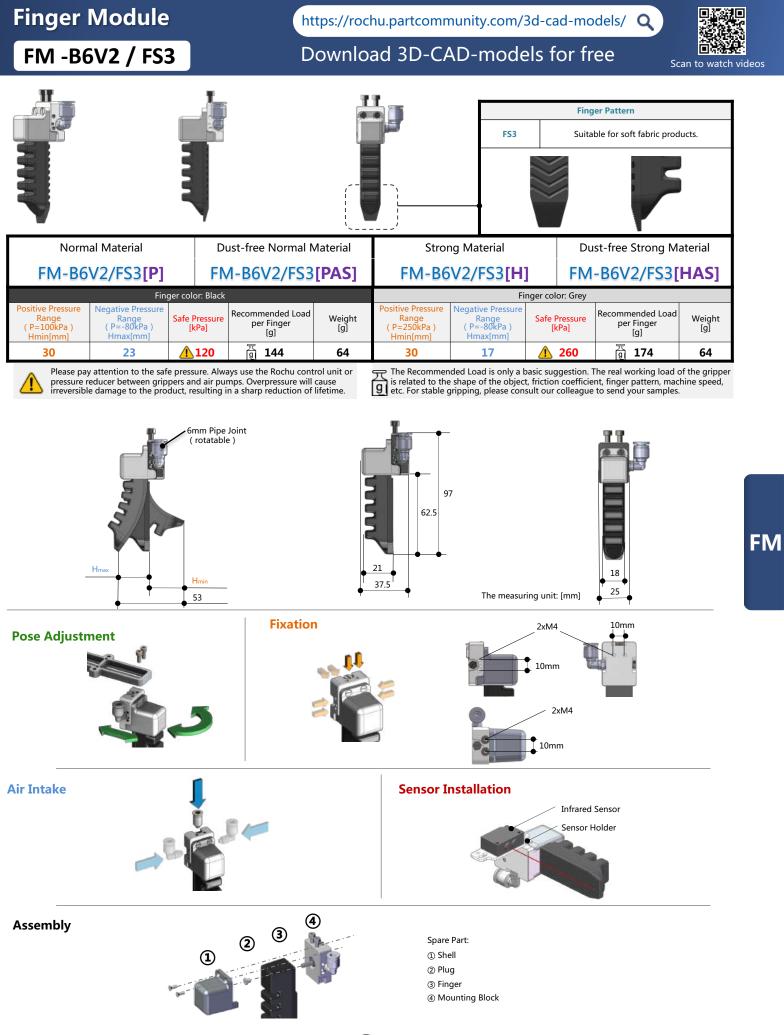








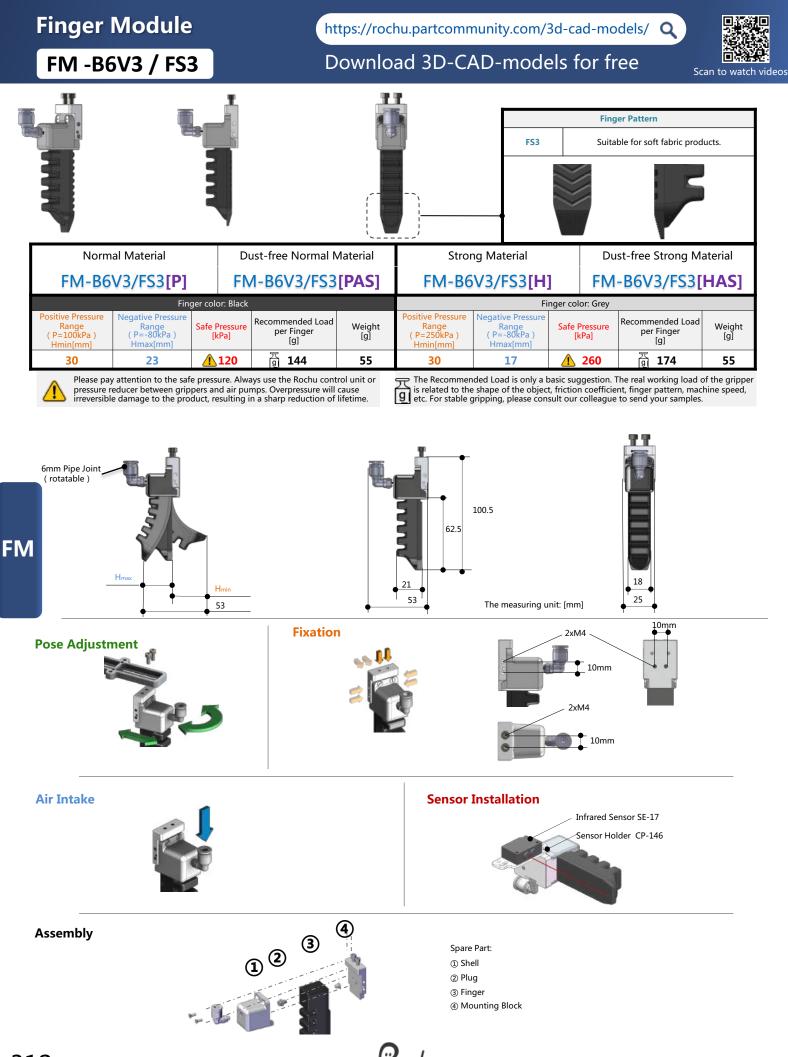
Rochu



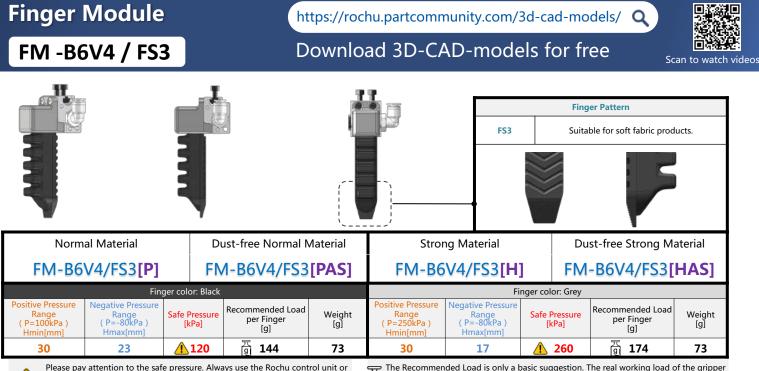
www.rochu.com

Rochu

Rochu soft Finger 311

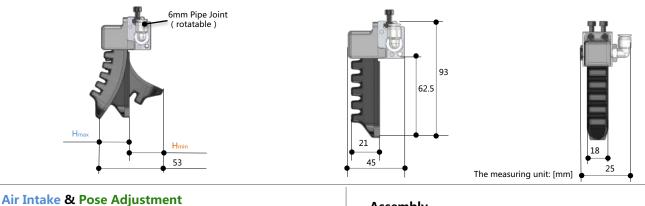


Rochu

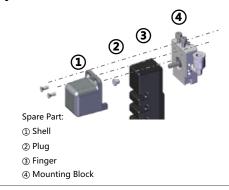


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## Assembly



### Series combination:

1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

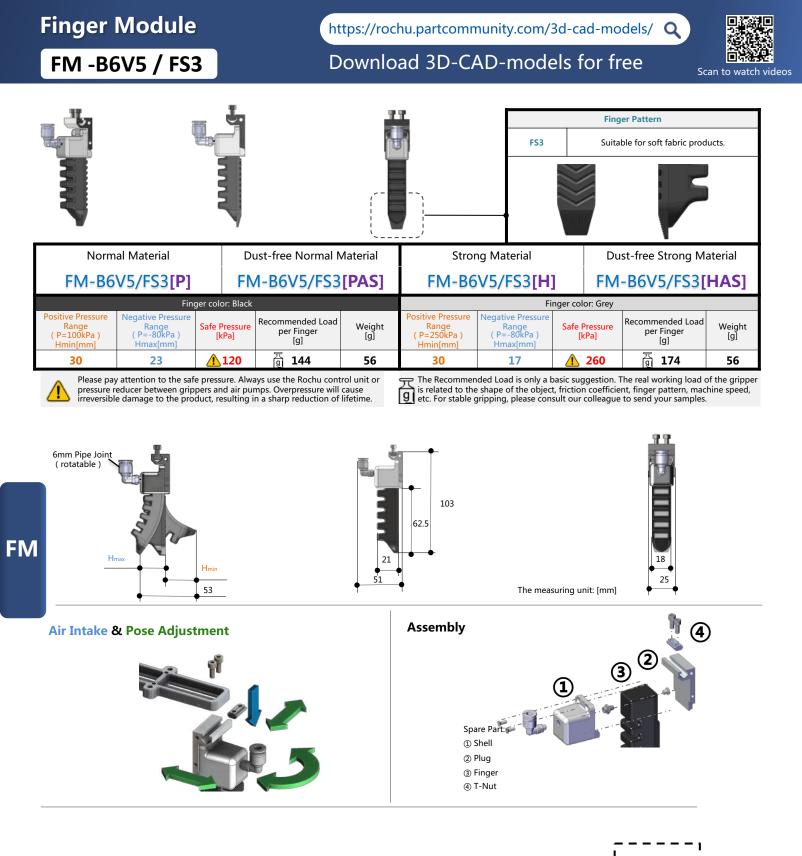
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Rochu



FM



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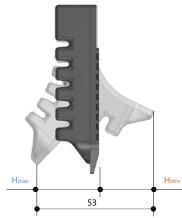


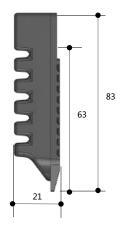
Finger	Module		https://rochu.partcommunity.com/3d-cad-models/ Q						
F -B6T	/ FS3		Download 3D-CAD-models for free Scan to wa						
Finger Pattern									
Finge	r Pattern				Fe	atures			
FS3	r Pattern Special Form					atures			
FS3		Du	ust-free Normal N	1aterial	Suitable for s		Du	ist-free Strong M	laterial
FS3 Norma	Special Form		ust-free Normal N -B6T/FS3[P		Suitable for s	oft fabric products.		ust-free Strong M - <b>B6T/FS3[H</b>	
FS3 Norma F-B6T	Special Form al Material <b>[/FS3[P]</b> Finge		-B6T/FS3[P		Suitable for s Stror <b>F-B6</b>	oft fabric products. ng Material <b>T/FS3[H]</b> Fir		Ū	
FS3 Norma	Special Form al Material <b>T/FS3[P]</b> Finge Negative Pressure	F	-B6T/FS3[P		Suitable for s	oft fabric products. ng Material <b>T/FS3[H]</b>	F	Ū	AS]

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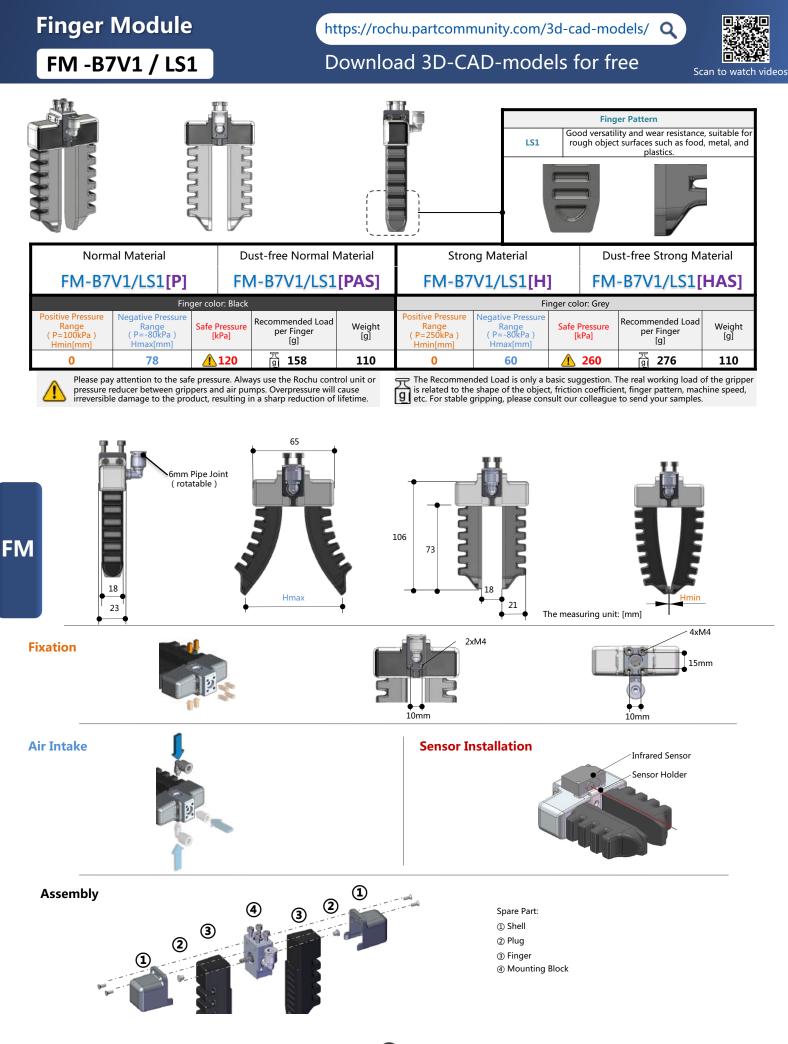
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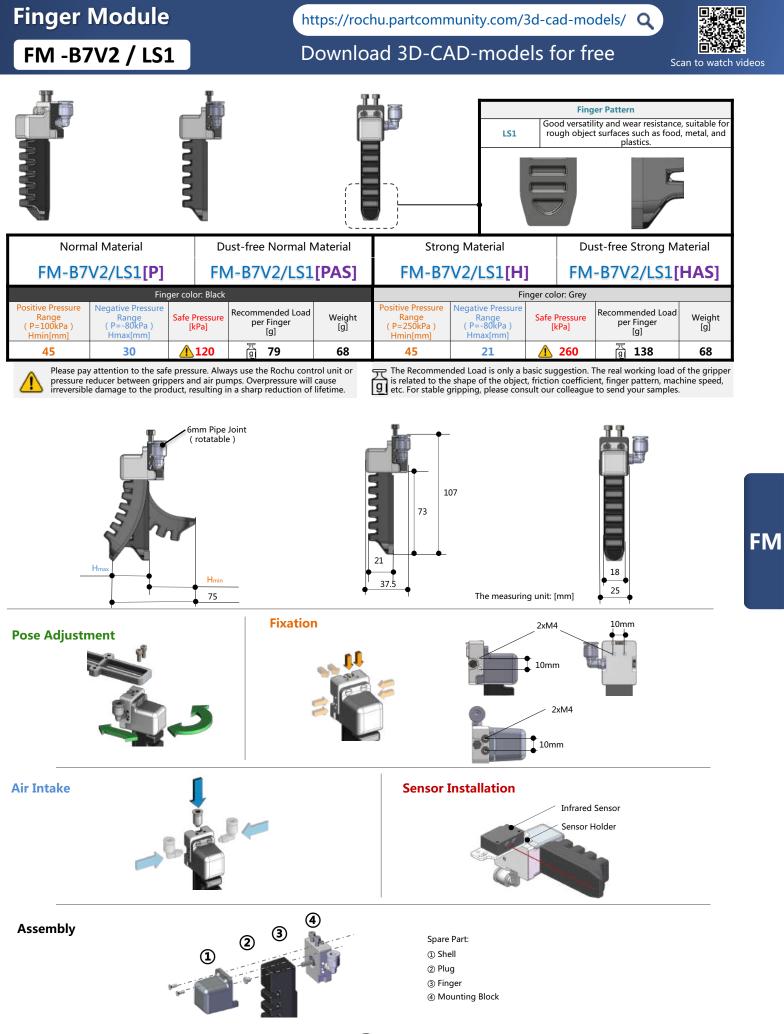
## **Dimension Parameters**



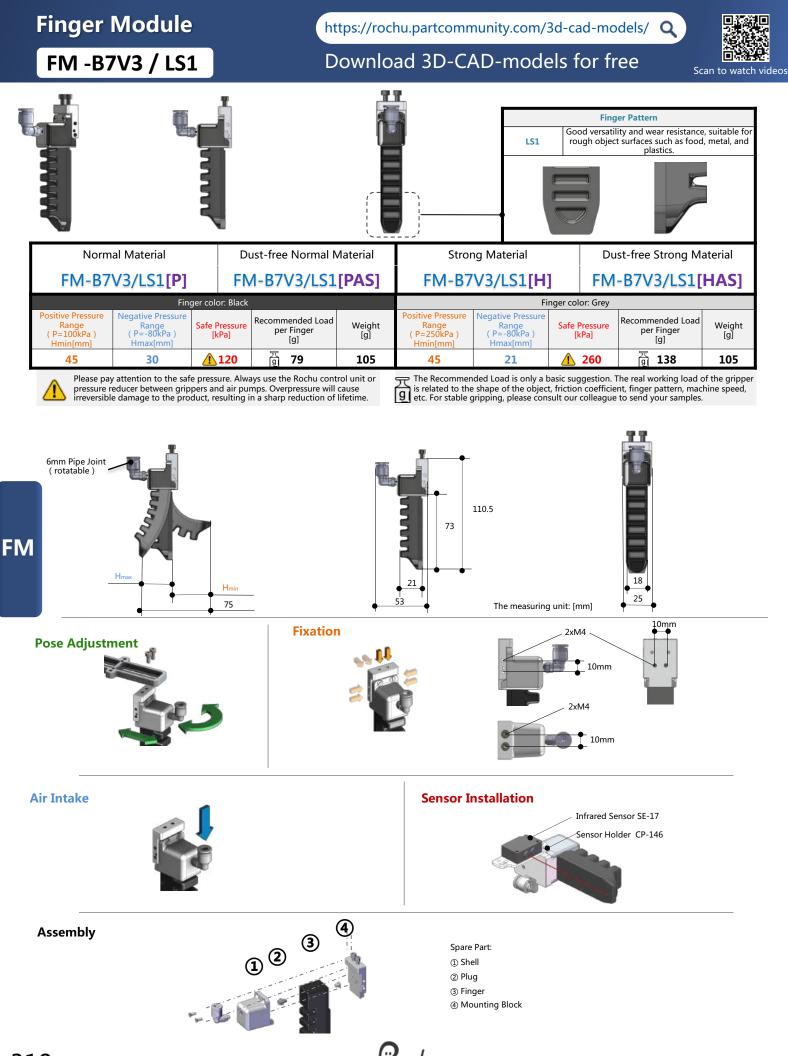




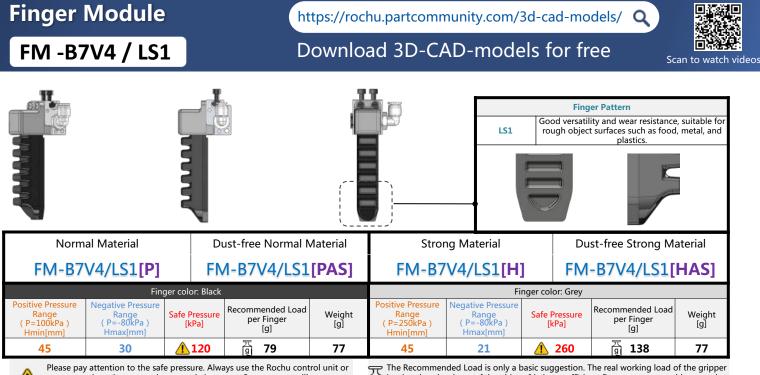




Rochu

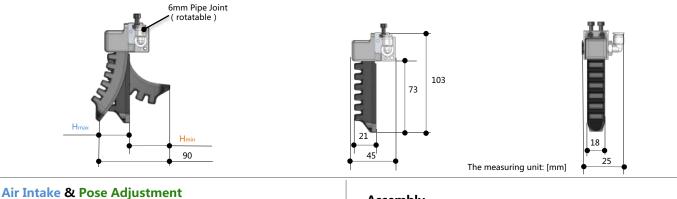


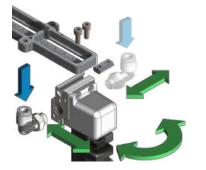




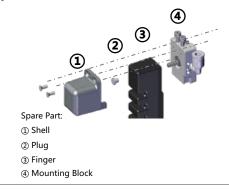
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Assembly

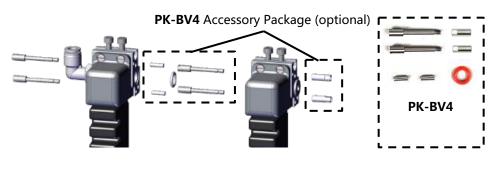


### Series combination:

1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

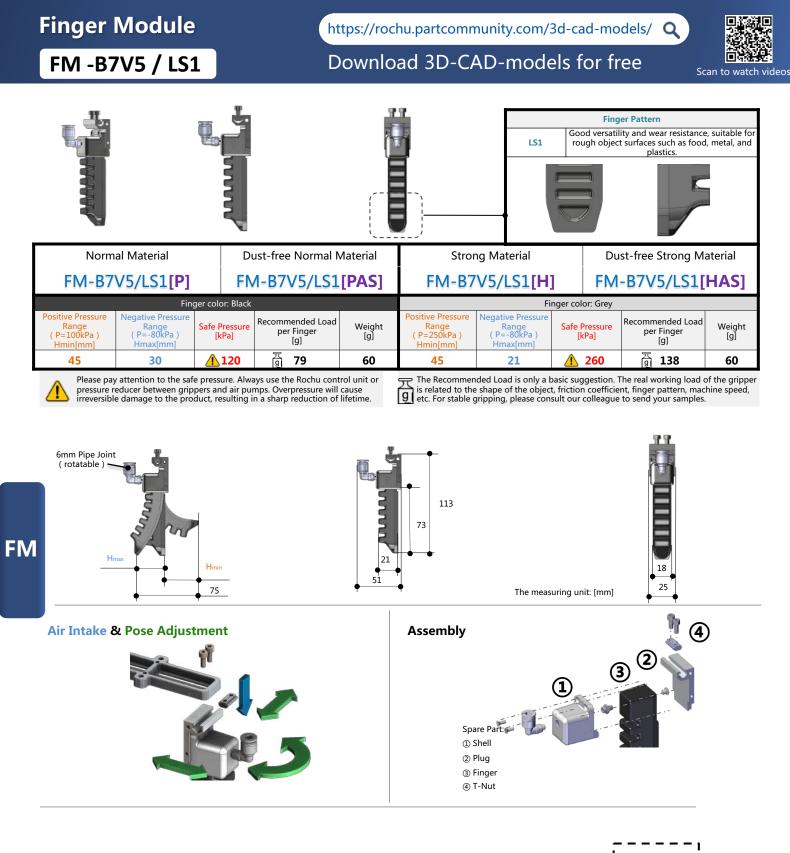
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.







FM

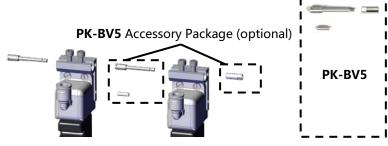


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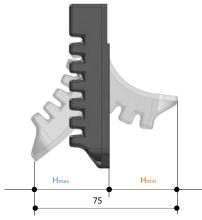


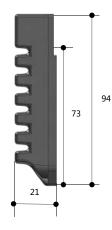
F.B7T / LS1       Download 3D-CAD-models for five         Image: Device of the product of	Finger <b>N</b>	Module		ht	ttps://roc	hu.partcomn	nunity.com/	3d-cad-mo	odels/ Q	
Finger Pattern       Features         LS1       Standard form         Normal Material       Good versatility and wear resistance, suitable for rough object surfaces such and plastics.         Normal Material       Dust-free Normal Material         F-B7T/LS1[P]       Dust-free Normal Material         F-B7T/LS1[P]       F-B7T/LS1[PAS]         Fereorer Range (PP-30kPa)       Safe Pressure (PP-30kPa)         Normal Material Ressure Range (PP-30kPa)       Safe Pressure Range (PP-30kPa)       Figure Oricinal (PP-30kPa)	F -B7T	/ LS1		D	ownlo	ad 3D-CA	D-mode	els for fr	ee so	can to watch vid
LS1       Standard form       Good versatility and wear resistance, suitable for rough object surfaces such as food, metal, and plastics.         Normal Material       Dust-free Normal Material       Strong Material       Dust-free Strong Material         F-B7T/LS1[P]       F-B7T/LS1[PAS]       F-B7T/LS1[H]       Dust-free Strong Material         Vormal Material       Strong Material       Strong Material       F-B7T/LS1[HAS]         Vormal Material       F-B7T/LS1[PAS]       F-B7T/LS1[H]       F-B7T/LS1[HAS]         Vormal Material       Strong Material       F-B7T/LS1[H]       Februal Material         Vormal Material       F-B7T/LS1[PAS]       F-B7T/LS1[H]       Februal Material         Positive Pressure Range (P=100KPa) Hmin(mm)       Negative Pressure (P=250KPa) Hmin(mm)       Negative Pressure Range (P=250KPa) Hmin(mm)       Safe Pressure (P=250KPa) Hmin(mm)       Safe Pressure (P=30KPa) Hmin(mm)       Safe Pressure (					nnn `					
Normal Material     Dust-free Normal Material     Strong Material     Dust-free Strong Material       F-B7T/LS1[P]     F-B7T/LS1[PAS]     F-B7T/LS1[H]     F-B7T/LS1[HAS]       Fositive Pressure Range (P=100kPa) Hmin[mm]     Negative Pressure (P=250kPa) Hmin[mm]     Recommended Load per Finger [g]     Weight [g]     Positive Pressure Range (P=250kPa) Hmin[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]     Positive Pressure Range (P=250kPa) Hmin[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]	Finger	Pattern				Fe	atures			
F-B7T/LS1[P]     F-B7T/LS1[PAS]     F-B7T/LS1[H]     F-B7T/LS1[HAS]       Finger color: Black       Positive Pressure Range (P=100kPa) Hmin[mm]     Negative Pressure (P=250kPa) Hmax[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]     Positive Pressure Range (P=250kPa) Hmin[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]     Negative Pressure Range (P=250kPa) Hmin[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]	LS1	LS1 Standard form Good versatility and wear re				sistance, suitable for	rough object surfac	es such as food, n	netal, and plastics.	
Positive Pressure Range (P=100kPa) Hmin[mm]     Negative Pressure (P==80kPa) Hmax[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]     Positive Pressure Range (P=250kPa) Hmin[mm]     Safe Pressure Range (P=-80kPa) Hmax[mm]     Safe Pressure [kPa]     Recommended Load per Finger [g]     Weight [g]	Norma	Material	Du	ust-free Normal N	Material	Stror	ng Material	Du	ist-free Strong M	aterial
Positive Pressure Range (P=100kPa) Hmin[mm]Negative Pressure Range (P=-80kPa) Hmax[mm]Negative Pressure Range (P=250kPa) Hmin[mm]Negative Pressure Range (P=-80kPa) Hmin[mm]Recommended Load per Finger [g]Weight [g]Positive Pressure Range (P=250kPa) Hmin[mm]Negative Pressure Range (P=-80kPa) Hmax[mm]Recommended Load per Finger [g]Weight [g]	F-B7T/LS1[P]			-B7T/LS1[F	F-B7T/LS1[H] F-B7T/LS1[H			AS]		
Range (P=100kPa)Range (P=-80kPa)Safe Pressure [kPa]Recommended Load per Finger [g]Weight [g]Range (P=250kPa) Hmin[mm]Range (P=-80kPa) Hmax[mm]Safe Pressure [kPa]Recommended Load per Finger [g]Weight [g]Range (P=-80kPa) Hmin[mm]Safe Pressure (P=-80kPa) Hmax[mm]Safe Pressure [kPa]Recommended Load per Finger [g]Weight [g]	Desitive Dresswar		r color: Black			Desitive Pressure		nger color: Grey		
45     30     ▲ 120     ₩ 79     28     45     21     ▲ 260     ₩ 138     28	Range ( P=100kPa )	Range (P=-80kPa)		per Finger [g]	weight	Range ( P=250kPa )	Range ( P=-80kPa )		per Finger [g]	
	45	30	<u>120</u>	표 및 <b>79</b>	28	45	21	1 260	जू <b>138</b>	28

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

# **Dimension Parameters**

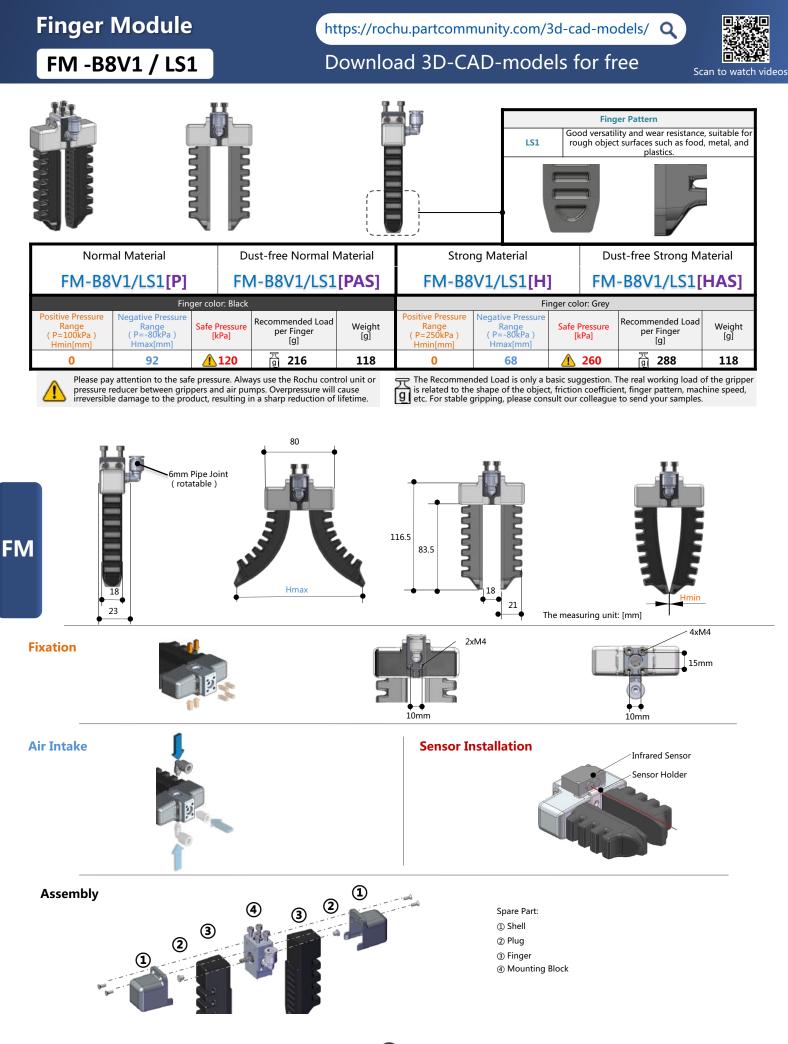


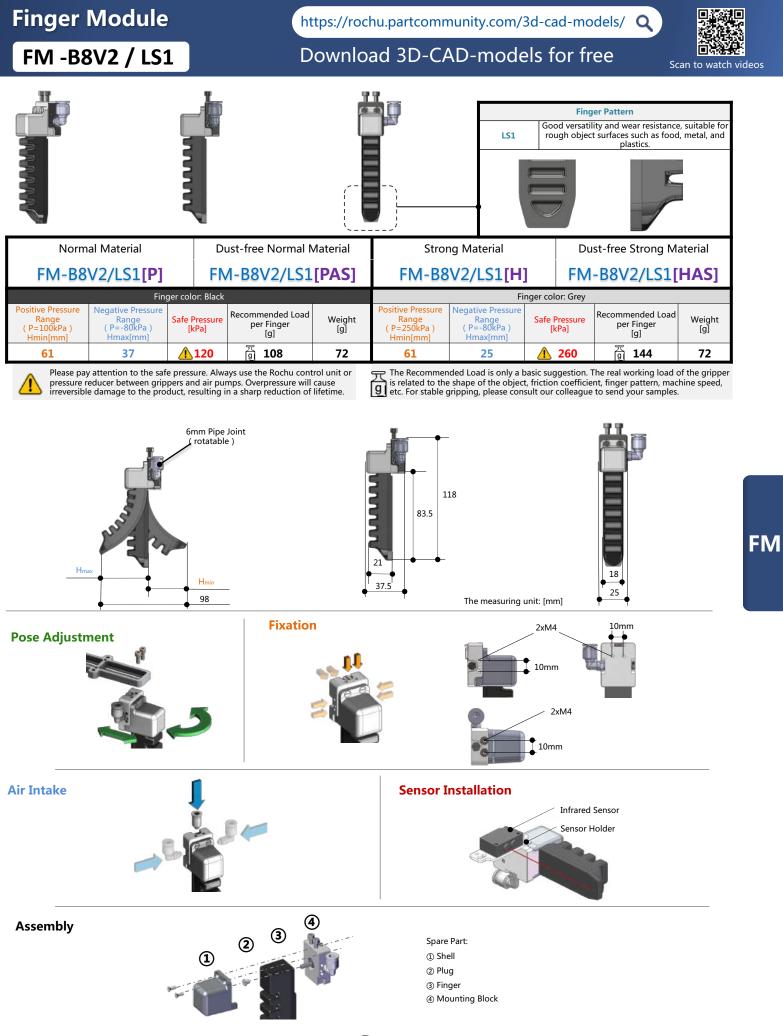




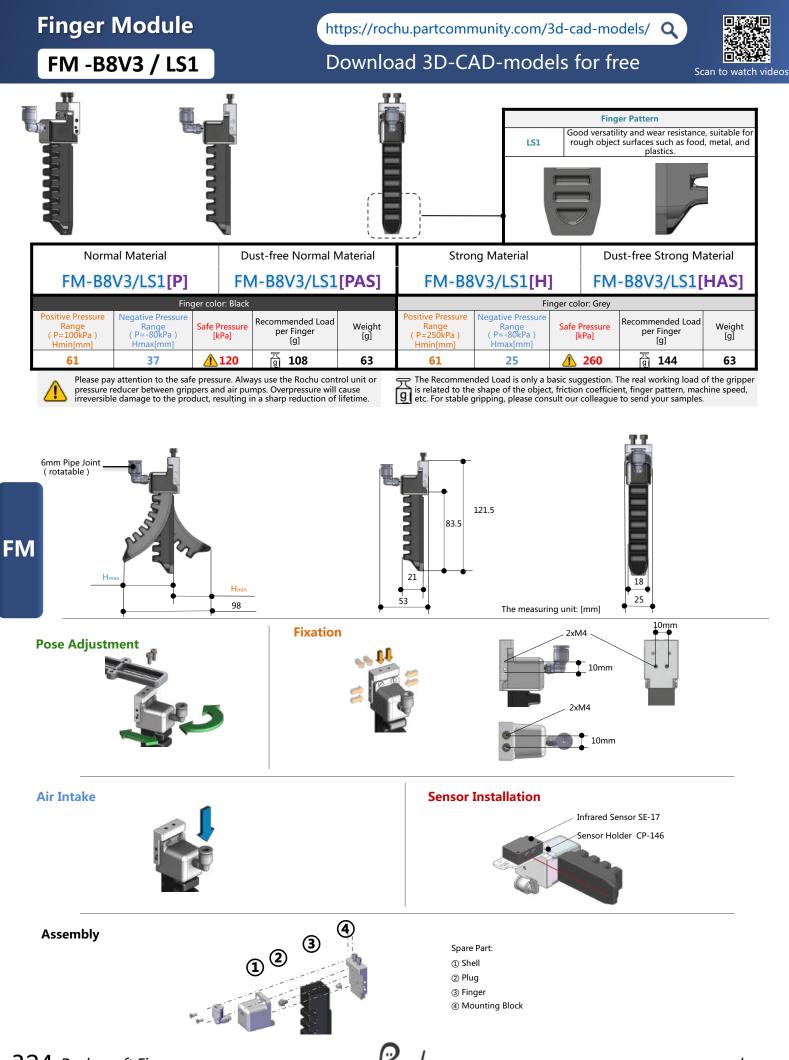
eos



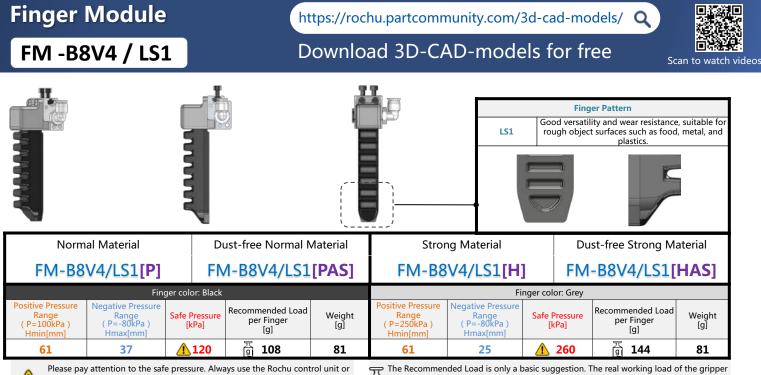




Pochu



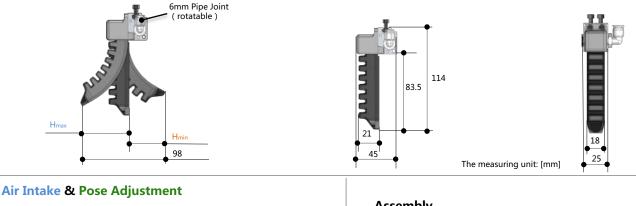
Rochu



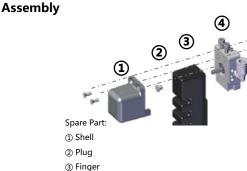


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④ Mounting Block

#### Series combination:

1. Build multiple finger modules in series to increase the grip force.

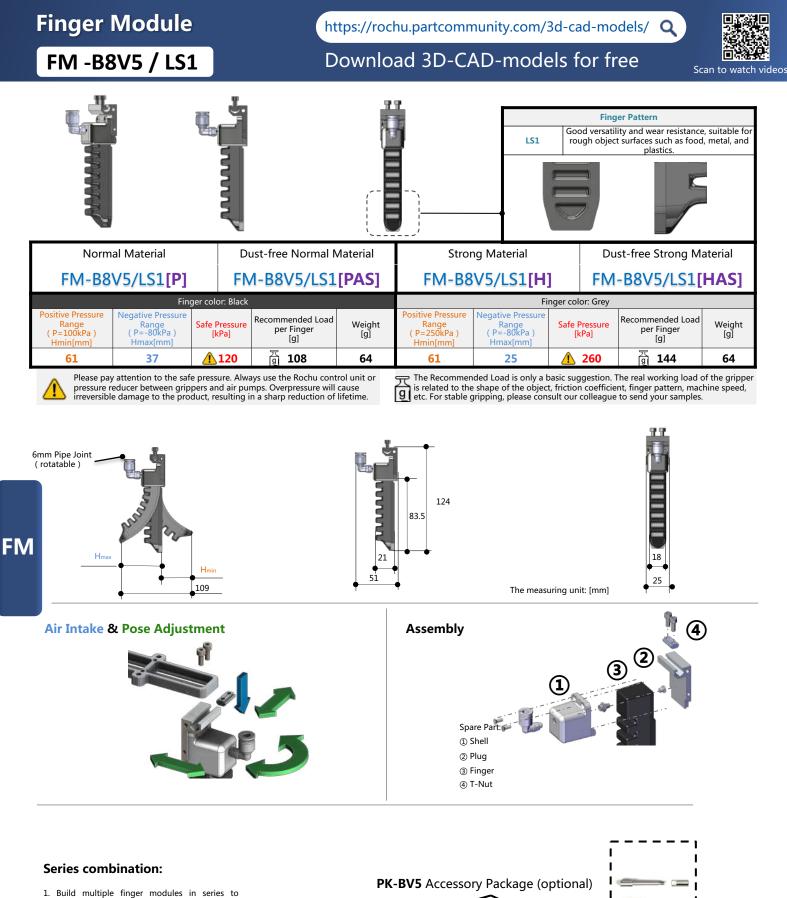
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

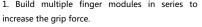
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.





FM





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326 Rochu soft Finger

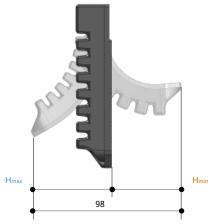
PK-BV5 Accessory Package (optional)

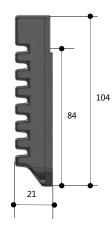


inger woud	er Module https://rochu.partcommunity.com/3d-cad-models/ Q								
F -B8T / LS1		D	ownloa	ad 3D-CA	D-mode	ls for fr	ee sc	an to watch	
			w						
Finger Pattern				Fe	atures				
LS1 Standard	form	Good versatilit	ty and wear res		rough object surface	s such as food, m	netal, and plastics.		
LS1 Standard Normal Material	-	Good versatilit Dust-free Normal M	-	istance, suitable for	rough object surface ng Material		netal, and plastics.	aterial	
	-		laterial	istance, suitable for Stror		Du	•		
Normal Material	Finger color: Bla	Dust-free Normal M	laterial	istance, suitable for Stror <b>F-B8</b>	ng Material T/LS1[H]	Du	st-free Strong Ma		
Normal Material	Finger color: Bla ure Safe Pressu	Dust-free Normal M F-B8T/LS1[PA lack	laterial	istance, suitable for Stror	ng Material	Du F-	st-free Strong Ma		

Please pay attention to the safe pressure. Always use the Kochu control unit of pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime. The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

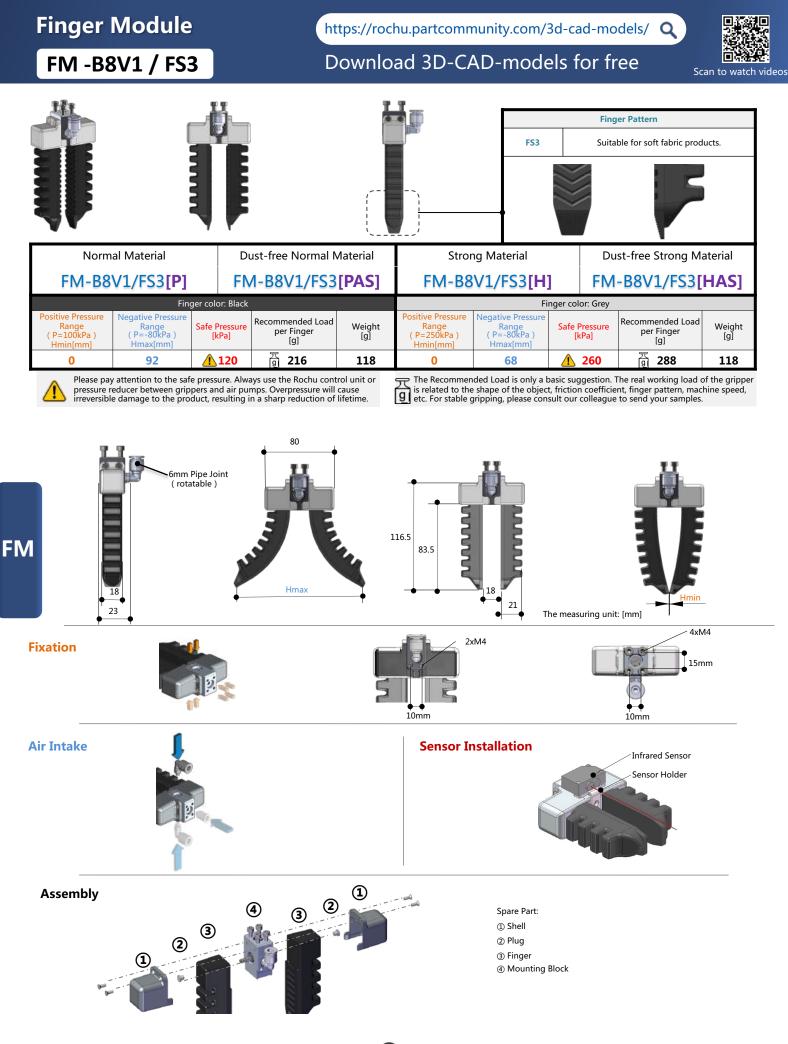
## **Dimension Parameters**



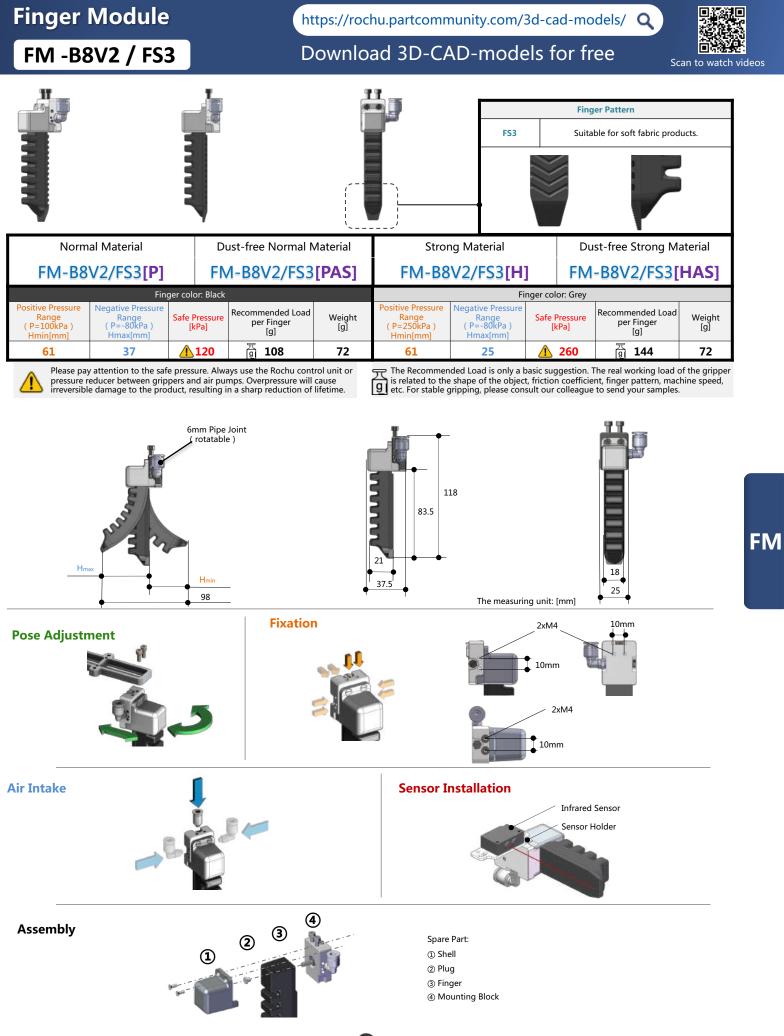




FM

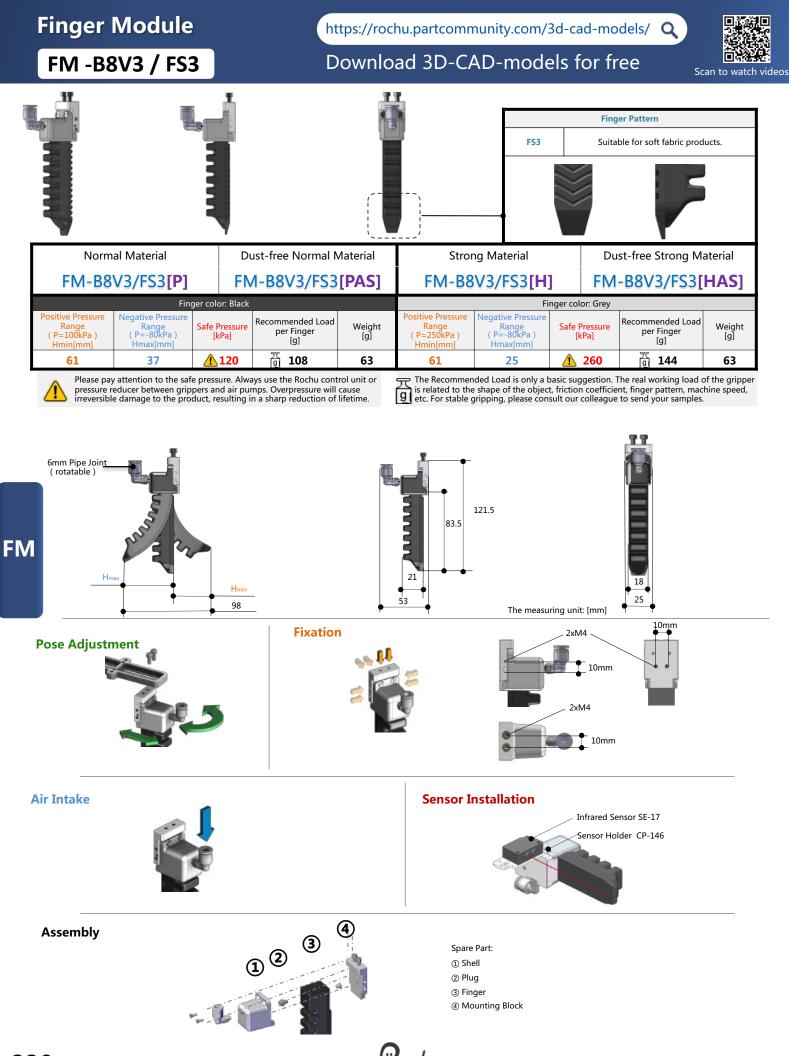




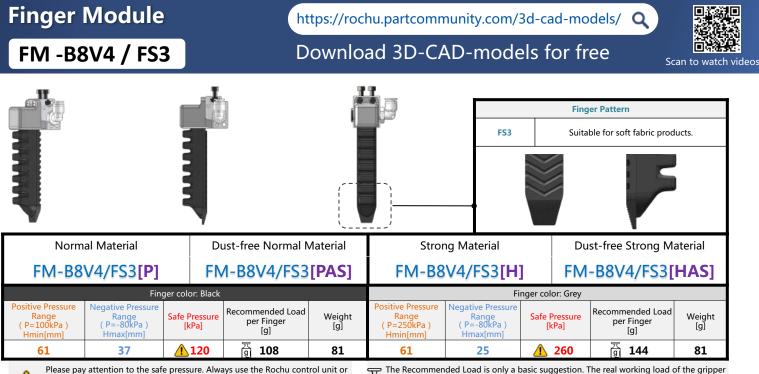


Pochu

Rochu soft Finger 329



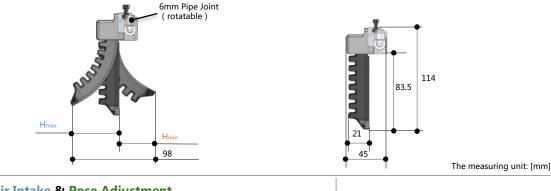
Rochu

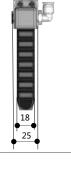




Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

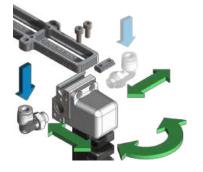
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.



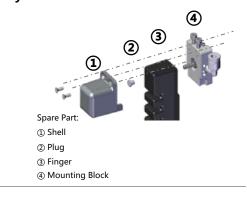


FM

Air Intake & Pose Adjustment



#### Assembly

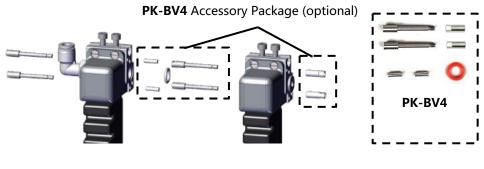


#### Series combination:

1. Build multiple finger modules in series to increase the grip force.

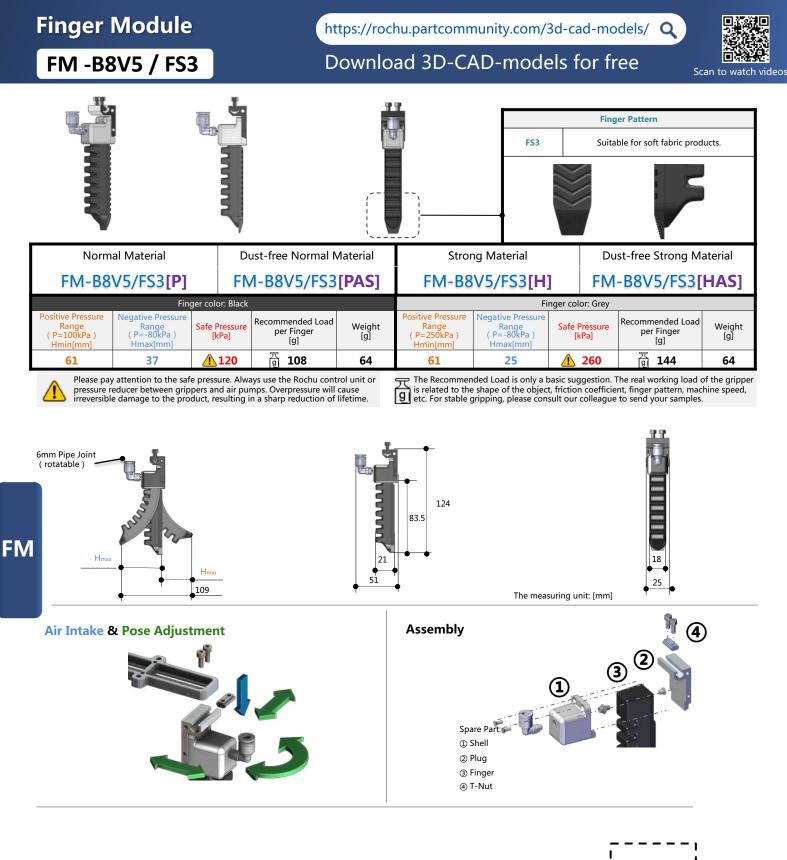
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

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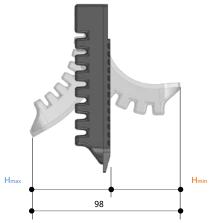


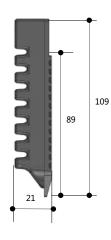
Finger I	Module		https://rochu.partcommunity.com/3d-cad-models/ Q								
F -B8T	/FS3		Download 3D-CAD-models for free								
LI LI LI	A COLOR										
Finger	r Pattern				Fe	atures					
<b>Finger</b> FS3	r Pattern Special Form					eatures					
FS3		Dus	st-free Normal N	Material	Suitable for s		Du	ust-free Strong N	Лaterial		
FS3 Norma	Special Form		st-free Normal N -B8T/FS3[F		Suitable for s	soft fabric products.		ust-free Strong M -B8T/FS3[H			
FS3 Norma <b>F-B8T</b>	Special Form Il Material (FS3[P] Finger				Suitable for s Stron <b>F-B8</b>	soft fabric products. ng Material <b>T/FS3[H]</b> Fir		-			
FS3 Norma	Special Form Il Material (/FS3[P] Finger of Negative Pressure	F-		PAS]	Suitable for s	soft fabric products. ng Material <b>T/FS3[H]</b>	F	-	IAS]		

Prease pay attention of the safe pressure. Always use the round of the of the pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

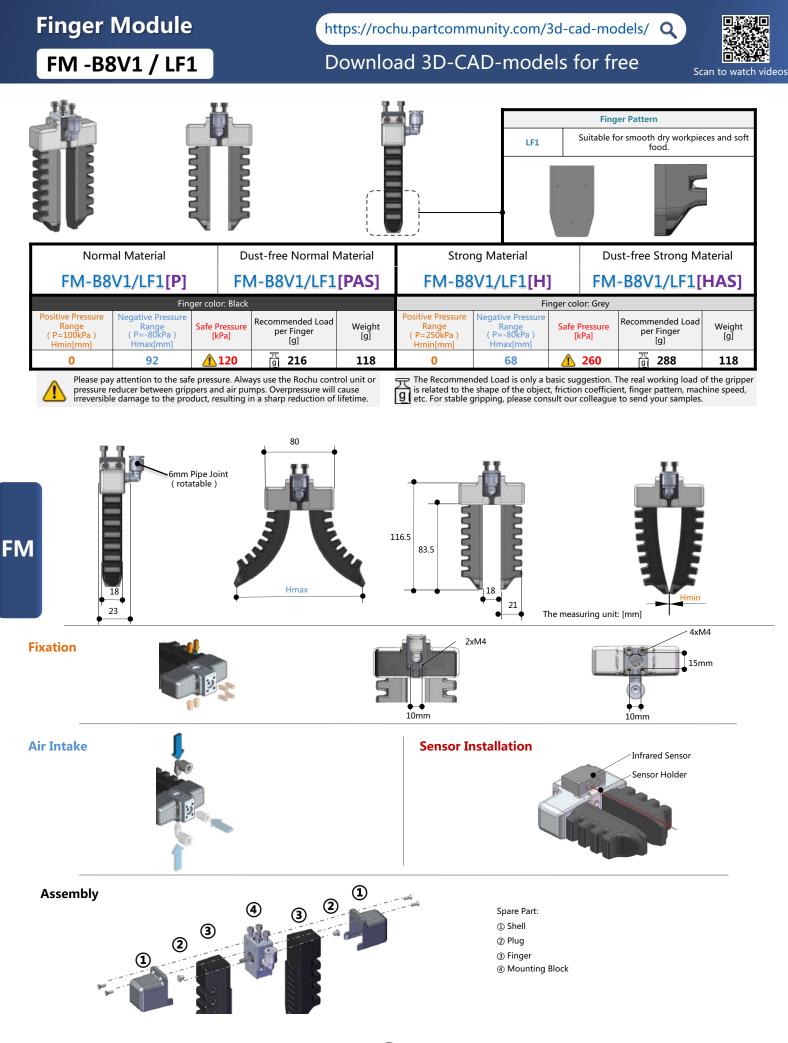
g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

## **Dimension Parameters**

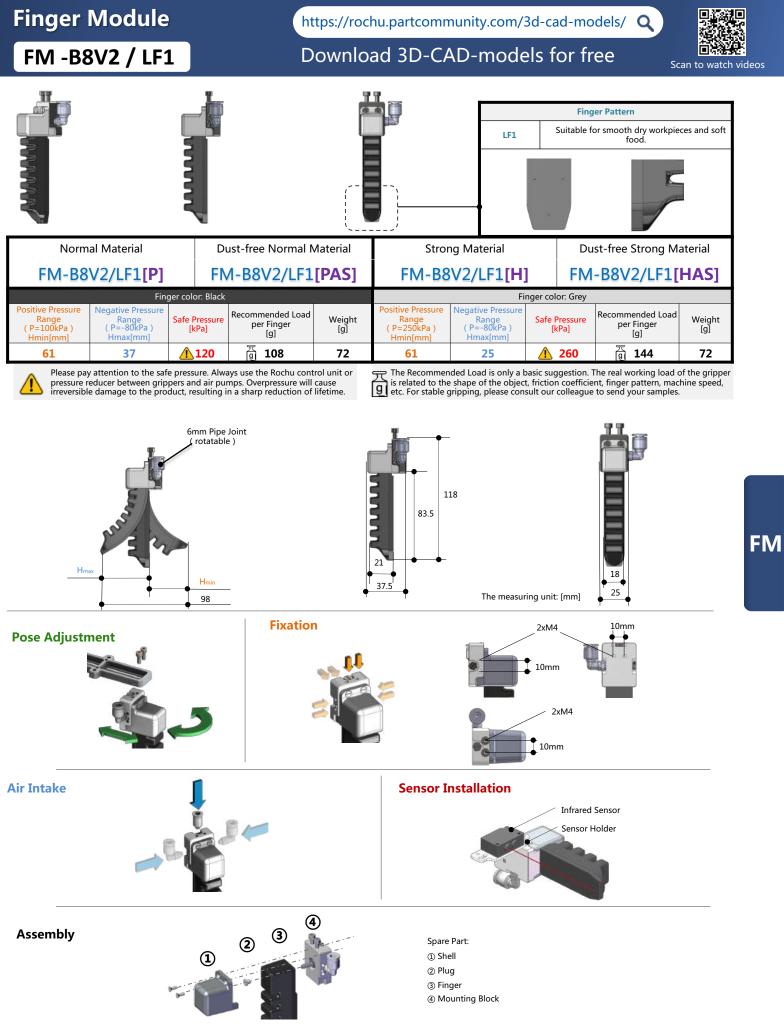




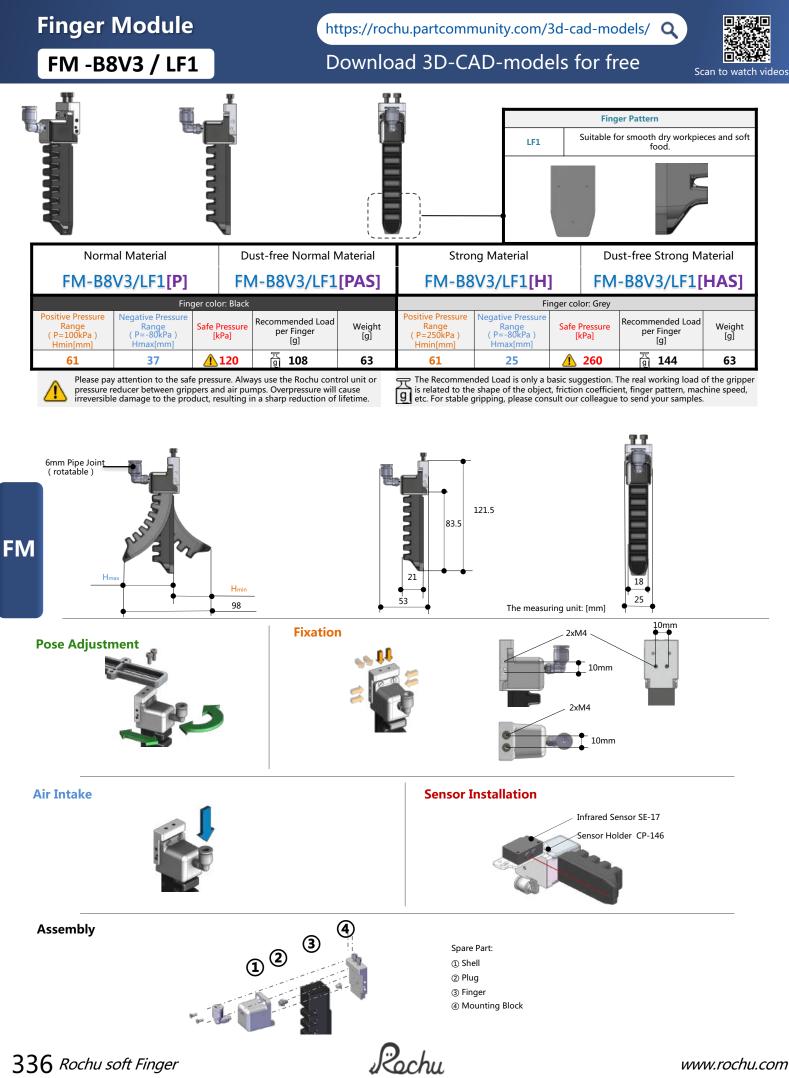


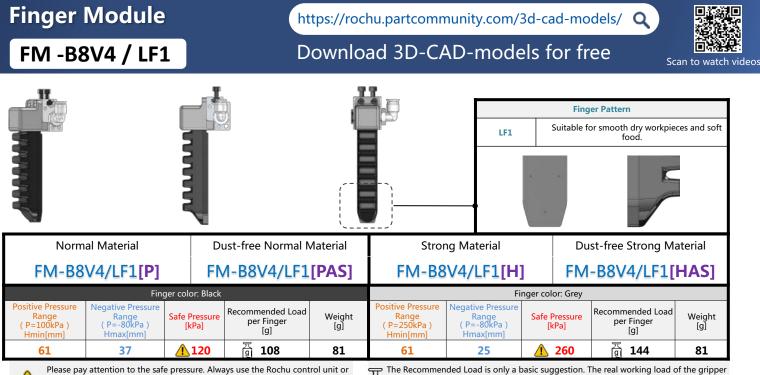


Rochu



Pochu

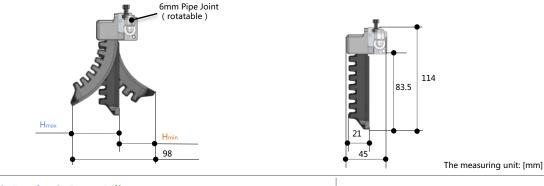


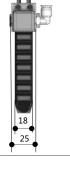




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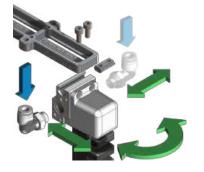
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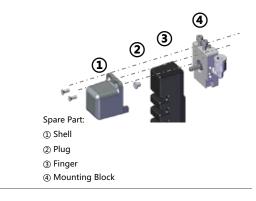


FM

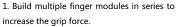
Air Intake & Pose Adjustment



Assembly

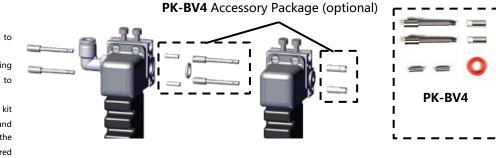




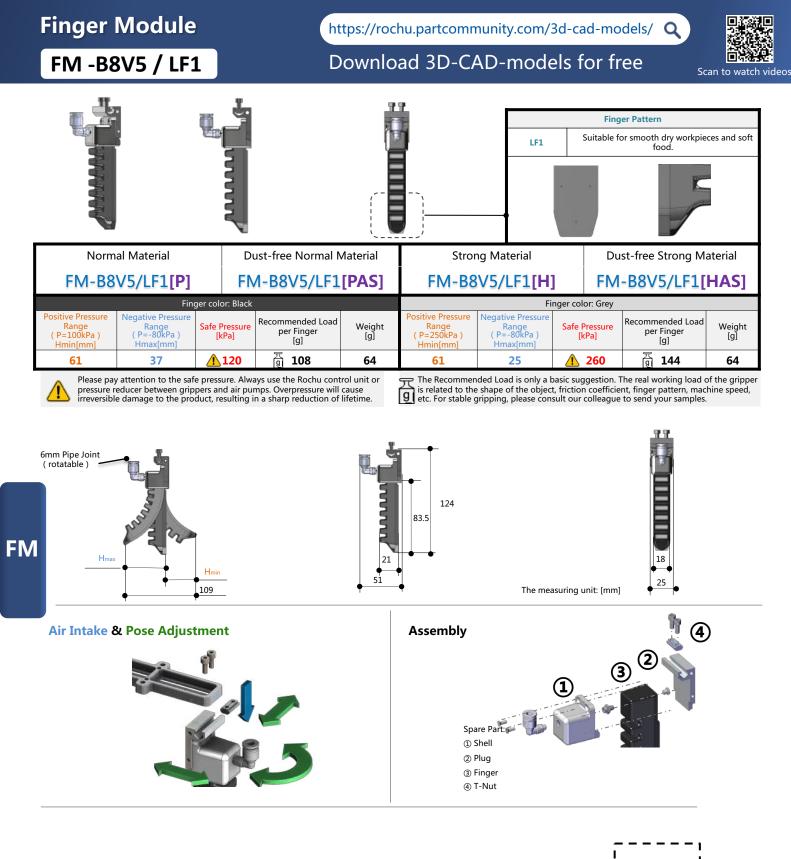


2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.









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Finger	Module	https://rock	cad-models/ Q	
F -B8T	/ LF1	Downloa	ad 3D-CAD-models	for free Scan to watch vide
Finge	r Pattern		Features	
LF1	Special Form	Su	iitable for smooth dry workpieces and soft for	pd.
Norma	al Material	Dust-free Normal Material	Strong Material	Dust-free Strong Material

F-B8T/LF1[PAS]

Recommended Load per Finger [g]

108

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Dimension	Parameters
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F-B8T/LF1[P]

Negative Pressure Range ( P=-80kPa )

Hmax[mm]

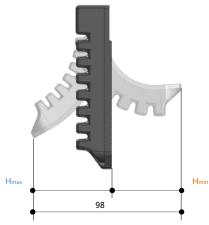
37

Positive Pressure Range ( P=100kPa )

Hmin[mm]

61

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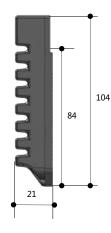


Finger color: Black

Safe Pressure [kPa]

<u>^ 120</u>

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.



Positive Pressure Range (P=250kPa) Hmin[mm]

61

Weight [g]

32

F-B8T/LF1[H]

Negative Pressure Range ( P=-80kPa )

Hmax[mm]

25

Finger color: Grey

1 260

The Recommended Load is only a basic suggestion. The real working load of the gripper g etc. For stable gripping, please consult our colleague to send your samples.

Safe Pressure [kPa]



F-B8T/LF1[HAS]

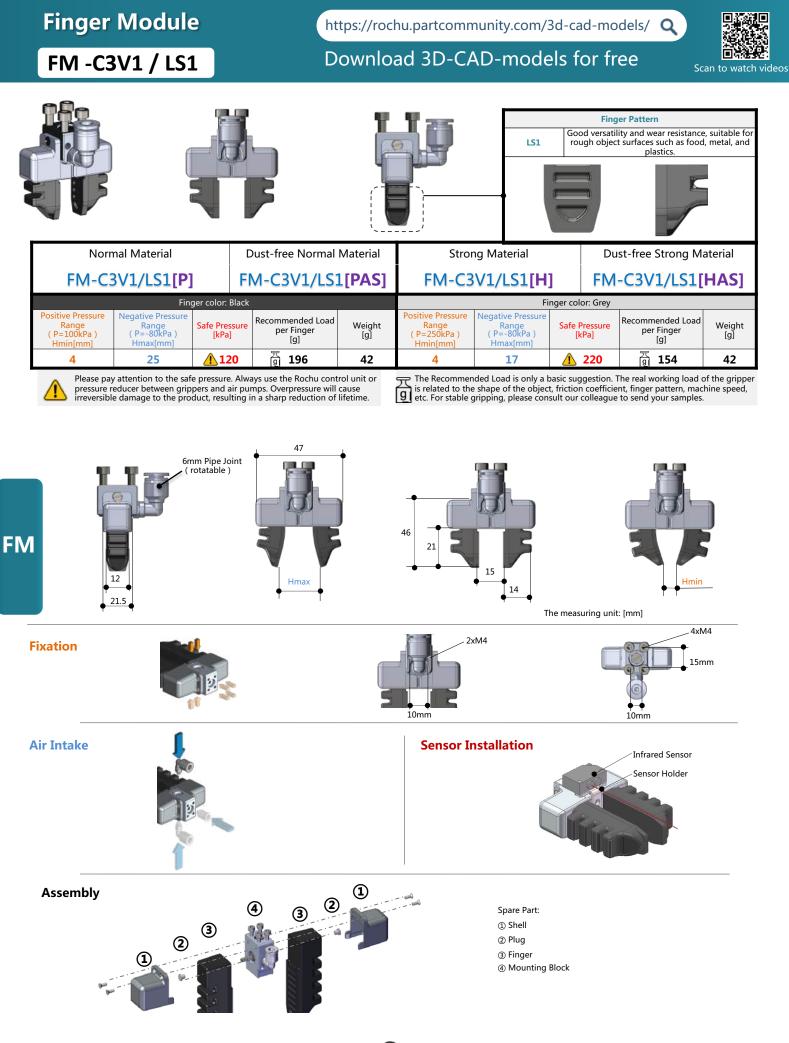
Recommended Load per Finger [g]

员 144

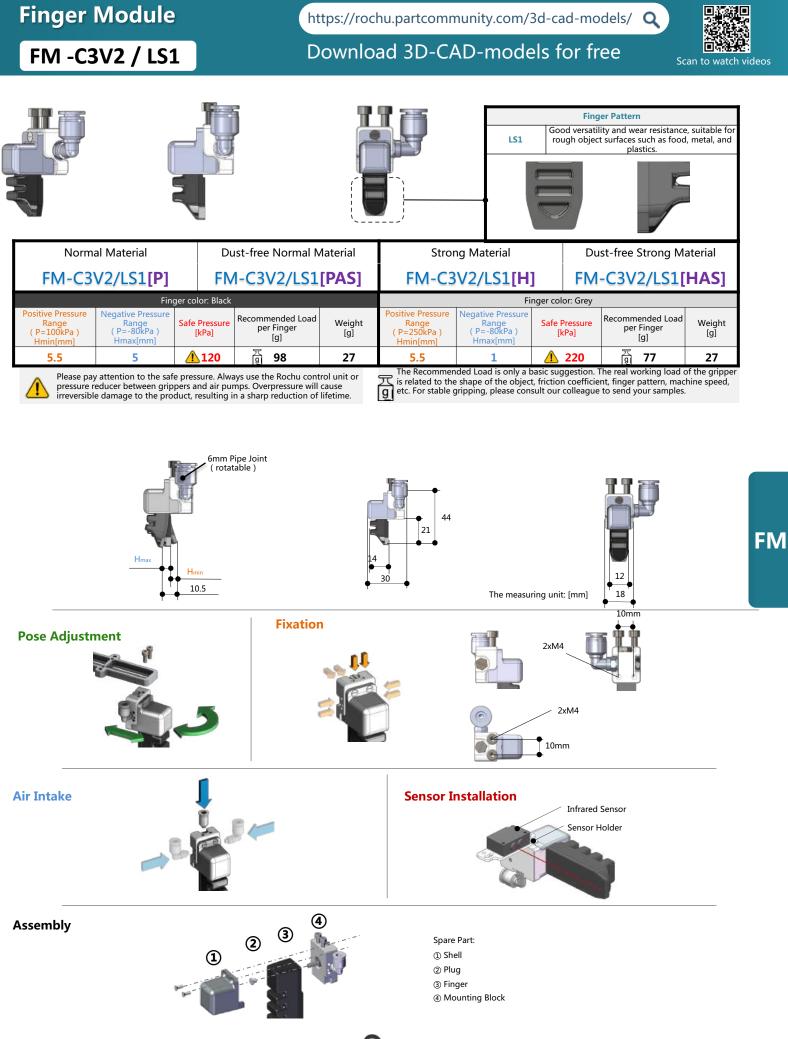
Weight [g]

32

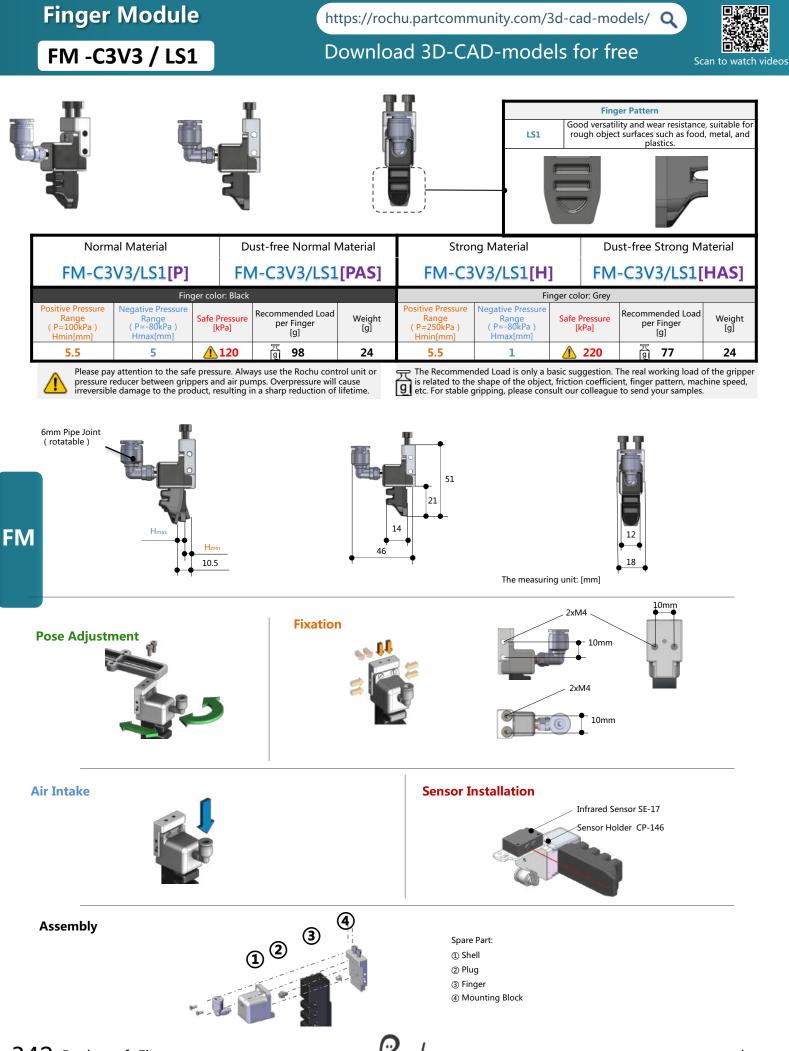
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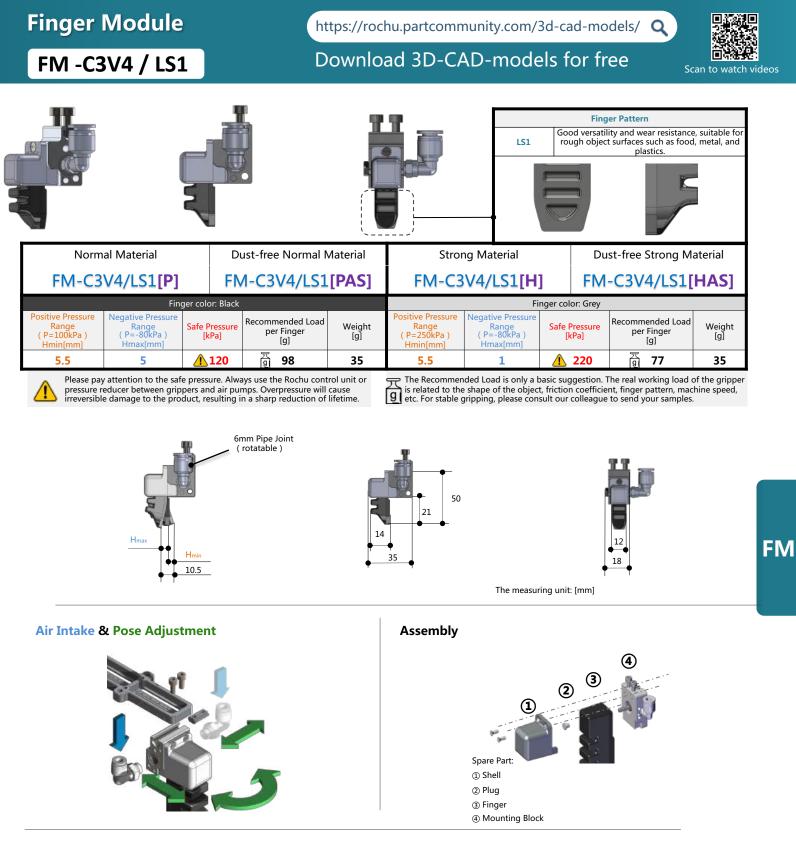
Rochu



Rochu



Rochu



#### Series combination:

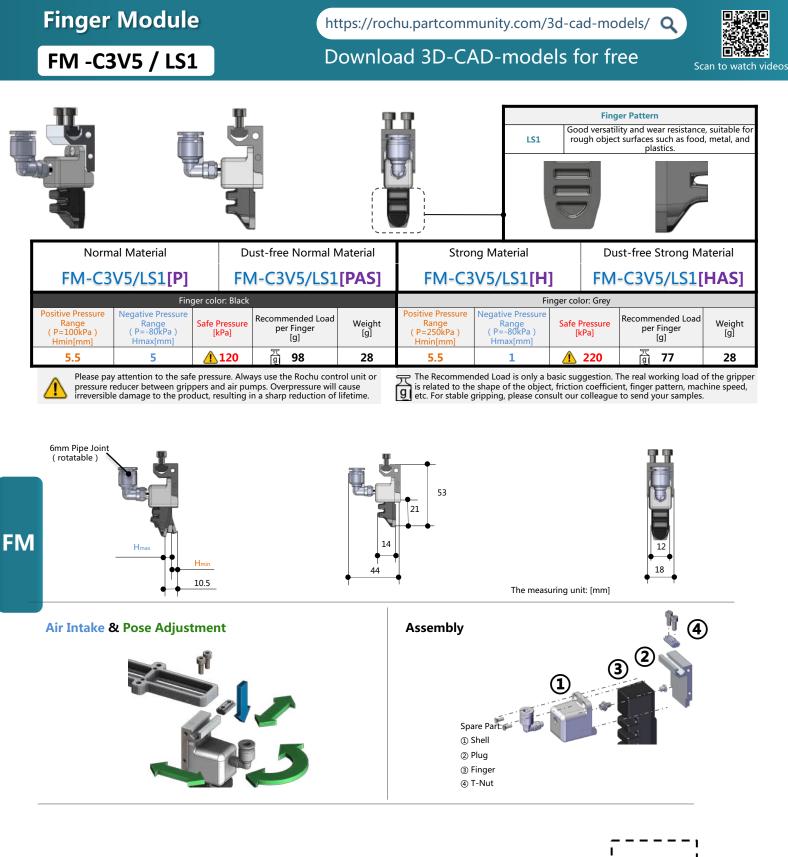
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Finger Module	https://rochu.partcommunity.com/3d-cad-models/ Q
F -C3T / LS1	Download 3D-CAD-models for free Scan to watch video
Finger Pattern	Features
LS1 Standard form	Good versatility and wear resistance, suitable for rough object surfaces such as food, metal, and plastics.

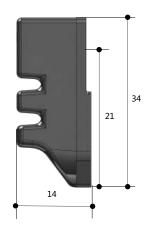
LS1	Standard forr	Standard form Good versatility and wear resistance, suitable for rough object surfaces such as food					es such as food, r	netal, and plastics.		
Norma	al Material	Du	ust-free Normal Material Strong Material Dust-free S			ist-free Strong Ma	aterial			
F-C31	[/LS1[ <b>P]</b>	F	-C3T/LS1[P	PAS]	F-C3	T/LS1[H]	F	F-C3T/LS1[HAS]		
	Fing	ger color: Black			Finger color: Grey					
Positive Pressure Range (P=100kPa) Hmin[mm]	Negative Pressure Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range (P=250kPa) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	
5.5	5	120	页 98	4	5.5	1	1 220	页 页 <b>77</b>	4	
- Please pay	vattention to the saf	o prossuro. Alw	ave use the Pochu cont	trol unit or		ded Load is only a h	asic suggestion	The real working load o	of the gripper	

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

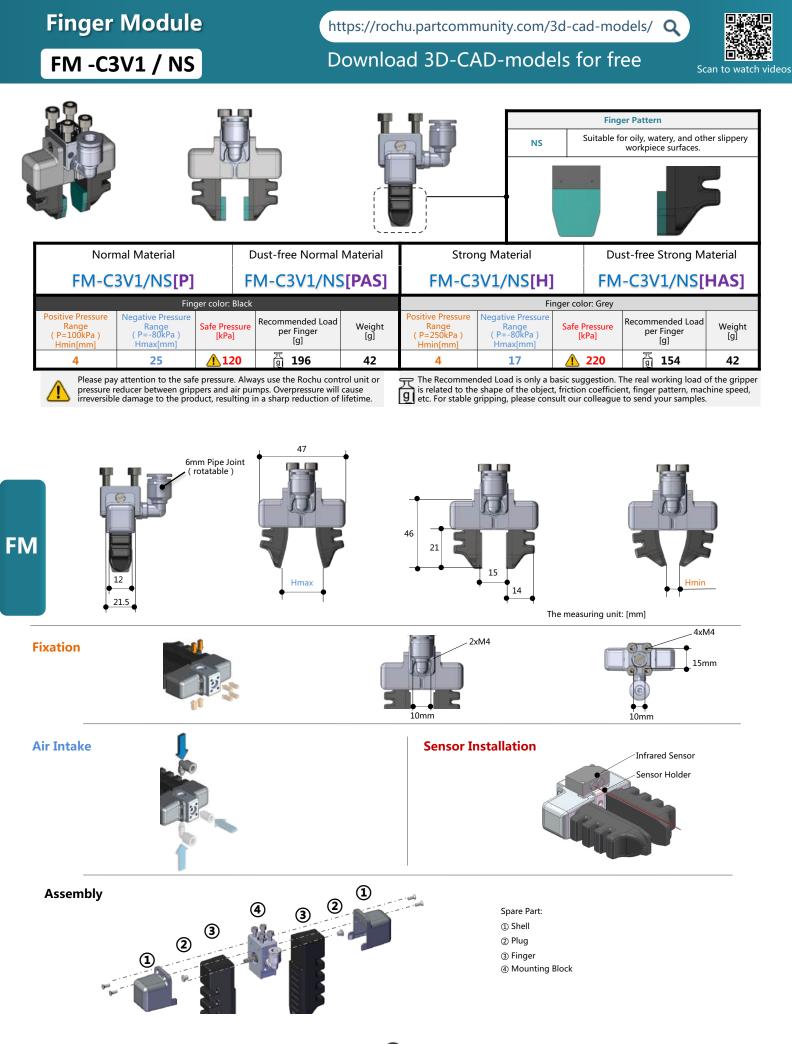
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

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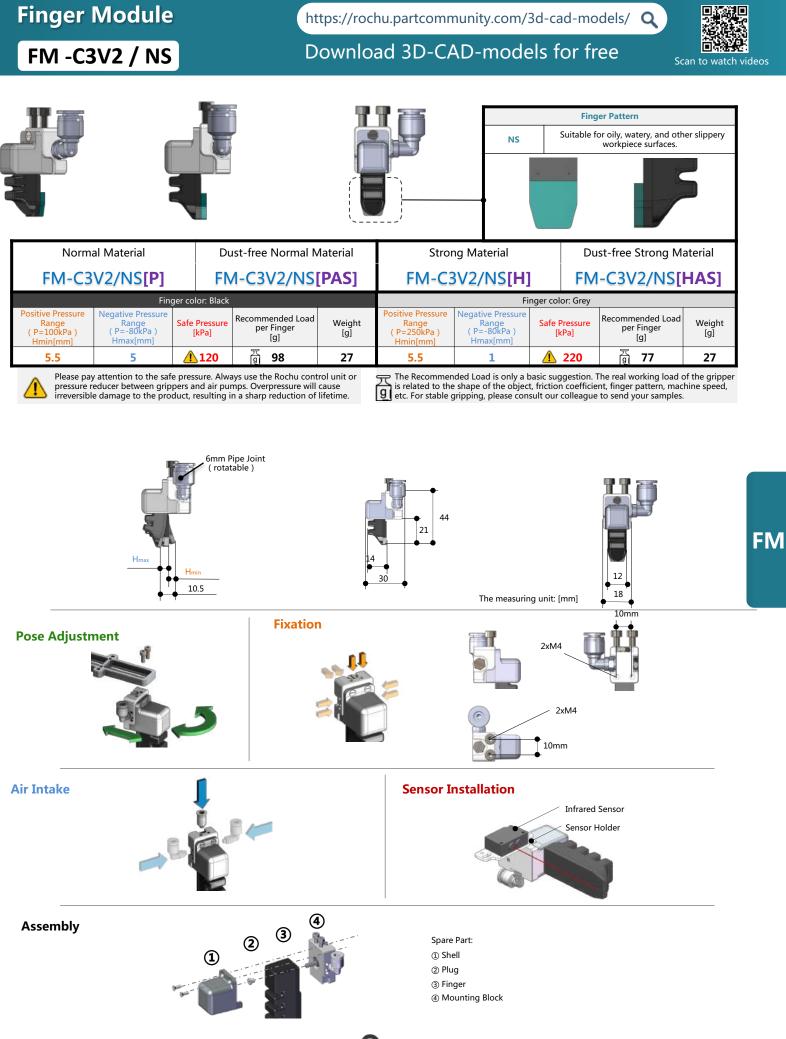






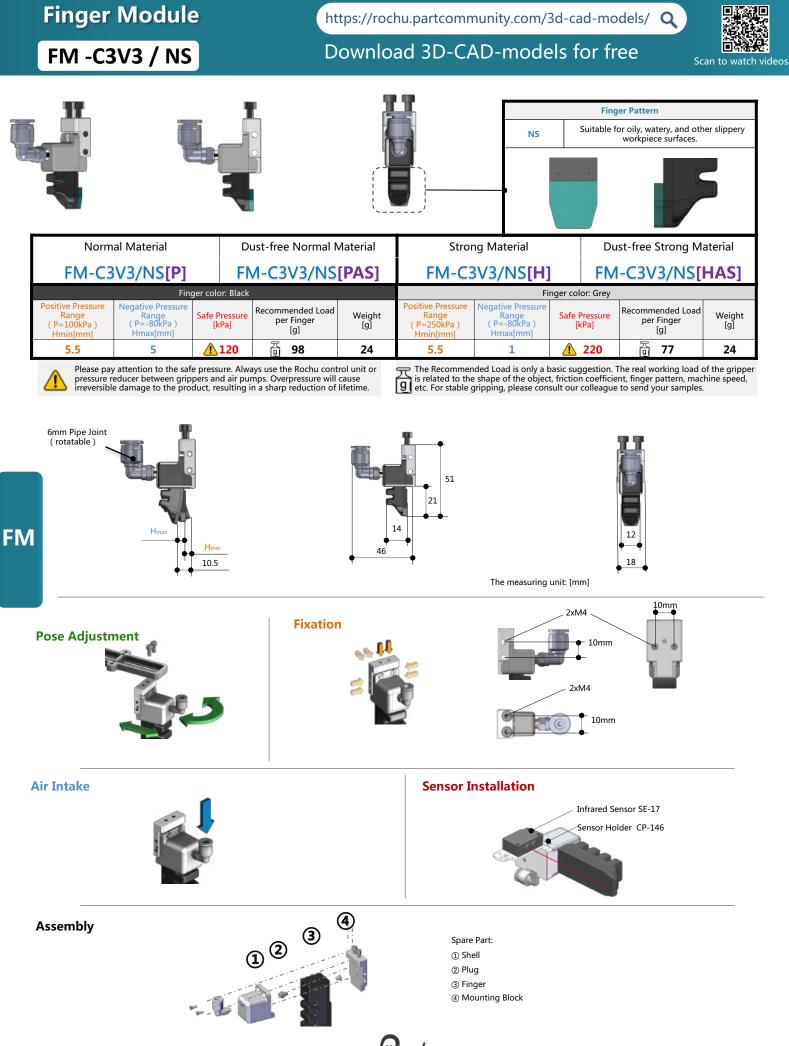


Rochu

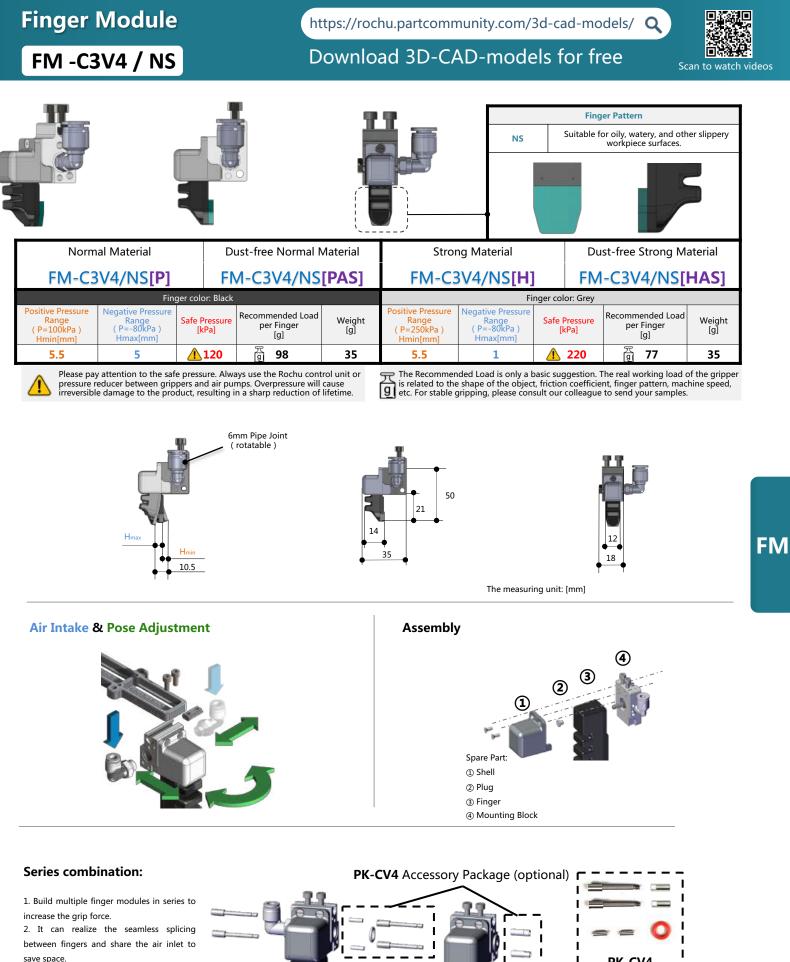


Rochu

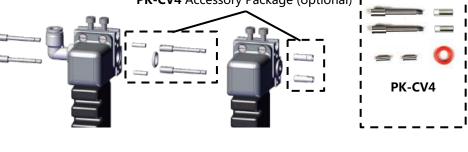
Rochu soft Finger 347



Rochu

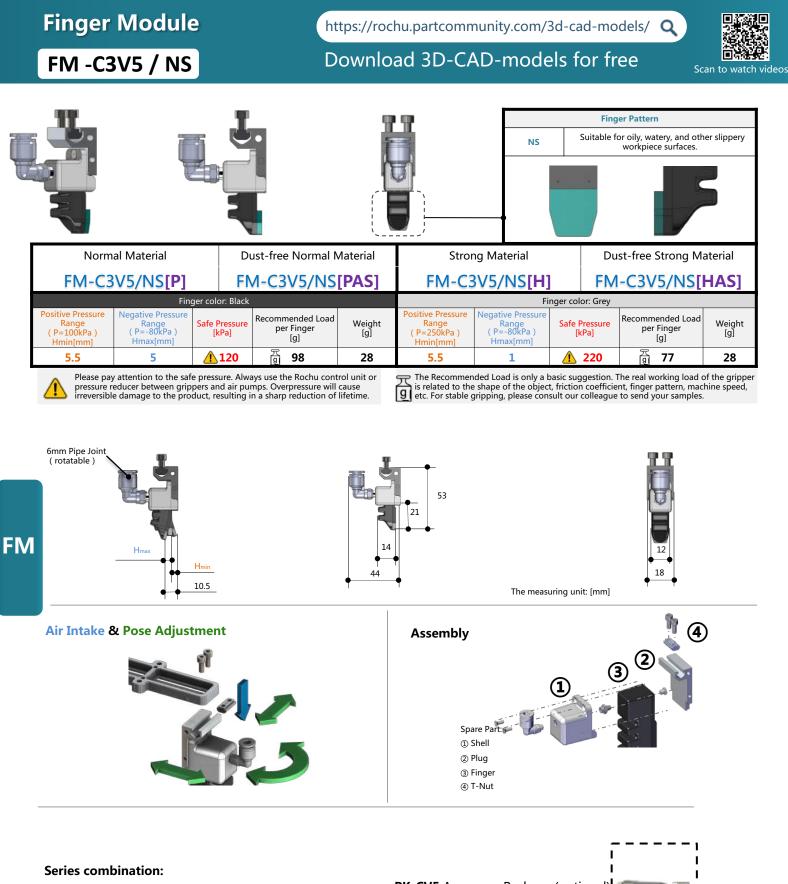


\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu





- 1. Build multiple finger modules in series to increase the grip force.
- 2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

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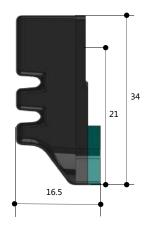
Finger	Module		https://rochu.partcommunity.com/3d-cad-models/ Q							
F -C3T	/ NS		۵	Downloa	ad 3D-CA	AD-mode	els for fr	ree	Scan to watch	
					<u> </u>		0			
Finge	r Pattern				Fe	eatures				
Finge	r Pattern Special Form			Suitable		e <b>atures</b> d other slippery worl	kpiece surfaces.			
NS		Dust-	free Normal		e for oily, watery, an			ust-free Strong	g Material	
NS Norma	Special Form		free Normal	Material	e for oily, watery, an Stroi	d other slippery worl	Du	ust-free Strong	-	
NS Norma	Special Form al Material T/NS[P] Finger of Negative Pressure	F-( olor: Black		Material PAS]	e for oily, watery, an Stroi	d other slippery worl ng Material ST/NS[H]	Du		[HAS]	

pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

g etc. For stable gripping, please consult our colleague to send your samples.

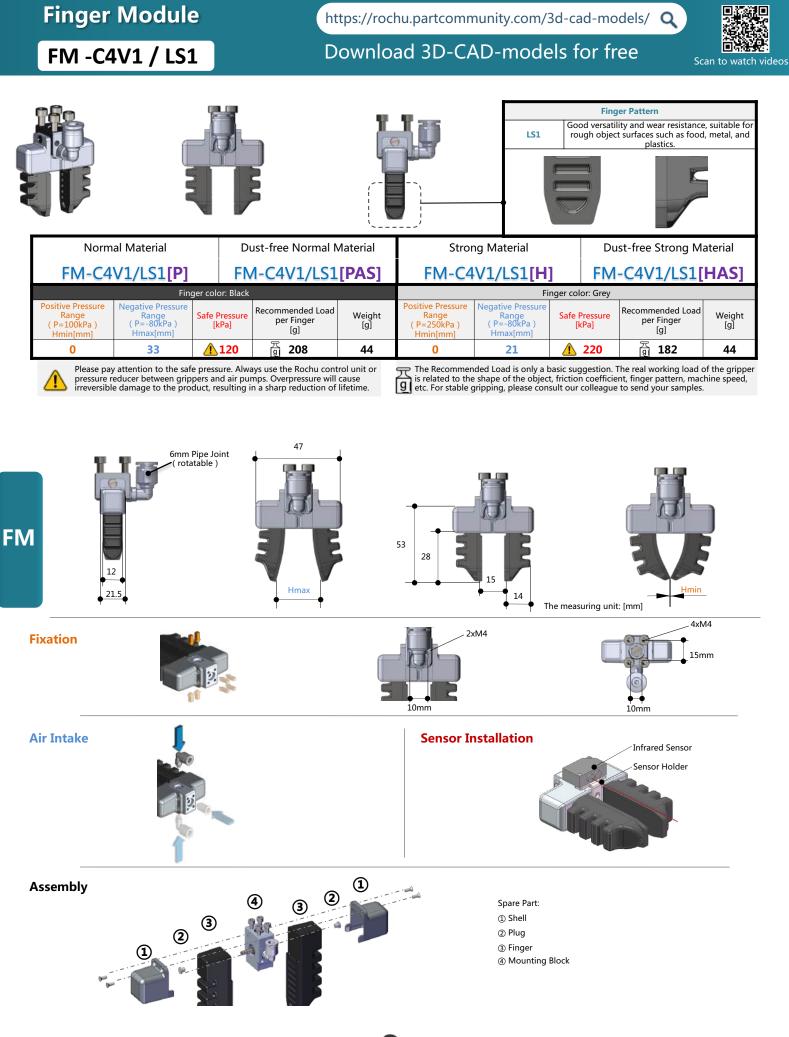
# **Dimension Parameters**

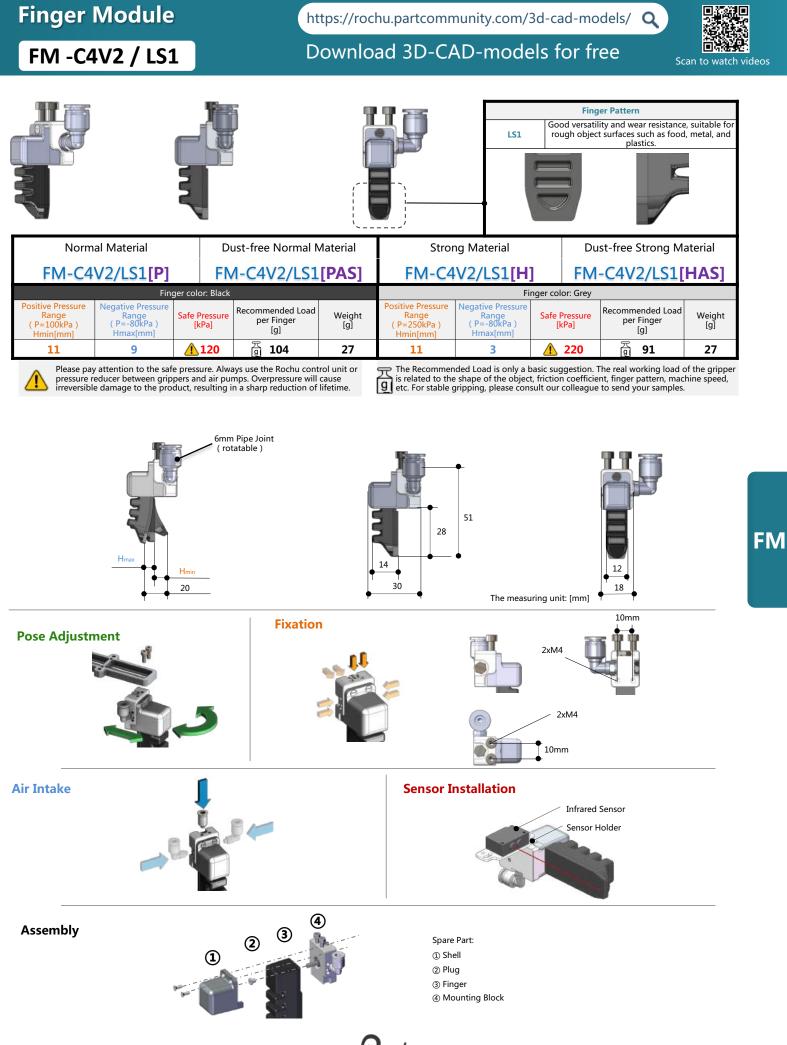






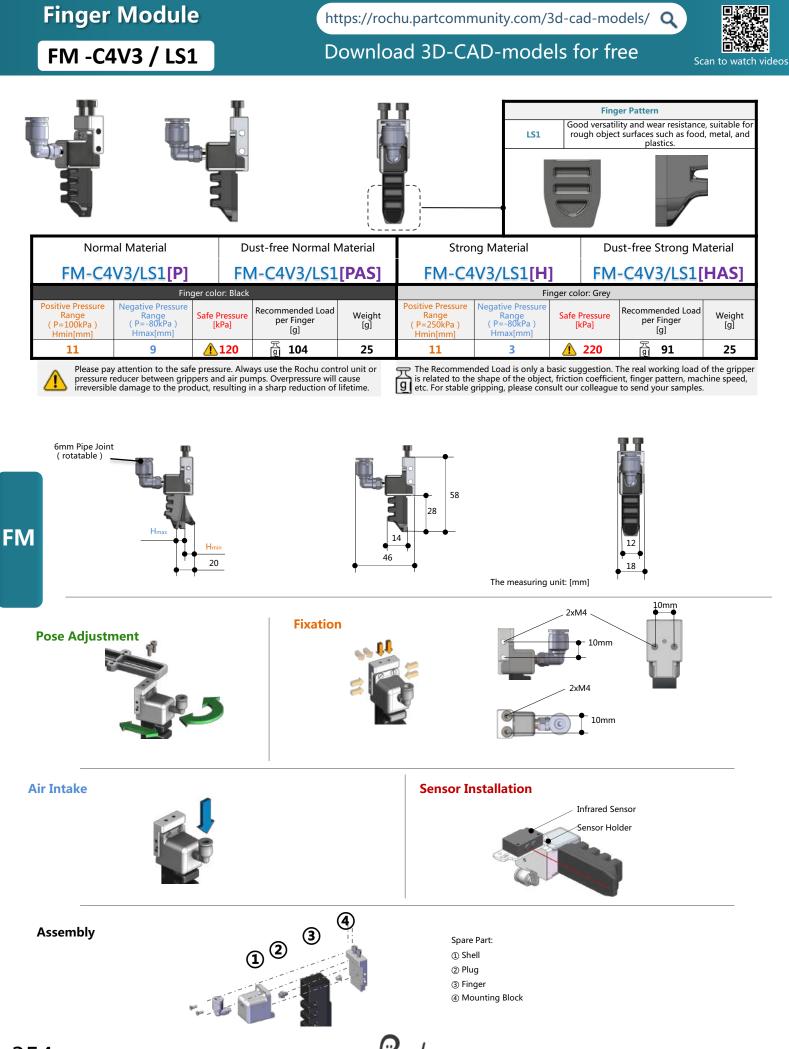




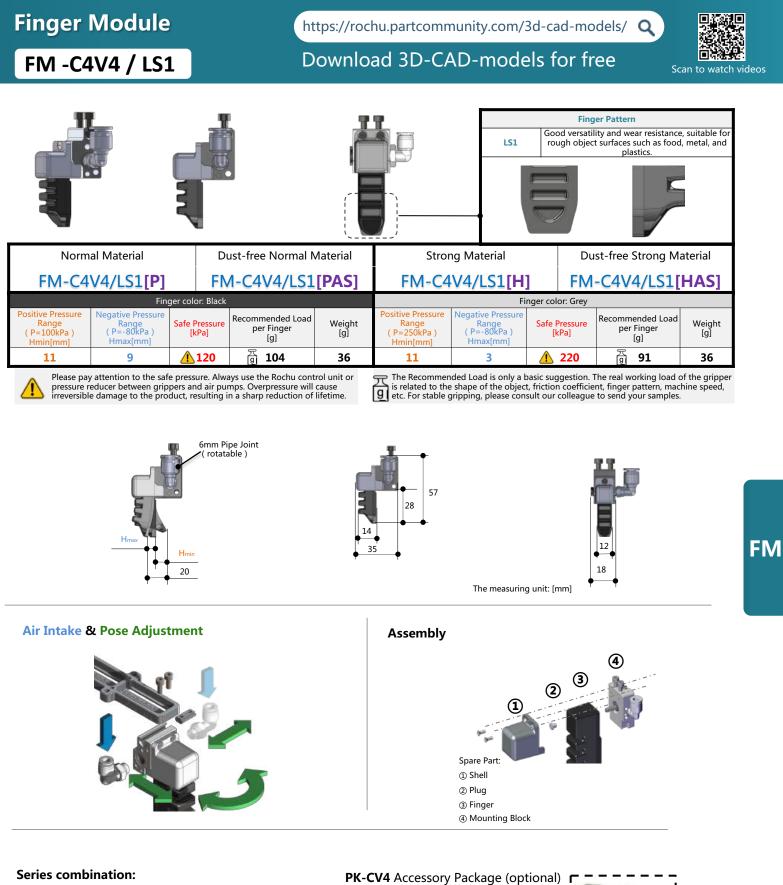


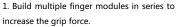
Rochu

Rochu soft Finger 353



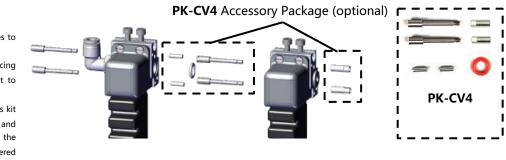
Rochu



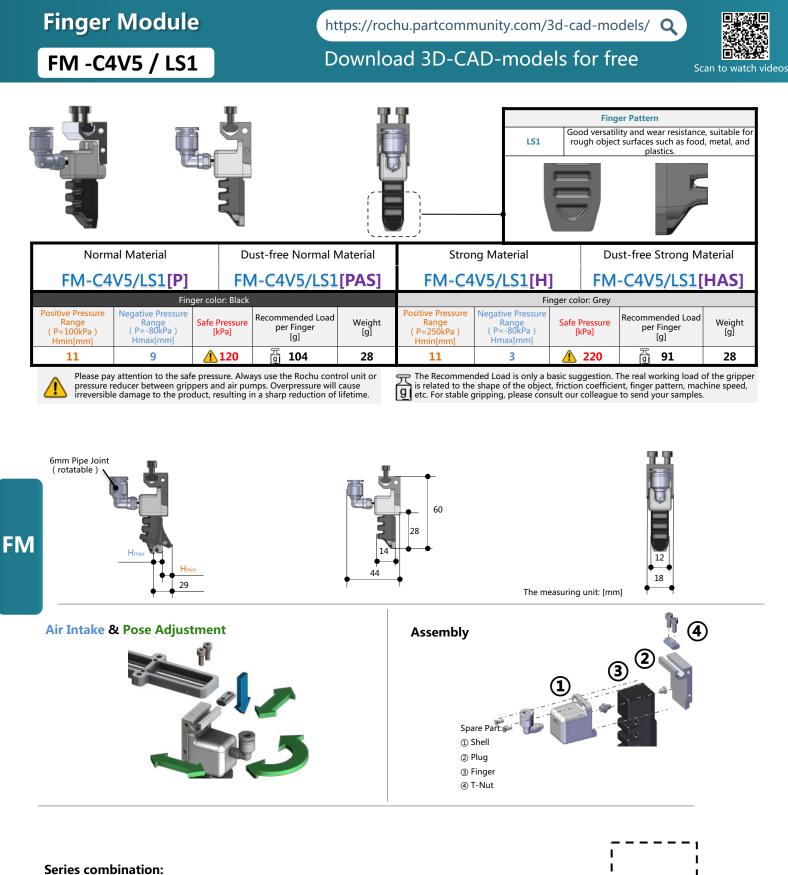


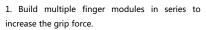
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu





2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

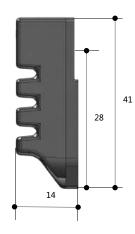
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Finger I	Module		https://rochu.partcommunity.com/3d-cad-models/ Q								
F -C4T	/ LS1		D	ownloa	ad 3D-CA	AD-mode	els for f	ree <sub>so</sub>	an to watch vi		
				, ,							
Finger	r Pattern				Fe	atures					
LS1	Standard form		Good versatili	ity and wear res	sistance, suitable for	rough object surface	es such as food,	metal, and plastics.			
Norma	Normal Material Dust-free Normal M				Strong Material Dust-free Strong Materia				aterial		
F-C4T/LS1[P] F-C4T/LS1[PAS				AS]	F-C4T/LS1[H] F-C4T/LS1[HAS]						
		Finger color: Black					Finger color: Grey				
	Finge	er color: Black					nger color: Grey	T			
Positive Pressure Range ( P=100kPa ) Hmin[mm]	Finge Negative Pressure	er color: Black Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range ( P=250kPa ) Hmin[mm]	Fin Negative Pressure Range (P=-80kPa) Hmax[mm]	nger color: Grey Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]		
Positive Pressure Range (P=100kPa)	Finge Negative Pressure Range ( P=-80kPa )	Safe Pressure	per Finger	Weight [g] 5	Range ( P=250kPa )	Negative Pressure Range ( P=-80kPa )	Safe Pressure	per Finger			

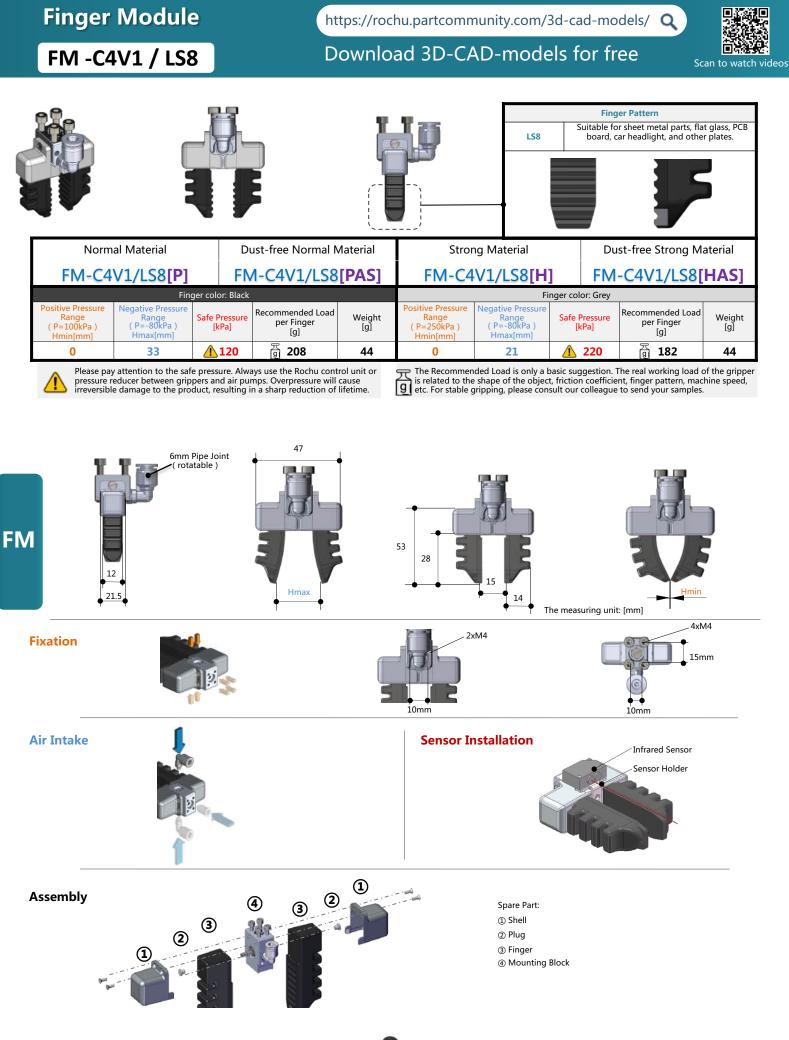
### **Dimension Parameters**



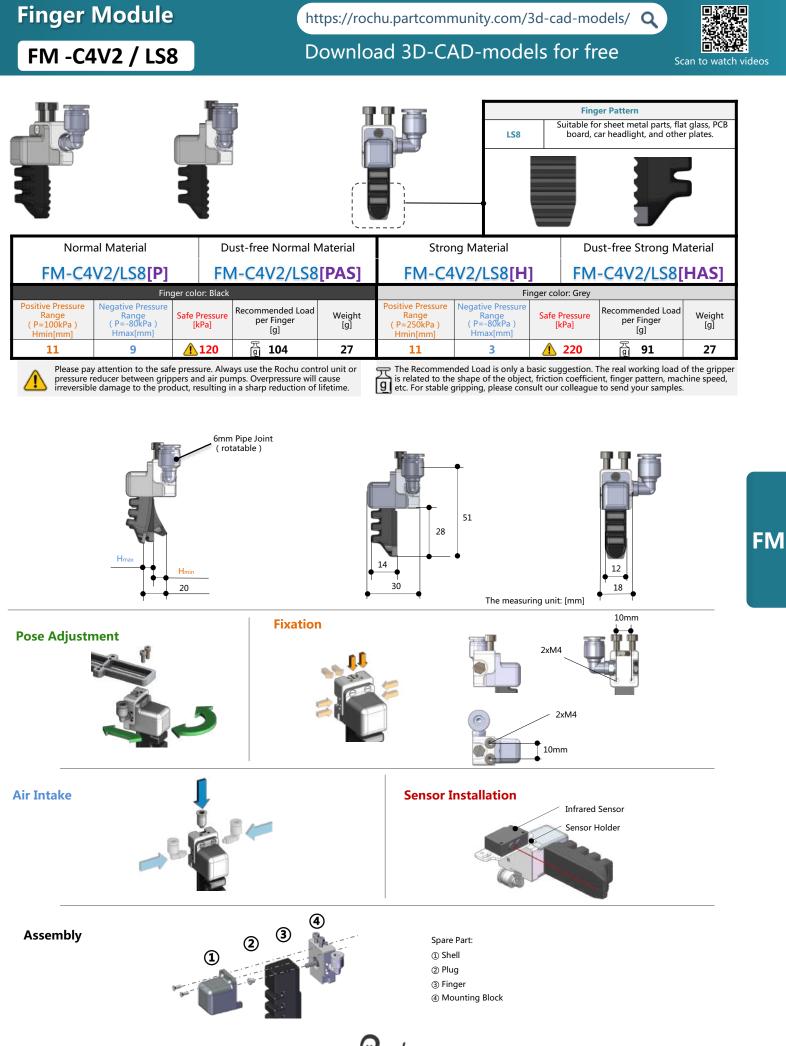




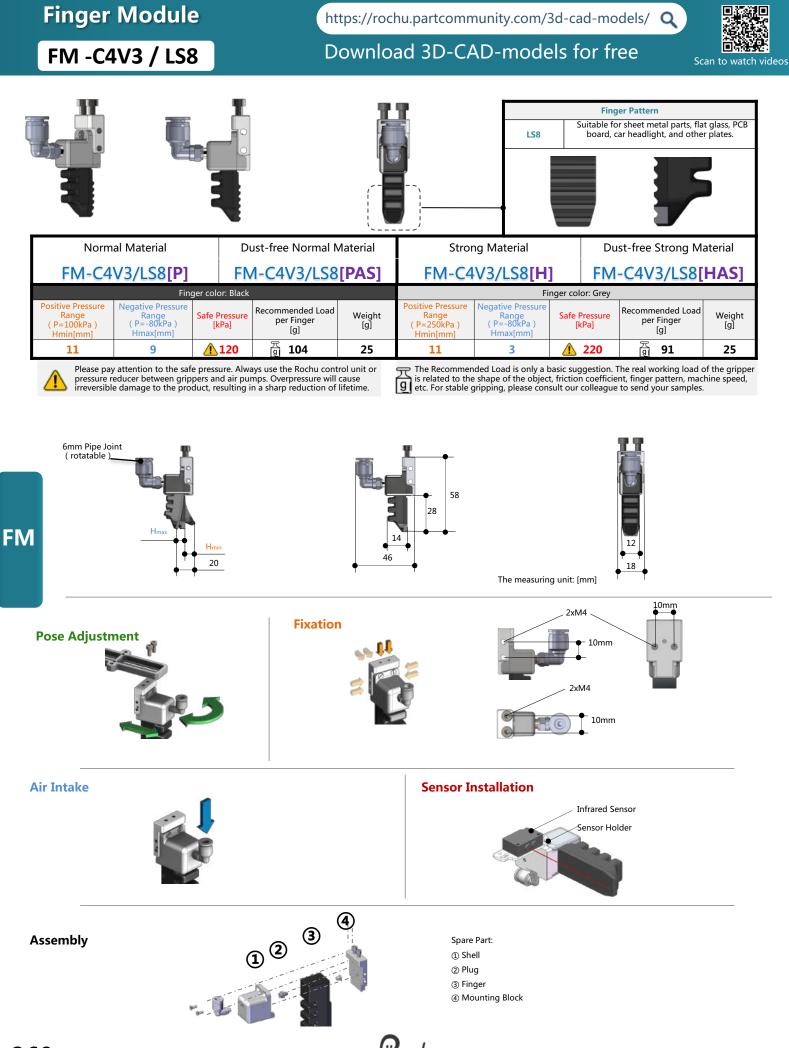
FM



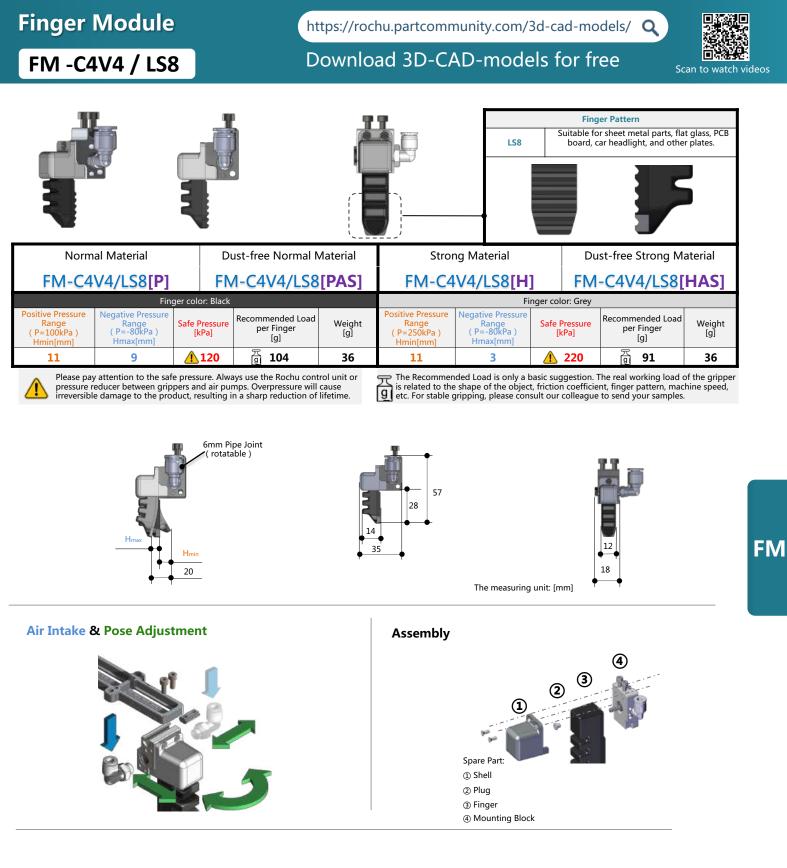




Rochu



Rochu

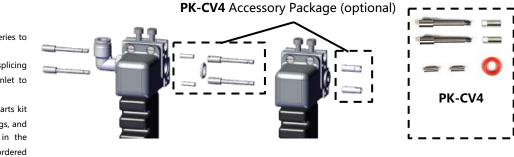


#### Series combination:

1. Build multiple finger modules in series to increase the grip force.

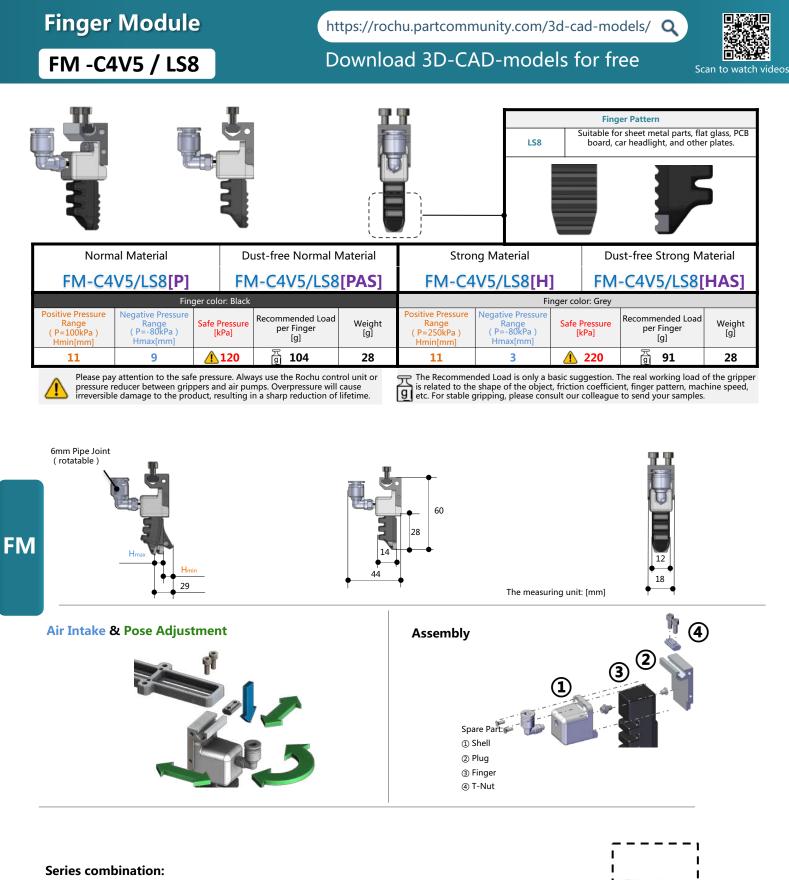
2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu





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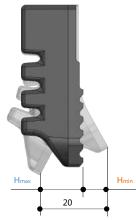


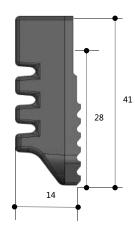
-inger	Module	http	ps://roch	nu.partcomn	nunity.com/3	d-cad-mo	dels/ Q	
F -C4T	/ LS8	Do	ownloa	ad 3D-CA	AD-model	s for fr	ee	Scan to watc
	<b>GGC</b>		vv	Y		0		
Finge	er Pattern			Fe	atures			
Finge	er Pattern Standard form	Suitab	ble for sheet r		<b>atures</b> s, PCB board, car heac	llight, and other	r plates.	
LS8		Suitab Dust-free Normal Mai		metal parts, flat glas			r plates. st-free Strong N	Material
LS8 Norma	Standard form		aterial	metal parts, flat glas Stror	s, PCB board, car heac	Du		
LS8 Norma F-C41	Standard form al Material T/LS8[P] Finger co	Dust-free Normal Mat	aterial	metal parts, flat glas Stror F-C4	s, PCB board, car heac ng Material <b>T/LS8[H]</b> Fing	Du	st-free Strong N	
LS8 Norma	Standard form al Material <b>[/LS8[P]</b> Finger co Negative Pressure	Dust-free Normal Mar F-C4T/LS8[PA	aterial	metal parts, flat glas Stror	s, PCB board, car head ng Material <b>T/LS8[H]</b> Fing Negative Pressure	Du F-	st-free Strong N	HAS]

Please pay attention to the safe pressure. Always use the Rochu control unit of pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

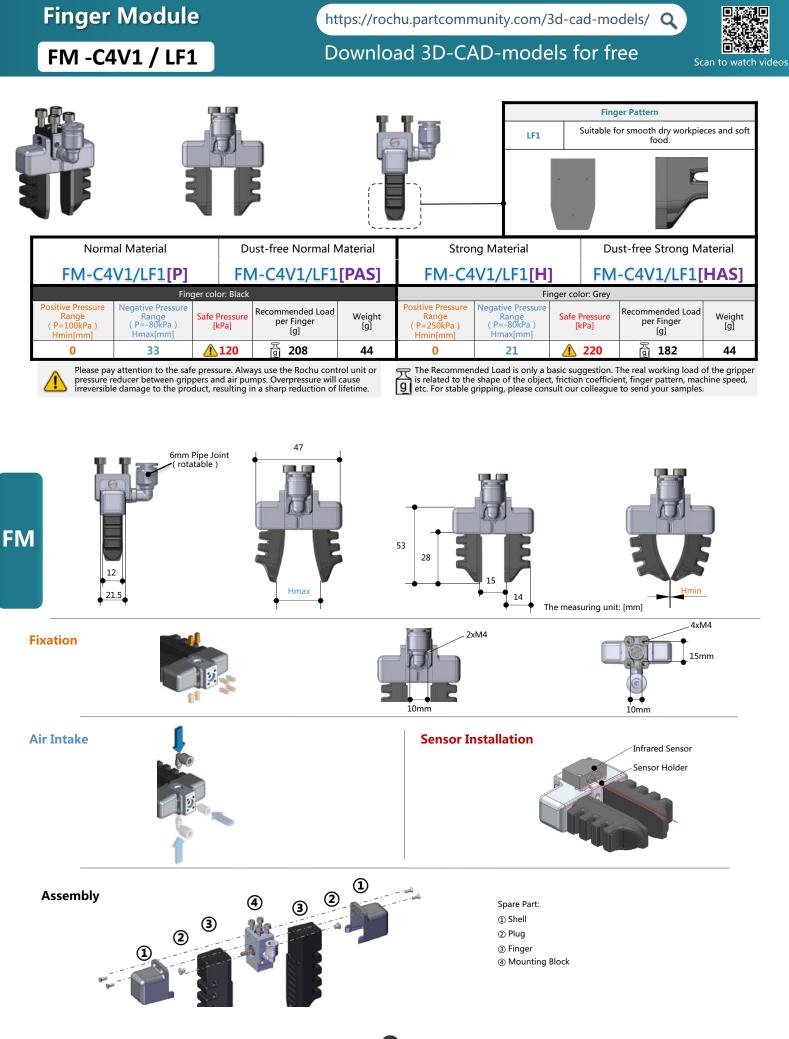
# **Dimension Parameters**



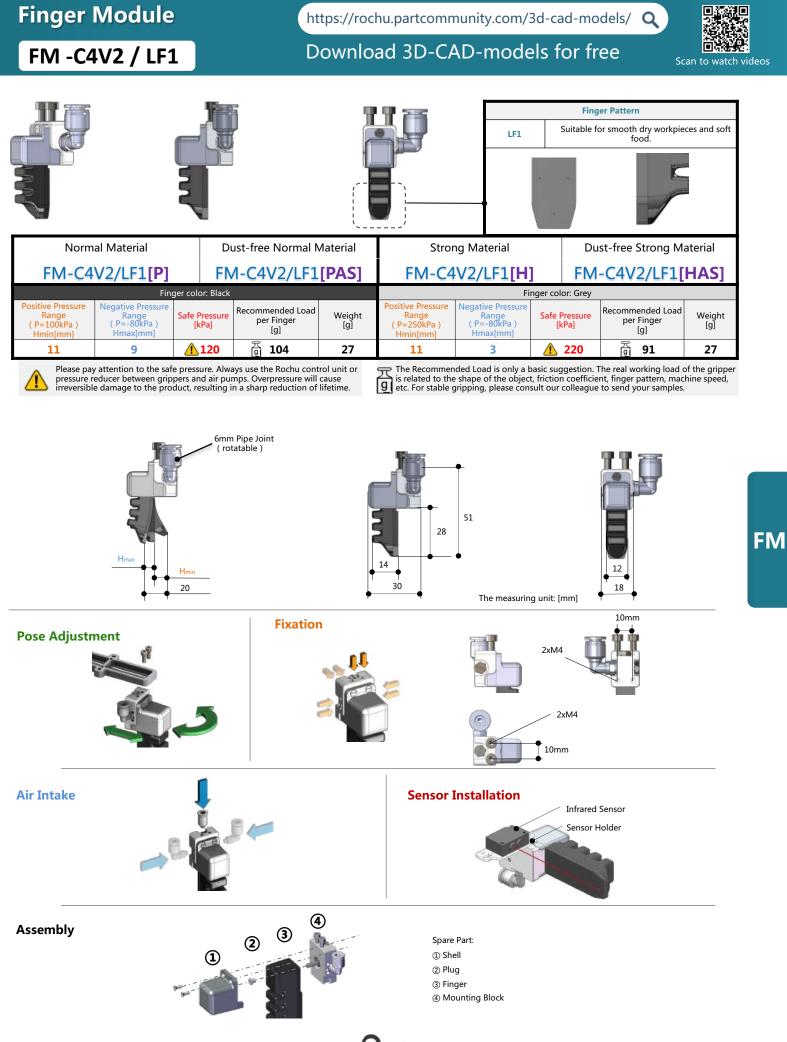




FM

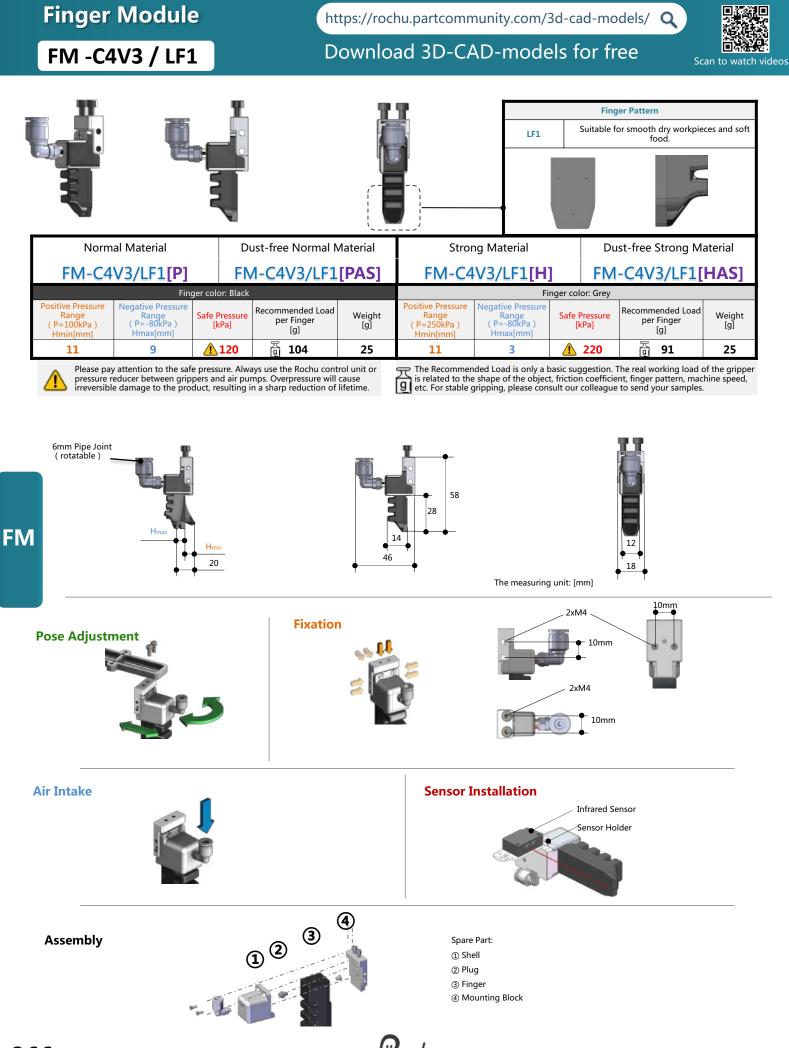


Rochu

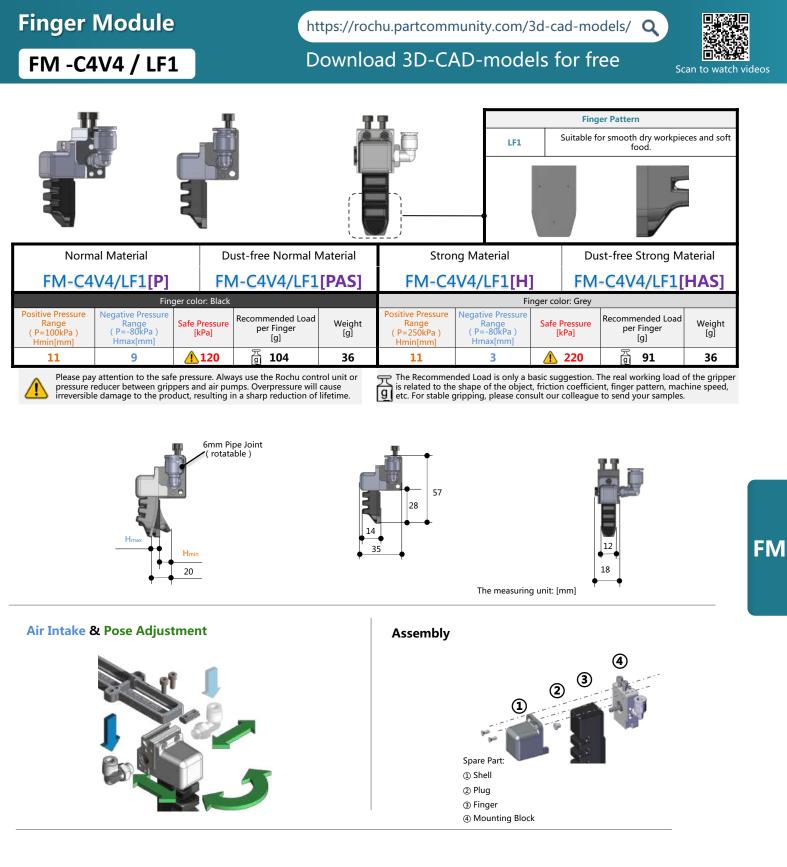


Rochu

Rochu soft Finger 365



Rochu

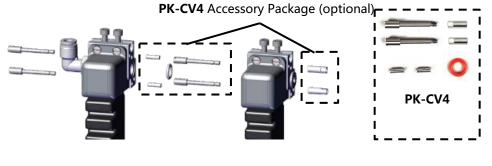




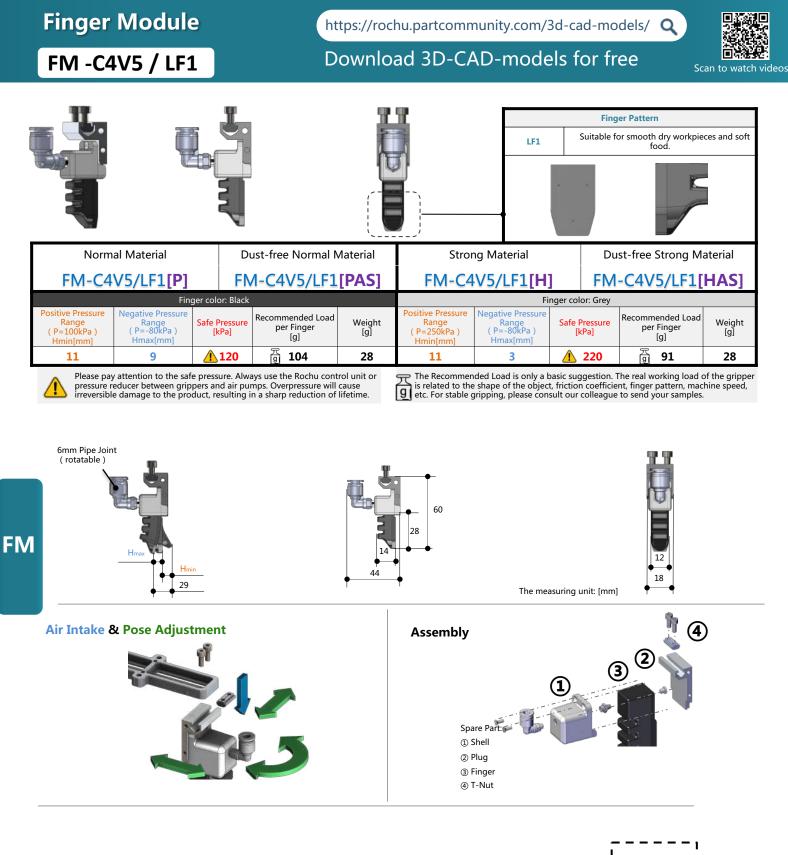
1. Build multiple finger modules in series to increase the grip force.

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Pochu





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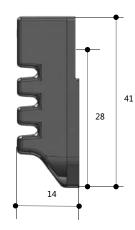
Finger N	/lodule		h	ttps://rocł	nu.partcomm	nunity.com/3	3d-cad-mo	odels/ Q		
F -C4T /	LF1		D	Download 3D-CAD-models for free sc					can to watch vic	
				<u>vv</u>						
Finger	Pattern				Fe	atures				
LF1	Special Form			Su	uitable for smooth d	ry workpieces and so	oft food.			
Normal Material			ust-free Normal N	Material	Strong Material		Du	Dust-free Strong Material		
F-C4T/LF1[P] F-C4T			-C4T/LF1[F	PAS]	F-C4T/LF1[H]			F-C4T/LF1[HAS]		
Positive Pressure	Finger color: Black Positive Pressure Negative Pressure Decommended Load					Fin Negative Pressure	nger color: Grey			
Range ( P=100kPa ) Hmin[mm]		fe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Positive Pressure Range (P=250kPa) Hmin[mm]	Range ( P=-80kPa ) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	
11	9	120	<b>斎 104</b>	5	11	3	1 220	<u> </u>	5	

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

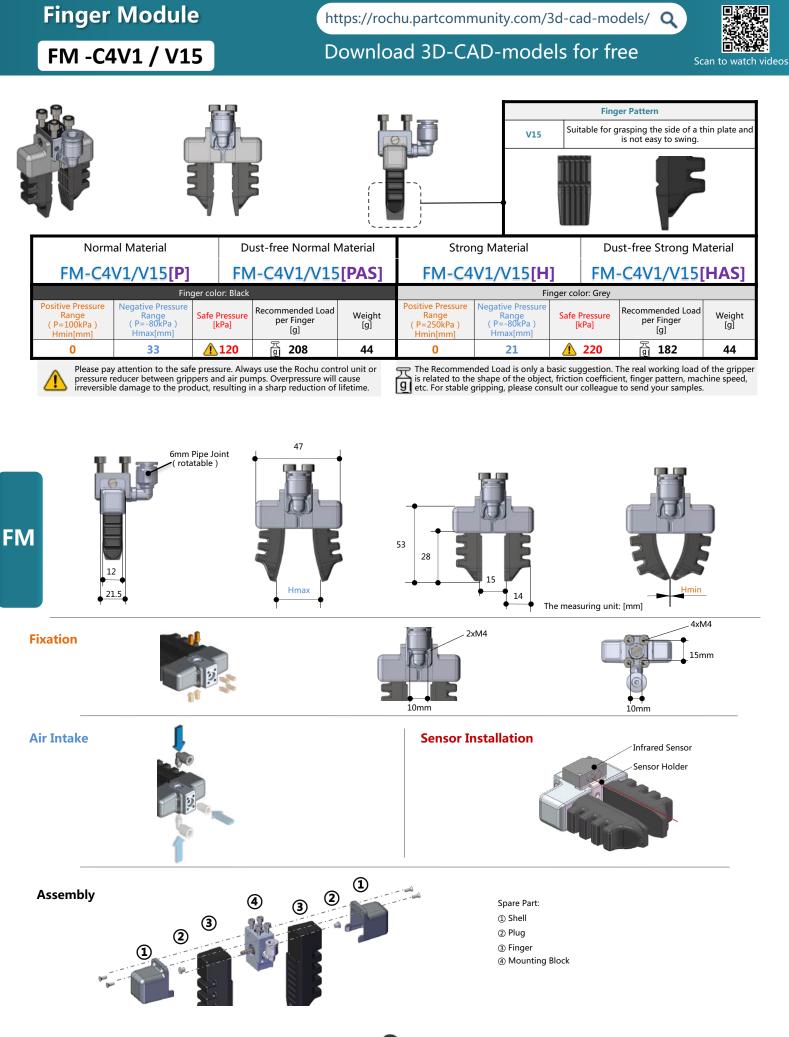
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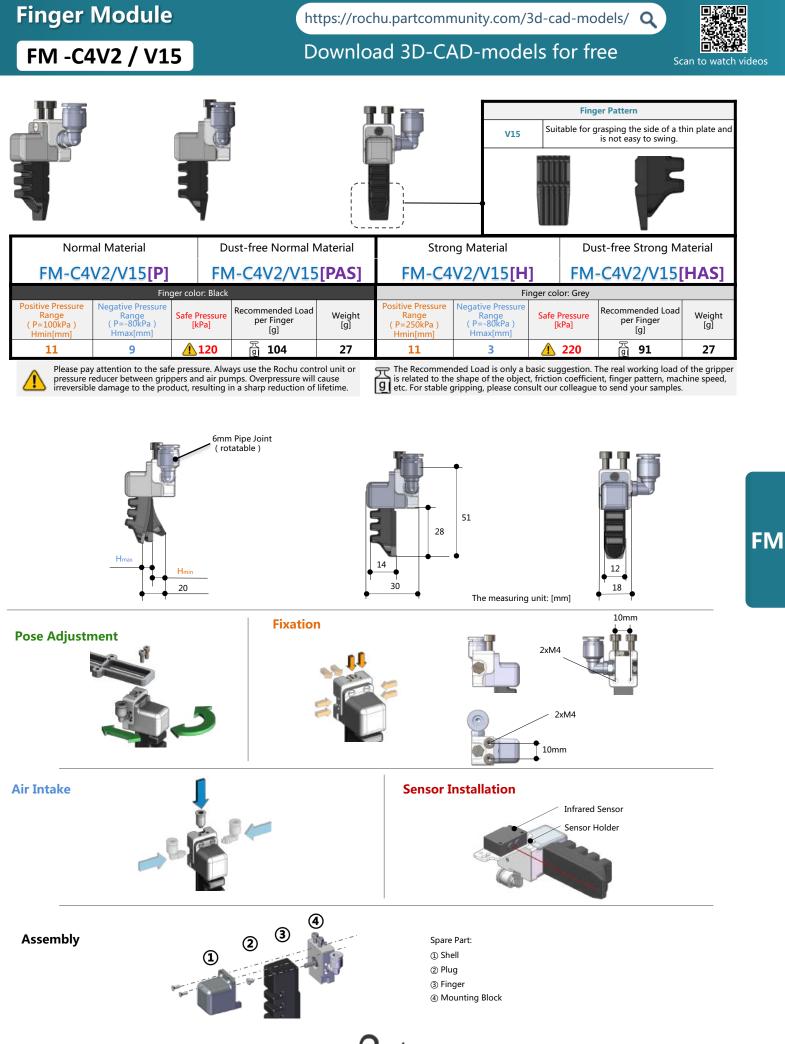






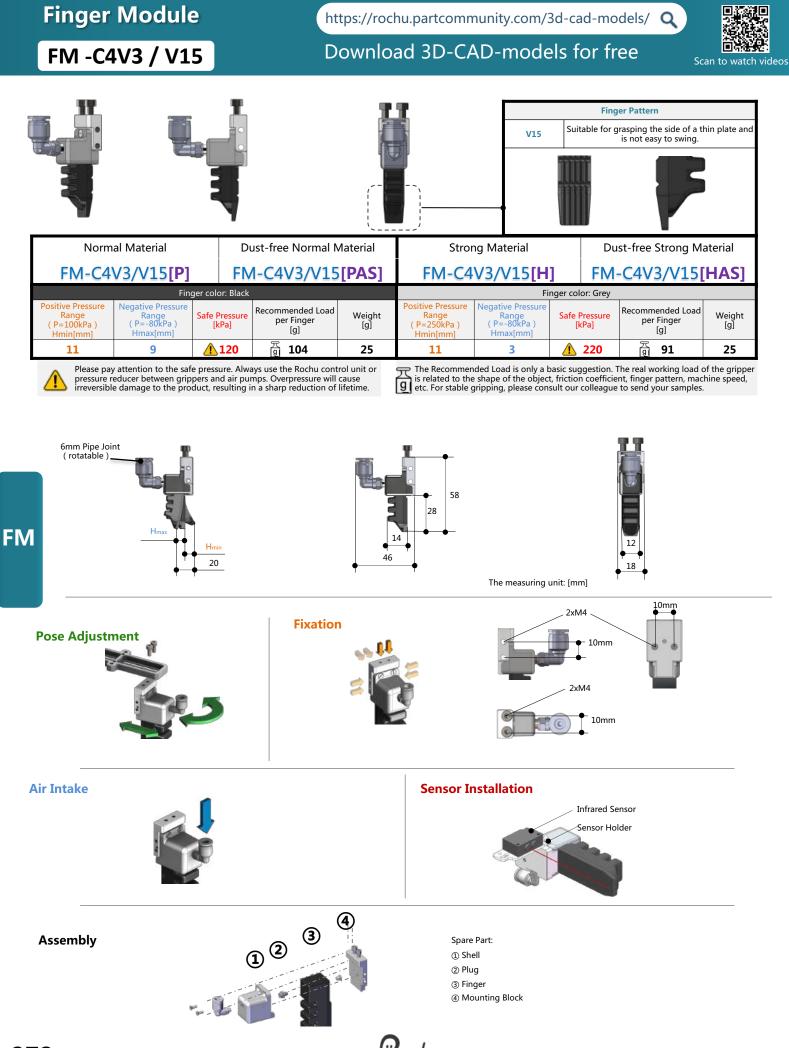


Rochu

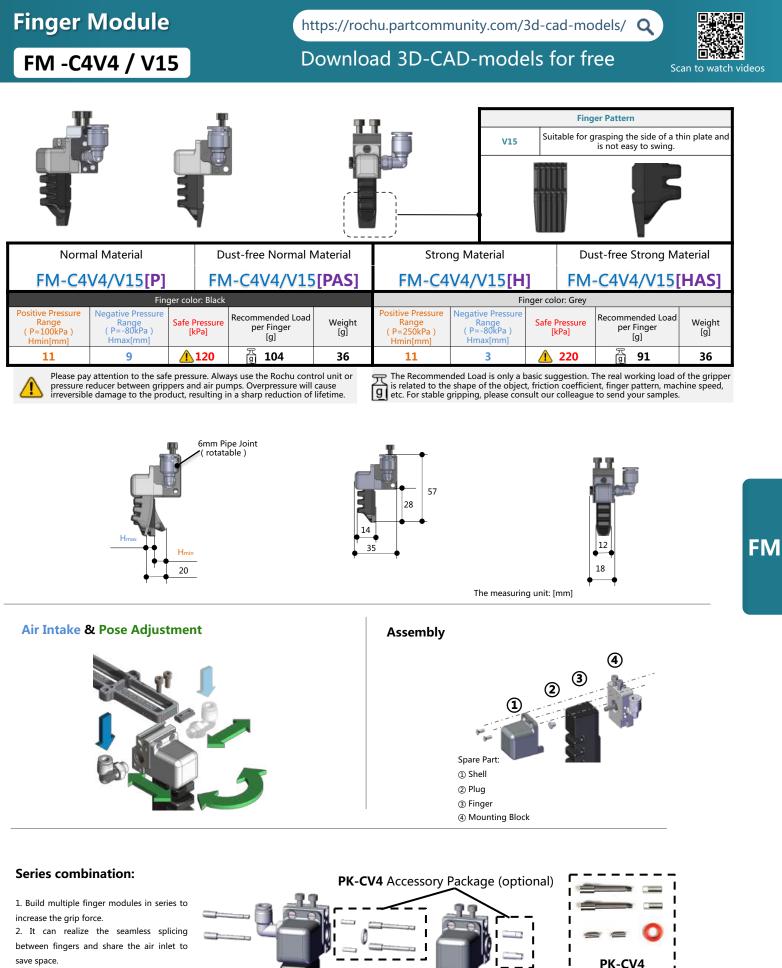


Rochu

Rochu soft Finger 371



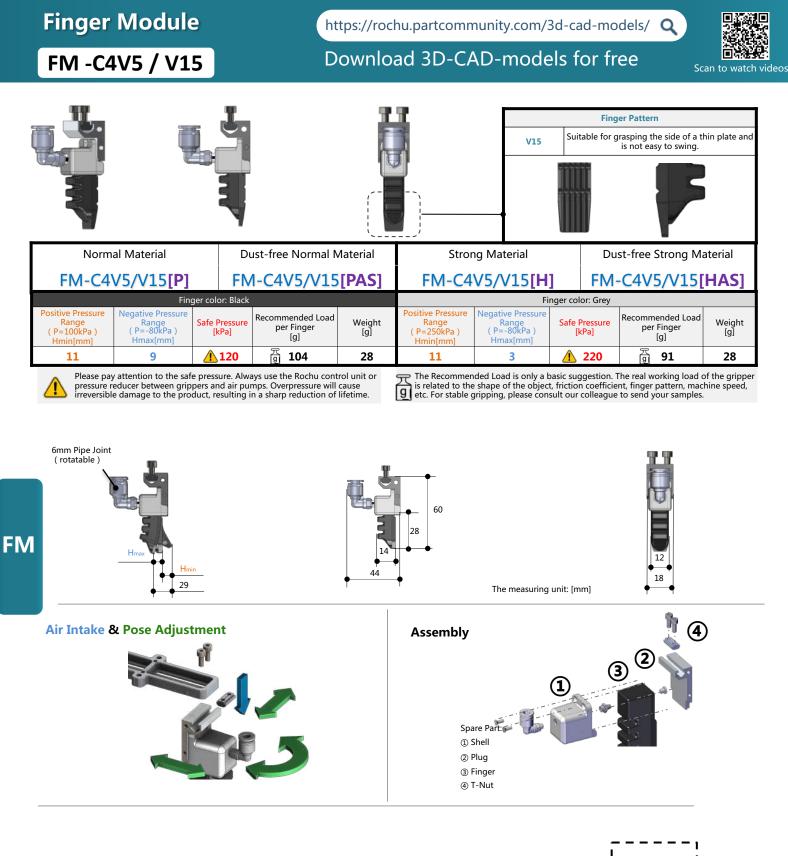
Rochu



\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



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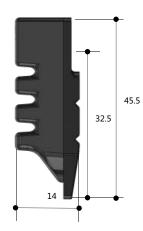
Finger I	Module			ht	ttps://roc	hu.partcomn	nunity.com/3	3d-cad-mo	odels/ Q	
F -C4T	/ V15			D	ownlo	ad 3D-CA	AD-mode	els for fi	ree	Scan to watch
12					w			Hoetur		
					•					
Finger	Pattern			_	<b>b</b>	Fe	atures			
Finger V15	Pattern Special Form				Suitable for		e <b>atures</b> of a thin plate and is r	not easy to swing	g.	
V15		Du	ıst-free N	Normal N		r grasping the side o			<sup>g.</sup> ust-free Strong	g Material
V15 Norma	Special Form			Normal N / <b>V15[F</b>	Material	r grasping the side o	f a thin plate and is r	Du		
v15 Norma F-C4T,	Special Form I Material //15[P] Finger of		-C4T/		Material	r grasping the side o Stron F-C4	of a thin plate and is r ng Material T/V15[H]	Du	ust-free Strong	
V15 Norma	Special Form I Material //15[P] Finger of Negative Pressure	F	Recommender F		Material PAS]	r grasping the side o	of a thin plate and is n ng Material T/V15[H]	Du F	ust-free Strong	[HAS]

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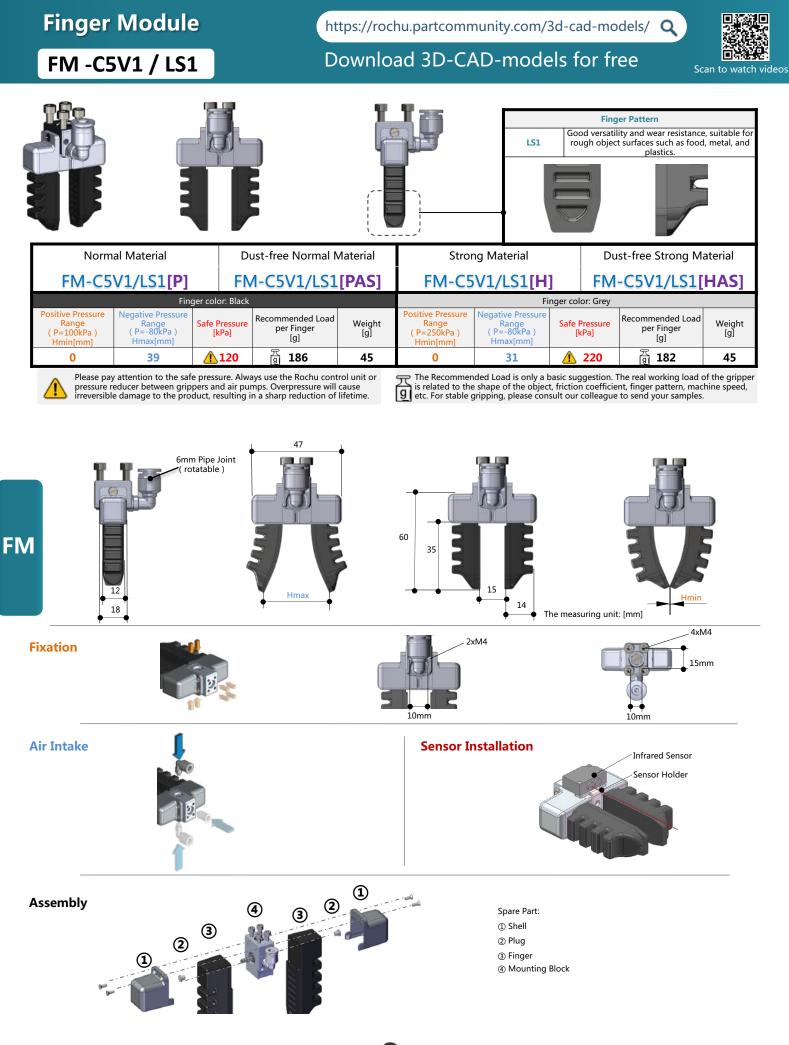
# **Dimension Parameters**

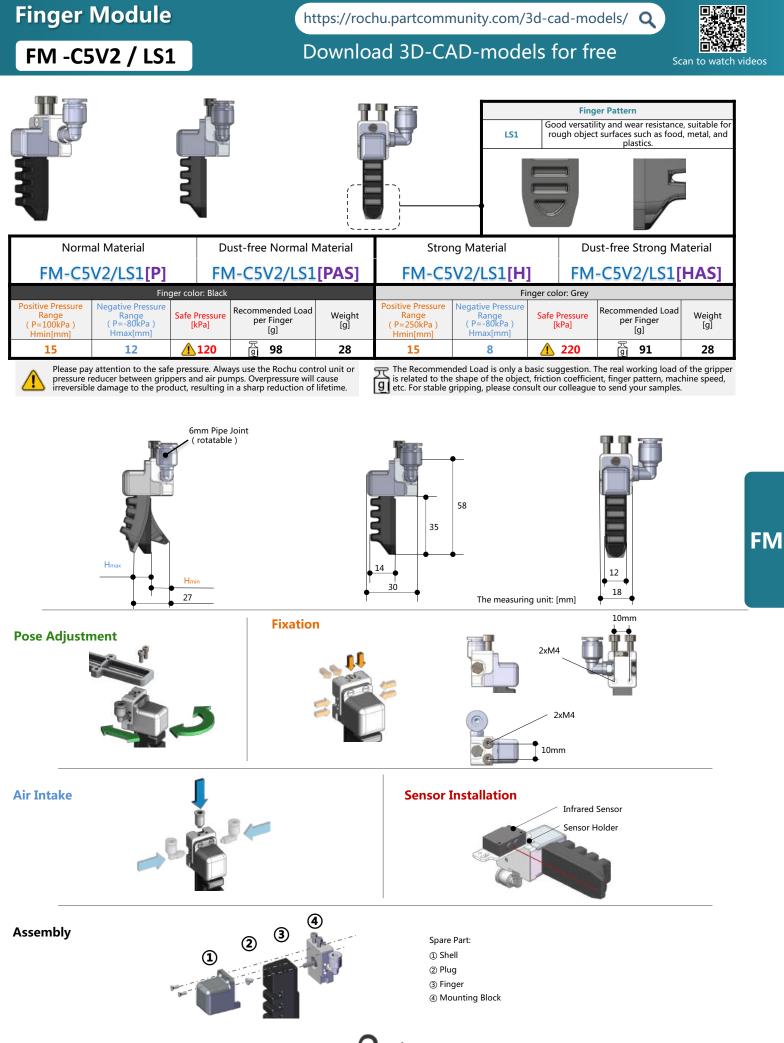






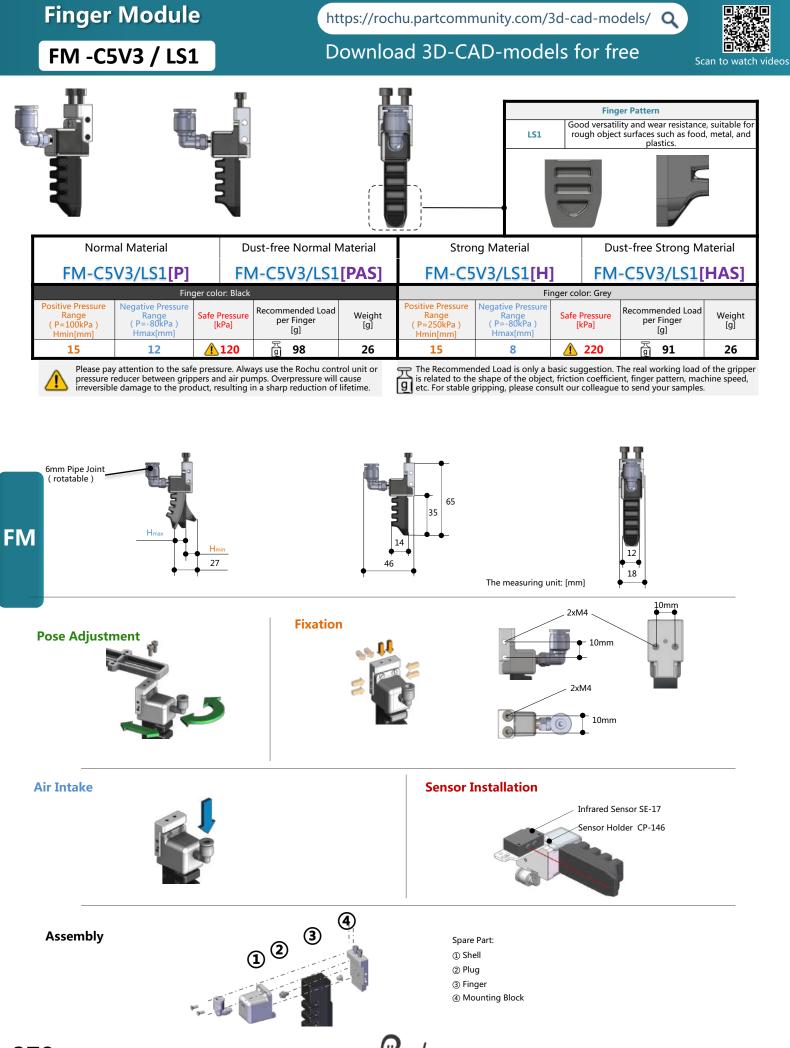
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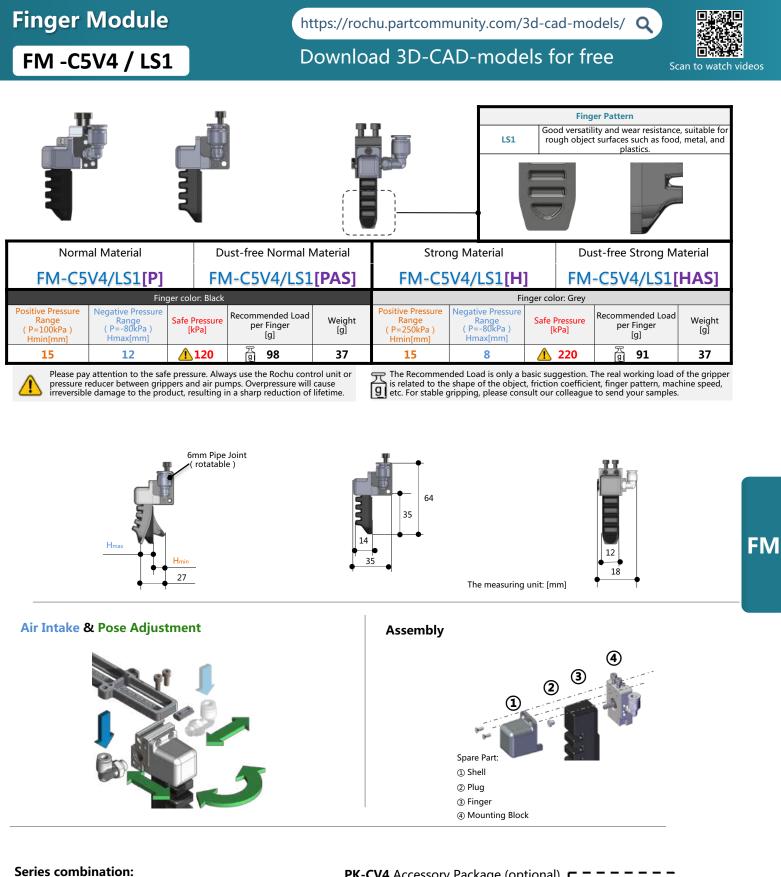


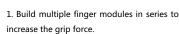
Rochu

Rochu soft Finger 377



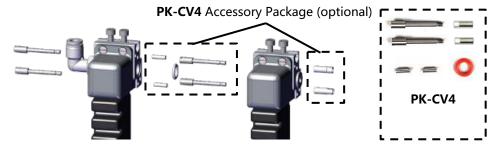
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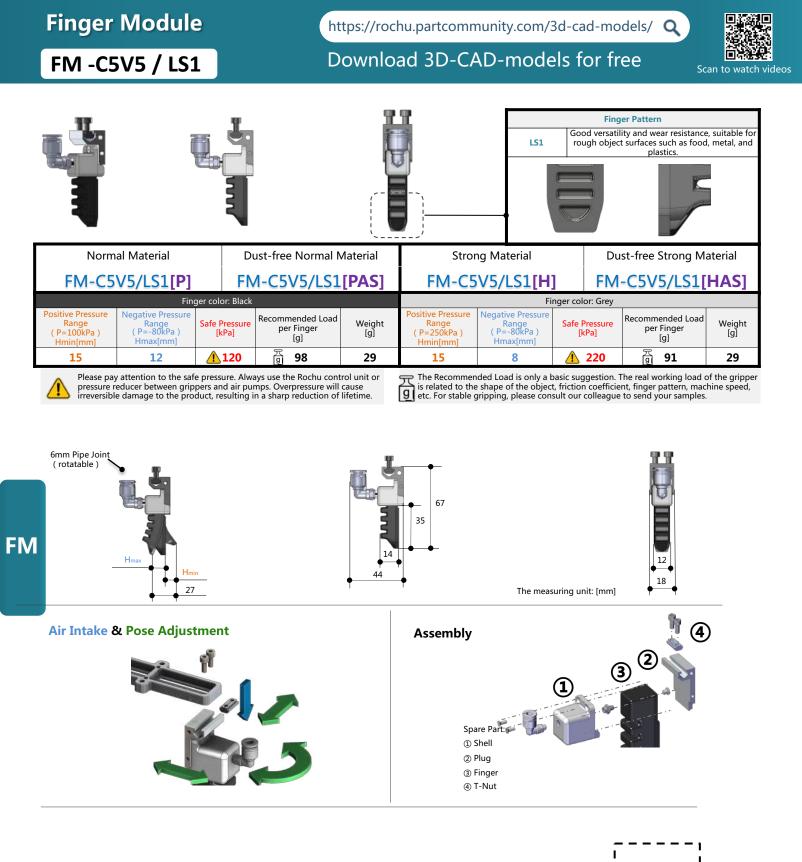


 It can realize the seamless splicing between fingers and share the air inlet to save space.

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2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

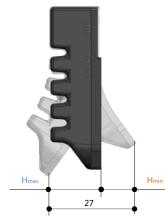
\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-CV5 Accessory Package (optional)

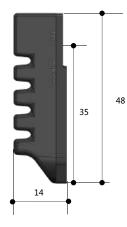
inger	Module	https	s://rochu	u.partcomm	nunity.com/3	3d-cad-m	odels/	Q )	日本の うまた 新たた
F -C5T	/ LS1	Dov	wnloa	d 3D-CA	AD-mode	els for f	ree	Sc	an to watch
	ALL.								
Finge	r Pattern	•		Fe	atures				
<b>Finge</b>	r Pattern Standard form	Good versatility ar	nd wear resist		atures		metal, and pl	astics.	
LS1		Good versatility ar Dust-free Normal Mate		stance, suitable for		es such as food,	metal, and pl		aterial
LS1 Norma	Standard form		erial	stance, suitable for	rough object surfac	es such as food,		trong Ma	
LS1 Norma F-C5T	Standard form al Material <b>[/LS1[P]</b> Finger c	Dust-free Normal Mate	erial S]	stance, suitable for Stror F-C5	rough object surfac ng Material T/LS1[H] Fi	es such as food,	ust-free St	trong Ma	
LS1 Norma	Standard form al Material <b>[/LS1[P]</b> Finger c Negative Pressure	Dust-free Normal Mate F-C5T/LS1[PAS	erial S]	stance, suitable for	rough object surfac ng Material T/LS1[H]	es such as food,	ust-free St	trong Ma	

pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

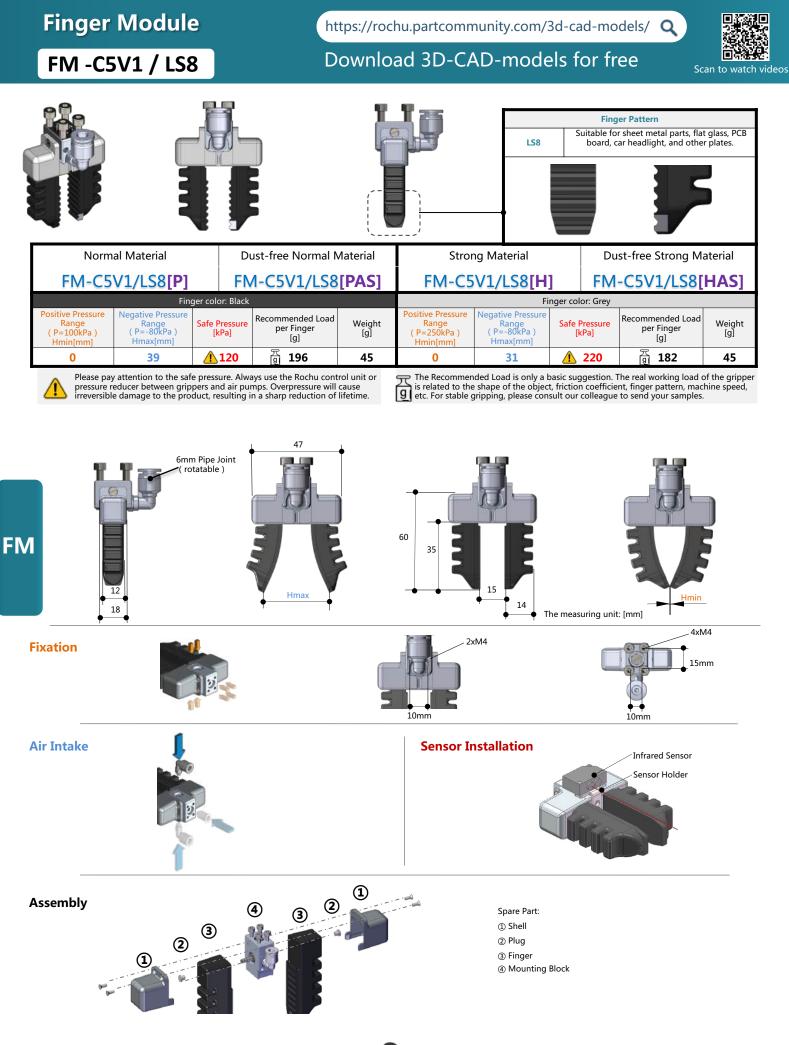
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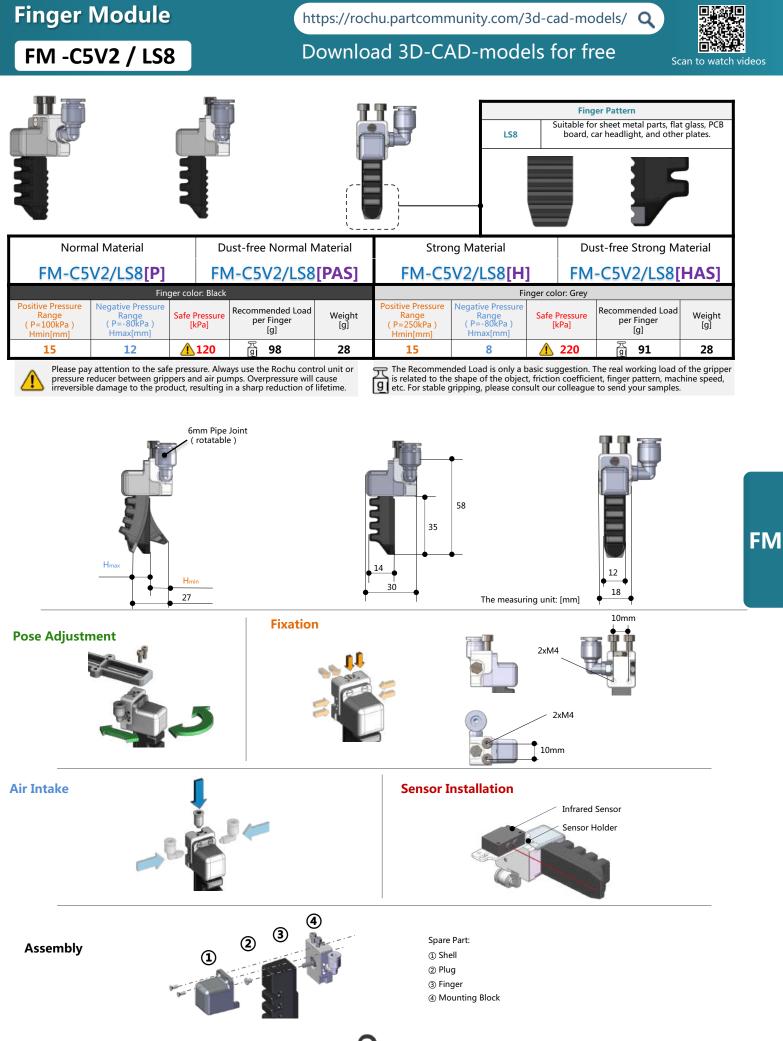




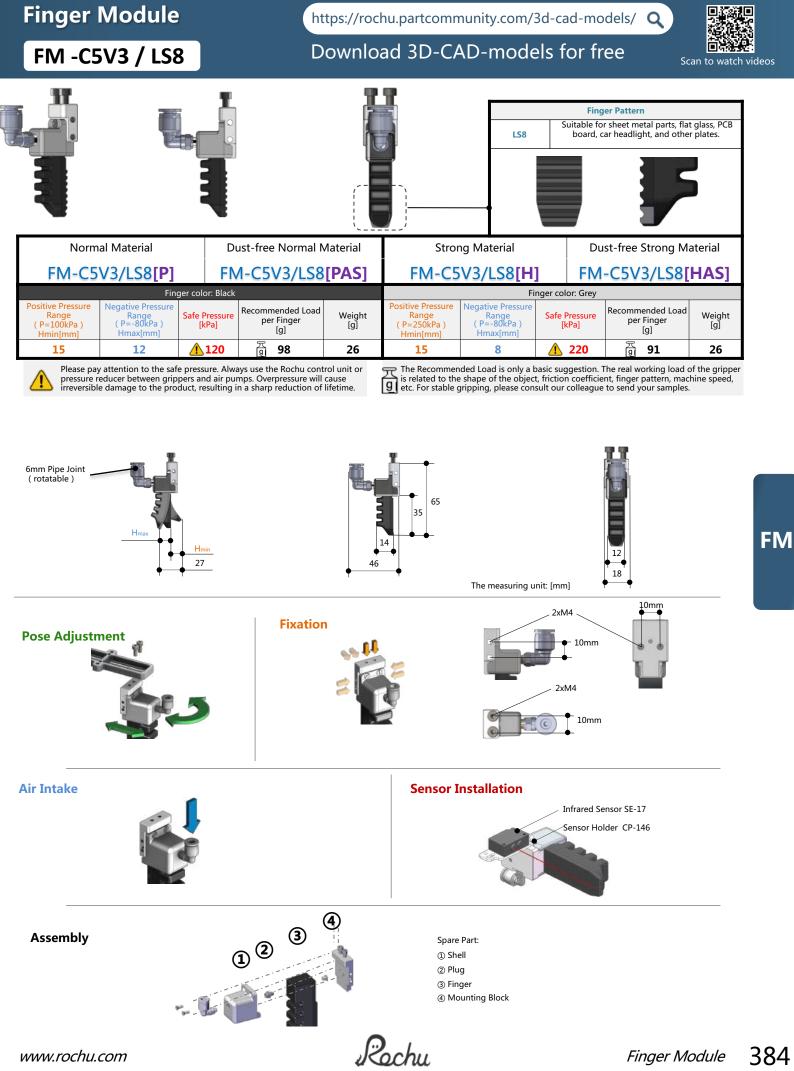


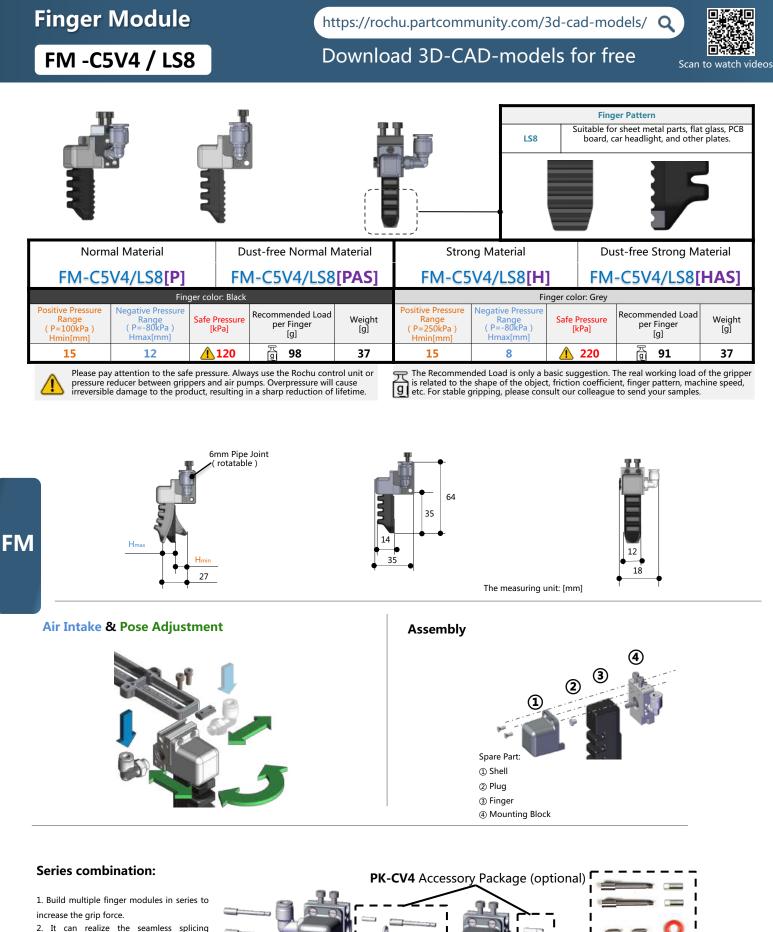


Rochu



Rochu

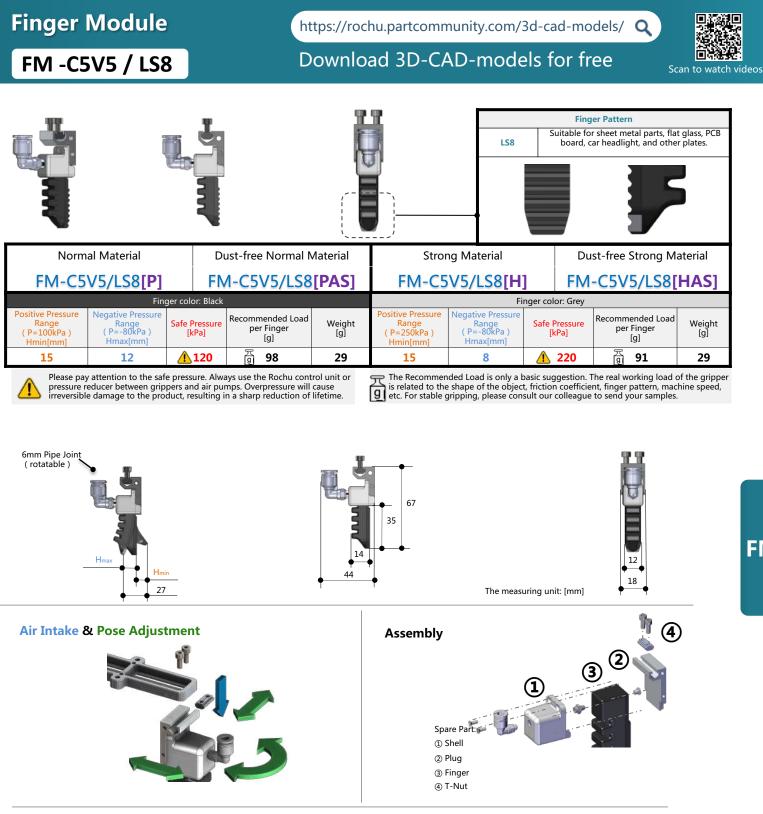




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Rochu



#### Series combination:

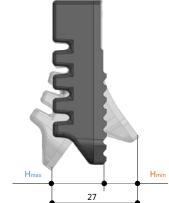
1. Build multiple finger modules in series to increase the grip force.

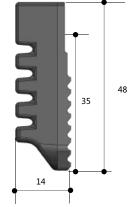
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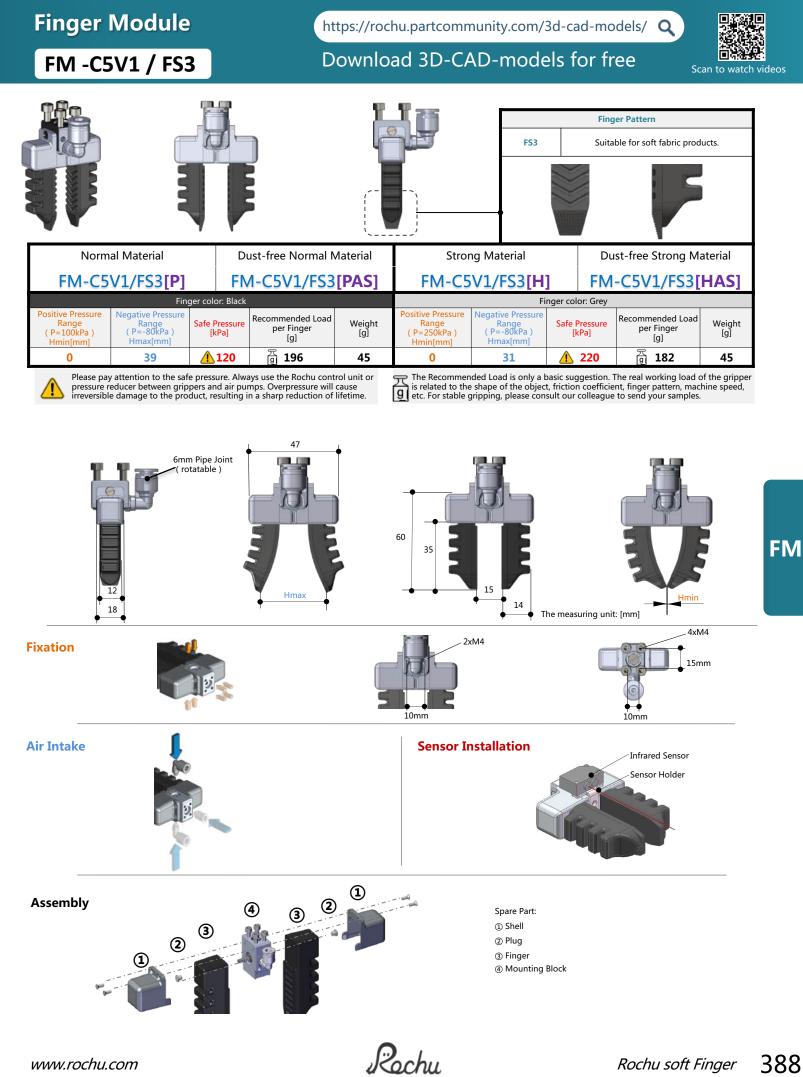
PK-CV5 Accessory Package (optional) 1 н PK-CV5

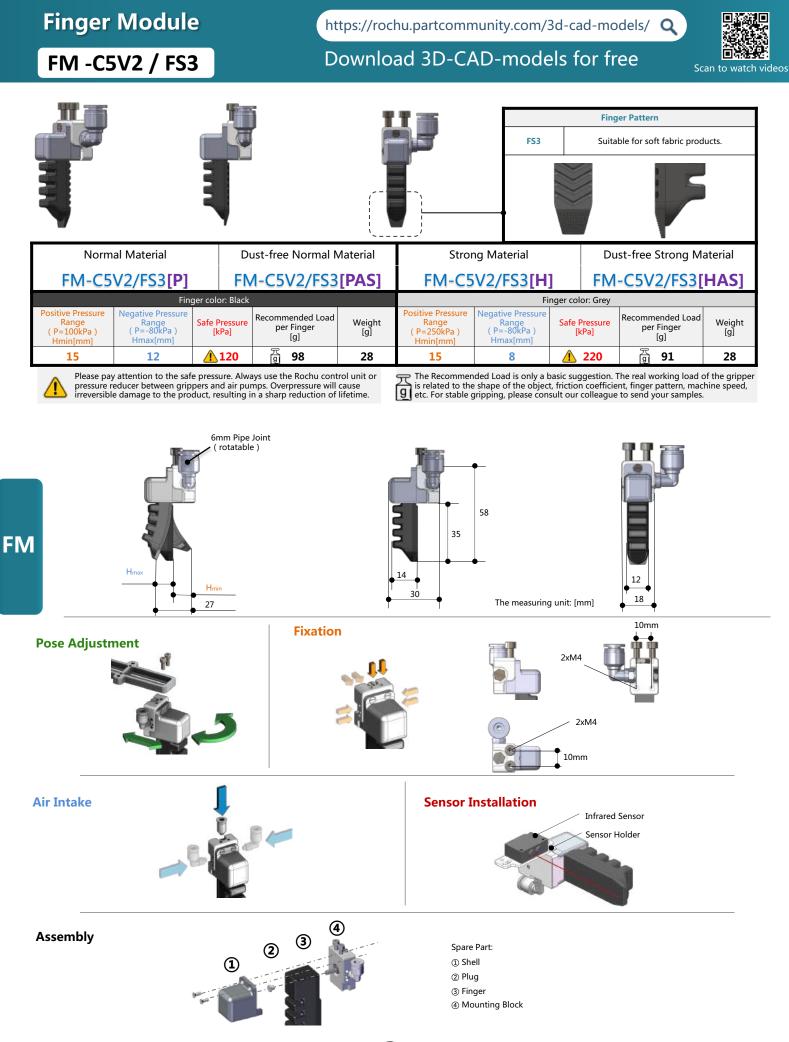
Finger I	Module		htt	ps://roch	u.partcomm	unity.com/3	d-cad-mod	dels/ Q	
F -C5T /	LS8		Do	ownloa	nd 3D-CA	D-model	ls for fre	ee <sub>Scar</sub>	n to watch vide
							0		
Finger	Pattern				Fe	atures			
Finger LS8	Pattern Special Form		Su	itable for sheet	<b>Fe</b> t metal parts, flat gla:		eadlight, and othe	er plates.	
LS8			Su ust-free Normal N		t metal parts, flat gla		-	er plates. ust-free Strong Ma	aterial
LS8 Norma	Special Form I Material	Du		/laterial	t metal parts, flat gla:	ss, PCB board, car he	Du		
LS8 Norma	Special Form I Material	Du	ust-free Normal N	/laterial	t metal parts, flat gla:	ss, PCB board, car he ng Material <b>T/LS8[H]</b>	Du	ust-free Strong Ma -C5T/LS8[H Recommended Load per Finger [g]	
LS8 Norma F-C5T Positive Pressure Range (P=100kPa) Hmin[mm] 15	Special Form I Material /LS8[P] Negative Pressure Range (P=-80kPa) Hmax[mm] 12	ger color: Black Safe Pressure [kPa]	Ist-free Normal N -C5T/LS8[P Recommended Load per Finger [g] 98	Material PAS] Weight [g] 6	t metal parts, flat glas Stron F-C5 Positive Pressure Range (P=250kPa) Hmin[mm] 15	ss, PCB board, car he ng Material <b>T/LS8[H]</b> Regative Pressure Range (P=-80kPa) Hmax[mm] <b>8</b>	Du F Inger color: Grey Safe Pressure [kPa] 220	Recommended Load per Finger [g] 91	AS] Weight [g] 6
LS8 Norma F-C5T Positive Pressure Range (P=100kPa) Hmin[mm] 15 Please pay pressure re	Special Form I Material VLS8[P] Negative Pressure Range (P=-80kPa) Hmax[mm] 12 attention to the safe ducer between grip	per color: Black Safe Pressure [kPa] 120 e pressure. Alwa pers and air pur	ust-free Normal N -C5T/LS8[P Recommended Load per Finger [g]	Material PAS] Weight [g] 6 trol unit or cause	t metal parts, flat gla: Stron F-C5 Positive Pressure Range (P=250kPa) Hmin[mm] 15	ss, PCB board, car he ng Material T/LS8[H] Negative Pressure Range (P=-80kPa) Hmax[mm] 8 nded Load is only a b	Du F nger color: Grey Safe Pressure [kPa] 220 Dasic suggestion.	ust-free Strong Ma -C5T/LS8[H Recommended Load per Finger [g]	AS] Weight [g] 6



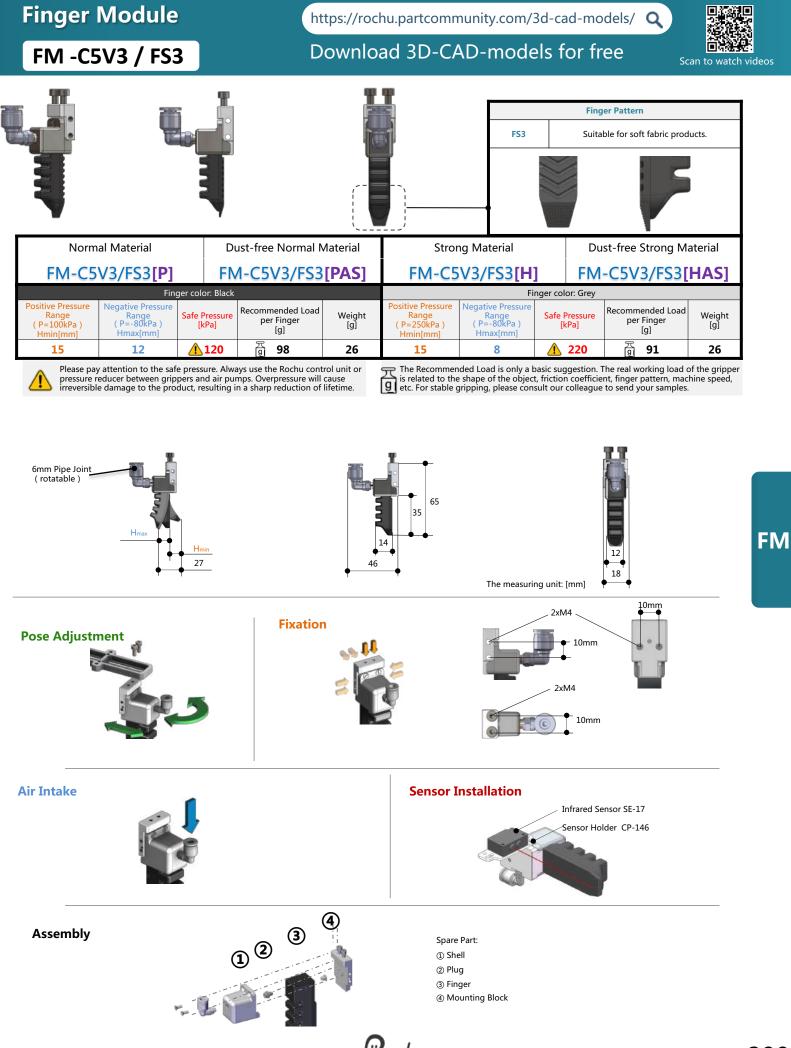




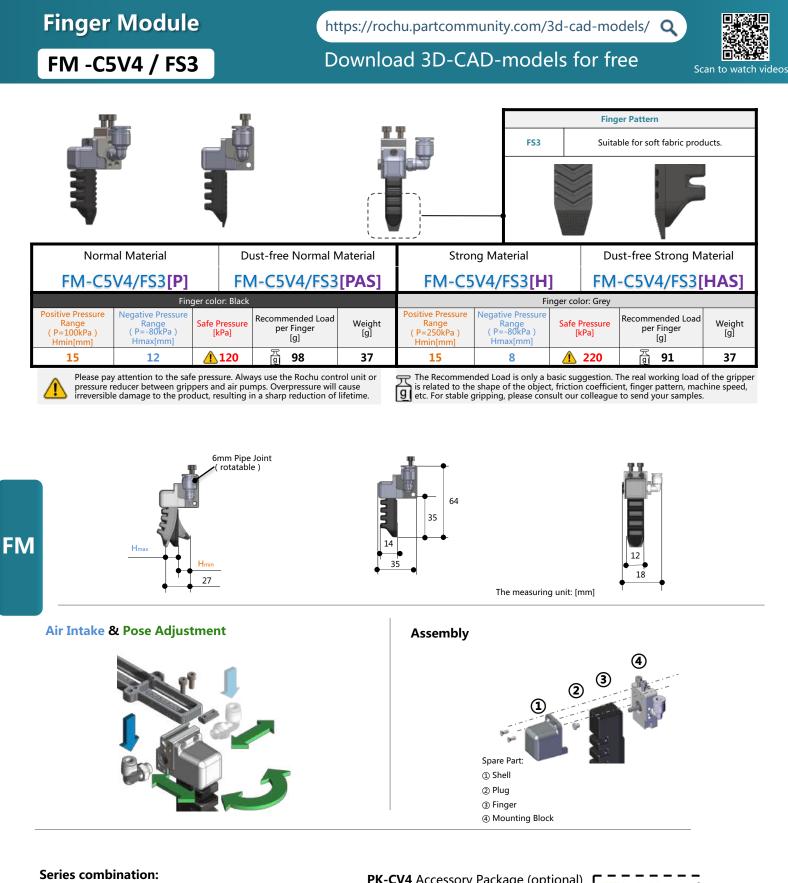


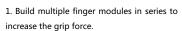


Rochu



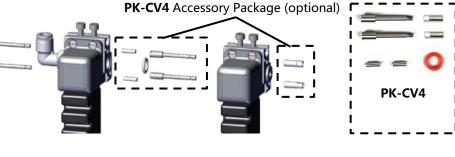
Rochu



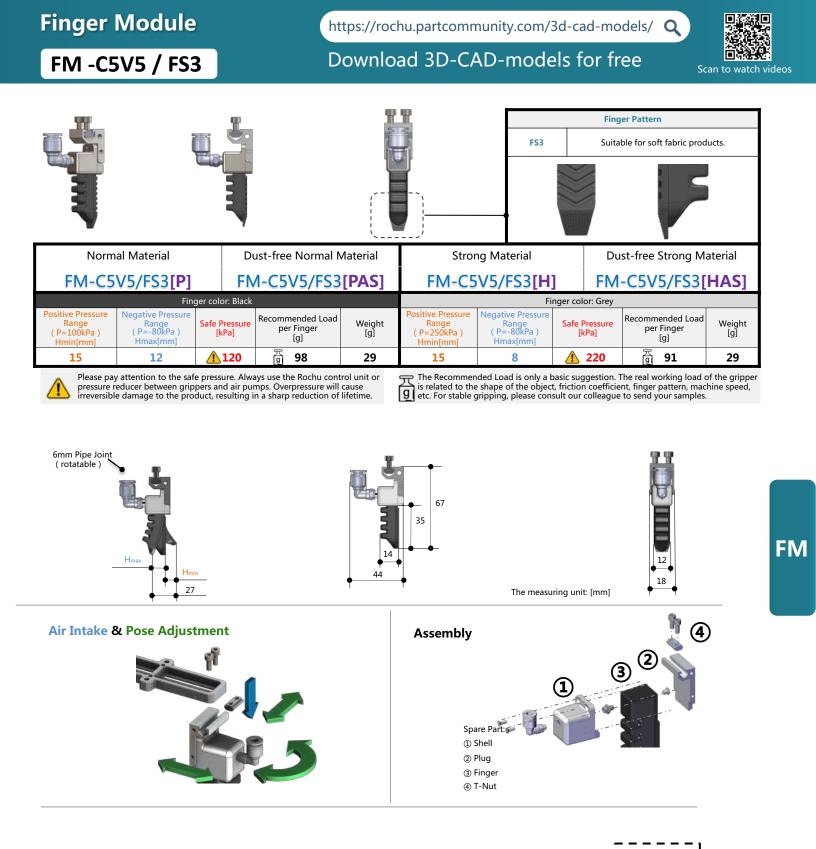


2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu



#### Series combination:

www.rochu.com

**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.

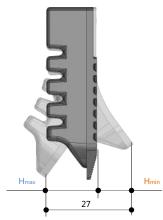


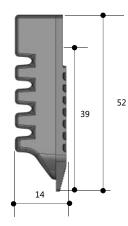


Finger Module	https://rochu	.partcommunity.com/3	d-cad-mo	dels/ Q	
F -C5T / FS3	Download	d 3D-CAD-model	s for fr	ee <sub>Scan</sub>	to watch video
Finger Pattern		Features			
FS3 Special Form		Suitable for soft fabric product	S.		
Normal Material	Dust-free Normal Material	Strong Material		Dust-free Strong M	aterial
F-C5T/FS3[P]	F-C5T/FS3[PAS]	F-C5T/FS3[H]		F-C5T/FS3[H	AS]
Finge Positive Pressure Negative Pressure	color: Black	Positive Pressure Negative Pressur	Finger color: Gre	-	
	fe Pressure [kPa] Recommended Load Per Finger [g] [g] Weight [g]	Range (P=250kPa) Hmin[mm] Hegative Pressure (P=-80kPa) Hmin[mm] Hmax[mm]	Safe Pressu [kPa]	re Recommended Load per Finger [g]	Weight [g]
	-				
15 12	<u>120</u> ☐ 98 6	15 8	<u> 1</u> 220	ਸੂ ਹੁ 91	6

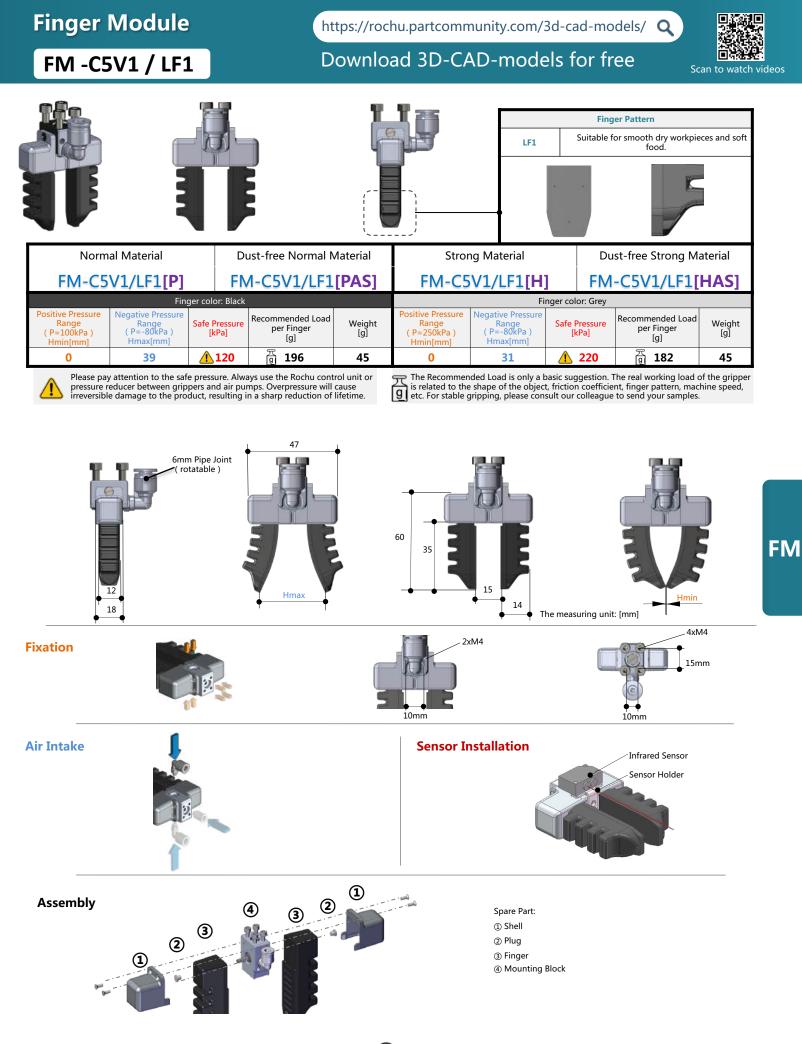
FM

### **Dimension Parameters**

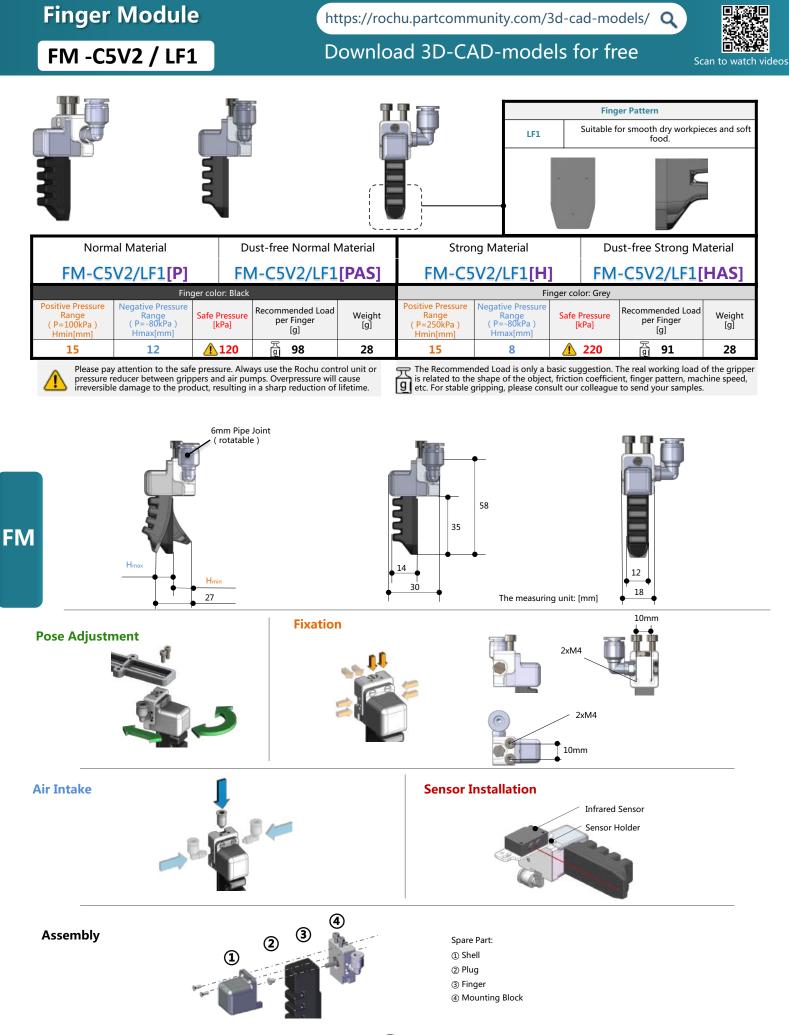




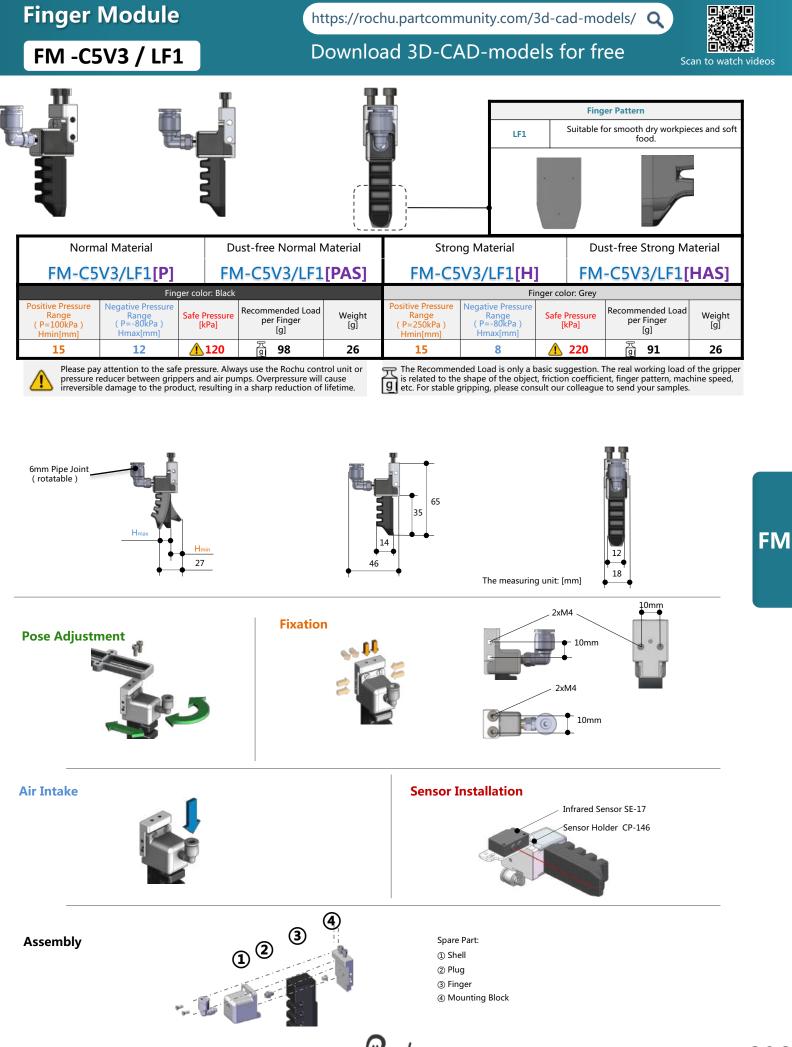




Rochu

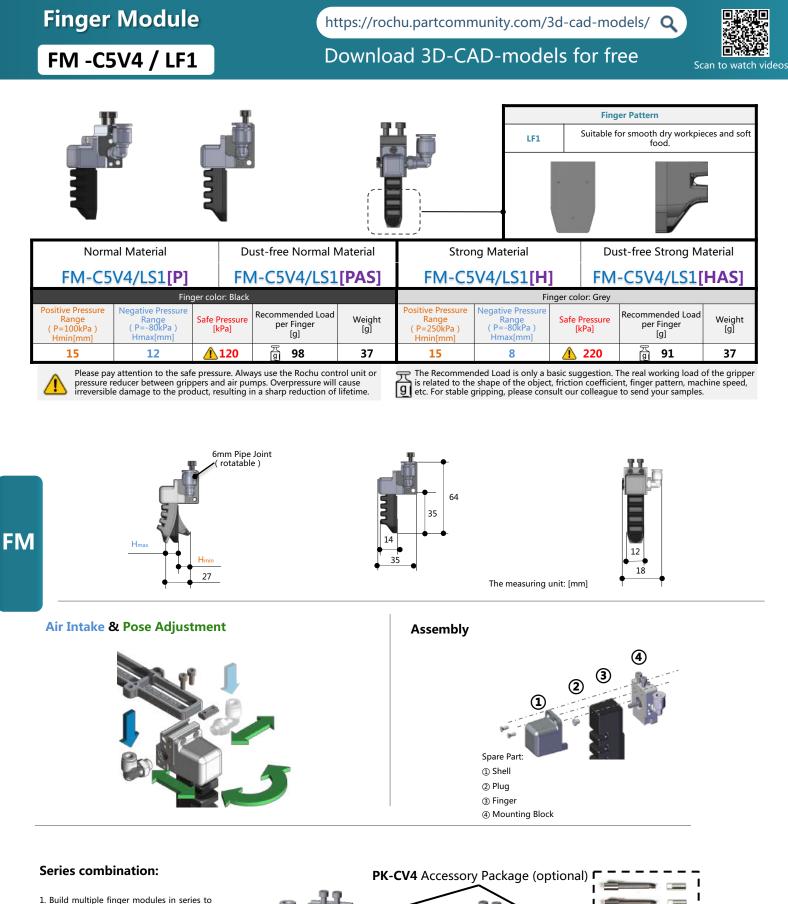


Rochu



Rochu

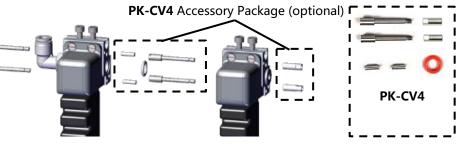
Rochu soft Finger 396



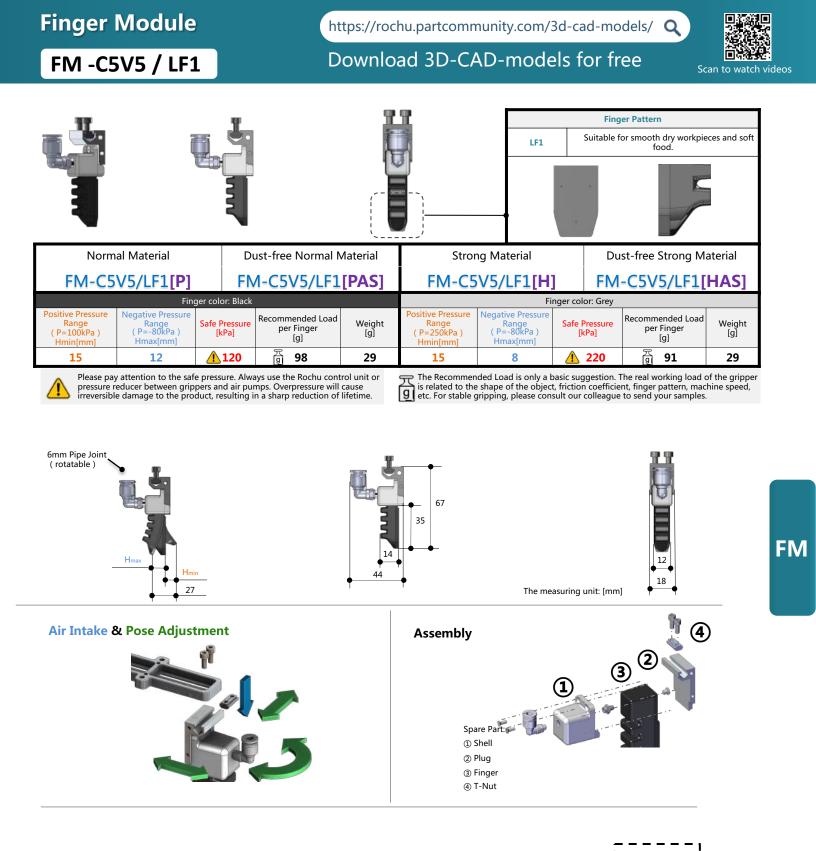
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Pochu



#### Series combination:

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Finger N	lodule		https://rochu.partcommunity.com/3d-cad-models/ Q									
F -C5T /	LF1		Dov	wnloac	3D-CAD	)-models	for free	<b>S</b> can	to watch video			
							•         •           •         •           •         •					
Finge	r Pattern		Features									
LF1	Special Form		Suitable for smooth dry workpieces and soft food.									
Norma	al Material	Du	ust-free Normal N	laterial	Stror	ng Material	Du	Dust-free Strong Material				
F-C51	[/LF1[P]	F	-C5T/LF1[P	PAS]	F-C5	T/LF1[H]	F	-C5T/LF1[HAS]				
Positive Pressure	Fing Negative Pressure	ger color: Black	December 1		Positive Pressure	Fi Negative Pressure	nger color: Grey	Deserverseded				
Range Range (P=100kPa) (P=-80kPa) [I			Recommended Load per Finger [g]	Weight [g]	Range (P=250kPa) Hmin[mm]	Range (P=-80kPa) Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]			
15				6	15	8	1 220	<u>j</u> 91	6			

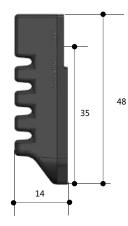
4

FM

#### **Dimension Parameters**

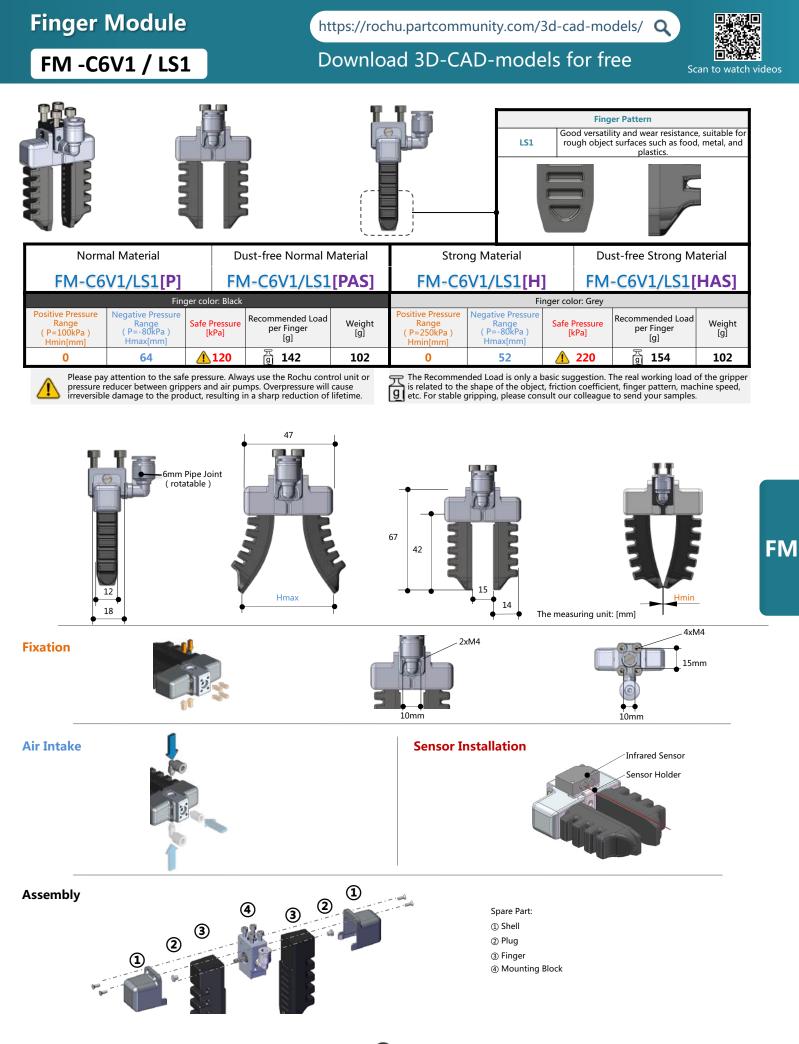


Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

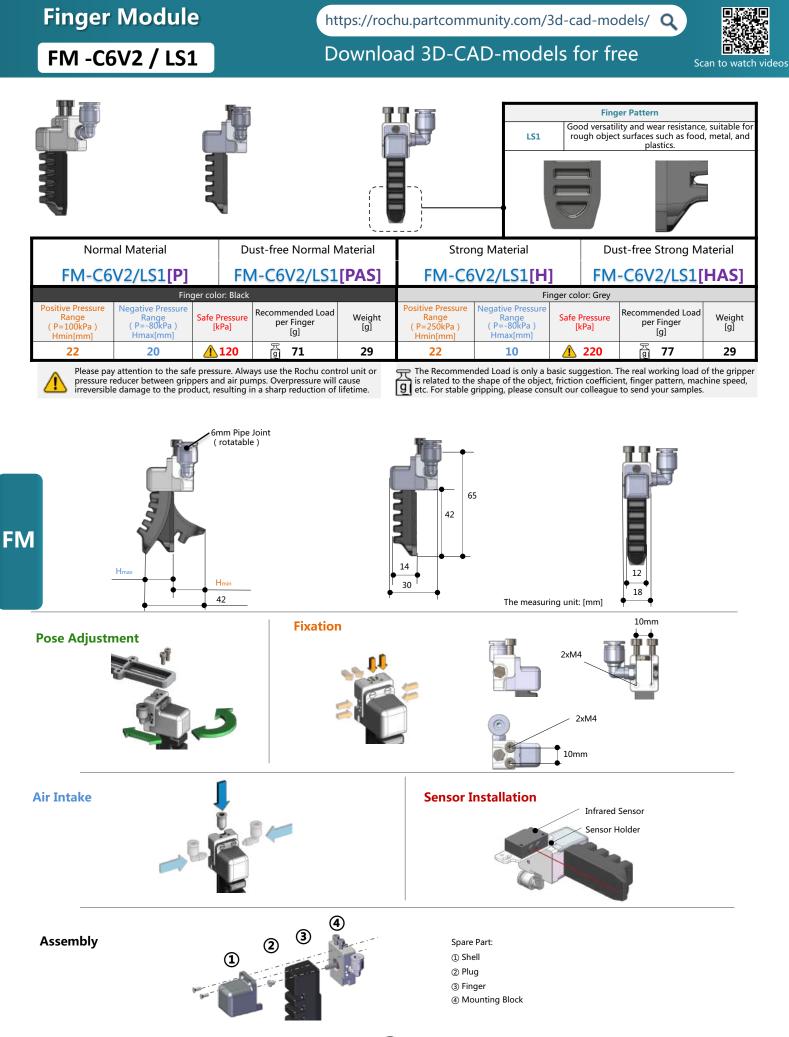




The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

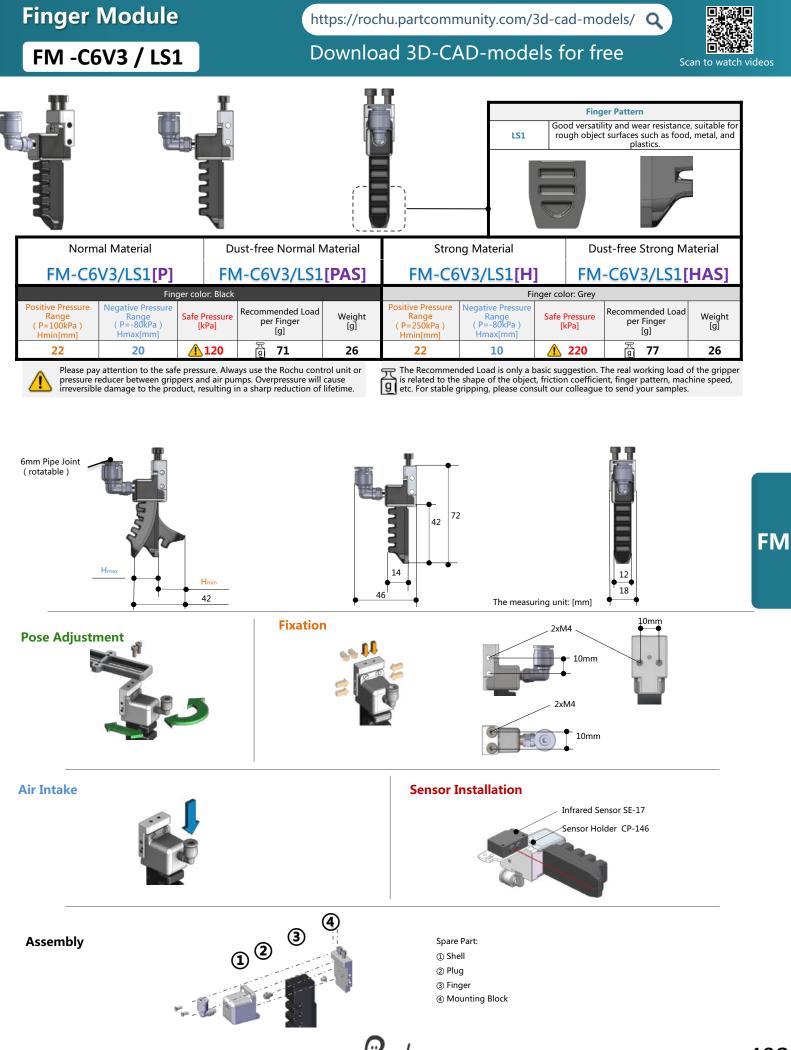


Rochu



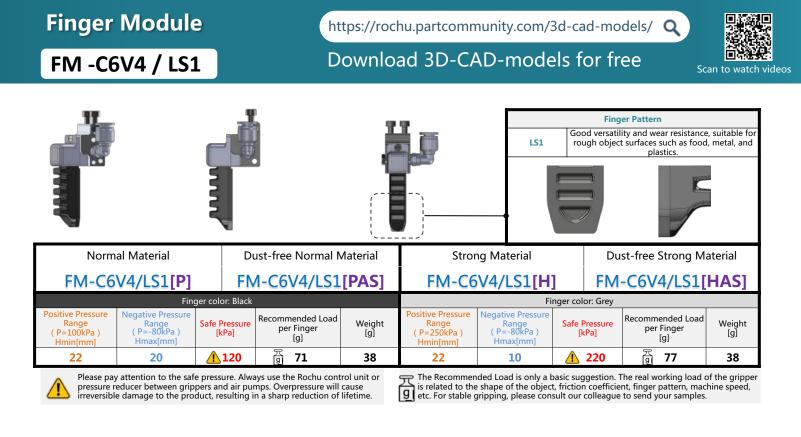
401 Rochu soft Finger

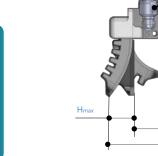
Rochu



Rochu

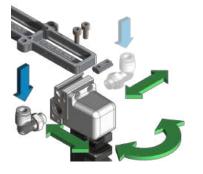
Rochu soft Finger 402





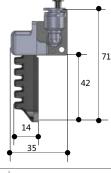
FM

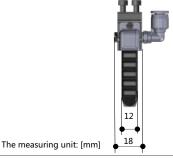
Air Intake & Pose Adjustment



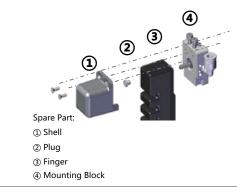
6mm Pipe Joint ( rotatable )

Hmin 42





Assembly

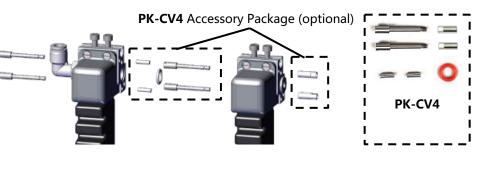


#### Series combination:

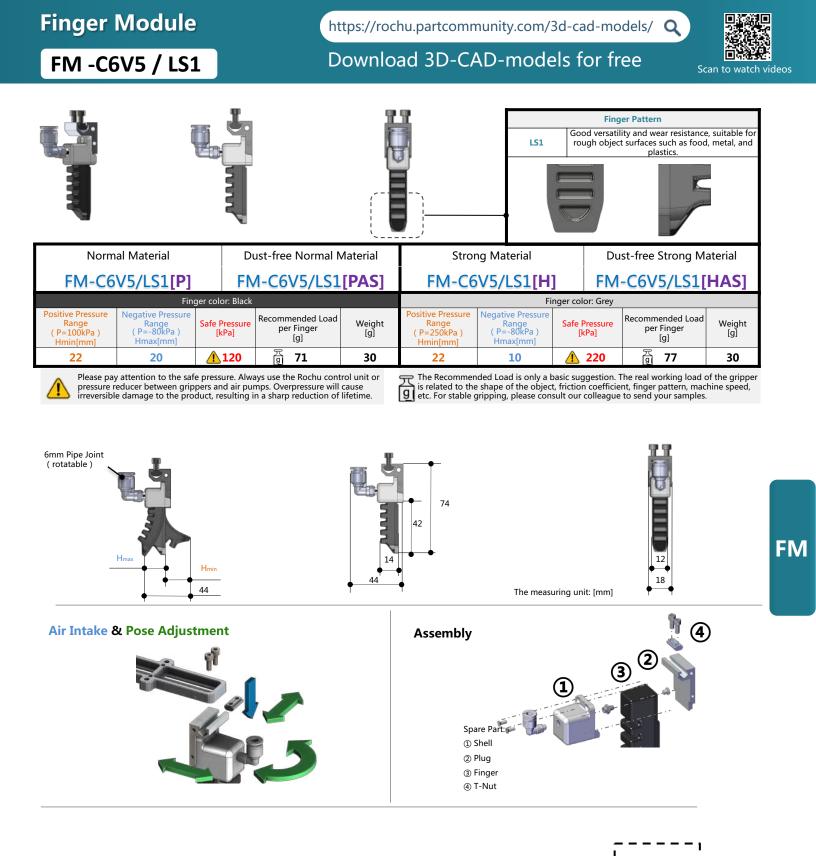
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.



Rochu



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	Finger N	lodule		https://rochu.partcommunity.com/3d-cad-models/ Q										
	F -C6T /	LS1		Dov	wnloac	3D-CAE	D-models	for	free	Sca	an to watch video			
	Finger	Pattern				Fe	eatures							
	LS1	Standard form		Good versatili	ty and wear res	ear resistance, suitable for rough object surfaces such as food, metal, and plastics.								
	Norma	l Material	Dust-free Normal Material			Strong Material			Dus	t-free Strong	Material			
	F-C6T	/LS1[P]	F-C6T/LS1[PAS]			F-C6T/LS1[H]			F-(	C6T/LS1	HAS]			
	Positive Pressure	Negative Pressure	olor: Black	Recommended Load		Positive Pressure Negative Pressure			plor: Grey Recommended Load					
	Range ( P=100kPa ) Hmin[mm]	Range (P=-80kPa) Hmax[mm]	Pressure [kPa]	per Finger [g]	Weight [g]	Range ( P=250kPa ) Hmin[mm]	Range (P=-80kPa) Hmax[mm]	Safe Pr [kP	essure	per Finger [g]	Weight [g]			
	22		120	页 頁 <b>71</b>	7	22	10		220	页 頁 <b>77</b>	7			
	pressure re	attention to the safe pre- ducer between grippers damage to the product,	and air pui	mps. Overpressure will	cause	The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.								
FM														
		S		1		42	55							

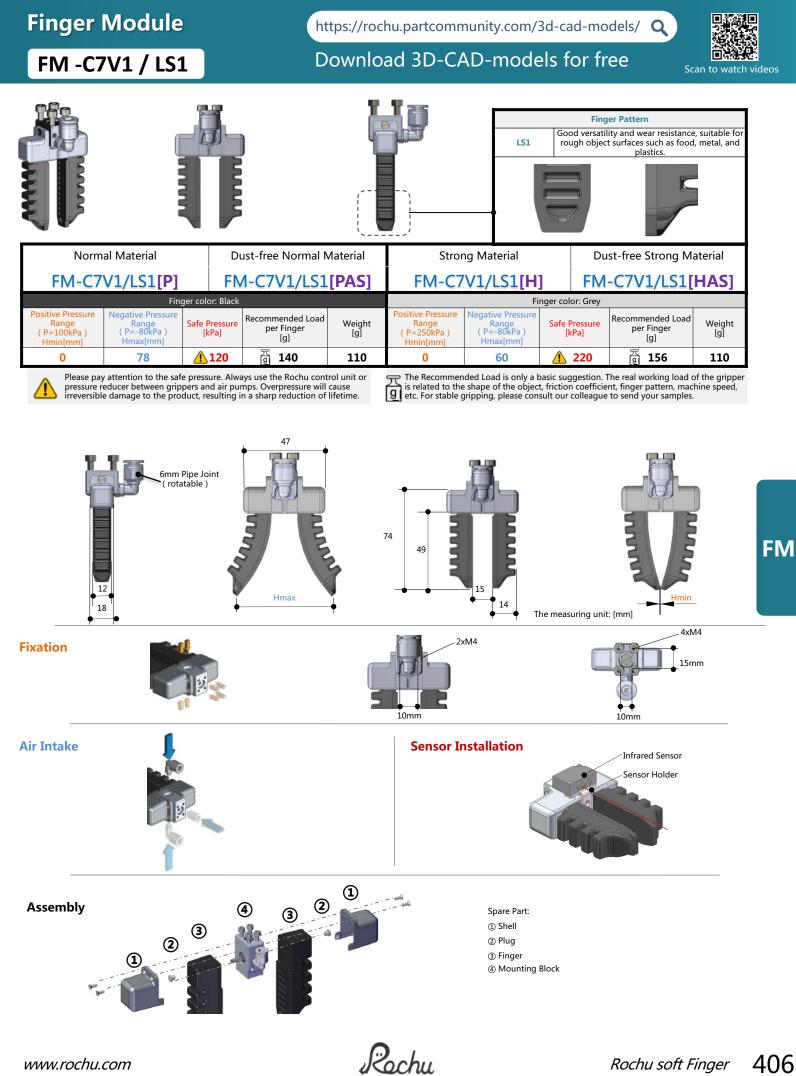
Hmax

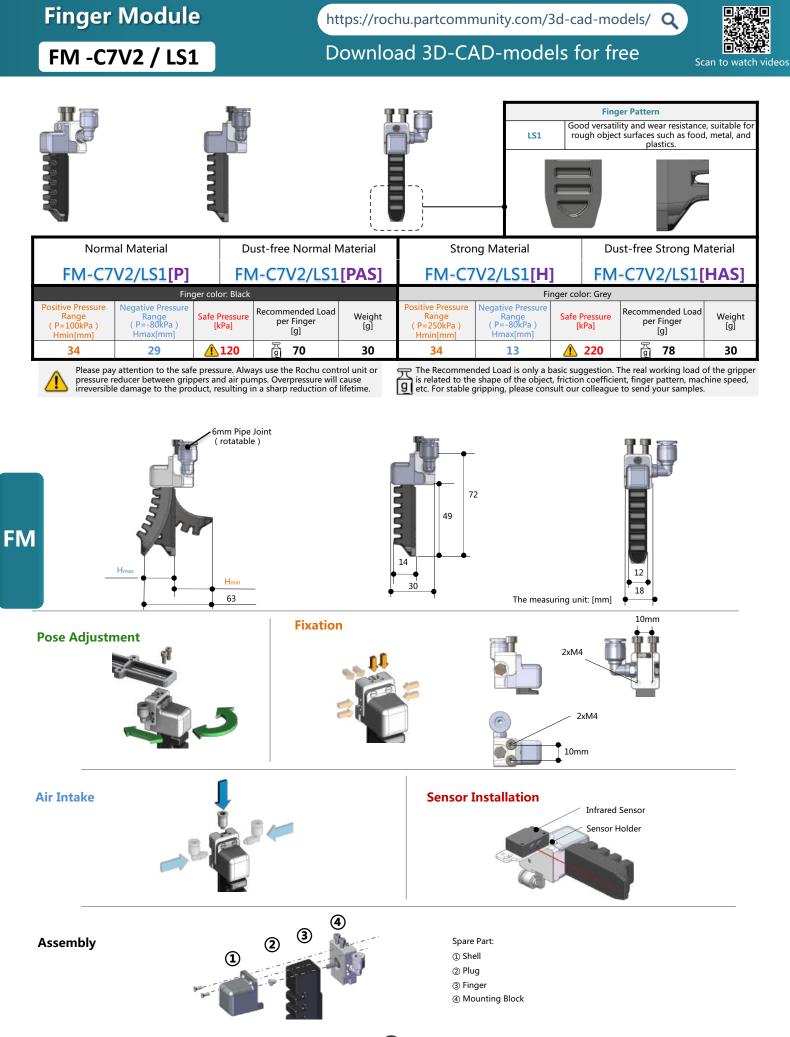
42

14

Hmin

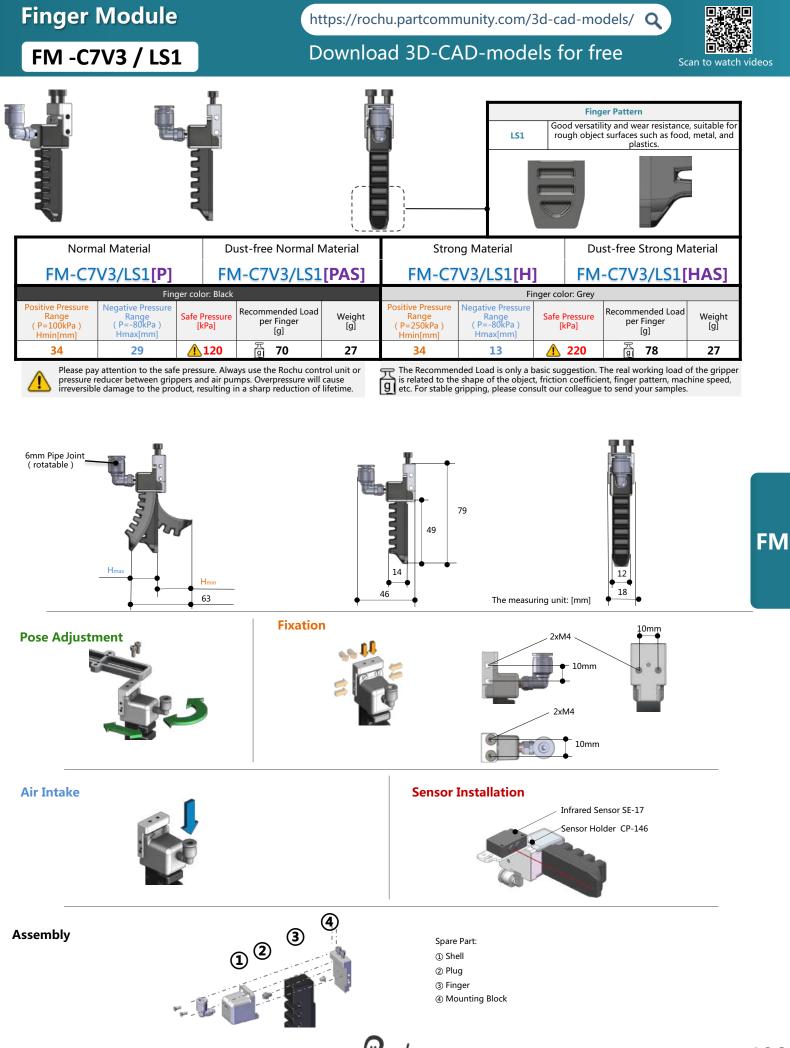
12





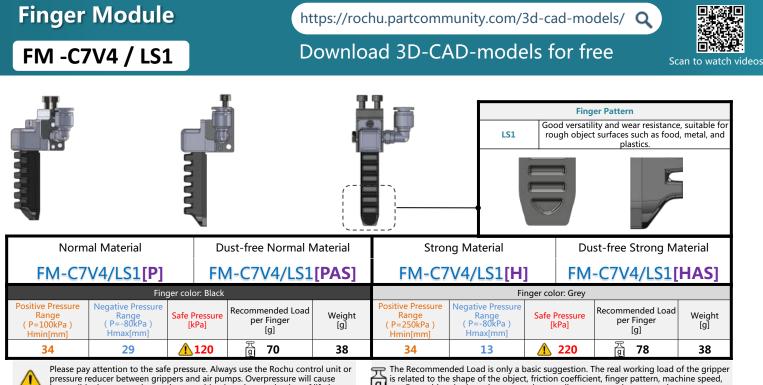
407 Rochu soft Finger

Rochu



Rochu

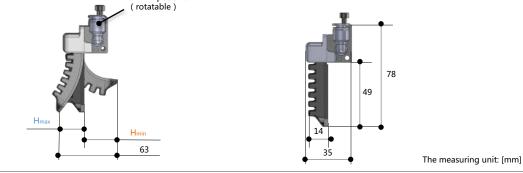
Rochu soft Finger 408



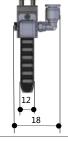
pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

6mm Pipe Joint

g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.

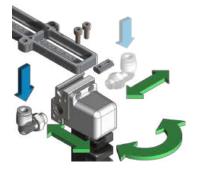




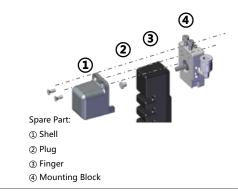


Air Intake & Pose Adjustment

FM



Assembly

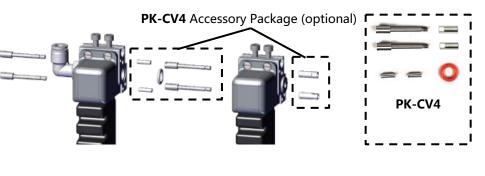


#### Series combination:

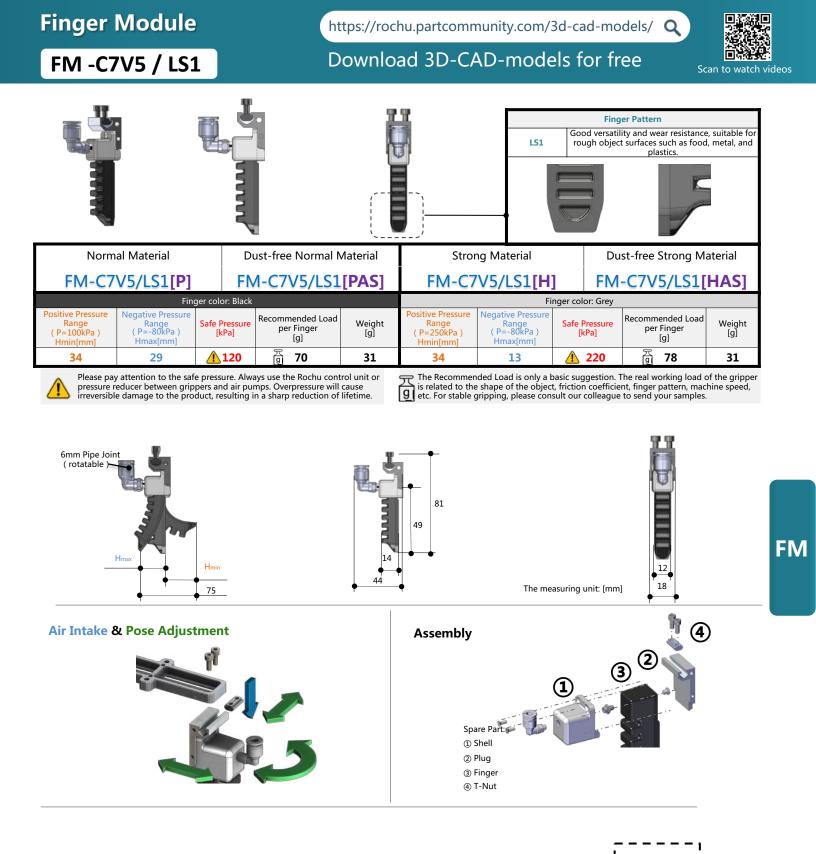
1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.







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	Finger N	lodule		http	els/ Q									
	F -C7T /	LS1		Dov	wnloac	3D-CAD	O-models	for	free	e s	can to watch video			
						M								
	Finger	Pattern		Features										
	LS1	Standard form		Good versatility and wear resistance, suitable for rough object surfaces such as food, metal, and plastics.										
	Norma	l Material	D	ust-free Normal N	/laterial	Strong Material			Dust-free Strong Material					
	F-C7T	/LS1[P]	F-C7T/LS1[PAS]			F-C7T/LS1[H] F-C7T				-C7T/LS1	/LS1[HAS]			
	Positive Pressure		olor: Black						color: Grey					
	Range ( P=100kPa ) Hmin[mm]		Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]	Range ( P=250kPa ) Hmin[mm]	Negative Pressure Range ( P=-80kPa ) Hmax[mm]		ressure Pa]	Recommended I per Finger [g]	- <sup>oad</sup> Weight [g]			
	34	29 🧘	120	页 <b>70</b>	7	34	13	<u> </u>	220	जू <b>78</b>	7			
	// pressure re	attention to the safe pres ducer between grippers a damage to the product,	and air pu	imps. Overpressure will	cause	is related to the	nded Load is only a b e shape of the object gripping, please cons	friction	coofficio	ont finder nattern	maching speed			
FM	Dimensio	n Parameter	S			_								
						6	2			0				

49

14

Hmin

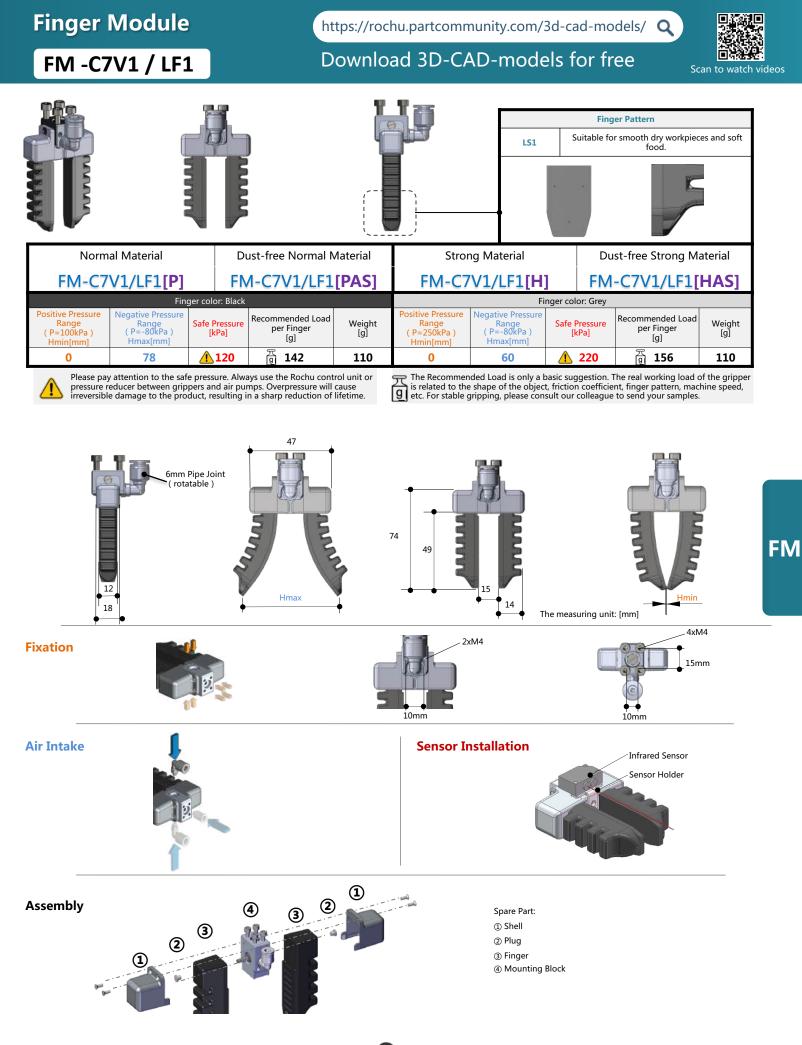
Hmax

63

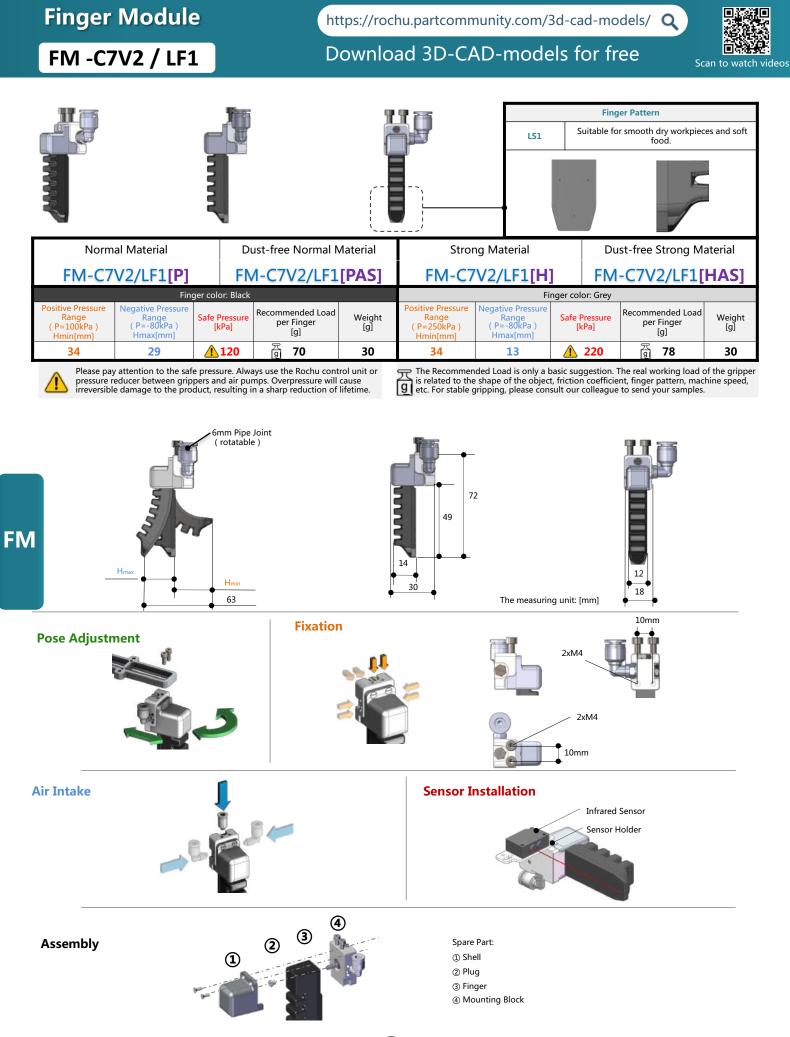


12

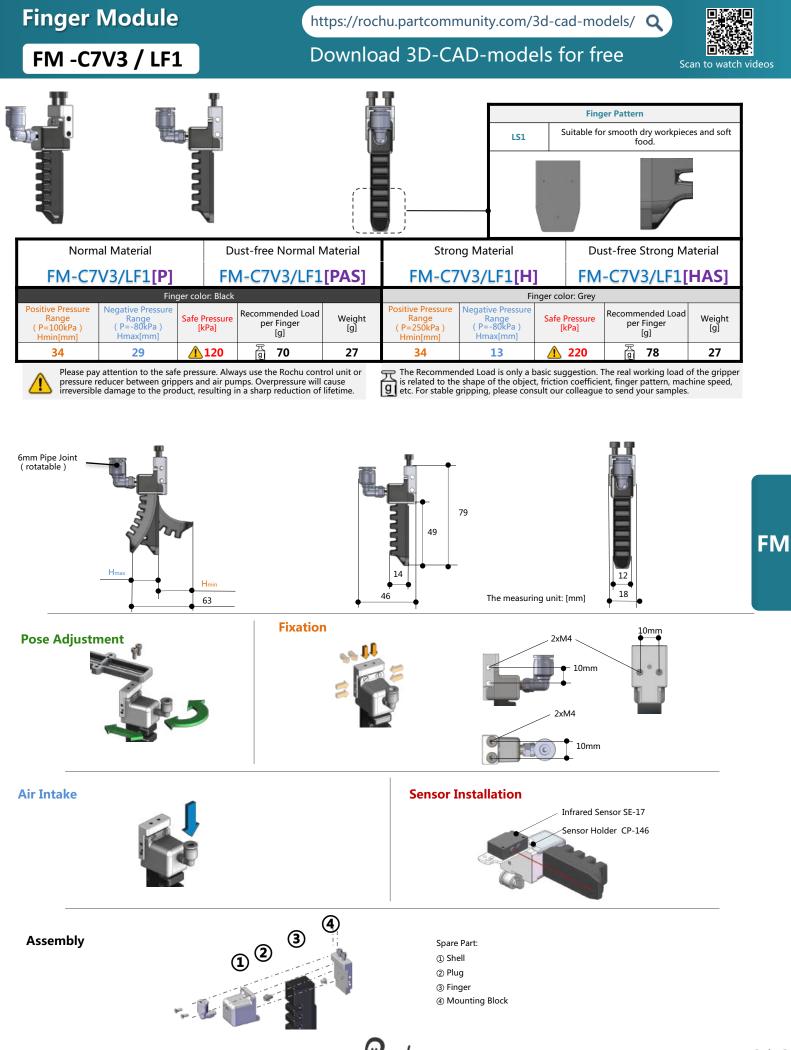
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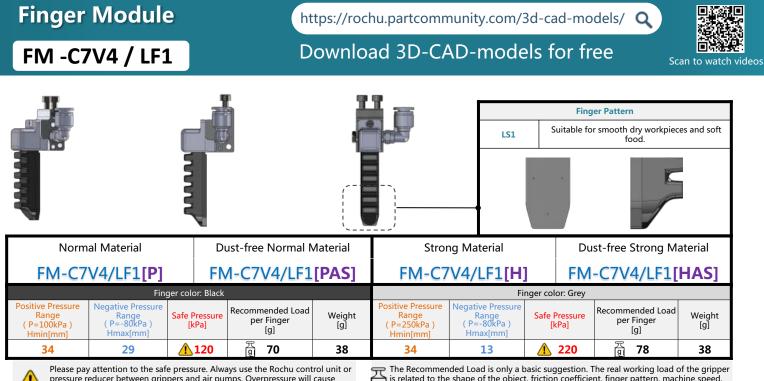
Rochu



413 Rochu soft Finger

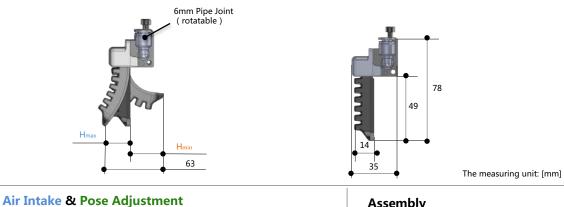


Rochu



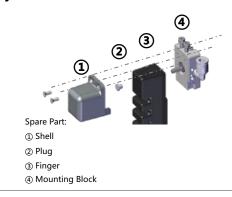
pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

g is related to the shape of the object, friction coefficient, finger pattern, machine speed, etc. For stable gripping, please consult our colleague to send your samples.





Assembly



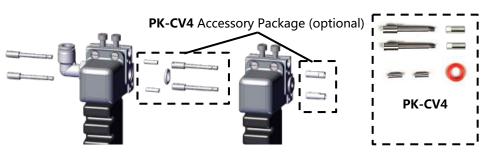


FM

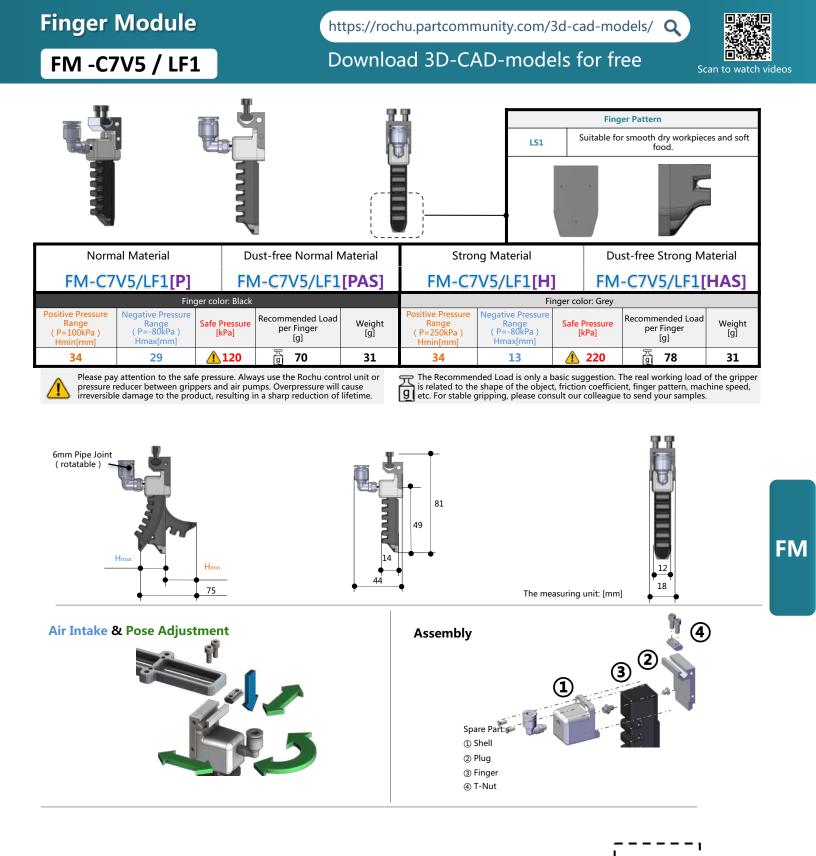
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Finger N	lodule	htt	https://rochu.partcommunity.com/3d-cad-models/ Q									
F -C7T /	LF1	De	Download 3D-CAD-models for free Scar									
					•         •           •         •           •         •           •         •           •         •           •         •							
Finge	r Pattern		Features									
LF1	Special Form	Suitable for smooth dry workpieces and soft food.										
Norma	al Material	Dust-free Norma	Material	Strong Material	D	Dust-free Strong Material						
F-C71	7/LF1[P]	F-C7T/LF1	PAS]	F-C7T/LF1[H]	F	-C7T/LF1[H	AS]					
Desitive Dress		olor: Black		Proiting Programs								
		e Pressure [kPa] Recommended Los per Finger [g]	d Weight [g]	Positive Pressure Range         Negative Pressure Range           (P=250kPa)         (P=-80kPa)           Hmin[mm]         Hmax[mm]	Safe Pressure [kPa]	Recommended Load per Finger [g]	Weight [g]					

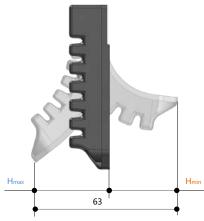
7

FM

34

#### **Dimension Parameters**

29

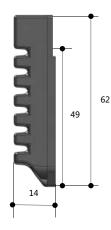


岡

70

120

Please pay attention to the safe pressure. Always use the Rochu control unit or pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.



34

13

220

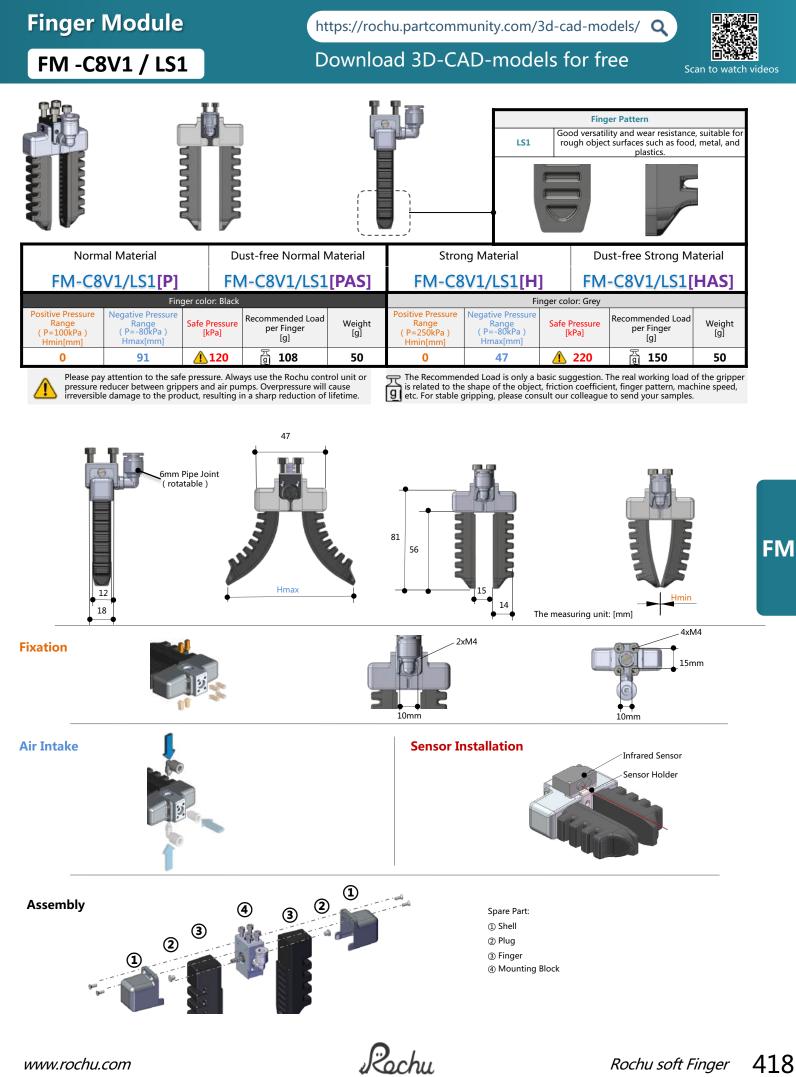
The Recommended Load is only a basic suggestion. The real working load of the gripper is related to the shape of the object, friction coefficient, finger pattern, machine speed, getc. For stable gripping, please consult our colleague to send your samples.

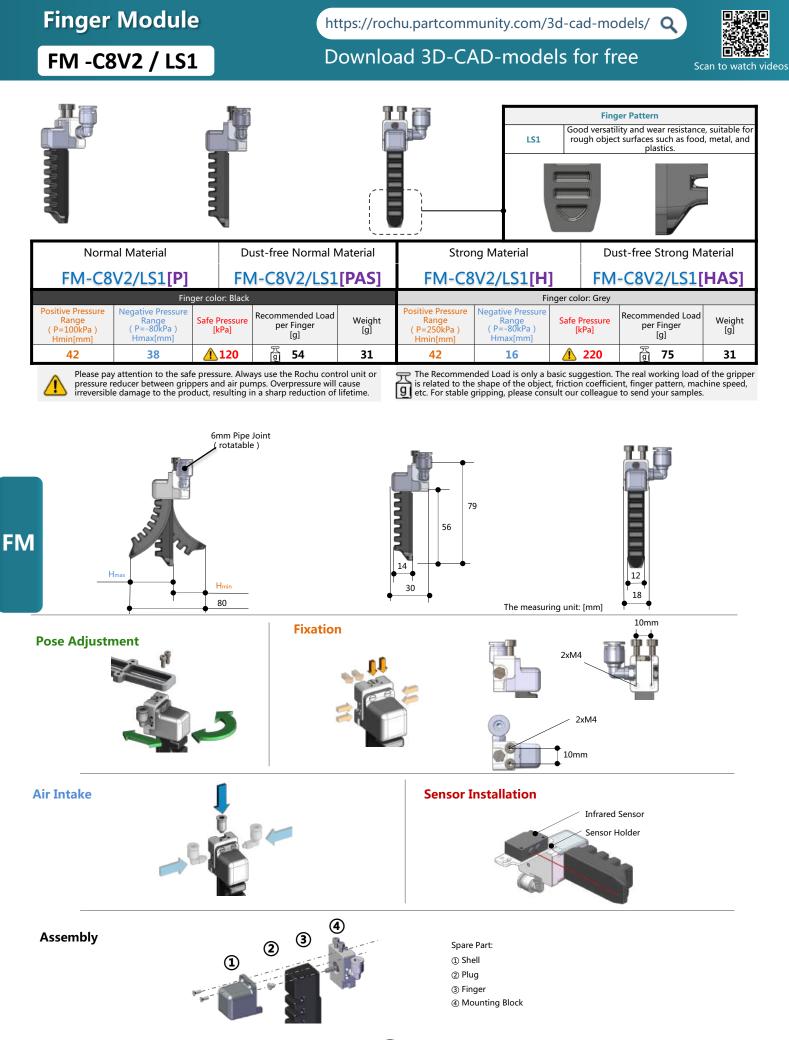


78

7

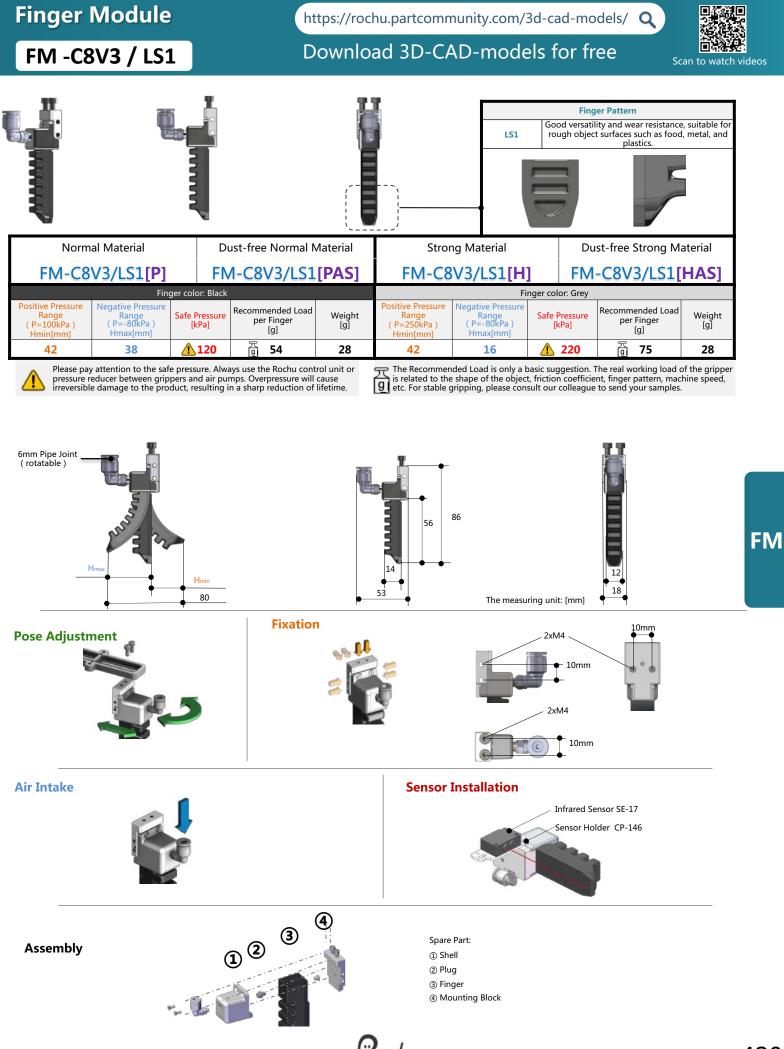
집





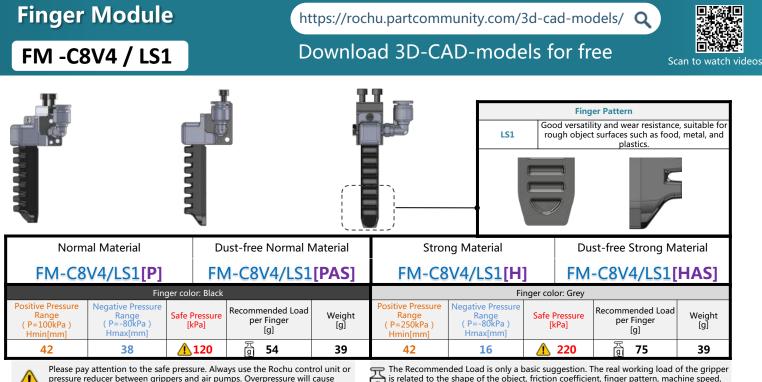
419 Rochu soft Finger

Pochu



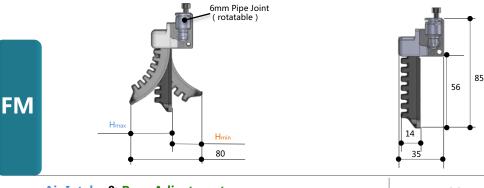
Rochu

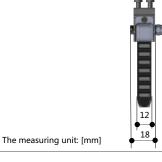
Rochu soft Finger 420



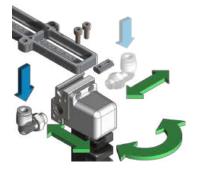
pressure reducer between grippers and air pumps. Overpressure will cause irreversible damage to the product, resulting in a sharp reduction of lifetime.

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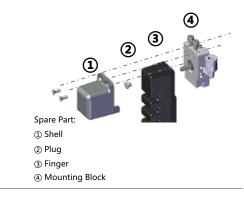




Air Intake & Pose Adjustment



Assembly

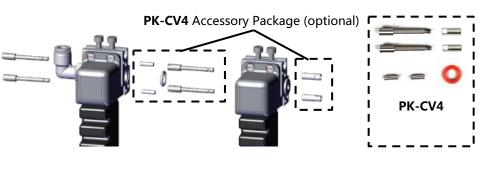


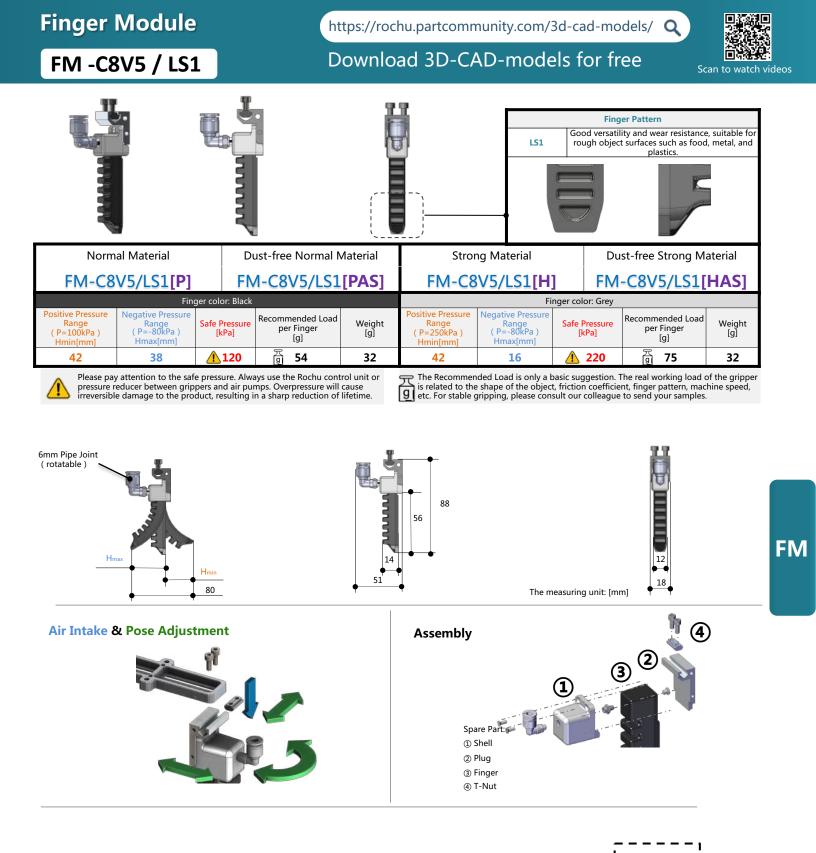
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1. Build multiple finger modules in series to increase the grip force.

2. It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately.





#### Series combination:

**1**. Build multiple finger modules in series to increase the grip force.

2. Realize seamless splicing between finger modules, with convenient assembly, good rigidity, and space-saving.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. This part kit is not included in the finger module and needs to be ordered separately. PK-CV5 Accessory Package (optional)

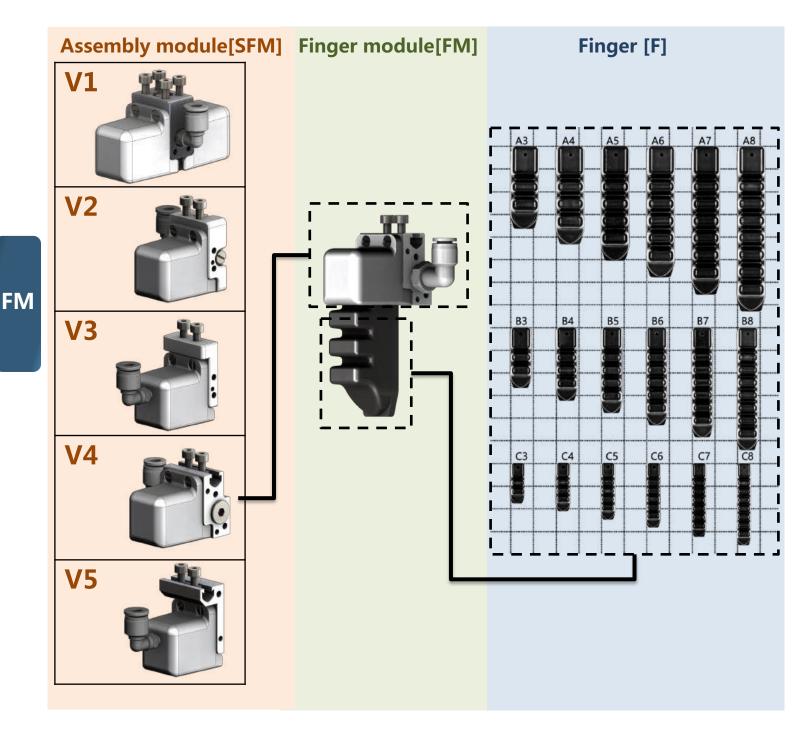
l i	Finger N	lodule	https://rochu.partcommunity.com/3d-cad-models/ Q									
	F -C8T /	LS1		Downlo	oac	3D-CAD	o-models	for f	ree	Scan	to watch vide	
	Finge	r Pattern	Features									
	LS1	Standard form	Good versatility and wear resistance, suitable for rough object surfaces such as food, metal, and plastics.									
		l Material		Normal Materia	ıl	Strong Material			Dust-free Strong Material			
	F-C8T	/LS1[P]	F-C8T/LS1[PAS]			F-C8		F-C8T/LS1[HAS]				
	Positive Pressure Range (P=100kPa) Hmin[mm]	Negative Pressure Range Safe	Pressure [kPa] Recommended Load per Finger [g] [g]			Positive Pressure Negative Pressure			Safe Pressure [kPa] Recommended Luper Finger [g]		Weight [g]	
	42	38		54 8		42	16	<u>^</u> 22	<u>v</u>	75	8	
	/ pressure re	attention to the safe pres educer between grippers a e damage to the product,	and air pumps. Overp	pressure will cause		The Recommen is related to the etc. For stable g	ded Load is only a b shape of the object ripping, please cons	t, friction co	efficient, finge	r pattern, mac	hine speed,	
FM	Dimensio	n Parameters	5									
	Hmax	Annual Room	Ни	<u>nin</u>		69 56						

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## Finger Module[FM]

- The Finger Module [FM] is composed of the Assembly module [SFM] and the Finger [F].
- Differrent Assembly module [SFM] has different air intake, fixation position, and combination mode.
- Select the appropriate Finger[F] according to the weight and size of the gripped workpiece. See page53 for the calculation method of gripping force.
- The safe pressure of the **Finger Module** [FM] is 120-300kpa. Please refer to the product label or packaging instructions.



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FM

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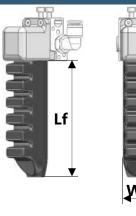
### Size of Finger Module [FM]

According to the width and length of Fingers[F], they are divided into the following 18 sizes\*.

A3 , A4 , A5 , A6 , A7 , A8; B3 , B4 , B5 , B6 , B7 , B8; C3 , C4 , C5 , C6 , C7 , C8.

Select different finger-widths [Wf] according to the weight of the workpiece. The larger the [Wf], the greater the gripping force According to the workpiece size, select different finger-lengths [Lf]. Long fingers have a better fitting of the big workpiece. Short fingers have higher accuracy.

\* : For customized finger, please contact our customer service.



	3 Segments	4 Segments	5 Segments	6 Segments	7 Segments	8 Segments	Wf [mm]
Finger Size	A3	A4	A5	A6	A7	A8	
Lf[mm]	41	55	69	83	97	111	
A							24
Finger SIze	B3	B4	B5	B6	B7	B8	
Lf[mm]	31	41.5	52	62.5	73	83.5	
В							18
Finger Size	C3	C4	C5	C6	C7	C8	
Lf[mm]	21	28	35	42	49	56	
с							12



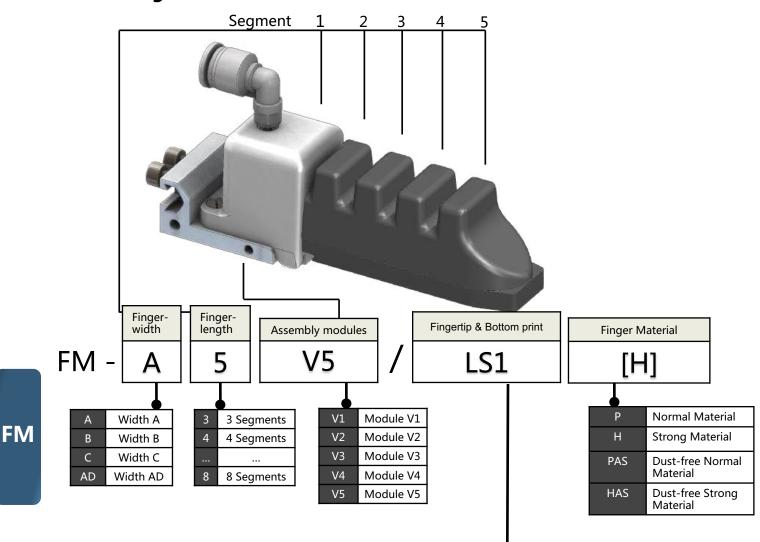


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## **Encoding Method**



Fingertip & E print	Bottom	Features	Pictures						
Standard	LS1	Good versatility and wear resistance, suitable for rough object surfaces such as food, metal, and plastics.							
		Suitable for smooth dry workpieces and soft food.	S.C.						
Special*	FS3	Suitable for soft fabric products.	RE						
	LS8	Suitable for sheet metal parts, flat glass, PCB, car headlights, and other plates.							

\* Please consult our customer service for more Special Fingertips and Bottom prints.

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## **Assembly Modules**

There are five Assembly Modules **V1**, **V2**, **V3**, **V4**, and **V5** with different air intakes, and fixation positions.

Assembly Modules	Pictures	Structural Features
V1 Compact two-finger module		<ul> <li>Features: Double finger module combination, compact structure, and small space. Finger spacing and installation angle are unadjustable. It is suitable for gripping small, light, and thin workpieces.</li> <li>Fixation: Can be fixed on three sides (optional).</li> <li>Air intake: Intake joints are installed on three sides (optional).</li> <li>Additional Sensor module (optional).</li> </ul>
V2 Single-finger Module		<ul> <li>Features: Single finger module combination, compatible with [SMP] sliding mounting plate, adjustable spacing and angle between fingers.</li> <li>Fixation: Can be fixed on four sides (optional).</li> <li>Air intake: Intake joints can be installed on three sides (optional).</li> <li>Additional Sensor module (optional).</li> </ul>
V3 Single-finger Module		<ul> <li>Features: Single finger module combination, compatible with [SMP] Slide Mounting Plate, adjustable spacing, and angle between fingers.</li> <li>Fixation: Can be fixed on three sides (optional).</li> <li>Air intake: The intake joint can only be installed on one side (the back of the finger).</li> <li>Additional Sensor module (optional).</li> </ul>
V4 Series-finger Module		<ul> <li>Features: Series-finger Module, the gripping force is large, which can be used in series (using a parts kit [PK]).Only one air intake when more finger modules build in series. More fingers in series are good at gripping large and heavy objects.</li> <li>Fixation: It is fixed with T-nut. When installed with a sliding mounting plate, it can adjust the front and rear, left and right, and rotation respectively.</li> <li>Air intake: Air intake on left or right sides (optional).</li> </ul>
V5 Series-finger Module		<ul> <li>Features: Series-finger Module, can be used in series. the minimum finger spacing of the installation module is only 10mm, which is suitable for clamping small and light workpieces. Compared with V4, each finger needs an independent air intake.</li> <li>Fixation: It is fixed with T-nut. When installed with a sliding mounting plate, it can adjust the front and rear, left and right, and rotation respectively.</li> <li>Air intake: Single air intake on finger backside.</li> </ul>

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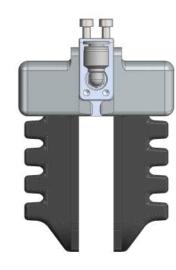
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# V1 Assembly module: Compact two-finger module

- **Features**: Double finger module combination, compact structure, and small space. Finger spacing and installation angle are unadjustable. It is suitable for gripping small, light, and thin workpieces.
- Fixation: Can be fixed on three sides (optional).
- Air intake: Intake joints are installed on three sides (optional).
- Additional Sensor module (optional).

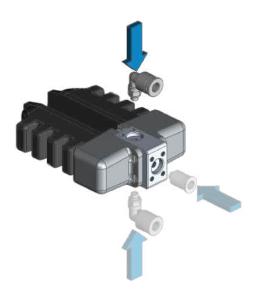






FM

**Air Intake** 



# Sensor Installation



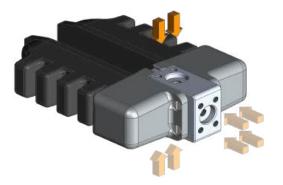
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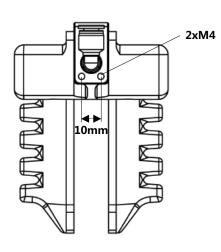


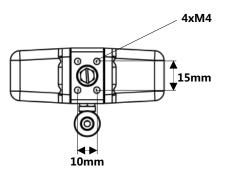
# V1Assembly module: Compact two-finger module

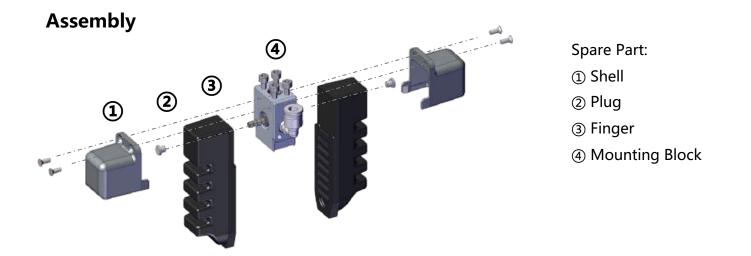
# **Fixation**

## Dimensions







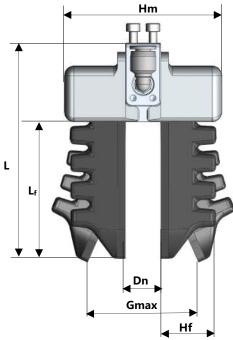


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# V1 Assembly module: Compact two-finger module





FM	Finger Size	Finger Module	Dn [mm]	Finger I	* [mm] Material [H]/[HAS ]	Hm [mm]	Hf [mm]	Lm [mm]	Lf [mm]	Wm [mm]	Wf [mm]	Weight [g]	[k Finger	ressure Pa] Material [ <b>H]/[HAS]</b>
	A3	FM-A3V1	18	34	32	80	28	81	41	29	24	153	120	300
	A4	FM-A4V1	18	38	42	80	28	95	55	29	24	167	120	300
	A5	FM-A5V1	18	56	50	80	28	109	69	29	24	181	120	300
	A6	FM-A6V1	18	84	62	80	28	123	83	29	24	195	120	300
	A7	FM-A7V1	18	96	72	80	28	137	97	29	24	210	120	300
	A8	FM-A8V1	18	108	82	80	28	151	111	29	24	224	120	300
	B3	FM-B3V1	18	38	30	65	21	64	31	23	18	77	120	260
	B4	FM-B4V1	18	44	38	65	21	74.5	41.5	23	18	85	120	260
	B5	FM-B5V1	18	50	46	65	21	85	52	23	18	94	120	260
	B6	FM-B6V1	18	64	52	65	21	95.5	62.5	23	18	102	120	260
	B7	FM-B7V1	18	78	60	65	21	106	73	23	18	110	120	260
	B8	FM-B8V1	18	92	68	65	21	116.5	83.5	23	18	118	120	260
	C3	FM-C3V1	15	25	17	47	14	46	21	21.5	12	42	120	220
	C4	FM-C4V1	15	33	21	47	14	53	28	21.5	12	44	120	220
	C5	FM-C5V1	15	39	31	47	14	60	35	21.5	12	45	120	220
	C6	FM-C6V1	15	55	35	47	14	67	42	21.5	12	47	120	220
	C7	FM-C7V1	15	73	41	47	14	74	49	21.5	12	48	120	220
	* C8	FM-C8V1 easured wher	15 real worl	91	47	47 a (vacuum	14	81	56	21.5	12	50	120	220
	. G <sub>max</sub> IT			ing pressu										



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## V2 Assembly module: Single-finger Module

- Features: Single finger module combination, compatible with [SMP] sliding mounting plate, adjustable spacing and angle between fingers.
- Fixation: Can be fixed on four sides (optional).
- Air intake: Intake joints can be installed on three sides (optional).
- Additional Sensor module (optional).







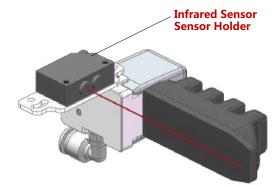
**Pose Adjustment** 



Air Intake



**Sensor Installation** 



FM



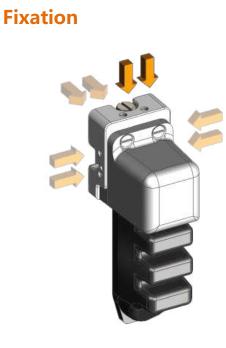
# Finger Module

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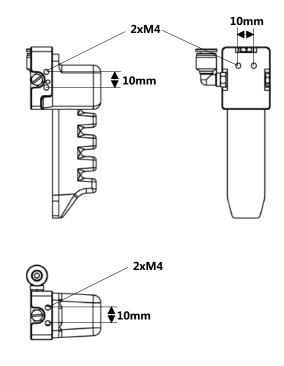
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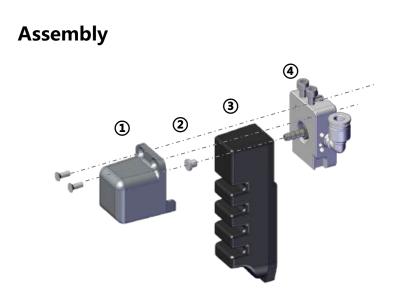


## V2 Assembly module: Single-finger Module



Dimensions





- Spare Part:
- 1 Shell
- ② Plug
- ③ Finger
- ④ Mounting Block

FM

## **Finger Module**

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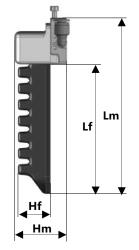
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## V2 Assembly module: Single-finger Module









Finger Size	Finger Module	HR [mm]	Negative Ran Hmax Finger M [P]/[PAS]	ge* [mm] ⁄laterial	Positive Pressure Range ** Hmin [mm]	Hm [mm]	Hf [mm]	Lm [mm]	Lf [mm]	Wm [mm]	Wf [mm]	Weight [g]	[k Finger	ressure Pa] Material [ <b>H]/[HAS</b> ]
A3	FM-A3V2	16.5	8	7	8.5	45	28	82	41	31	24	92	120	300
				12										
A4	FM-A4V2	27	10		17	45	28	96	55	31	24	99	120	300
A5	FM-A5V2	43.5	19	16	24.5	45	28	110	69	31	24	106	120	300
A6	FM-A6V2	72	33	22	39	45	28	124	83	31	24	113	120	300
A7	FM-A7V2	90	39	27	51	45	28	138	97	31	24	120	120	300
A8	FM-A8V2	109	45	32	64	45	28	152	111	31	24	127	120	300
B3	FM-B3V2	19	10	6	9	37.5	21	65	31	25	18	52	120	260
B4	FM-B4V2	29	13	10	16	37.5	21	76	41.5	25	18	56	120	260
B5	FM-B5V2	40	16	14	24	37.5	21	86	52	25	18	60	120	260
B6	FM-B6V2	53	23	17	30	37.5	21	97	62.5	25	18	64	120	260
B7	FM-B7V2	75	30	21	45	37.5	21	107	73	25	18	68	120	260
B8	FM-B8V2	98	37	25	61	37.5	21	118	83.5	25	18	72	120	260
C3	FM-C3V2	10.5	5	1	5.5	30	14	44	21	18	12	27	120	220
C4	FM-C4V2	20	9	3	11	30	14	51	28	18	12	27	120	220
C5	FM-C5V2	27	12	8	15	30	14	58	35	18	12	28	120	220
C6	FM-C6V2	42	20	10	22	30	14	65	42	18	12	29	120	220
C7	FM-C7V2	63	29	13	34	30	14	72	49	18	12	30	120	220
C8	FM-C8V2	80	38	16	42	30	14	79	56	18	12	31	120	220

\* : Negative Pressure Range **H<sub>max</sub>** Working pressure is -80kPa。 \*\* : Positive Pressure Range **H<sub>min</sub>** : For Normal Material Finger[P]/[PAS] , working pressure is 100kPa. For Strong Material Finger[H]/[HAS] , working pressure is 250kPa.(缩进)



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## V3 Assembly module: Single-finger Module

- Features: Single finger module combination, compatible with [SMP] Slide Mounting Plate, adjustable spacing, and • angle between fingers.
- Fixation: Can be fixed on three sides (optional). ٠
- Air intake: The intake joint can only be installed on one side (the back of the finger).
- Additional Sensor module (optional). •







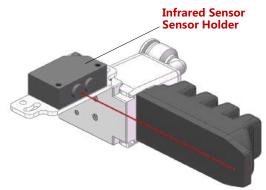
**Pose Adjustment** 



**Air intake** 



#### **Sensor Installation**



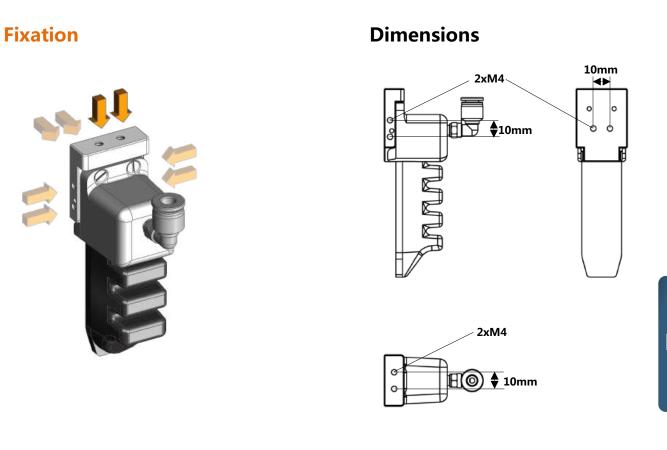
FM

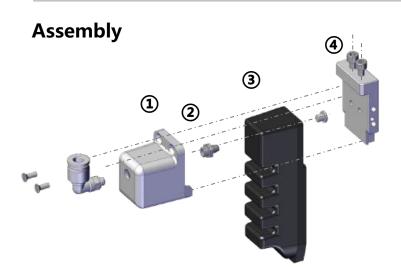


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#### V3 Assembly module: Single-finger Module





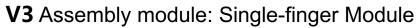
- Spare Part:
- 1 Shell
- ② Plug
- ③ Finger
- ④ Mounting Block

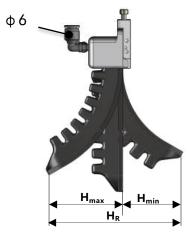


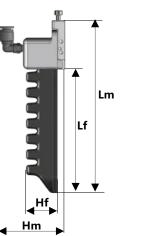
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	Finger Size	Finger Module	HR [mm]	Ran Hmax Finger	e Pressure oge * ([mm] Material [ <b>H]/[HAS</b> ]	Positive Pressure Range ** Hmin [mm]	Hm [mm]	Hf [mm]	Lm [mm]	Lf [mm]	Wm [mm]	Wf [mm]	Weight [g]	[ŀ Finger	Pressure (Pa] Material [ <b>H]/[HAS]</b>
			_		-										
Ì	A3		16.5	8	7	8.5	60	28	85.5	41	31	24	77	120	300
	A4	FM-A4V3	27	10	12	17	60	28	99.5	55	31	24	84	120	300
Μ	A5	FM-A5V3	43.5	19	16	24.5	60	28	113.5	69	31	24	91	120	300
	A6	FM-A6V3	72	33	22	39	60	28	127.5	83	31	24	98	120	300
	A7	FM-A7V3	90	39	27	51	60	28	141.5	97	31	24	105	120	300
	A8	FM-A8V3	109	45	32	64	60	28	155.5	111	31	24	112	120	300
	B3	FM-B3V3	19	10	6	9	53	21	68.5	31	25	18	43	120	260
	B4	FM-B4V3	29	13	10	16	53	21	79.5	41.5	25	18	47	120	260
	B5	FM-B5V3	40	16	14	24	53	21	89.5	52	25	18	51	120	260
	B6	FM-B6V3	53	23	17	30	53	21	100.5	62.5	25	18	55	120	260
	B7	FM-B7V3	75	30	21	45	53	21	110.5	73	25	18	59	120	260
	B8	FM-B8V3	98	37	25	61	53	21	121.5	83.5	25	18	63	120	260
	C3	FM-C3V3	10.5	5	1	5.5	46	14	51	21	18	12	24	120	220
	C4	FM-C4V3	20	9	3	11	46	14	58	28	18	12	25	120	220
	C5	FM-C5V3	27	12	8	15	46	14	65	35	18	12	26	120	220
	C6	FM-C6V3	42	20	10	22	46	14	72	42	18	12	26	120	220
	C7	FM-C7V3	63	29	13	34	46	14	79	49	18	12	27	120	220
	C8	FM-C8V3	80	38	16	42	46	14	86	56	18	12	28	120	220

\* : Negative Pressure Range  $\mathbf{H}_{max}$ : Working pressure is -80kPa.

\*\* : Positive Pressure Range **H**<sub>min</sub> : For Normal Material Finger[P]/[PAS] , working pressure is 100kPa. For Strong Material Finger[H]/[HAS] , working pressure is 250kPa.

FN

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## **Finger Module**

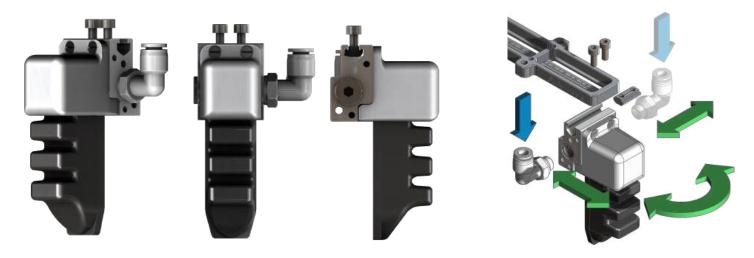
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#### V4 Series-finger Module: Series air circuit, high load.

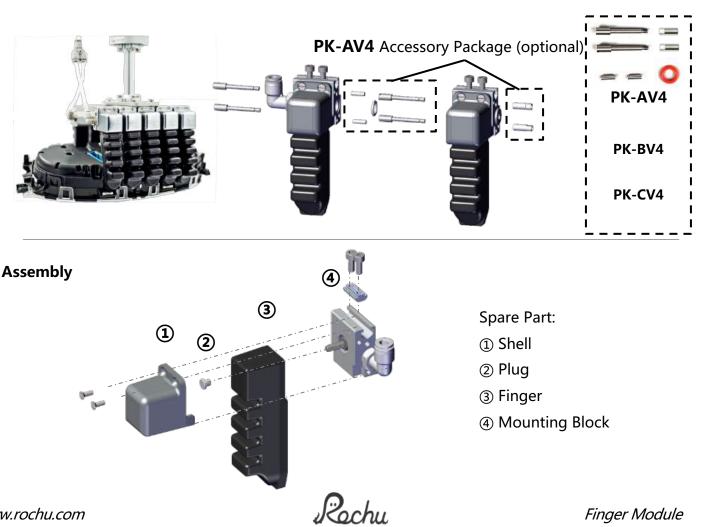
- Features: Series-finger Module, the gripping force is large, which can be used in series (using a parts kit [PK]). Only one air intake when more finger modules build in series. More fingers in series are good at gripping large and heavy objects.
- Fixation: It is fixed with T-nut. When installed with a sliding mounting plate, it can adjust the front and rear, left and right, and rotation respectively.
- Air intake: Air intake on left or right sides (optional).



#### Series combination:

- Multiple finger modules are combined in series to increase the gripping force.
- It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. The parts kit is not included in the finger module and needs to be ordered separately.



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AS

# V4 Assembly Module: Series-finger Module

	H <sub>max</sub> H <sub>min</sub>				8			Lf Lm					Þ <b>6</b>		
	Finger Size	Finger Module	HR [mm]	Rai Hma	e Pressure nge * x [mm] Material [H]/[HAS]	Positive Pressure Range ** Hmin [mm]	Hm [mm]	Hf [mm]	Lm [mm]	Lf [mm]	Wm [mm]	Wf [mm]	Weight [g]	[k	Pressure Pa] Material [H]/[H4 ]
M	A3	FM-A3V4	16.5	8	7	8.5	51	28	78	41	31	24	97	120	300
	A4	FM-A4V4	27	10	12	17	51	28	92	55	31	24	104	120	300
	A5	FM-A5V4	43.5	19	16	24.5	51	28	106	69	31	24	111	120	300
	A6	FM-A6V4	72	33	22	39	51	28	120	83	31	24	119	120	300
	A7	FM-A7V4	90	39	27	51	51	28	134	97	31	24	126	120	300
	A8	FM-A8V4	109	45	32	64	51	28	148	111	31	24	133	120	300
	B3	FM-B3V4	19	10	6	9	45	21	61	31	25	18	61	120	260
	B4	FM-B4V4	29	13	10	16	45	21	72	41.5	25	18	65	120	260
	B5	FM-B5V4	40	16	14	24	45	21	82	52	25	18	69	120	260
	B6	FM-B6V4	53	23	17	30	45	21	93	62.5	25	18	73	120	260
	B7	FM-B7V4	75	30	21	45	45	21	103	73	25	18	77	120	260
	B8	FM-B8V4	98	37	25	61	45	21	114	83.5	25	18	81	120	260
		_													
	C3	FM-C3V4	10.5	5	1	5.5	35	14	50	21	18	12	35	120	220
	C4	FM-C4V4	20	9	3	11	35	14	57	28	18	12	36	120	220
	C5	FM-C5V4	27	12	8	15	35	14	64	35	18	12	37	120	220
	C6	FM-C6V4	42	20	10	22	35	14	71	42	18	12	38	120	220
	C7	FM-C7V4	63	29	13	34	35	14	78	49	18	12	38	120	220
	C8	FM-C8V4	80	38	16	42	35	14	85	56	18	12	39	120	220
	* : N	egative Pres	sure Ran	ge <b>H<sub>max∶∖</sub></b>	Working pre	ssure is -8	30kPa。								

\*\* : Positive Pressure Range  $\mathbf{H}_{min}$  : For Normal Material Finger[P]/[PAS] , working pressure is 100kPa. For Strong Material Finger[H]/[HAS], working pressure is 250kPa.

FΝ

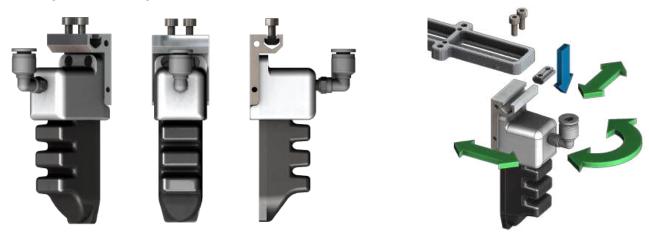


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#### V5 Assembly Module: Series-finger Module

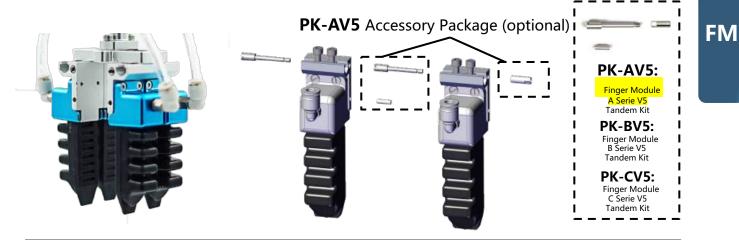
- Features: Series-finger Module, can be used in series. the minimum finger spacing of the installation module is only 10mm, which is suitable for clamping small and light workpieces. Compared with V4, each finger needs an independent air intake.
- Fixation: It is fixed with T-nut. When installed with a sliding mounting plate, it can adjust the front and rear, left and right, and rotation respectively.
- Air intake: Single air intake on finger backside.

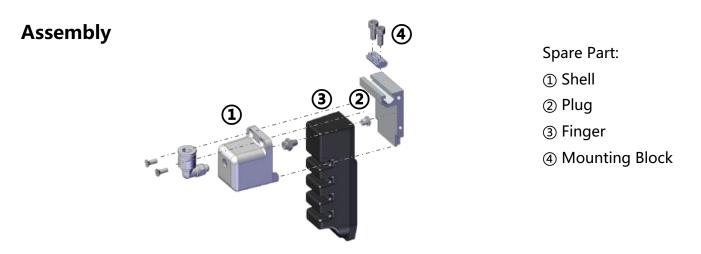


#### Series combination:

- Multiple fingers are combined in series to work at the same time to increase the gripping force
- It can realize the seamless splicing between fingers and share the air inlet to save space.

\*Splicing finger modules requires a parts kit [PK] containing the bolts, nuts, sealings, and pins. The parts kit is not included in the finger module and needs to be ordered separately.



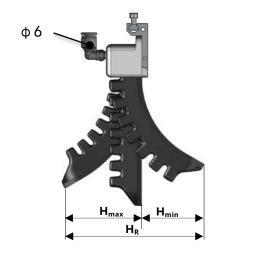


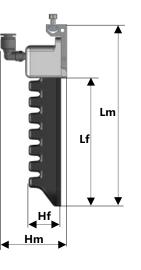


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# V5 Assembly Module: Series-finger Module







	Finger	Finger	Finger			Positive Pressure	Hm	Hf	Lm	Lf	Wm	Wf	Weight	Safe Pr [kF	
	Size	Module		Finger N	/laterial	Range ** Hmin	[mm]	[mm]	[mm]	[mm]	[mm]	[mm]	[g]	Finger N	/laterial
FM				[P]/[PAS]	[H]/[HAS ]	[mm]								[P]/[PAS]	[H]/[HAS]
	A3	FM-A3V5	16.5	8	7	8.5	58	28	88	41	31	24	76	120	300
	A4	FM-A4V5	27	10	12	17	58	28	102	55	31	24	83	120	300
	A5	FM-A5V5	43.5	19	16	24.5	58	28	116	69	31	24	90	120	300
	A6	FM-A6V5	72	33	22	39	58	28	130	83	31	24	97	120	300
	A7	FM-A7V5	90	39	27	51	58	28	144	97	31	24	104	120	300
	A8	FM-A8V5	109	45	32	64	58	28	158	111	31	24	111	120	300
	B3	FM-B3V5	19	10	6	9	51	21	71	31	25	18	44	120	260
	B4	FM-B4V5	29	13	10	16	51	21	82	41.5	25	18	48	120	260
	B5	FM-B5V5	40	16	14	24	51	21	92	52	25	18	52	120	260
	B6	FM-B6V5	53	23	17	30	51	21	103	62.5	25	18	56	120	260
	B7	FM-B7V5	75	30	21	45	51	21	113	73	25	18	60	120	260
	B8	FM-B8V5	98	37	25	61	51	21	124	83.5	25	18	64	120	260
	C3	FM-C3V5	10.5	5	1	5.5	44	14	53	21	18	12	28	120	220
	C4	FM-C4V5	20	9	3	11	44	14	60	28	18	12	28	120	220
	C5	FM-C5V5	27	12	8	15	44	14	67	35	18	12	29	120	220
	C6	FM-C6V5	42	20	10	22	44	14	74	42	18	12	30	120	220
	C7	FM-C7V5	63	29	13	34	44	14	81	49	18	12	31	120	220
	C8	FM-C8V5	80	38	16	42	44	14	88	56	18	12	32	120	220

\* : Negative Pressure Range  $\boldsymbol{H}_{max}$  :Working pressur is -80kPa.

\*\* : Positive Pressure Range  $\mathbf{H}_{min}$  : For Normal Material Finger[P]/[PAS] , working pressure is 100kPa , For Strong Material Finger[H]/[HAS] , working pressure is 250kPa.





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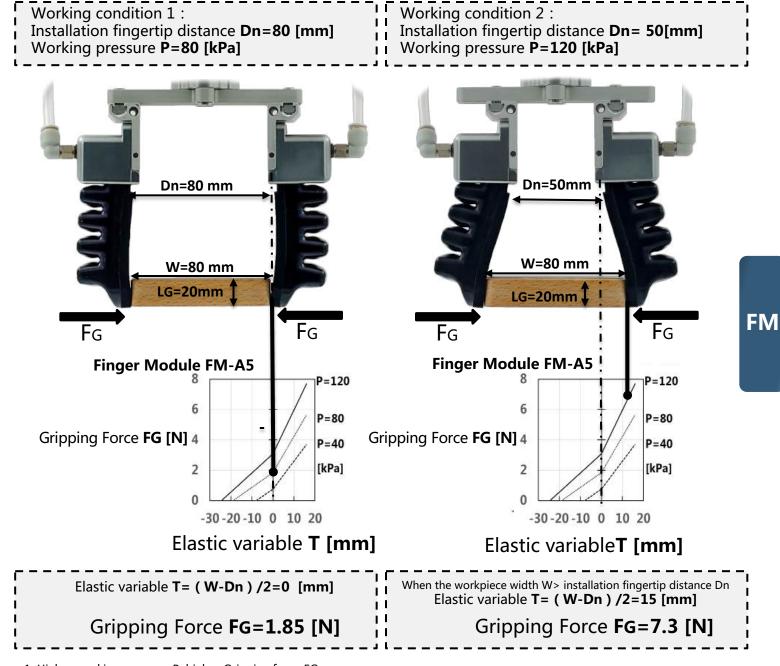
#### Characteristic parameter : Adjustment and calculation method of gripping force of finger module

When the finger module is inflated, it bends inward and generates a horizontal gripping force FG when contacting the gripped

workpiece. This gripping force is related to the shape of the workpiece, the type of finger, the contact area between the finger and the

workpiece, the installation fingertip distance Dn (page. 59), and the working air pressure P.

Take FM-A5 finger module (normal material) as an example to clamp a square workpiece under different working conditions. The width of the workpiece is W = 80mm, and the covering length of the fingertip is LG = 20mm:



1, Higher working pressure P, higher Gripping force FG.

2, Shorter finger distance Dn, higher Gripping force FG.

3, Bigger finger size, higher Gripping force FG.

4, The strong material finger can hold higher air pressure and has a stronger force than the normal material finger.

5, Exceeding the safe working pressure will cause irreversible damage to the soft finger and a shorter lifetime, while shorter Dn may increase the abrasion of the finger bottom.

6, More fingers in series (Page. 37,39) can also improve the overall Gripping force.

7, Besides the Gripping force FG, the real handling load of the gripper is also related to the shape of the object, friction coefficient, finger bottom print, machine speed, etc.

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## **Finger Module**

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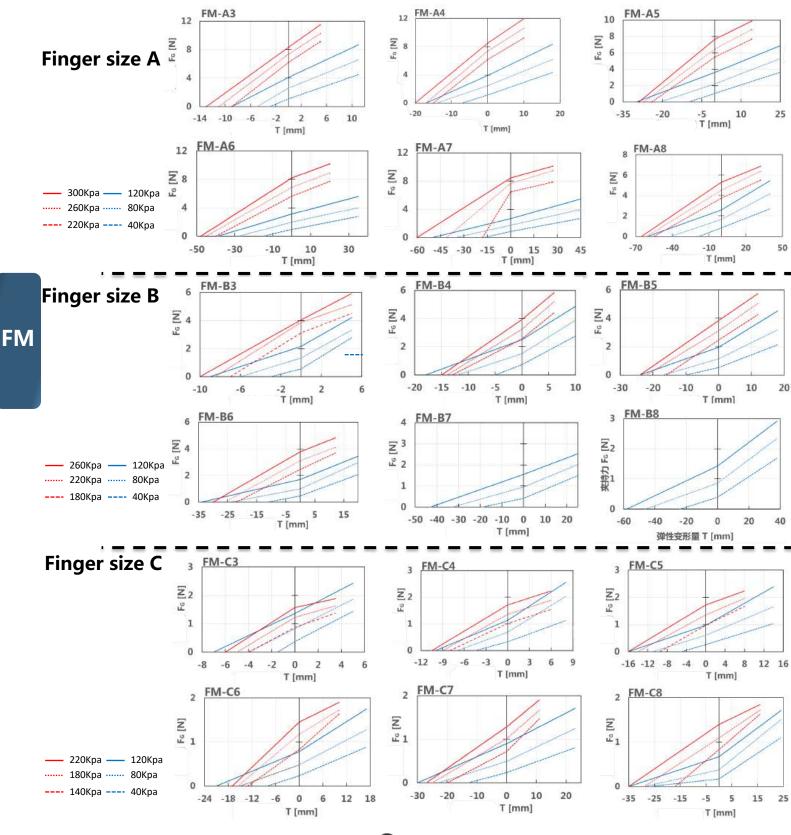
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#### Finger Module Gripping force diagram

The relevant values in the curve are determined under the following conditions:

- finger material: normal material, strong material
- use square workpiece, finger pattern LS1, (page. 53)
- only the fingertip part is in contact with the workpiece, and the fingertip covering length LG = 10mm.
- the following data is for reference only. Under other working conditions, the values will be different





442 Finger Module

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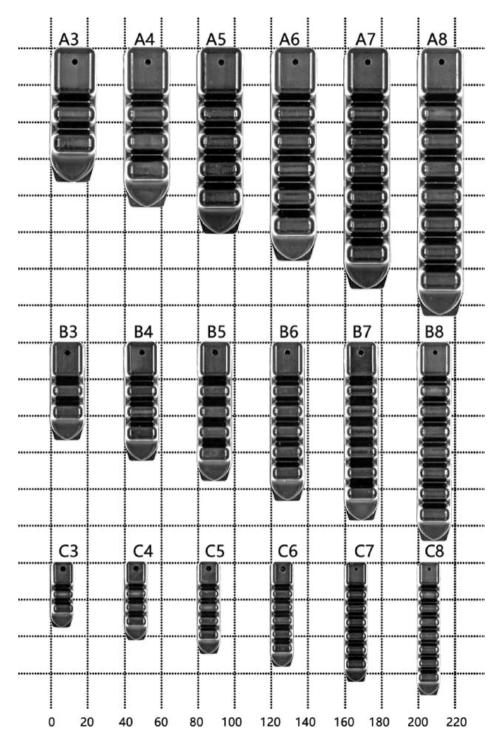
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**Rochu Finger [F]** can be replaced independently. There are 18 finger sizes (A3 , A4 , A5 , A6 , A7 , A8; B3 , B4 , B5 , B6 , B7 , B8; C3 , C4 , C5 , C6 , C7 , C8).

With the same working pressure, the wider fingers have higher gripping force, and the shorter fingers have better positioning accuracy and stability.

For customized finger sizes, please contact our customer service.

#### **Finger Sizes**



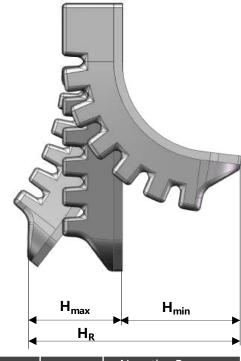
FM

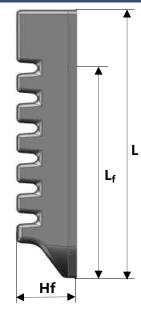


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		Negative	Pressure	Positive							
			ge *	Pressure						Safe Pr [kF	
Finger Size	HR [mm]		Material	Range **	Hf [mm]	Lf [mm]	L [mm]	Wf [mm]	Weight [g]	Finger N	/laterial
0.20	[]		[H]/[HAS]	Hmin [mm]	[]	[]	[]		191	[P]/[PAS]	[H]/[HAS 1
<b>F-A3</b>	16.5	8	7	8.5	28	41	69	24	33	120	300
F-A4	27	10	12	17	28	55	83	24	40	120	300
<b>F-A5</b>	43.5	19	16	24.5	28	69	97	24	47	120	300
F-A6	72	33	22	39	28	83	111	24	55	120	300
<b>F-A7</b>	90	39	27	51	28	97	125	24	62	120	300
<b>F-A8</b>	109	45	32	64	28	111	139	24	69	120	300
F-B3	19	10	6	9	21	31	52	18	11	120	260
F-B4	29	13	10	16	21	42	62	18	16	120	260
F-B5	40	16	14	24	21	52	73	18	20	120	260
F-B6	53	23	17	30	21	63	83	18	24	120	260
<b>F-B7</b>	75	30	21	45	21	73	94	18	28	120	260
F-B8	98	37	25	61	21	84	104	18	32	120	260
F-C3	10.5	5	1	5.5	14	21	34	12	4	120	220
F-C4	20	9	3	11	14	28	41	12	5	120	220
F-C5	27	12	8	15	14	35	48	12	6	120	220
F-C6	42	20	10	22	14	42	55	12	7	120	220
F-C7	63	29	13	34	14	49	62	12	7	120	220
F-C8	80	38 Range <b>H</b>		42 ssure is -80kP	a. 14	56	69	12	8	120	220

\*\* : Positive Pressure Range H<sub>min</sub> : For Normal Material Finger[P]/[PAS] , working pressure is 100kPa , For Strong Material Finger[H]/[HAS] , working pressure is 250kPa.

FM

Rochu



#### **CU** Control Unit



iPCU2

Integrated Passive Control Unit

page. 448



ACU2-B Active Control Unit page. 452



ACU2-H Active Control Unit page. 454



PCU2 Passive Control Unit page. 457



**LCU-H** Light Control U

page. 462





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## iPCU2

#### Compact Passive control unit

- -90~300kPa three levels can adjust the output pressure range, fully support from soft Beak to soft finger drive.
- Manual knob type pressure regulating.
- Integrated panel with digital display and operation buttons.
- With manual (button) and automatic (I/O level signal) two control modes, with all kinds of mechanical arm, PLC and others.
- Equipped with Installation bracket and industrial rail buckle, a variety of Installation.
- Intelligent alarm function, safe and stable, no need to worry about misoperation.
- with European CE safety certification.



#### Parameter

Item	Range	Item	Range	
Power	24VDC±10%	Frame material	ABS	
Rated power	12W	Size	208x134x141mm	
Life time	50 million times	N.W.	2.0kg	
Input air	0.45~1.00MPa Dry, Clear, stable flow > 200L/min	Protection grade Control mode	IP54 1. Manual button 2. I/O , level signal Continuous drive mode	C
Output air pressure	-90~300kPa	Working mode	Continuous drive mode	
Working noise	50db			

#### Model

IPCU2 has two options: standard **iPCU2-SMN** and high-speed **iPCU2-HMN**. High-speed ipCU2-HMN has a larger Vacuum flow, which is suitable for high-speed handling.

М	odel	manual	electron ic	Wireless remote	feedbac k	Safe pressur e	Max pressure [kPa]	Pressure flow [L/min]	Vacuum flow [L/min]
Standard	iPCU2-SMN	•				adjusta ble	-90	260	40
High speed	iPCU2-HMN	٠				adjusta ble	-80	260	80

The flow parameters test conditions: air source port Pressure= 0.6mpa, gripper set Pressure=100kPa



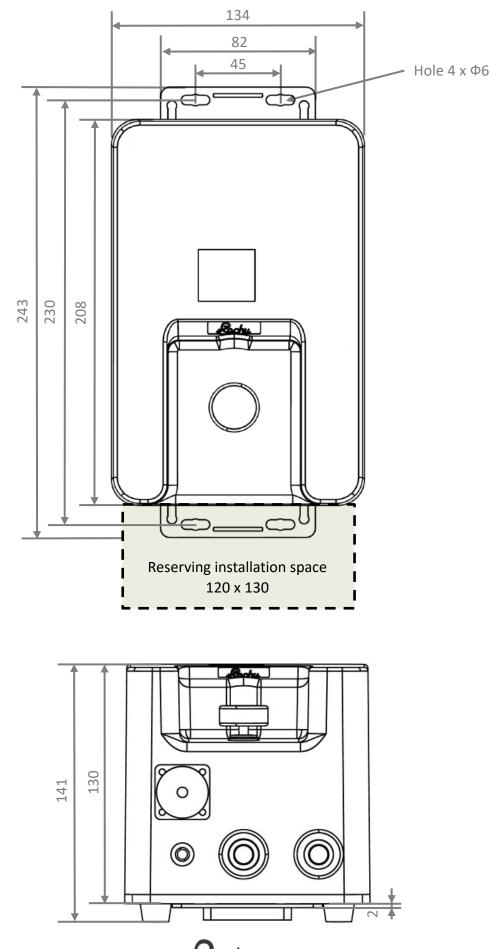
## **Control Unit / Control Unit**

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## iPCU2 Size



CU Control

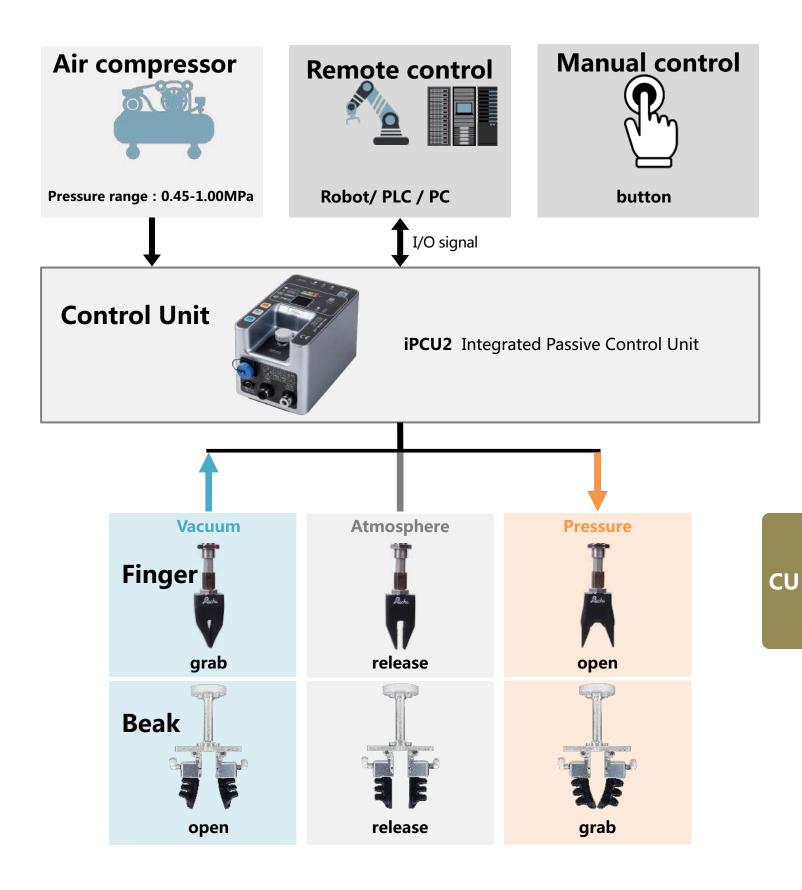


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#### How to use iPCU2?

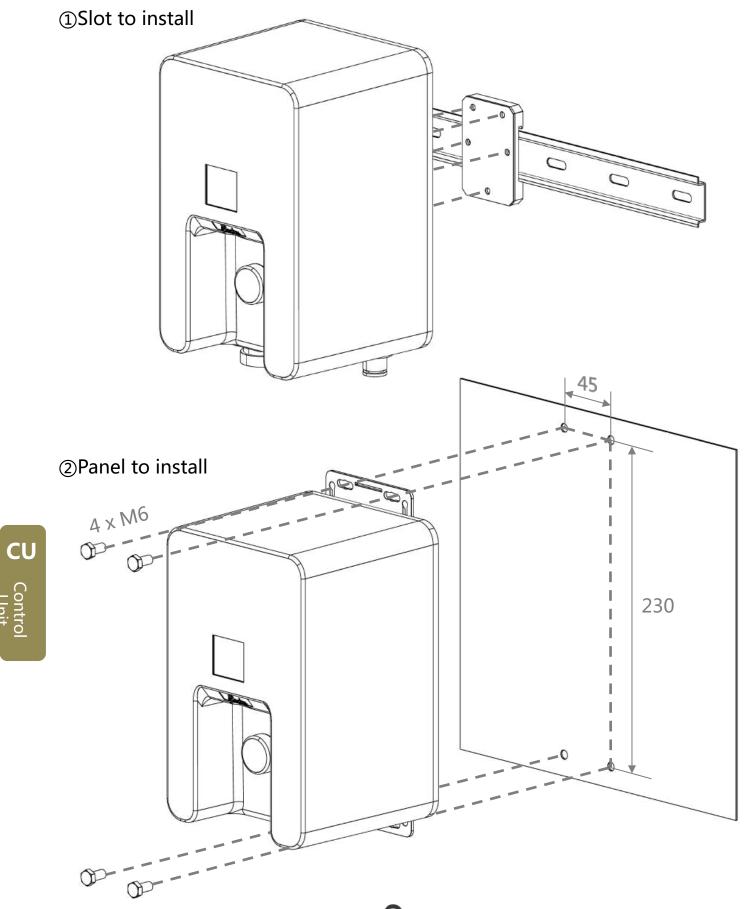






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# iPCU2 Installation





## **Control Unit**

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## ACU2-B

- Compact Control Unit
- Built-in air source, compact and light.
- Suit for some soft grippers drive.
- Six levels of Pressure and four levels of Vacuum output, which can be adjusted in real time by buttons on the panel, with output accuracy of  $\pm$  10kPa.
- Integrated panel with digital display and operation buttons.
- With manual (button) and automatic (I/O level signal) two control modes, suit for all kinds of mechanical arm, PLC terminal.
- Products pass the European CE safety certification.



#### Parameter

Item	Range	Item	Range
Nominal Voltage	24VDC±10%	Frame Material	Anodic oxidation of aluminum alloy
Rated Power	18W	Size	120x158x75mm
Life time	5000小时	Net Weight	980g
Output proceuro	setting	Protect grade	IP54
Output pressure	-80/-60/-40/-20/0/20/40/60/80/100/120 [kPa]	Mode	1. Manual button
Output accuracy	±10kPa	wode	2. I/O , level signal
PressureFlow	4L/min	working mode	Continuous signal drive
VacuumFlow	4L/min	working noise	50db

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Control Unit 451

CU

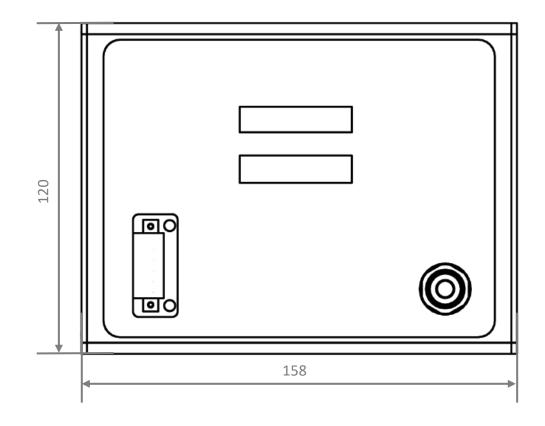
### **Control Unit / Control Unit**

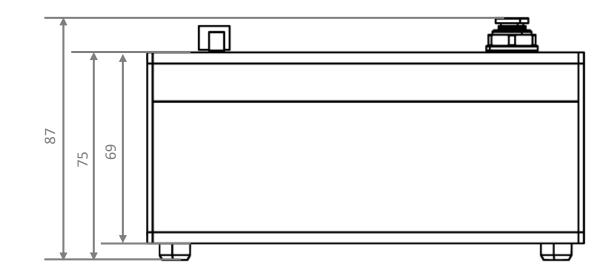
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## ACU2-B Size





## **Control Unit**

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#### ACU2-H

- All-in-one flexible active Control Unit.
- Built-in air source, full interface.
- -80~280kPa Output pressure Range, suitable for all series of soft gripper drive.
- Work Pressure, work Vacuum can be real-time digital Adjust through the panel button, Output accuracy  $\pm$  3kPa.
- Integrated panel with digital display and operation buttons.
- With manual (button), I/O, analog and MODBUS control modes, suit for all kinds of mechanical arm, PLC terminal.
- Products through the European CE safety certification.



#### Parameter

Item	Range	Item	Range
Nominal Voltage	24VDC±10%	Frame Material	Anodic oxidation of aluminum alloy
Rated Power	48W	Size	120x223x75mm
Life time	5000小时	Net Weight	1.8kg
Output pressure	-80~280kPa	Protect grade	IP54
Output accuracy	±3kPa		1. Manual button
PressureFlow	8L/min		2. I/O , level signal
VacuumFlow	8L/min	Mode	3. Voltage analog regulating pressure
working noise	50db		4. MODBUS TCP/RTU
		working mode	Continuous signal drive

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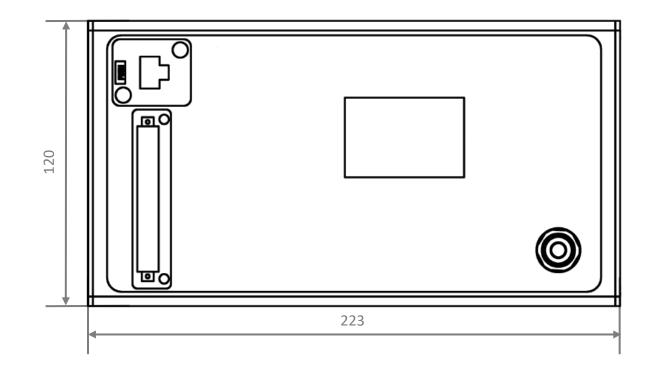
Control Unit 453

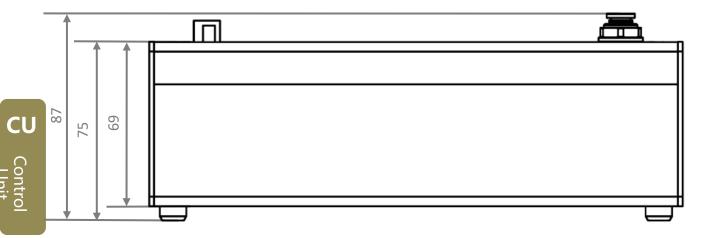
CU



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## ACU2-H Size

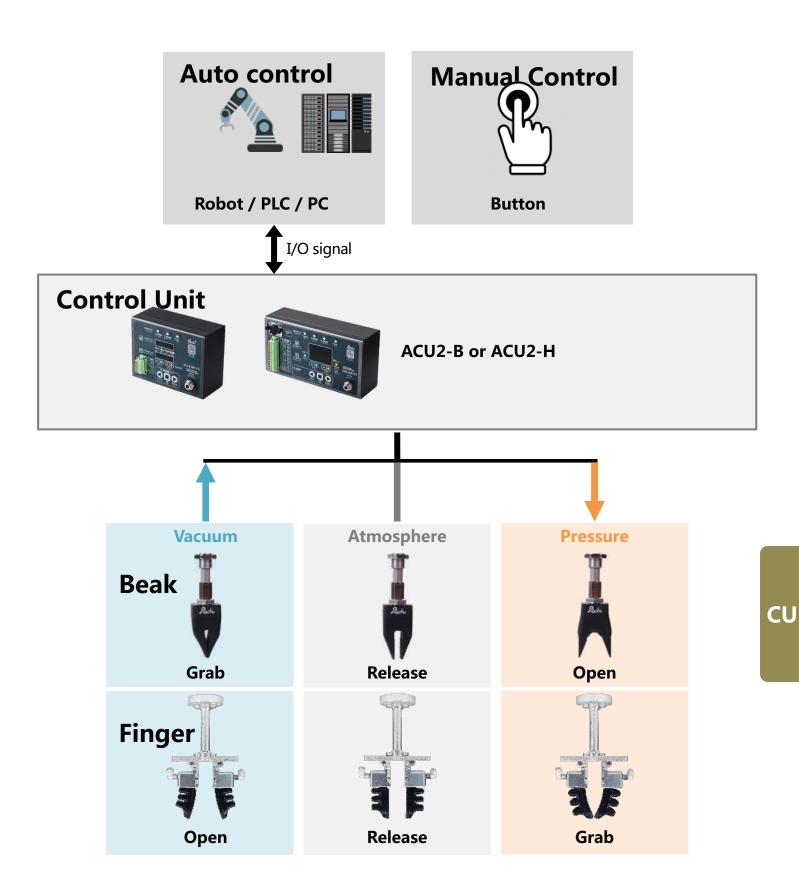






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#### How to use ACU2-B & ACU2-H





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## **PCU2** Control Unit

#### Full function controller

- -80~300kPa digital Adjust Output pressure Range , suit for all kinds of Beak & Finger.
- It can precisely adjust the working Pressure or Vacuum, and can choose the manual knob pressure regulating type PCU2-M or the electronic analog pressure regulating type PCU2-V.
- The integrated panel integrates digital display and operation buttons.
- It has various control modes of manual (button), I/O and MODBUS, and is compatible with various mechanical arms and PLC terminals.
- With attitude feedback signal function.
- With an intelligent output alarm signal, it is safe, and there is no need to worry about misoperation.



#### Parameter

	Item	Range	Item	Range
CU	Nominal Voltage	24VDC±10%	Frame Material	Anodic oxidation of aluminum alloy
0	Rated Power	24W	Net Weight	3.85kg
Control Unit	Life time	50 million times	Protect grade	IP54
+ <u>o</u>		0.45~1.00MPa		1. Manual button
	input air	dry、clean、stable	Mada	2. I/O , level signal
		Flow > 200L/min	Mode	3. remote ( PCU2-M )
	Output pressure	-80~300kPa		4. Modbus TCP/RTU
	Pressure Flow	260L/min	working mode	Continuous signal drive
	Vacuum Flow	80L/min	working noise	50db
	Model			

#### Model

Мос	del	Manual	Electronic	remote	feedback	Safe pressure	Size [mm]	Net Weight [kg]
Manual regulator	PCU2-M	•		•	•	adjustable	165x280x124	3.85
Electronic regulator	PCU2-V		•		•	adjustable	165x280x154	4.40

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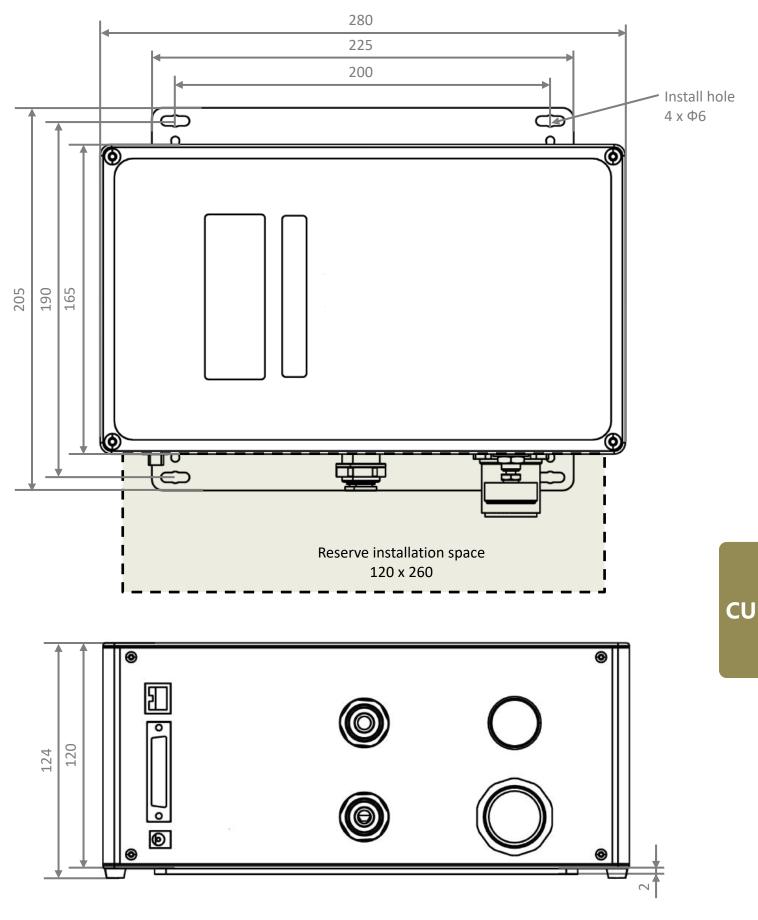
## **Control Unit**

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**PCU2-M Size** 





#### **Control Unit / Control** Unit

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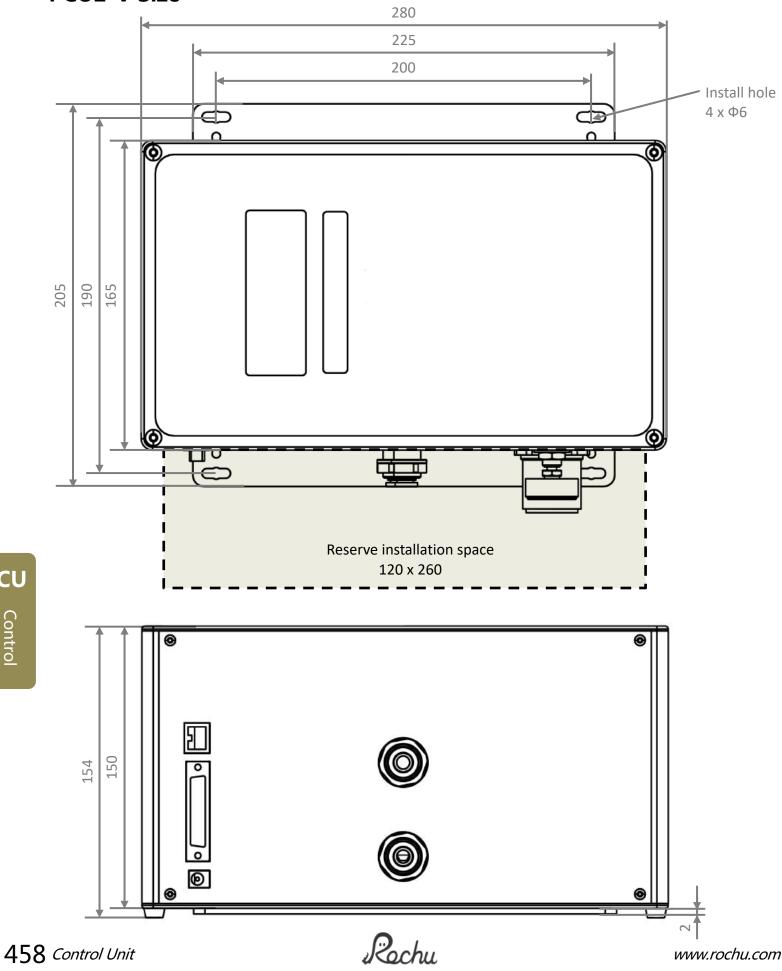


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**PCU2-V Size** 

CU

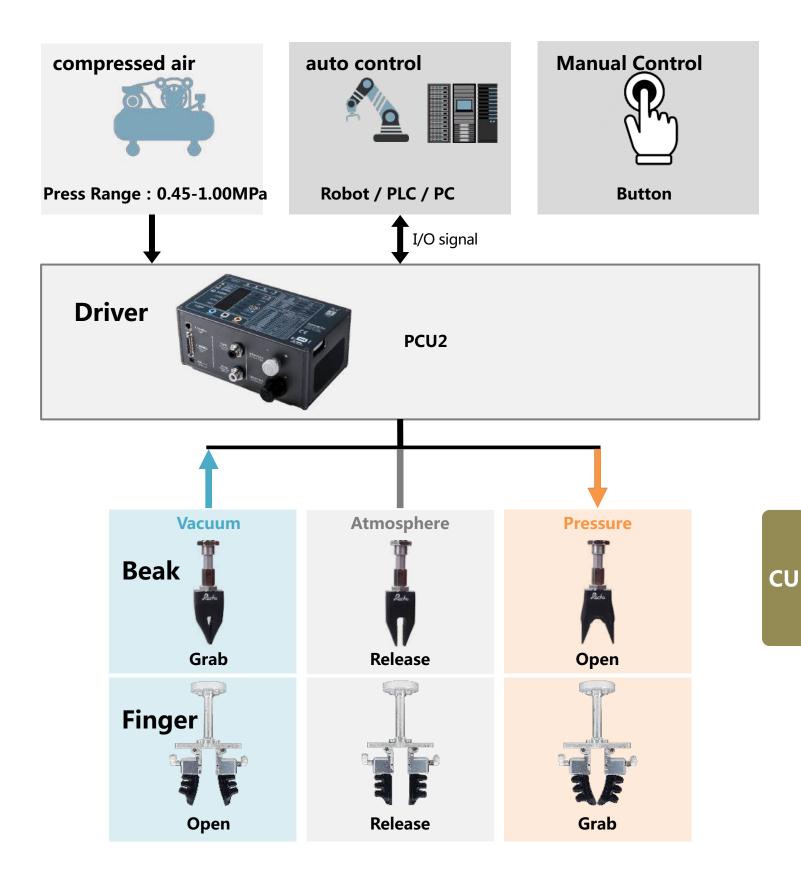
Control



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#### How to use PCU2



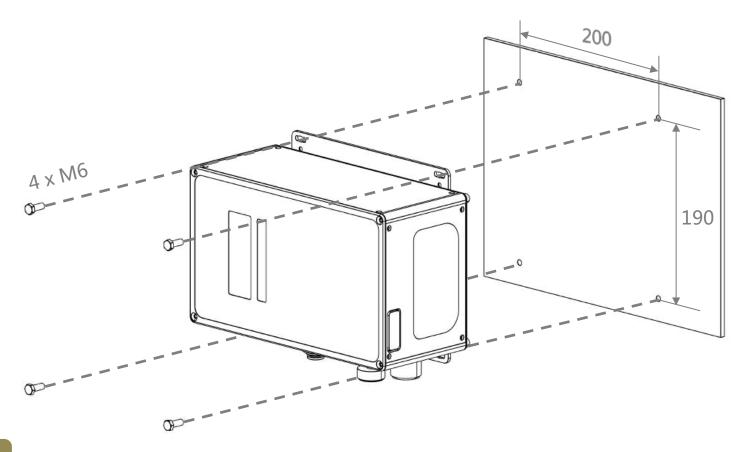




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## **PCU2** Installation

Panel to install





## **Control Unit**

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#### LCU-H Micro Control Unit

- Micro Driver
- -85~300kPa Output pressure Range, Suit for all Beaks and Fingers.
- Cylinder pneumatic Mode, simple operation, convenient replacement.
- Small size, light weight, multi way and composed of asynchronous drive mode
- Equipped with plane, flange Installation hole and industrial rail buckle, a variety of Installation.



#### Parameter

Item	Range	Item	Range
Output pressure	-85~300kPa	Frame material	Anodic oxidation of aluminum alloy
working noise	50db	Size	85x63.6x31mm
Life time	50 million times	Net Weight	350g
	0.45~0.80MPa	working mode	penumatic
input air	dry、clean、stable	Pressure Flow	165L/min*
	Flow > 200L/min	Vacuum Flow	55L/min

\* : The Flow Parameter test conditions are :

High pressure air source port H=0.6MPa , Low pressure air source port L=100kPa



Control Unit 461

CU

## Control Unit / Control Unit

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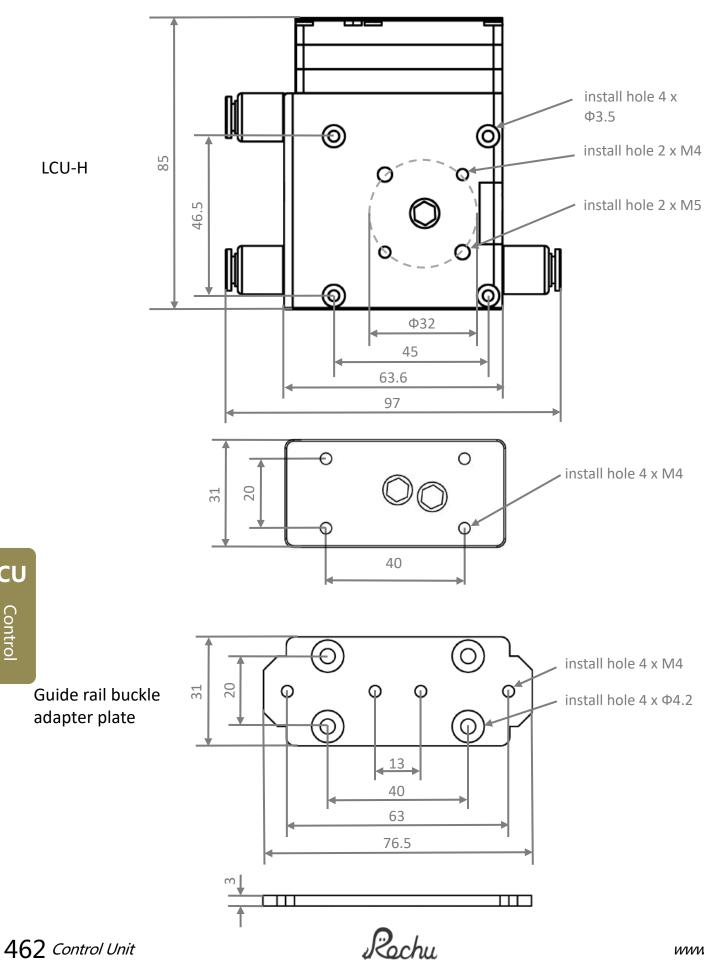
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**LCU-H Size** 

CU

Control

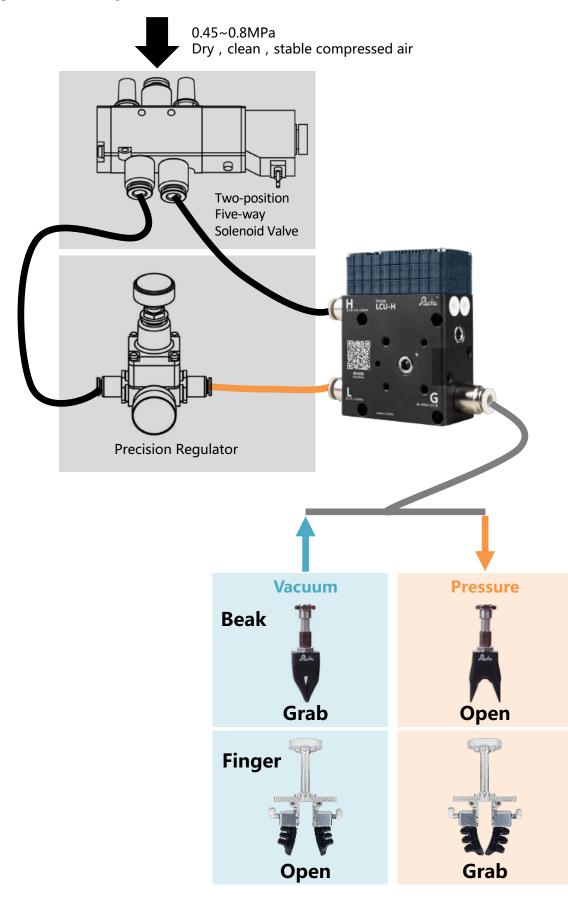


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# Way 1 : Two- position Single drive





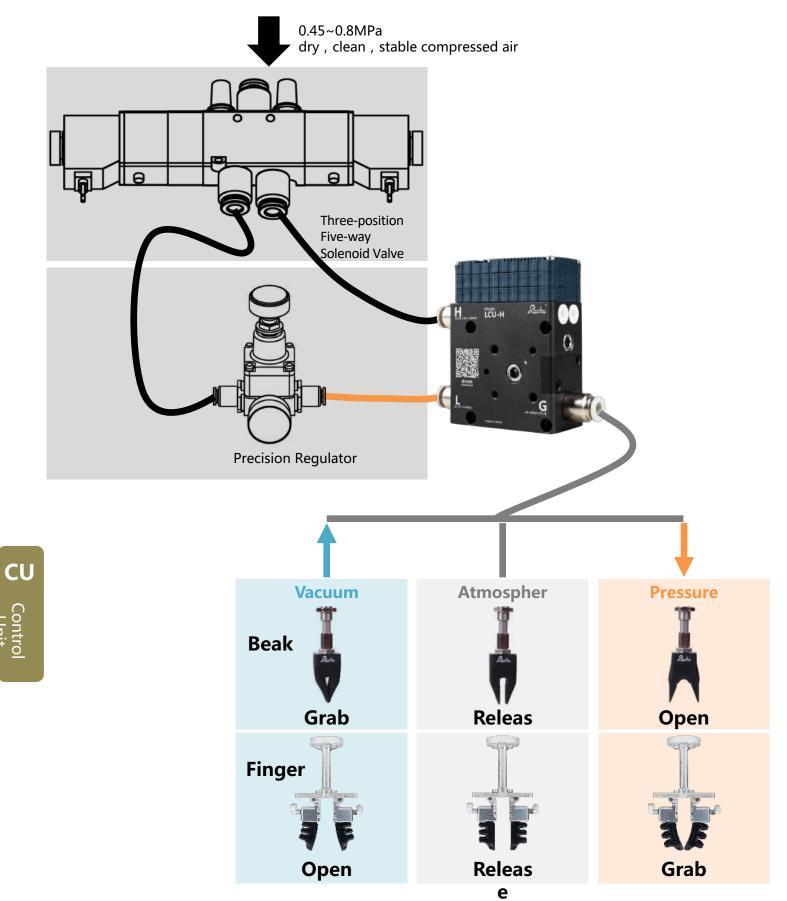
#### **Control Unit / Control** Unit

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## Way 2 : three-position single drive



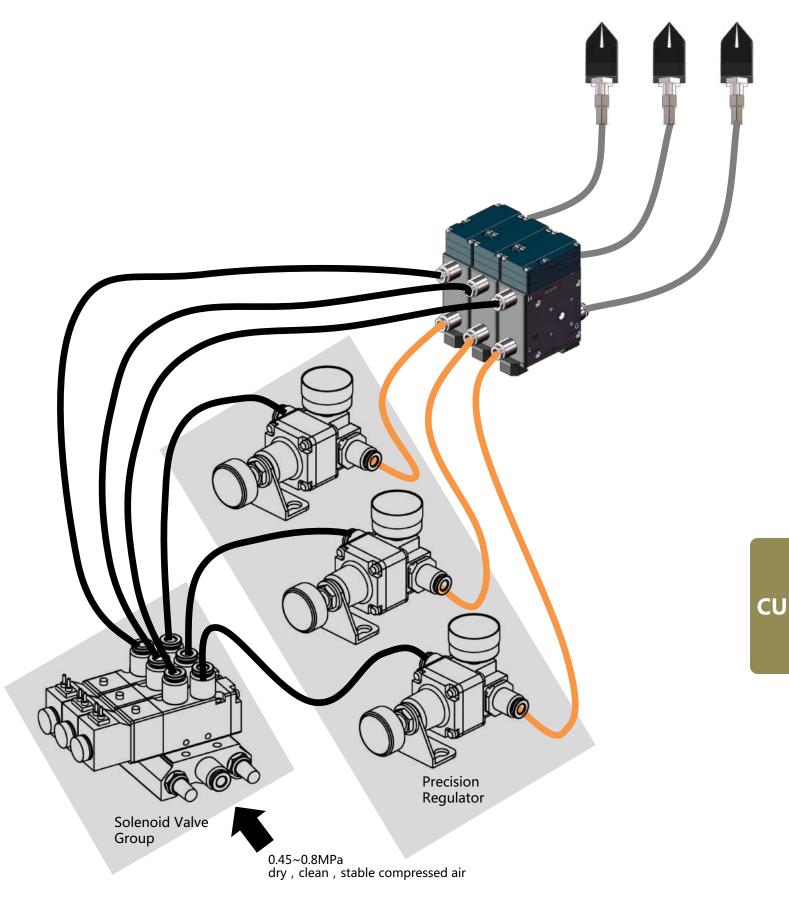
Control



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# Way 3: Multiple Drive





Control Unit 465

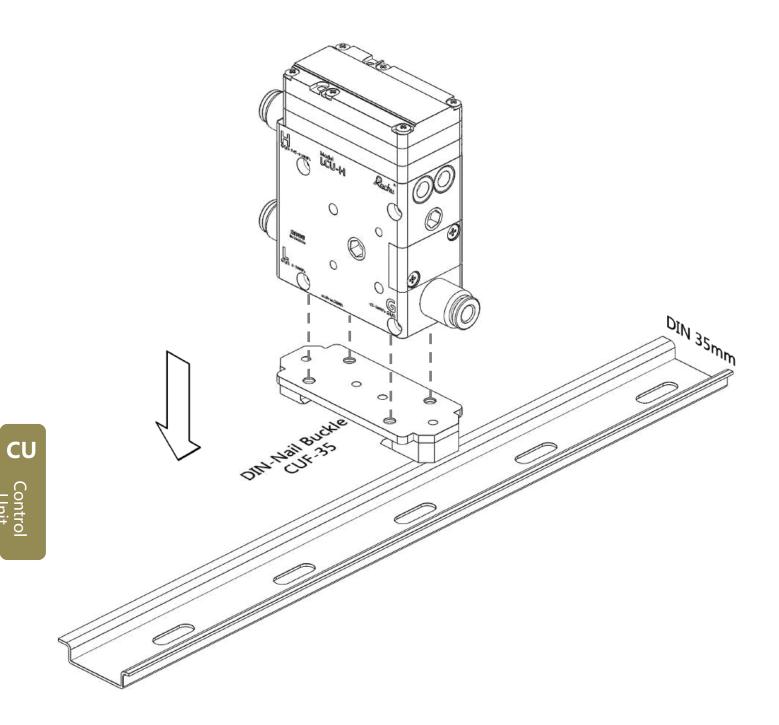
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## **LCU-H Installation**

**①DIN-Rail Installation** 

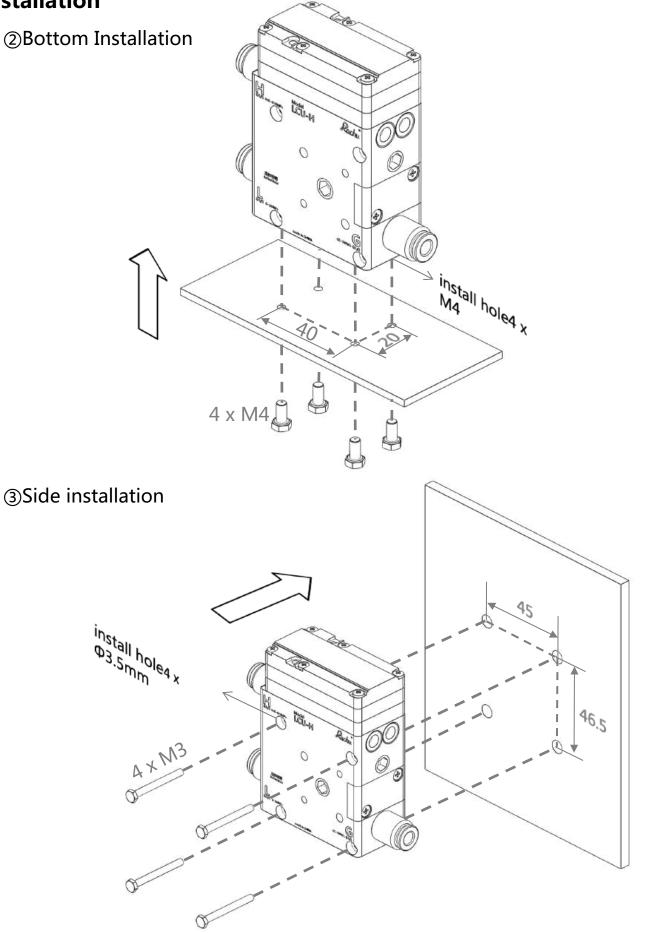




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## Installation





Control Unit 467

CU

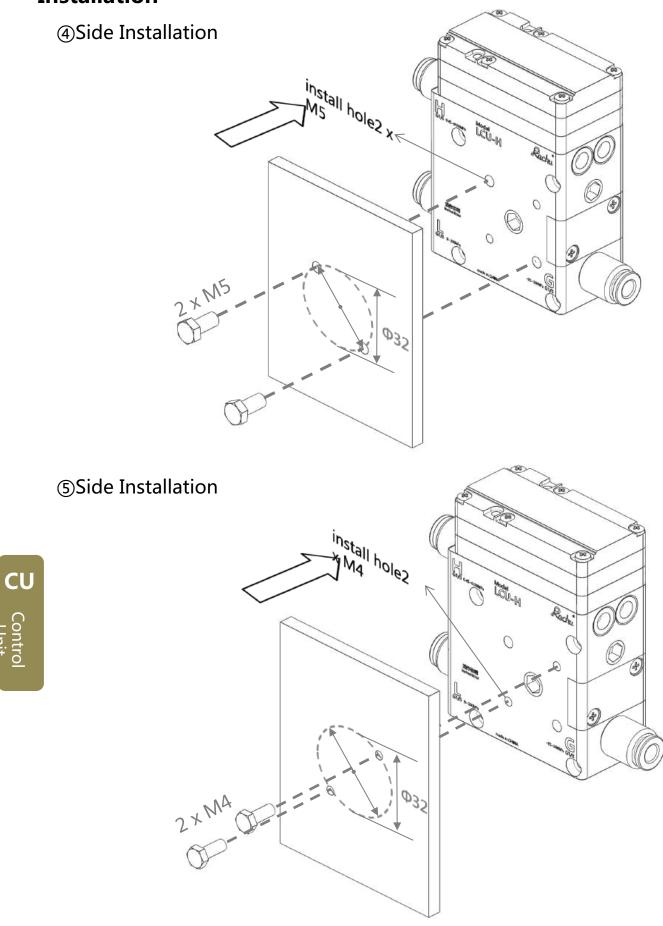
## **Control Unit / Control** Unit

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#### Installation



Control



### **Control Unit**

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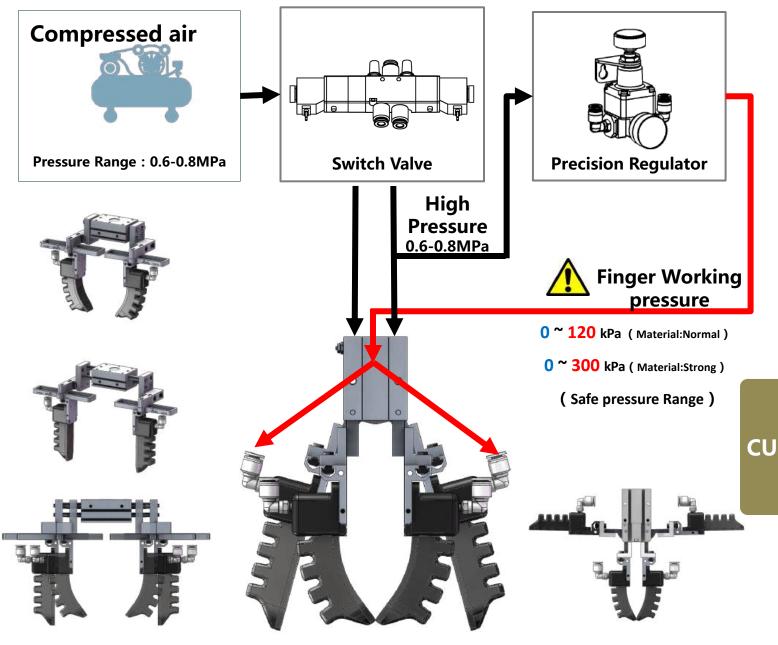
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# 组合驱动方式

# **Controling of Cylinder & Finger module combination**

- The combination of cylinder and finger module is a specific combination of the basic control mode
- It has the advantages of large clamping force of traditional clamping cylinder and soft and self-adaptive of
  - flexible fingers, and the clamping force can reach up to 70N
- Independent solenoid valve control, simple structure, small size, low deployment cost.
- Grasp a wider range, can be combined with various brands of cylinder, Y cylinder, 180 degree cylinder



Translational cylinder

Y Cylinder

180 degree Cylinder

The air pressure must be strictly controlled within the Safe limit. Overloading may cause irreversible damage to the product.

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# CM



SMP Slide Mounting Plate



**CM** Connection Module



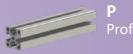
FCM Flange Connection Module



QCM Quick changer Module

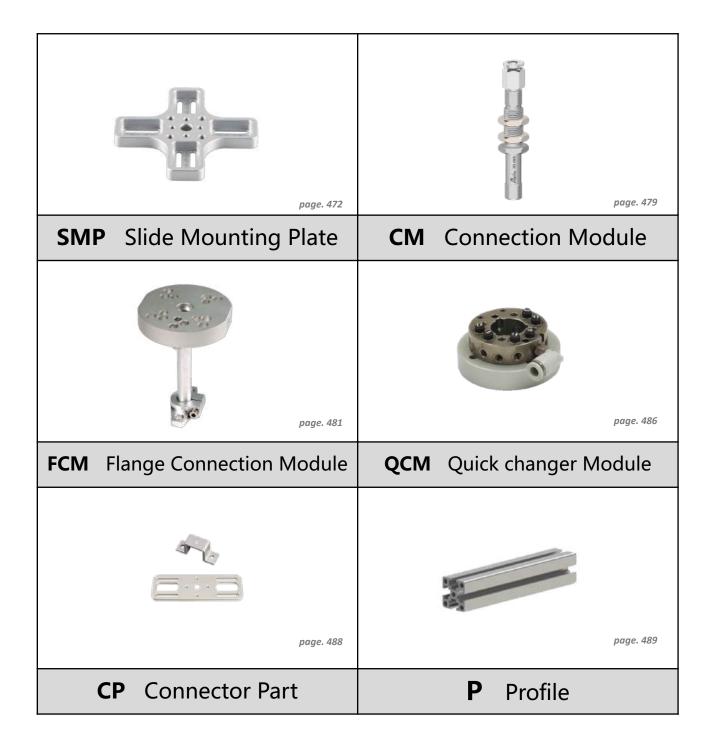


CP





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471 Connection module

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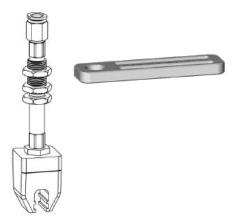
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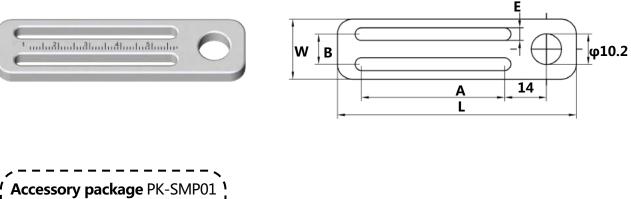
### **Slide Mounting Plate**

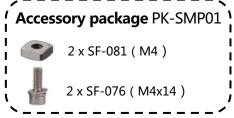
#### **SMP-**Soft Beak Module Series

#### **Product features**

- Length: SMP-13/ SMP-14 / SMP-15/ SMP-16.
- Assembling between soft beak module [BM], connection module [CM] and aluminum profile [P].
- The installation Angle and position of the soft beak module **[BM]** can be adjusted freely.
- Accessory package (PK-SMP01 ) included.







Model	Slot Length A [mm]	Slot Space B [mm]	Slot Width E [mm]	Length L [mm]	Width W [mm]	Thickness [mm]	Weight [g]
SMP-13	20	10	4.2	50	20	6	10.7
SMP-14	48	10	4.2	80	20	6	16.2
SMP-15	80	10	4.2	110	20	6	21.6
SMP-16	110	10	4.2	140	20	6	27.1

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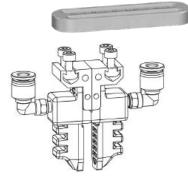
W

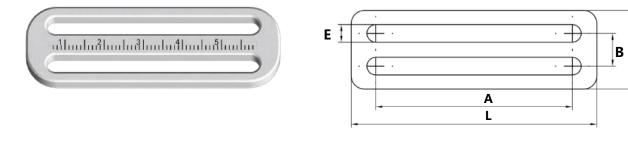
# Slide Mounting Plate/ Slide Mounting Plate

**SMP-**Independent finger module series

#### **Product features**

- Length: SMP-01 / SMP-02 / SMP-03
- Assembling between soft finger module [FM], and aluminum profile [P].
- The installation Angle and position of the soft finger module **[FM]** can be adjusted freely.
- Accessory package (PK-SMP01) included.





Model	Slot Length A [mm]	Slot Space B [mm]	Slot Width E [mm]	Length L [mm]	Width W [mm]	Thickness [mm]	Weight [g]
SMP-01	50	10	4.2	65	20	6	10.8
SMP-02	75	10	4.2	90	20	6	16.1
SMP-03	100	10	4.2	115	20	6	18.5



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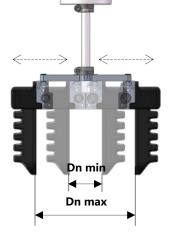
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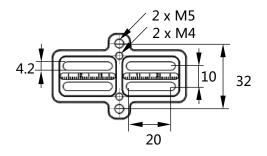
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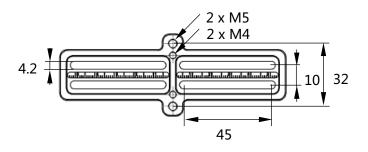
#### **SMP-**Multidirection series

#### **Product features**

- Different styles according to shape and slot length.
- Assembling between soft finger module [FM], and flange connection module [FCM].
- The installation Angle and position of the soft finger module **[FM]** can be adjusted freely.









SMP-2S



SMP-2L

			Model	Thickness	Atmospheric Finge Dnmi	Weight	
				[mm] ·	V2,V4 Finger Module	V3,V5 Finger Module	[g]
CM		Тжо-жау	SMP-2S	8	40~69	10~37	18.2
		Two-way	SMP-2L	8	40~119	10~87	28.2

\* : Maximum gripping range of gripper combination Gmax=Dnmax+2Hmax. For Hmax, please refer to the Finger Module parameter page.



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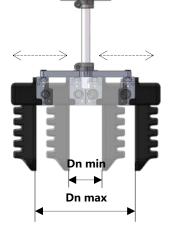


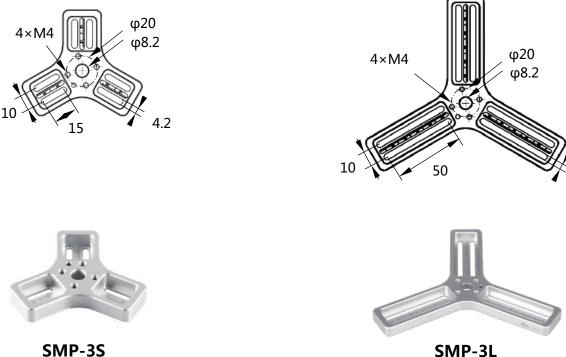
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#### **SMP**-Multidirection series

#### **Product features**

- Different styles according to shape and Slot Length. •
- Assembling between soft finger module **[FM]**, and flange connection module **[FCM]**.
- The installation Angle and position of the soft finger • module [FM] can be adjusted freely.





SMP-3L

	Model	Thickness	AtmosphereFinge Dnmi	Weight[g]	
		[mm]	V2,V4Finger Module	V3,V5Finger Module	5 -5-
Three-way	SMP-3S	8	58~82	28~50	34.6
	SMP-3L	8	58~152	28~120	54.1

\* : Maximum gripping range of gripper combination Gmax=Dnmax+2Hmax. For Hmax, please refer to the Finger Module parameter page.



CM

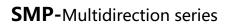
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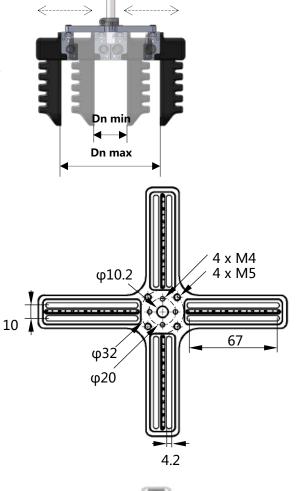
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#### **Product features**

- Different styles according to shape and Slot Length.
- Assembling between soft finger module [FM], and flange connection module [FCM].
- The installation Angle and position of the soft finger module **[FM]** can be adjusted freely.





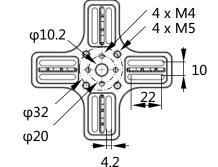


SMP-4S

SMP-4L

		Model	Thickness	AtmosphereFinge Dnmi	Weight[g]	
			[mm]	V2,V4Finger Module	V3,V5Finger Module	
м	Faur	SMP-4S	8	72~104	41~72	55
	Four-way	SMP-4L	8	72~194	41~162	89.5

\* : Maximum gripping range of gripper combination Gmax=Dnmax+2Hmax. For Hmax, please refer to the Finger Module parameter page.



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#### **SMP-**Multidirection series

φ10.2

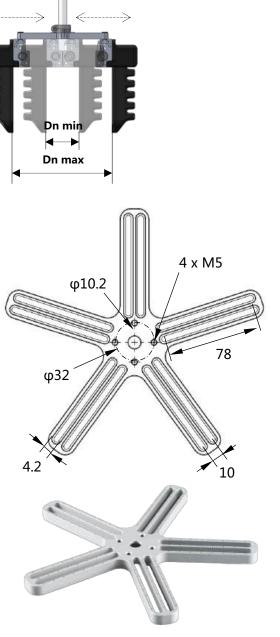
φ32

#### **Product features**

- Different styles according to shape and Slot Length.
- Assembling between soft finger module [FM], and flange connection module [FCM].
- The installation Angle and position of the soft finger module **[FM]** can be adjusted freely.

4 x M5

10



SMP-5S

SMP-5L

	Model	Thickness	AtmosphereFinge Dnmi	Weight[g]	
		[mm]	V2,V4Finger Module	V3,V5Finger Module	
Five-way	SMP-5S	10	91~112	53~80	95.4
	SMP-5L	10	91~222	53~109	181

\* : Maximum gripping range of gripper combination Gmax=Dnmax+2Hmax. For Hmax, please refer to the Finger Module parameter page.

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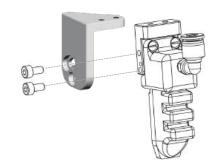
#### **Connector Part**

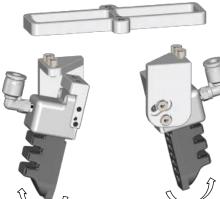
**CP-AC** Soft finger module installation Angle adjustment piece

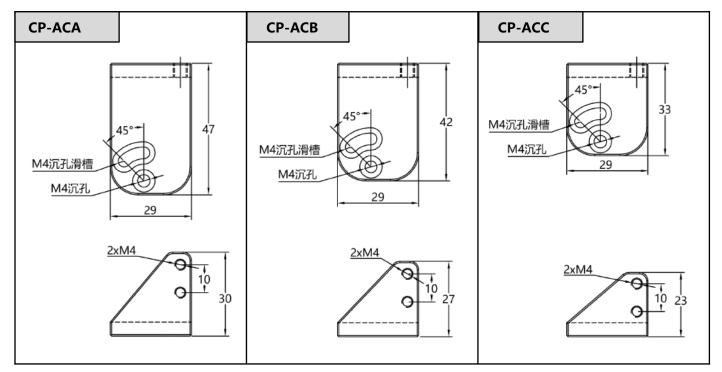
- Can be used to adjust the installation angle of soft finger module **[FM]**.
- Assembling between finger module [FM] and slide mounting plate[SMP].

45









СМ

Model	Angle range[°]		Adaptive soft finger module[FM]							
		V1	V2	V3	V4	V5				
CP-ACA	0~45		√	$\checkmark$			22			
CP-ACB	0~45		$\checkmark$	√			19			
CP-ACC	0~45			$\checkmark$			15			

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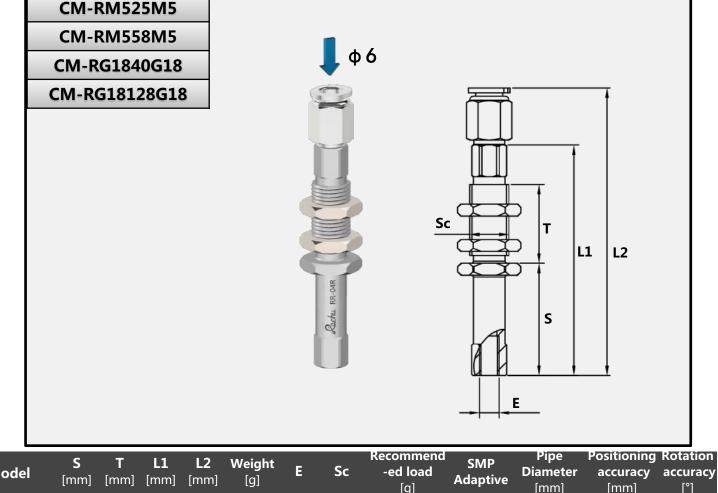
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**CM** -**R** Soft Beak rigid connection module series

#### **Product features**

- Aluminum alloy rigid structure design, can be used for high positioning accuracy scenes. Soft Beak Module [BMC/BML] can be installed at the end.
- •
- Can be installed with Slide Mounting Plate [SMP].





Model	<b>S</b> [mm]	<b>T</b> [mm]	<b>L1</b> [mm]	<b>L2</b> [mm]	Weight [g]	E	Sc	-ed load [g]	SMP Adaptive	Diameter [mm]	accuracy [mm]	accuracy [°]	
CM- RM525M5	3	12	25	39.5	11	M5	M10x1	500	Yes	6	±0.01	±0.01	
CM- RM558M5	28.5	20	58	73	17	M5	M10x1	500	Yes	6	±0.01	±0.01	
CM- RG1840G18	9.5	16.5	40	57	33	G1/8	M14x1	1500	No	6	±0.01	±0.01	
CM- RG18128G18	59	47	128	145	58	G1/8	M14x1	1500	No	6	±0.01	±0.01	



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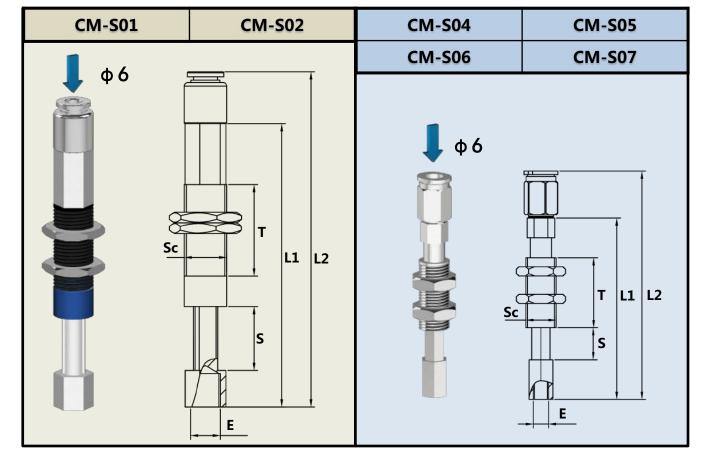
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#### **CM** -S Soft Beak buffer connection module series

#### **Product features**

- It has elastic cushioning function. We do not recommend it to be used in scenarios requiring high Positioning accuracy
- Soft Beak Module [BMC/BML] can be installed at the end.
- Some Modesl ca be installed with Slide Mounting Plate[SMP]





	Model	<b>S</b> [mm]	<b>T</b> [mm]	<b>L1</b> [mm]	<b>L2</b> [mm]	<b>Weight</b> [g]	E	Sc	Elastic buffer force [N]	Recommend -ed Load [g]	<b>SMP</b> Adaptive	Pipe diameter [mm]	Positioning accuracy [mm]	Rotation accuracy [°]
ΞΜ	CM-S01	21	30	93	110	38.4	G1/8	M14x1	0~10	800	No	6	±0.5	±3
	CM-S02	36	50	128	145	45.4	G1/8	M14x1	0~10	800	No	6	±0.5	±3
	CM-S04	10.5	23	58.5	73.9	28	M5	M10x1	0~3	300	Yes	6	±0.5	±3
	CM-S05	20	51	96	111.4	43	M5	M10x1	0~3	200	Yes	6	±0.5	±3
	CM-S06	30	51	106	121.4	50	M5	M10x1	0~3	200	Yes	6	±0.5	±3
	CM-S07	40	77	142	157.4	56	M5	M10x1	0~3	200	Yes	6	±0.5	±3

С



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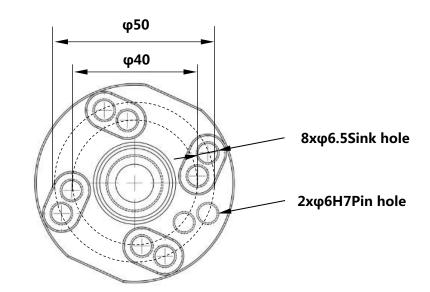
Flange connection module [FCM] is fixed between the robot flange and the slip mounting plate [SMP]. It can also be connected with quick change module [QCM], There are two kinds of [FCM], the spring rod type (S) and rigid rod type (R).

#### FCM-S01 Sping rod flange connection module

#### **Product features**

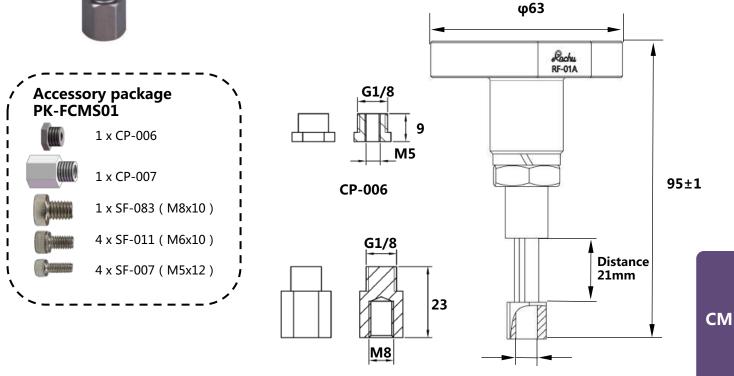
- Meet ISO 9409-1:2004 robot flange standard •
- Robot connection with the soft beak module [BM], or light soft grippers. The max. loading is 500g.
- Better adaptability in gripping of very different size object . For better positioning, pls. use the [FCM] with rigid rod.
- Accessory package (PK-FCMS01) included





G1/8





**CP-007** 



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# FCM-R(01~05) Fixed rod type flange connection module (light)

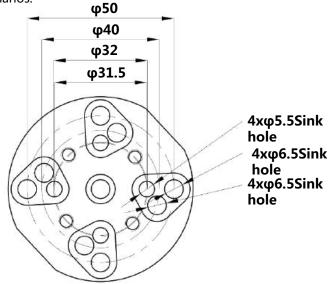
#### **Product features**

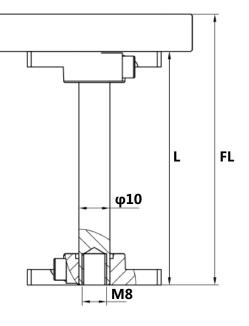
- Conform to ISO 9409-1:2004 standard (GB/T 14468.1-2006/), suitable for most robot flanges in the market.
- Light weight, suitable for lightweight multi-joint robot. Recommended maximum load : 5 kg.
- Can be used for high-precision handling, assembly and other scenarios.
- Different lengths are available.
- Accessory package PK-FCMR01 included.

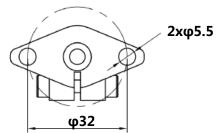


#### Lightweight FCM series sizes

Model	Length L[mm]	Overall Length FL [mm]	Weight[g]
FCM-R01	35	42	116
FCM-R02	55	62	113
FCM-R03	75	82	117
FCM-R04	95	102	121
FCM-R05	115	122	165









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#### **Flange connection**

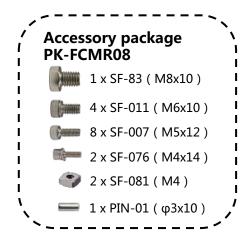
#### FCM-R08 Fixed rod type flange connection module

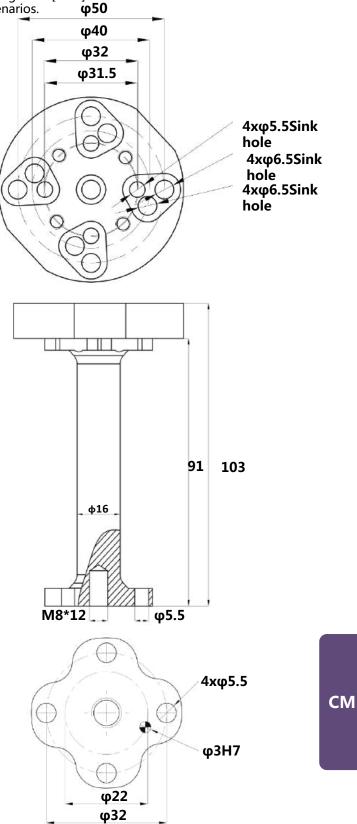
#### **Product features**

- Conform to ISO 9409-1:2004 standard (GB/T 14468.1-2006/), suitable for most robot flanges in the market.
- Suitable for non-standard gripper combination and Slide Mounting Plate [SMP].
- Can be used for high-precision handling, assembly and other scenarios.  $oldsymbol{\phi}$
- Accessory package PK-FCMR08 included.



Weight159g







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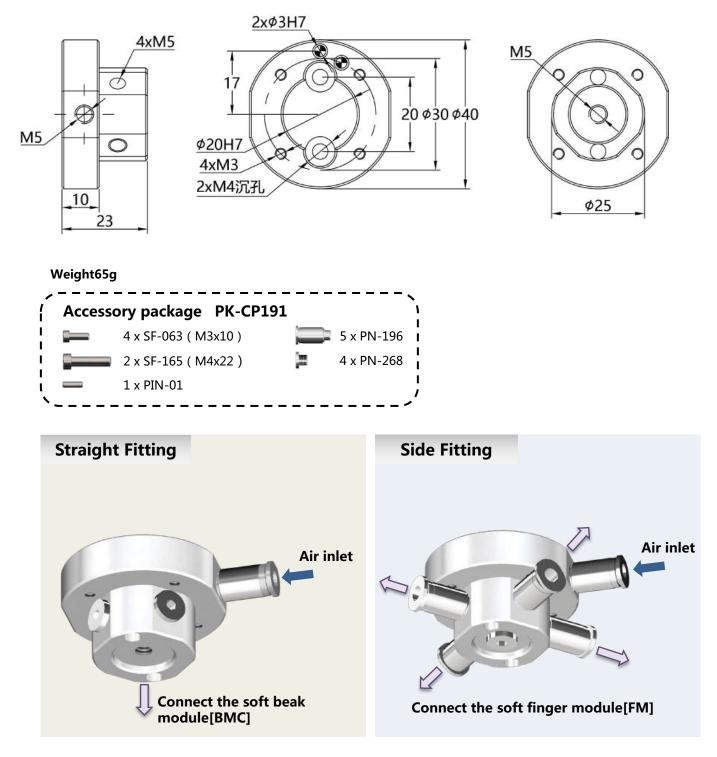
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# **Connector Part**

#### **CP-191** Connecting flange

• Internal multi-channel ventilation manipulator adapter flange







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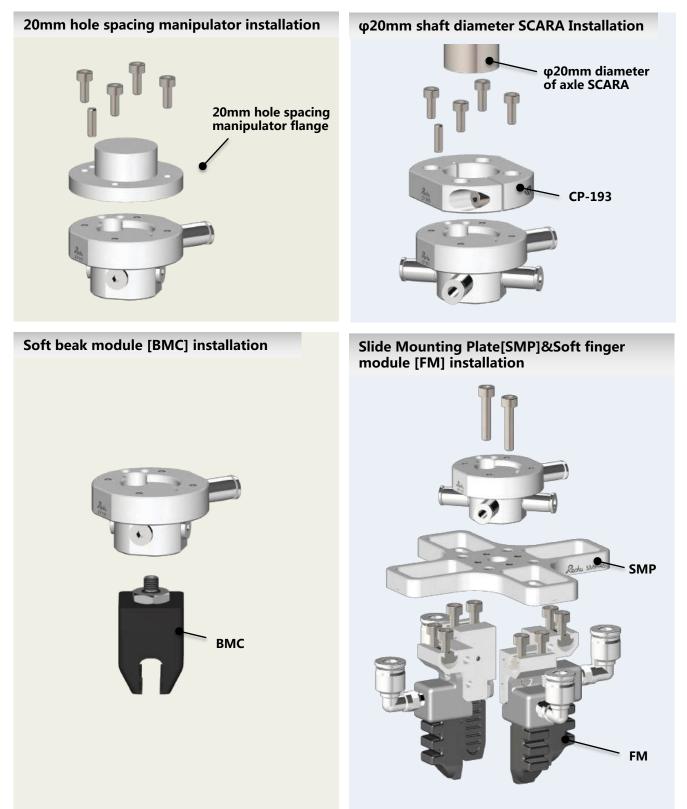
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# **Connector Part**

#### Installation

- Suitable for 20mm hole spacing manipulator flange or  $\varphi$ 20mm shaft diameter SCARA manipulator end. Assembling **soft beak module [BMC] or Slide Mounting Plate[SMP]** •





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# **Quick changer Module**

Quick change module **[QCM]** is used for quick replacement of gripper.Quick change module **[QCM]** is installed between the flange connection module **[FCM]** and robot flange, which is uncoupled into the robot side (**R side**) and the gripper side (**G side**).

### QCM-01 Manual quick change module

#### **Product features**

- Conform to ISO 9409-1:2004 (i.e. GB / T 14468.1:2006).
- Manual locking/unlocking.
- Recommended Load 5kg , Vertical tension.

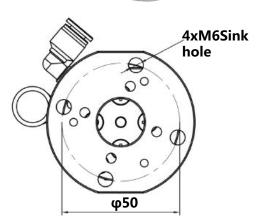


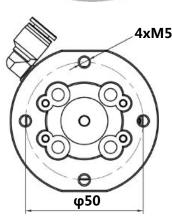


QCM-01R ( R side module, installed at the end of the manipulator )

#### **QCM-01G** ( G side module, mounted on the gripper end )







Lock Max 2Nm



QCM-01RWeight [g]	146	QCM-01GWeight [g]	135
Vertical tension F	150[N]	Tracheal tube diameter	φ 6mm
Rotary torque Mt	20[Nm]	Recommend-ed Load	5[kg]
Flip torque Mb	10[Nm]		

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# **Quick changer Module**

Quick change module **[QCM]** is used for quick replacement of gripper.Quick change module **[QCM]** is installed between the flange connection module **[FCM]** and robot flange, which is uncoupled into the robot side (**R side**) and the gripper side (**G side**).

QCM-02 Pneumatic quick change module

#### **Product features**

- Conform to ISO 9409-1:2004 (i.e. GB / T 14468.1:2006).
- Pneumatic control, air-out self-locking protection.
- Recommended Load 5kg.





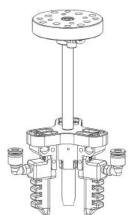


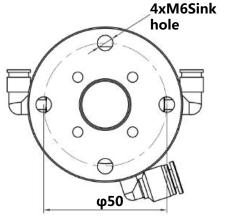


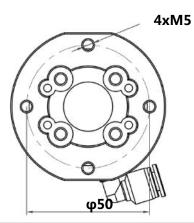
QCM-02R

( R side module, installed at









Quick change suction control joint M5+ $\phi$ 6 pipe

#### Installation/control mode

- Quick change is controlled by pneumatic mode, similar to cylinder control mode, can be controlled by CV-SV series switch valve.
- The R side pipe connector is connected to the Rochu controller
- The pipe connector on the G side is connected to the gripper
- Note: When installing the R-side flange module, you need to install the flange piece with Robotic Arm first and then connect the quick switch to the flange piece



Controller pipe connector M5+ $\phi$ 6 pipe



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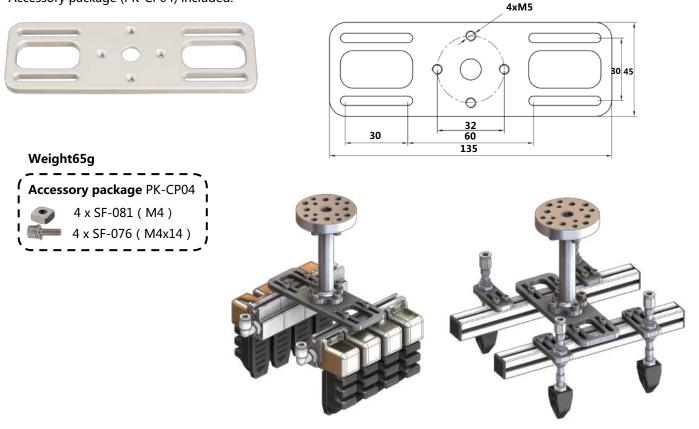


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### **Connector Part**

#### **CP-04** Connector Part

- Assembling Finger Module[FM] or aluminum profile [P].
- Accessory package (PK-CP04) included.



#### CP-01 Connector Part

Profile [P] cross fixed arch mounting bracket
 Accessory package (PK-CP01) included.
 22.5
 Ueight10g
 Accessory package PK-CP01
 2 x SF-081 (M4)
 2 x SF-075 (M4x12)



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# Profile

	Model	Length L [mm]	Width W [mm]	Height H [mm]	Weight [g]
	P-20100	100	20	20	47
	P-20150	150	20	20	70.5
н	P-20200	200	20	20	94
	P-20300	300	20	20	141
W A	P-20400	400	20	20	188
	P-20500	500	20	20	235

СМ





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